Padrões de Projeto

Unidade 1

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INTRODUCTION

- What is a design pattern?
- How to decompose a system into objects?
 - O Nouns?
 - Collaborations among objects ?
 - Responsibilities ?
 - Real world?
- Modelling a system as the real world may represent the present, but not the future
- The abstractions used during the project are the key for flexible designs



INTRODUCTION

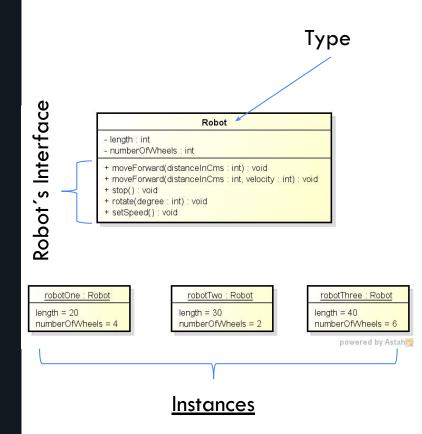
- Design Patterns assist in finding out not so obvious abstractions
 - States,
 - o Strategies,
 - o Observers,
 - O Composites,
 - Etc..
- Would you create a class with these names in your project?



INTERFACES

Interfaces

- o Interfaces are the set of signatures an object exposes
- The interface of an object states all the requisitions can be sent to it
- A Type is a name used to denote a specific interface
- Objects can have several types (hierarchy)
- Interfaces do not say anything about the object's implementation (i.e., the o methods)



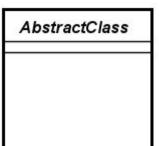
STATIC OR DYNAMIC BINDING? POLYMORPHISM?

- Static Binding / Dynamic
 - Static: The link between a **request** to an object **to one of its operations** is in design/compile time
 - Opynamic: The link between a **request** to an object **to one of its operations** is in run-time

Class	

Client c = new Client
...
c.myMethod()

Client não é abstrata/interface Os serviços oferecidos são "linkados" ao tipo concreto antecipadamente... em tempo de compilação

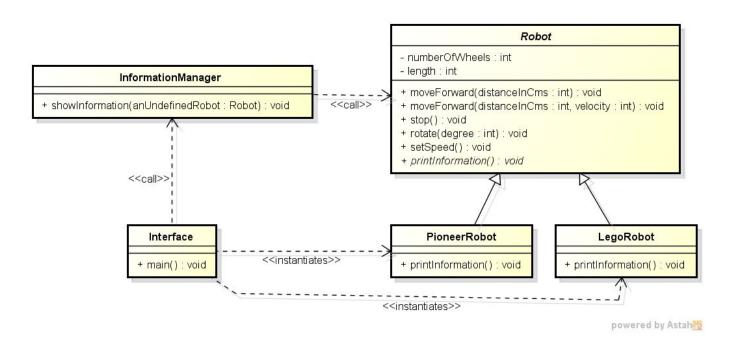


Abstract Client c;
...
c.myMethod()

Client é abstrata Os serviços oferecidos podem ser demandados mesmo sem saber quem irá efetivamente executá-los.

STATIC OR DYNAMIC BINDING? POLYMORPHISM?

Let's understand this example :



STATIC OR DYNAMIC BINDING? POLYMORPHISM?

What is "Dynamic binding"?

 The link between a request to an object to one of its operations in runtime (thanks to polymorphism)

Aqui está a mágica

```
public static void main(String args[]) {

Important!

Robot robotOne;

if (condition) {
    robotOne = new LegoRobot();
} else {
    robotOne = new PioneerRobot();
}

InformationManager.showInformation(robotOne);
}
```

public class PioneerRobot extends Robot



```
STATIC BINDING...
                                                                                                    InformationManager
                                                                                                                       <<call>>
                                                                                            + showInformation(aLegoRobot : LegoRobot) : void
                                                                                            + showInformation(aPioneerRobot : PioneerRobot) : void
                                                                                                                             + rotate(degree : int) : void
                                                                                                                             + setSpeed(): void
                                                                                                                             + print/nformation(): void
                                                                                                    <<call>>
public class InformationManager {
                                                                                                                                LegoRobot
                                                                                                       Interface
                                                                                                                   <<call>>
                                                                                                                             + printInformation(): void
    public static void showInformation(LegoRobot aLegoRobot) {
                                                                                                      + main(): void
          aLegoRobot.printInformation();
     public static void showInformation(PioneerRobot aPioneerRobot) {
          aPioneerRobot.printInformation();
                                                                                    public static void main(String args[]) {
                                                                                    PioneerRobot pioneerRobot = new PioneerRobot();
                                                                                    LegoRobot aLegoRobot = new LegoRobot();
public class PioneerRobot extends Robot
                                                                                    String type = "null";
   public void printInformation() {
           System.out.println('This is a pionner robot');
                                                                                    if (type == "pioneer") {
```

```
public class LegoRobot extends Robot {
    public void printInformation() {
         System.out.println('This is a lego robot !');
```

```
+ moveForward(distanceInCms : int) : void
+ moveForward(distanceInCms : int, velocity : int) : void
                                  printInformation(): void
```

```
ShowInformation.showInformation(pioneerRobot);
} else {
```

ShowInformation.showInformation(aLegoRobot);

STATIC BINDING...

```
class InformationManager:
   def showInformation(aLegoRobot: LegoRobot):
        aLegoRobot.printInformation()
   def showInformation(aPioneerRobot: PioneerRobot):
        aPioneerRobot.printInformation()
class Robot:
   def printInformation( self ):
       raise NotImplementedError
class PioneerRobot(Robot):
   def printInformation( self ):
        print("This is a pionner robot")
class LegoRobot(Robot):
   def printInformation( self ):
        print("This is a lego robot")
```

```
Robot
                                                                    - numberOfWheels int
                                                                    - length : int
                      InformationManager
                                                                    + moveForward(distanceInCms:int):void
                                                                    + moveForward(distanceInCms : int, velocity : int) : void
                                                         <<call>>
        + showInformation(aLegoRobot : LegoRobot) : void
                                                                    + stop(): void
        + showInformation(aPioneerRobot : PioneerRobot) : void
                                                                    + rotate(degree : int) : void
                                                                    + setSpeed(): void
                                                                    + print(nformation(): void
                      <<call>>
                           Interface
                                                                         LegoRobot
                                                                                                 PioneerRobot
                                                <<call>>
                         + main(): void
                                                                    + printInformation(): void
                                                                                             printInformation(): void
                                                                <<call>>
if name == " main ":
      if condition:
             robotOne = LegoRobot()
       else:
             robotOne = PioneerRobot()
      InformationManager.showInformation(robotOne)
```



YOU NEED TO PROGRAM FOR INTERFACES...

You need to program for interfaces, not for particular implementations

- o Using inheritance you can define family of objects sharing identical interfaces
- All subclasses are able to reply to the requests forwarded to the interface of the abstract class
- The main benefit of manipulating objects only considering their interfaces is that clients keep unaware of the type of the objects they use

GAMMA'S DESIGN PATTERNS

		Purpose			
		Creational	Structural	Behavioral	
Escopo	Class	Factory Method	Adapter	Interpreter Template Method	
	Object	Abstract Factory Builder Prototype Singleton	Adapter Bridge Composite Decorator Façade Flyweight proxy	Chain of Responsibility Command Iterator Mediator Memento Observer State Strategy Visitor	

TEMPLATE FOR DESCRIBING PATTERNS

- Pattern Name and Classification
- Intent
- Also Known As
- Applicability
- Structure

- Participants
- Collaborations
- Consequences
- Implementation
- Sample Code
- Known Uses
- Related Patterns





Singleton

(Creational pattern)





SINGLETON

When to use?

You should use this pattern when classes must have just one instance



SINGLETON

Examples

Classes responsible for establishing connections with DB. It is not necessary create a new connection object every time you need to connect to the DB... this will overload memory and make your code polluted. You can use the same object every time.

Classes that represent sensors in robots

Classes responsible for logging events of the system execution

SINGLETON

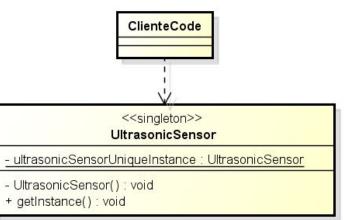
```
Singleton
```

- instance: Singleton
- + instance(): Singleton

```
public class Singleton {
    private static Singleton instance;
    private Singleton() {
      this.instance = new Singleton()
    public Singleton getInstance() {
      if (instance == null)
            instance= new Singleton();
      return instance;
} }
                                     class Singleton:
                                         instance = None
                                         @classmethod
                                         def instance(cls): #cls == class
                                             if cls. instance is None:
                                                 cls. instance = cls()
                                             return cls. instance
```

ROBOT SENSOR - SINGLETON IN JAVA

```
public class UltrasonicSensor {
   private static UltrasonicSensor ultrasonicSensorUniqueInstance;
   private UltrasonicSensor() { ... }
   public static UltrasonicSensor getInstance() {
       if (ultrasonicSensorUniqueInstance ==null)
                synchronized (UltrasonicSensor.class)
                   if (ultrasonicSensorUniqueInstance ==null) {
                        ultrasonicSensorUniqueInstance =new UltrasonicSensor();
       return ultrasonicSensorUniqueInstance;
```

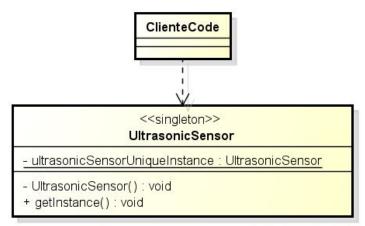


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ROBOT SENSOR - SINGLETON IN PYTHON

```
class UltrasonicSensor:
    ultrasonicSensorinstance = None
    @classmethod
   def instance(cls): #cls == class
       if (cls.ultrasonicSensorinstance is None):
           cls.ultrasonicSensorinstance=cls
       return cls.ultrasonicSensorinstance
if name == " main ":
   ultrasonicSensor1 = UltrasonicSensor.instance()
   ultrasonicSensor2 = UltrasonicSensor.instance()
   print(ultrasonicSensor1 == ultrasonicSensor2)#true
```







DB CONNECTION - SINGLETON IN JAVA

```
public class DatabaseConnection {
   private static DatabaseConnection instance = null;
   private DatabaseConnection() {
                    // Establish a database connection
       public synchronized static DatabaseConnection instance() {
           if( instance == null ) {
                instance = new DatabaseConnection();
           return instance;
           public synchronized String getAssignmentGrade String student, String course, String assignment) {
                return ...;
```

```
class Singleton:
    instance = None
   @classmethod
   def instance(cls): #cls == class
        if cls. instance is None:
            cls. instance = cls()
        return cls. instance
```



DB CONNECTION - SINGLETON IN JAVA

```
public class Client {
    public void printTranscript(String student) {
        DatabaseConnection db = DatabaseConnection.instance();
        ...
        String grade = db.getAssignmentGrade (student, course, assignment);
        ...
    }
}
```



LET'S PRACTICE?

You must reimplement the DB example (provided in Java) using the Python language



Strategy (Behavioral pattern)





STRATEGY

When to use?

Use the Strategy pattern when you want to use different variants of an algorithm (family of algorithms) and be able to switch between them during execution.



STRATEGY

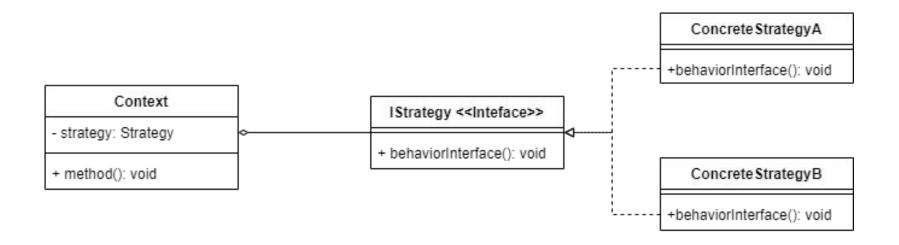
Example:

Consider the example of sorting. We implemented bubble sort, but the data started to grow and bubble sort started getting very slow.

In order to tackle this we implemented Quick sort. But now although the quick sort algorithm was doing better for large datasets, it was very slow for smaller datasets.

In order to handle this we implemented a strategy where for small datasets, bubble sort will be used and for larger, quick sort.

STRATEGY





STRATEGY IN PYTHON

```
class Strategy:
    def behavior(self) -> None:
        raise NotImplementedError

class ConcreteStrategyA(Strategy):
    def behavior(self) -> None:
        Pass

class ConcreteStrategyB(Strategy):
    def behavior(self) -> None:
        Pass
```

```
class Context():
    def __init__ (self, strategy: Strategy) -> None:
        self.__strategy = strategy

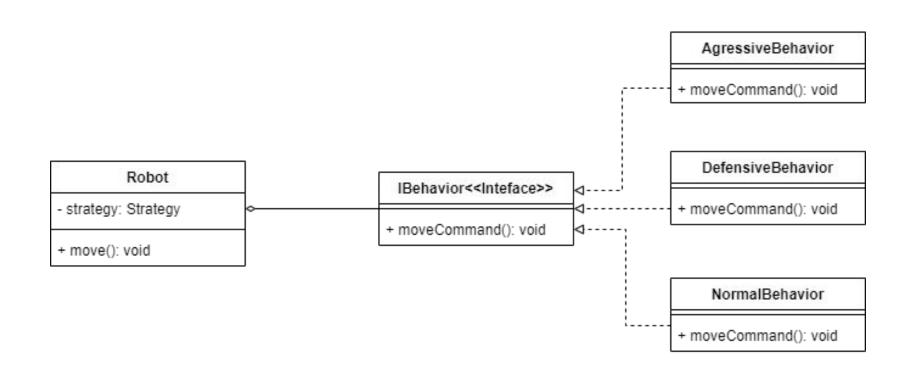
def method(self) -> None:
        self.__strategy.behavior()
```



STRATEGY IN JAVA

```
public abstract class IStrategy {
public class Context {
     private strategy IStrategy;
                                                                    public abstract void behaviorInterface();
  public class ConcreteStrategyA extends IStrategy {
      public void behaviorInterface() {
      //code for behaviorInterface A
                   public class ConcreteStrategyB extends IStrategy {
                       public void behaviorInterface() {
                        //code for behaviorInterface B
                                              public class ConcreteStrategyC extends IStrategy {
                                                  public void behaviorInterface() {
                                                  //code for behaviorInterface C
```

ROBOT EXAMPLE



ROBOT EXAMPLE - IN JAVA

```
public interface IBehaviour {
    public int moveCommand();
}
```

```
public class DefensiveBehaviour implements Ibehaviour {
   public int moveCommand()
   {
      System.out.println('\tDefensive Behaviour: if find another robot run from it");
      return -1;
    }
}
```

```
public class NormalBehaviour implements Ibehaviour {
    public int moveCommand()
    {
        System.out.println("\tNormal Behaviour: if find another robot ignore it");
        return 0;
    }
}
```

ROBOT EXAMPLE - IN JAVA

```
public class Robot {
   IBehaviour behaviour:
   String name;
   public Robot(String name)
   public void move()
        int command = behaviour.moveCommand();
```

Represent the behavior of the class, i.e., all methods that would be here, they are not anymore

It is a way of separating the structure from the behavior.

The class is less propense to receive modifications

ROBOT EXAMPLE - IN JAVA

```
public class Main {
                                                                                         Initial behavior
public static void main(String[] args) {
     Robot r1 = new Robot("Big Robot");
                                                                                            (Default)
     Robot r2 = new Robot("George v.2.1");
     Robot r3 = new Robot("R2");
    r1.setBehaviour(new AgressiveBehaviour());
    r2.setBehaviour(new DefensiveBehaviour());
     r3.setBehaviour(new NormalBehaviour());
    r1.move();
    r2.move();
                                                                                 Behavioral changes in
    r3.move();
    if (some condition)
                                                                                         runtime
         r1.setBehaviour(new DefensiveBehaviour());
    if (some condition)
         r2.setBehaviour(new AgressiveBehaviour());
                                                                                 Behavioral changes in
    r1.move();
    r2.move();
                                                                                         runtime
    r3.move();
```

ROBOT EXAMPLE - IN PYTHON

```
class DefensiveBehavior(BehaviorStrategy):
class BehaviorStrategy:
                                                def moveCommand(self) -> None:
                                                    print ("Defensive Behaviour: if find another robot run from it)"
   def moveCommand(self) -> None:
       raise NotImplementedError
  class AgressiveBehavior(BehaviorStrategy):
      def moveCommand(self) -> None:
          print("Agressive Behaviour: if find
                                                class NormalBehavior(BehaviorStrategy):
                                                    def moveCommand(self) -> None:
                                                        print("Normal Behaviour: if find another robot ignore it)"
```

ROBOT EXAMPLE - IN PYTHON

```
Initial behavior
       == " main ":
name
                                                                                       (Default)
robot1 = Robot("Big Robot")
robot2 = Robot("George v2.1")
robot3 = Robot("R2")
robot1.behavior(AgressiveBehavior())
robot2.behavior(DefensiveBehavior())
robot3.behavior(NormalBehavior())
robot1.move()
                                                                           Behavioral changes in
robot2.move()
robot3.move()
                                                                                    runtime
if condition:
    robot1.behavior(DefensiveBehavior())
if condition:
    robot2.behavior(AgressiveBehavior())
                                                                           Behavioral changes in
robot1.move()
                                                                                    runtime
robot2.move()
robot3.move()
```

LET'S PRACTICE?

Suppose a system that generates "safe routes" for pedestrians. However, the system must adapt itself in runtime as the person walk for streets. As the intention is to generate safe routes, the context can change in runtime, for example, if an attack or robbery happened in the generated route. When the context change, the system must be smart enough for proposing a new route.

There are different ways (algorithms) for generating routes:

- 1 generates a not-to-save but a shortest route
- 2 generate a safe route in an acceptable distance
- 3 generate a super-safe-route, but usually the distance is the largest Depending on the context, the generation of the route can change in runtime.