Build Petalinux 2021.2 with Vitis AI 2.0 and Smartcam

首先需要的環境有

- 1. Ubuntu 18.04
- 2. PetaLinux Tools Installer 2021.2
- 3. Kria K26 SOM Board Support Package 2021.2

建置開始

Step 1:

下載完 PetaLinux Tools - Installer 後

安裝 Dependencies

可以參考 Xilinx community 之 PetaLinux - Product Update Release Notes and

Known Issues 頁面

<command> sudo apt-get install gcc g++ libncurses5-dev libncursesw5dev libtool net-tools autoconf xterm texinfo gcc-multilib gawk zlib1g libz1:i386 zlib1g-dev build-essential

<mark><command></mark> ./petalinux-v2021.1-final-installer.run -d <自訂安裝的路徑>

不能執行請先 sudo chmod -R 777

以上便安裝完 PetaLinux Tools 與設定好環境變數

<mark>(optional)</mark>有時候同個版本像是 petalinux 2021.1 有 update 1,有加入新的 Vitis ai layers,會影響到使 用,因此會建議更新 petalinux tool

---> From Network:

<command> petalinux-upgrade -u http://petalinux.xilinx.com/sswreleases/relv2021/sdkupdate/2021.1_update1/ -p "aarch64" --wget-args "--wait 1 -nH --cut-dirs=4" ---> From Local:

<mark><command></mark> petalinux-upgrade -f <Local eSDK Directory Path> -p "aarch64"

Step 2: 創建 petalinux project

<mark><command></mark> petalinux-create -t project -s /<放 kv260 BSP的路徑>/xilinx-

k26-starterkit-v2021.1-final.bsp -n kv260 os(此為專案名稱與資料夾)

<command> cd ./kv260 os

<mark><command></mark> 1s 後可看見下圖:

parallels@parallels-Parallels-Virtual-Platform:~/kria_kv260\$ petalinux-create -t project -s ../kria_bsp/xilinx-k26-starterkit-v2 021.1-final.bsp -n kv260_os
INFO: Create project: kv260_os
INFO: New project successfully created in /home/parallels/kria_kv260/kv260_os
parallels@parallels-Parallels-Virtual-Platform:~/kria_kv260\$ cd ./kv260_os/
parallels@parallels-Parallels-Virtual-Platform:~/kria_kv260/kv260_os} ls
components config.project hardware pre-built project-spec README README.hw
parallels@parallels-Parallels-Virtual-Platform:~/kria_kv260/kv260_os\$

要先將基本的 Petalinux build 起來,後面再加入 accelerated application 和 AI 等

等之類的項目

<command> petalinux-build

- 看電腦性能,我筆電 build 了兩小時
- ◆ Step 3: 將 Vitis AI 2.0 跟一些 application 加入到 Project 中
 - 1. Vitis AI 2.0

原始在 petalinux 2021.2 的 vitis ai 為 1.4, 因此我們要先將原始的刪除

<command> cd components/yocto/layers/

<command> sudo rm -r meta-vitis-ai

然後再裝新的 meta-vitis-ai

<command> git clone -b rel-v2021.2

https://github.com/jlamperez/meta-vitis-ai.git meta-vitis-ai

再來要去將預設的 meta-vitis-ai config 路徑刪掉

<command> cd ~/kv260 os

<command> vi build/conf/bblayers.conf

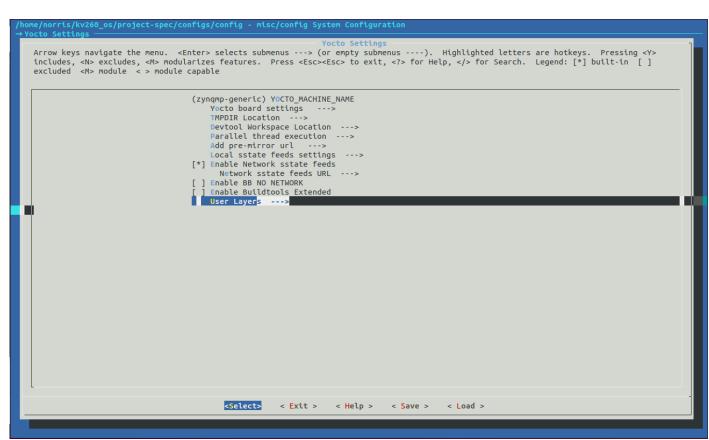
找到 \${SDKBASEMETAPATH}/layers/meta-vitis-ai 刪掉

再來需要將新的 meta-vitis-ai 加入到 config 裡面

<command> petalinux-config

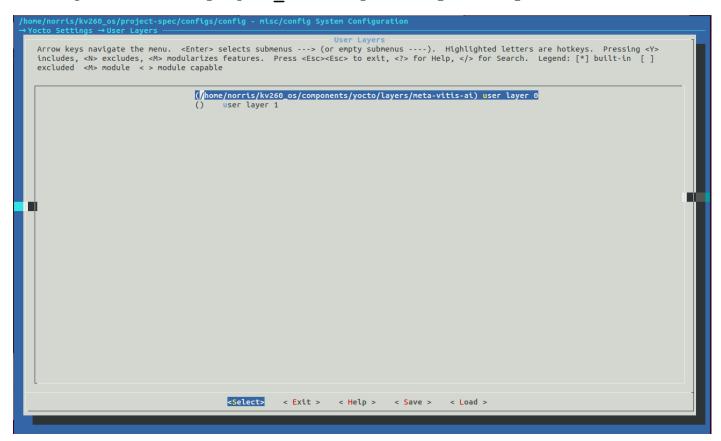
出現下圖

選擇 Yocto Settings ---> User Layers



打上如下圖中的這串文字,但前面需依照你自己的路徑

eg. /home/xxx/<project name>components/yocto/layers/meta-vitis-ai



Save ---> Exit 直到退出整個 GUI

成功會看到下圖

```
norris@ubuntu:~/kv260_os/build/conf$ petalinux-config
[INFO] Sourcing buildtools
[INFO] Menuconfig project

*** End of the configuration.

*** Execute 'make' to start the build or try 'make help'.

[INFO] Sourcing build environment
[INFO] Generating kconfig for Rootfs
[INFO] Silentconfig rootfs
[INFO] Generating plnxtool conf
[INFO] Generating workspace directory
[INFO] Successfully configured project
```

再來,petalinux build時預設是使用petalinux-image-minimal

你可以在 petalinux-image-minimal.bbappend 或是 petalinux-image-

full.bbappend 中透過

<command> vi components/yocto/layers/meta-petalinux/recipescore/images/petalinux-image-full.bb

添加下列文字

如此 Vitis ai 2.0 的部分就結束了

2. Applications

將 kv260 加入到 BOARD VARIANT 中

<command> echo 'BOARD_VARIANT = "kv"' >> project-spec/metauser/conf/petalinuxbsp.conf

接下來再將每個 kv260 四個 demo 加入到 user-rootfsconfig 中

• 這步應該是確保在用 xmutil getpkgs 時找得到相對應的 app 包

<command> echo 'CONFIG_packagegroup-kv260-smartcam' >> projectspec/meta-user/conf/user-rootfsconfig

<command> echo 'CONFIG_packagegroup-kv260-aibox-reid' >> projectspec/meta-user/conf/user-rootfsconfig

<command> echo 'CONFIG_packagegroup-kv260-defect-detect' >>
project-spec/meta-user/conf/user-rootfsconfig

<command> echo 'CONFIG_packagegroup-kv260-nlp-smartvision' >>
project-spec/meta-user/conf/user-rootfsconfig

3. Add FPGA Firmware

直接加入現有的 Firmware 即可

<command> cd ~/kv260_os

<command> git clone -b xlnx_rel_v2021.2

https://github.com/Xilinx/kv260-firmware

再來各自加入 firmware

benchmark-b4096.bb

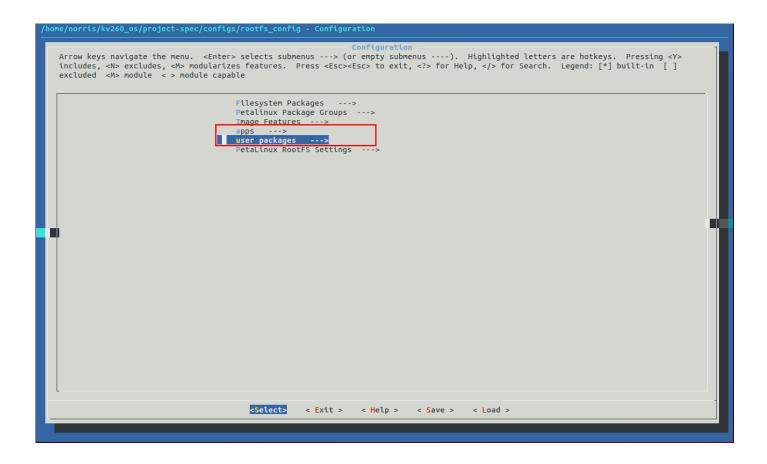
command> petalinux-create -t apps --template fpgamanager -n
benchmark-b4096 --enable --srcuri "./kv260-firmware/benchmarkb4096/kv260-benchmark-b4096.bit ./kv260-firmware/benchmarkb4096/kv260-benchmark-b4096.xclbin ./kv260-firmware/benchmarkb4096/shell.json ./kv260-firmware/benchmark-b4096/kv260-benchmarkb4096.dtsi"

smartcam.bb

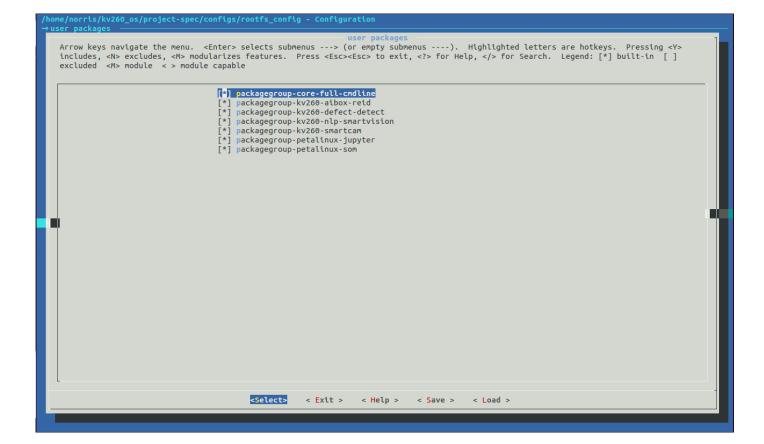
<command> petalinux-create -t apps --template fpgamanager -n karpsmartcam --enable --srcuri "./kv260-firmware/smartcam/kv260smartcam.bit ./kv260-firmware/smartcam/kv260smartcam.xclbin ./kv260-firmware/smartcam/shell.json ./kv260firmware/smartcam/kv260-smartcam.dtsi"

最後啟用 root config 來勾選 image 要使用的應用

<command> petalinux-config -c rootfs



	me/norris/kv260_os/project-spec/configs/rootfs_config - Configuration pps
	Arrow keys navigate the menu. <enter> selects submenus> (or empty submenus). Highlighted letters are hotkeys. Pressing <y> includes, <n> excludes, <m> modularizes features. Press <esc><esc> to exit, <? > for Help, for Search. Legend: [*] built-in [] excluded <m> module <> module capable</m></esc></esc></m></n></y></enter>
	["] benchmark-b4096 [] gplo-demo [*] kv260-smartcam [] peekpoke
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ı	
L	<pre><select> < Exit > < Help > < Save > < Load ></select></pre>



一樣儲存後退出,會看到

```
norris@ubuntu:~/kv260_os$ petalinux-config -c rootfs
[INFO] Sourcing buildtools
[INFO] Silentconfig project
[INFO] Generating kconfig for Rootfs
[INFO] Menuconfig rootfs

*** End of the configuration.

*** Execute 'make' to start the build or try 'make help'.

[INFO] Generating plnxtool conf
[INFO] Successfully configured rootfs
```

- ◆ Step 5: Create SD Card Image