core.camera.Camera
init(self, position, h_orientation, v_orientation, fov=pi/4)
m position(self)
vueorientation(self)
m horizontalorientation(self)
m verticalorientation(self)
m fov(self)
<u>f</u> position
<pre>fv_orientation</pre>
ffov
<pre>fvue_orientation</pre>
<pre>fh_orientation</pre>