# **Vitis Training Lab**





## **Agenda**

- > Lab 1: Get data from PL BRAM through AXI Bus
  - Vivado Block Design
  - Vitis code result of execution
- ➤ Lab 2: Use High-Level API Driver to drive AXI GPIO (with ILA)
  - Vivado Block Design
  - Vitis code result of execution
  - ILA result



# Lab 1: Get data from PL BRAM through AXI Bus

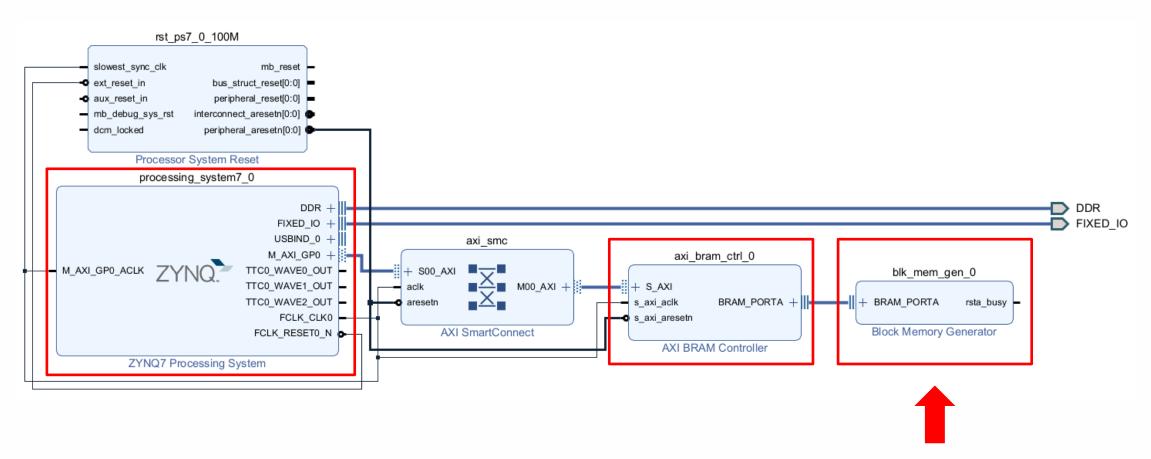


# **Vivado Part**



Block Design

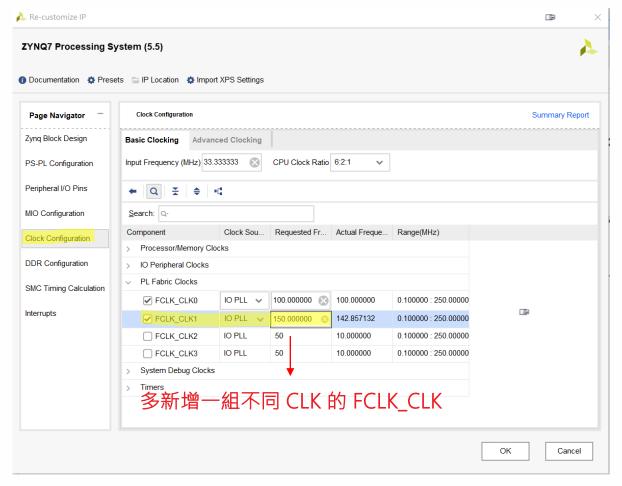
Designer Assistance available. Run Connection Automation

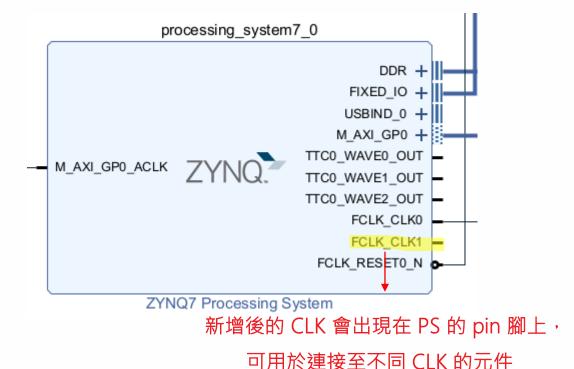




Question: 若 PS 端的工作頻率與 AXI BRAM Controller 不同怎辦?

Answer: 打開 PS 端的自定義,如下

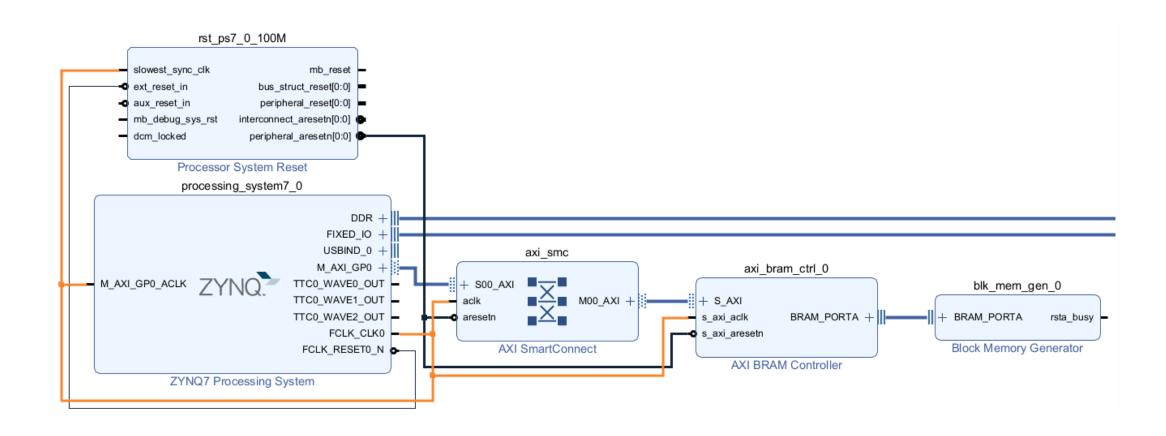






• Question: 若 PS 端的工作頻率與 AXI BRAM Controller 不同怎辦?

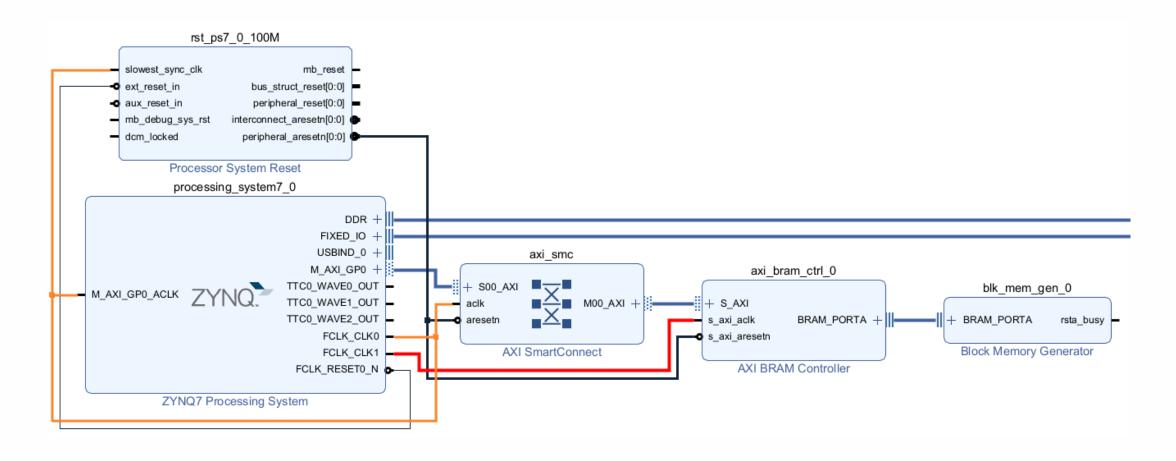
• Answer: 比較圖 — 同頻率





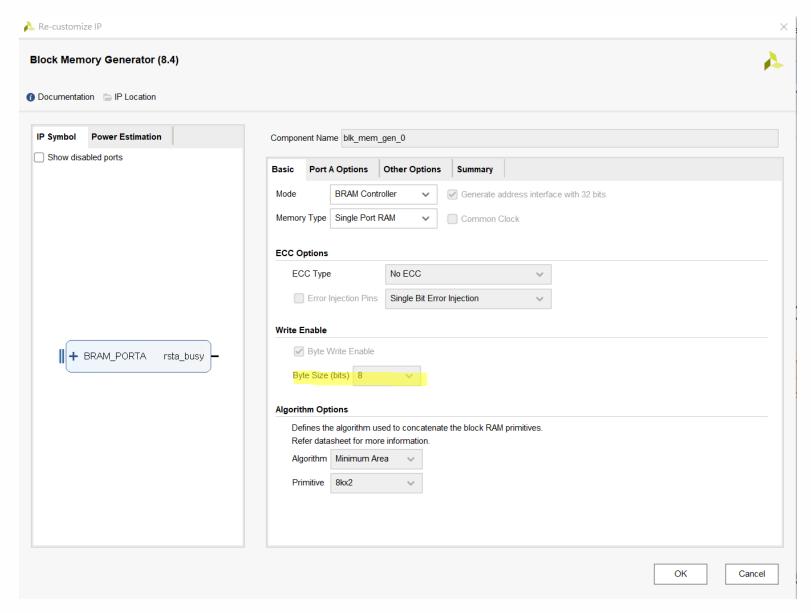
Question: 若 PS 端的工作頻率與 AXI BRAM Controller 不同怎辦?

Answer: 比較圖 — 不同頻率



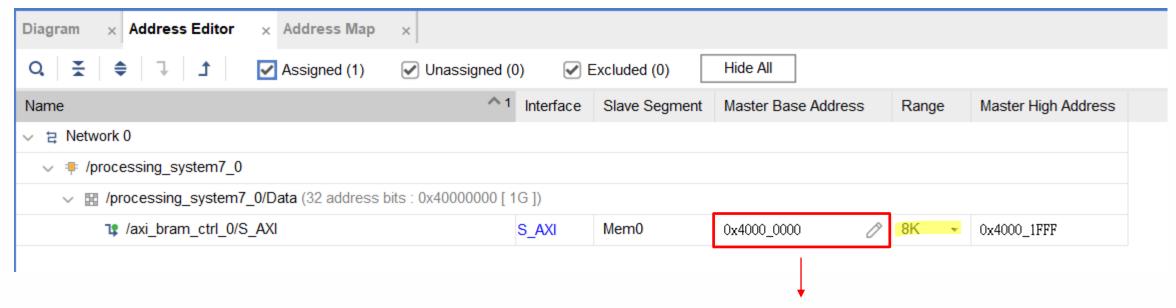


Block Design



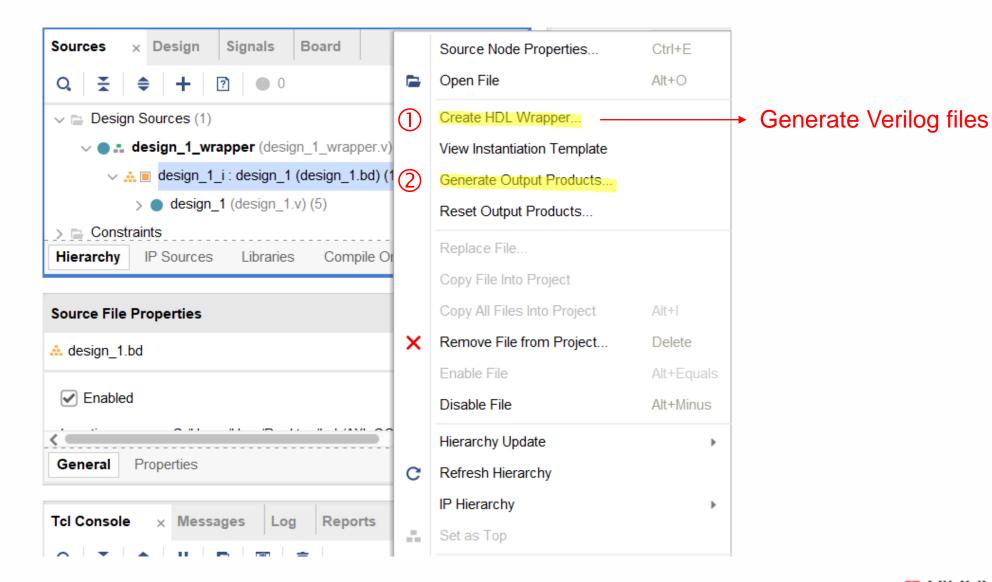


Block Design

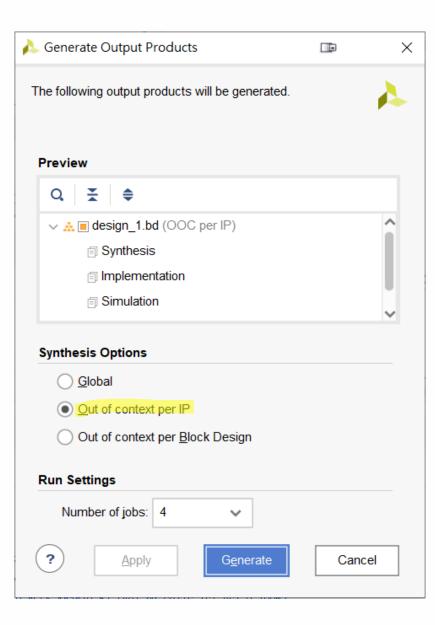


初始地址若由 Vivado 自動連線的話則會被自動 assign,可提供使用者進行修改,但必 須依照該開發板的 address map 進行範圍內的修改

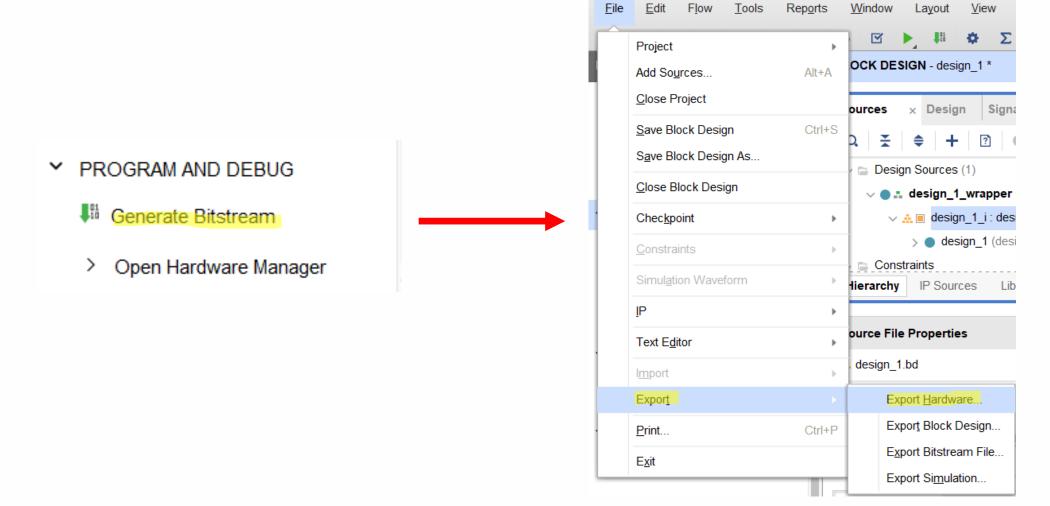




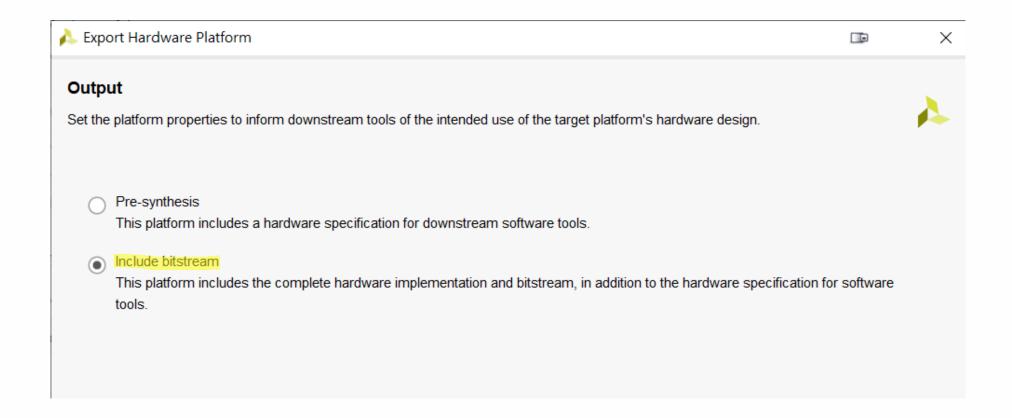










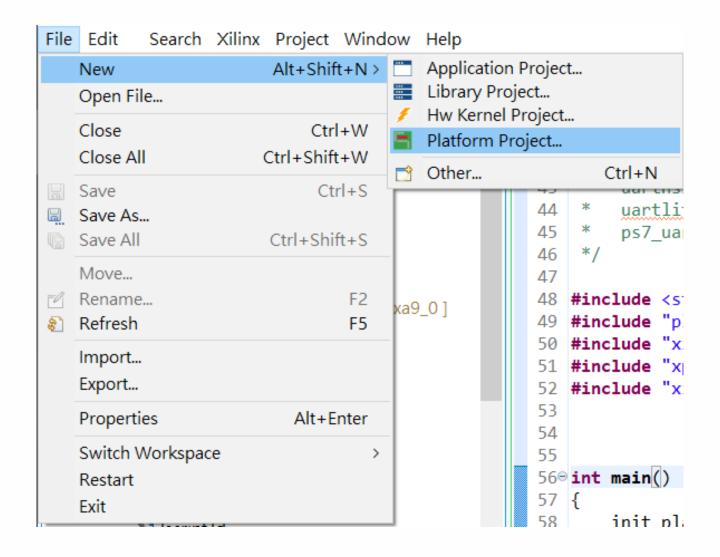




## **Vitis Part**

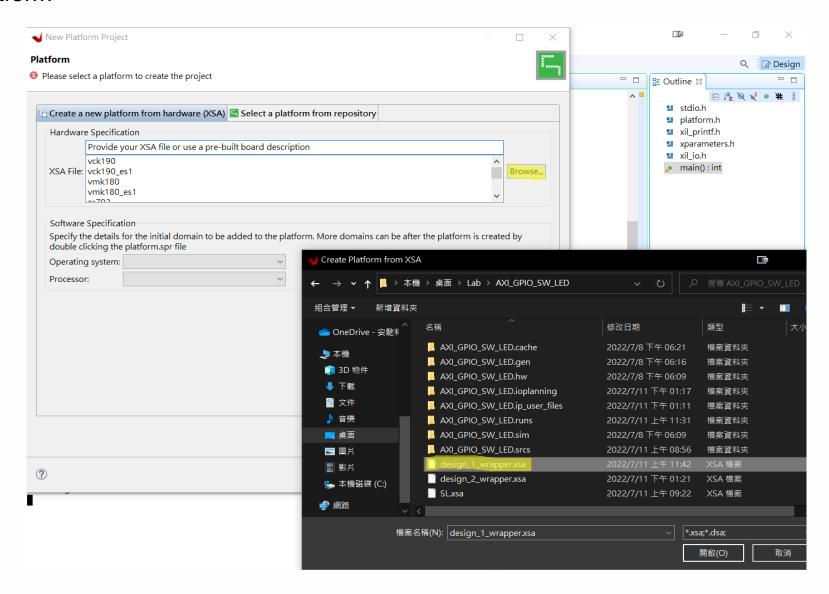


Create Platform



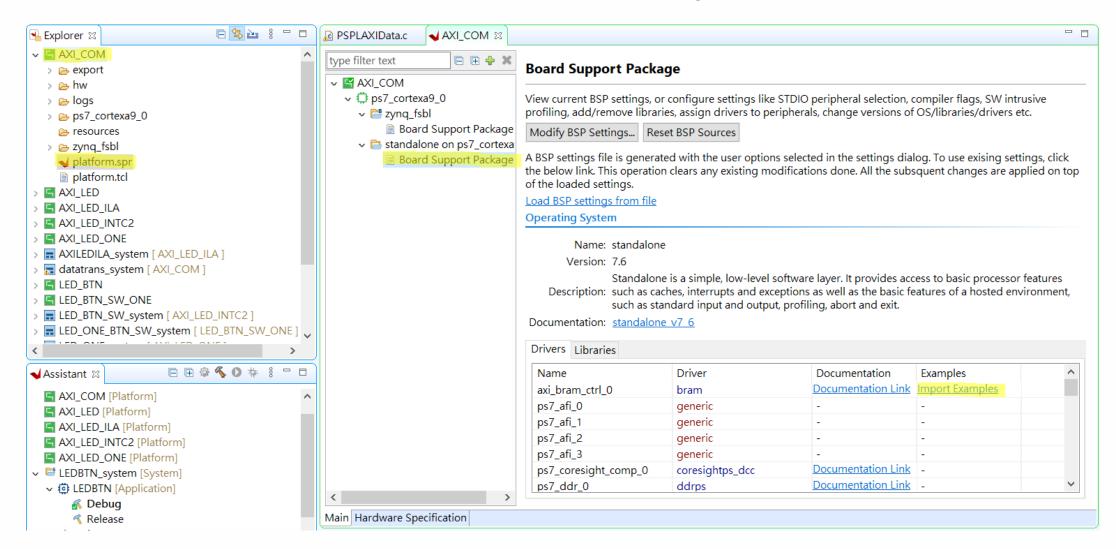


Create Platform



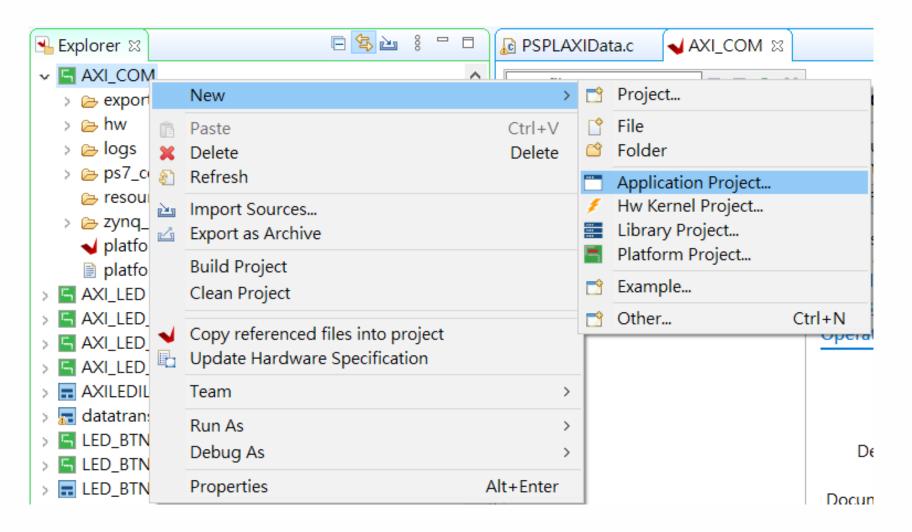


Create Application – Import example from Board Support Package



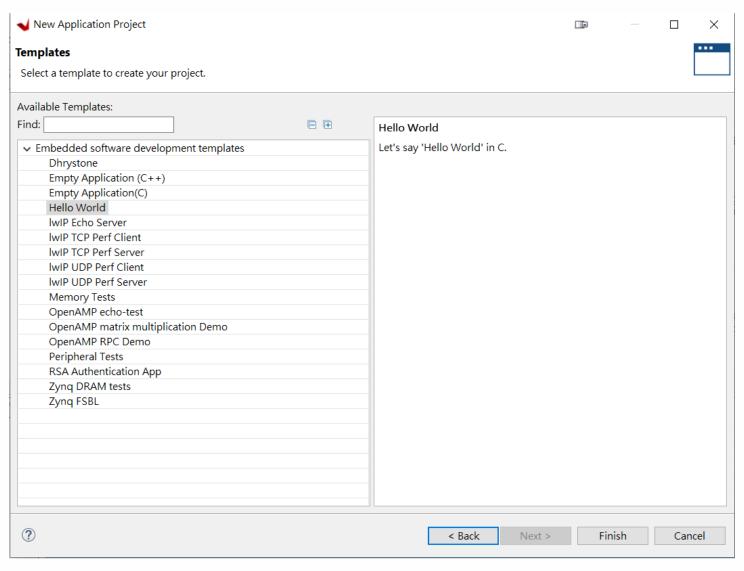


Create Application – Create a new Application Project





Create Application – Import example from Application project





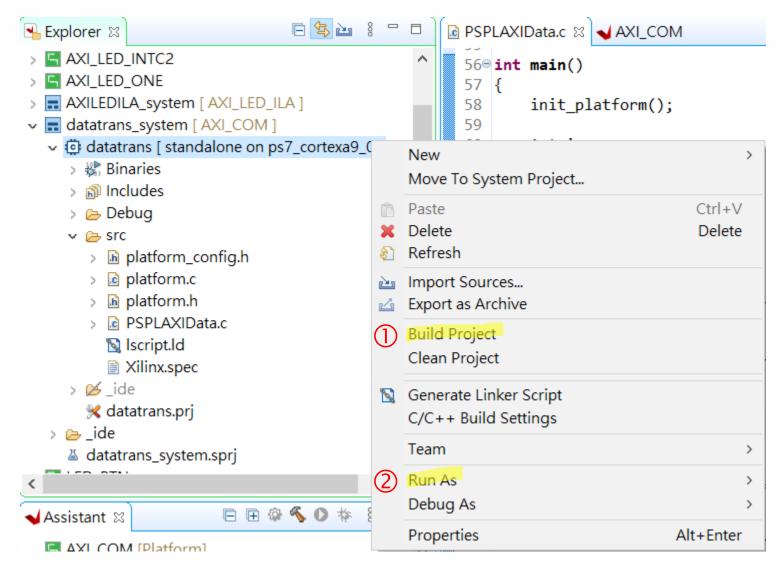
Open Vitis to review the code

```
    PSPLAXIData.c 
    □ helloworld.c

47
 48 #include <stdio.h>
 49 #include "platform.h"
 50 #include "xil_printf.h"
51 #include "xparameters.h"
52 #include "xil io.h"
 54
55
56⊖ int main()
 57 {
      init_platform();
61
      unsigned int addr = 0;
      int value = 0;
64
66
      int j = 128; //要寫入的數值
67
68
      printf("-----\n");
69
70
      for(i=0;i<10;i=i+2){ // +2 是因為一次寫入16bit,需要兩個記憶體位置來存
 71
          addr = XPAR_AXI_BRAM_CTRL_0_S_AXI_BASEADDR + i; // XPAR_AXI_BRAM_CTRL_0_S_AXI_BASEADDR 為 BRAM 一開始的記憶體地址
 72
          Xil_Out16(addr, j); // 寫入 16bit 的資料
 73
          printf("Write ADDR ---> 0x%02X, VALUE ---> %d\n", addr, j);
74
          j*=4;
75
76
77
      printf("======\n");
78
      for(i=0;i<10;++i){// +1 是因為一次讀取 8bit,需要一個記憶體位置來存
 80
          addr = XPAR_AXI_BRAM_CTRL_0_S_AXI_BASEADDR + i;
81
          value = Xil In8(addr);// 讀取 8bit 的資料
82
          printf("Read ADDR ---> 0x%02X, VALUE ---> %d\n", addr, value);
83
          if(i%2 == 1) printf("=======\n");
84
85
86
      printf("-----\n\n");
87
88
      printf("-----\n");
89
      Xil_Out8(XPAR_AXI_BRAM_CTRL_0_S_AXI_BASEADDR + 0, 0xAB);// 寫入 8bit 資料
```



Build the Project and Run





Result on MobaXterm

```
-----Write16Read8------
Write ADDR ---> 0x40000000, VALUE ---> 128
Write ADDR ---> 0x40000002, VALUE ---> 512
Write ADDR ---> 0x40000004, VALUE ---> 2048
Write ADDR ---> 0x40000006, VALUE ---> 8192
Write ADDR ---> 0x40000008, VALUE ---> 32768
     ADDR ---> 0x40000000, VALUE ---> 128
     ADDR ---> 0x40000001, VALUE ---> 0
    ADDR ---> 0x40000002, VALUE ---> 0
     ADDR ---> 0x40000003, VALUE ---> 2
    ADDR ---> 0x40000004, VALUE ---> 0
     ADDR ---> 0x40000005, VALUE ---> 8
    ADDR ---> 0x40000006, VALUE ---> 0
     ADDR ---> 0x40000007, VALUE ---> 32
    ADDR ---> 0x40000008, VALUE ---> 0
     ADDR ---> 0x40000009, VALUE ---> 128
  -----END-----
-----Write8Read16-----
Read Value: 0xFFAB
Read Value: 0x8C34
   -----END------
```



volatile

某變數被抓取時必須都是最新的狀態,並從該變數的地址取值,而不是直接從Cache抓取資料時,必須命為volatile e.g.,兩CPU對某一變數都會進行修改,但CPU取該變數數值時必須為最新的值,而不是抓上次存取至Cache的值,因此每次都必須從該變數的地址取值



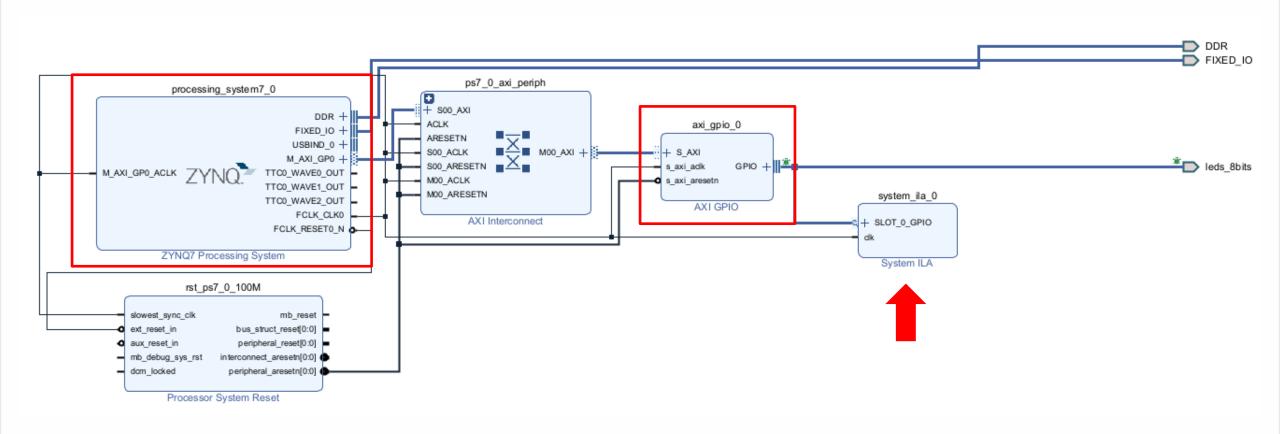
# Lab 2: Use High-Level API Driver to drive AXI GPIO (with ILA)



# **Vivado Part**

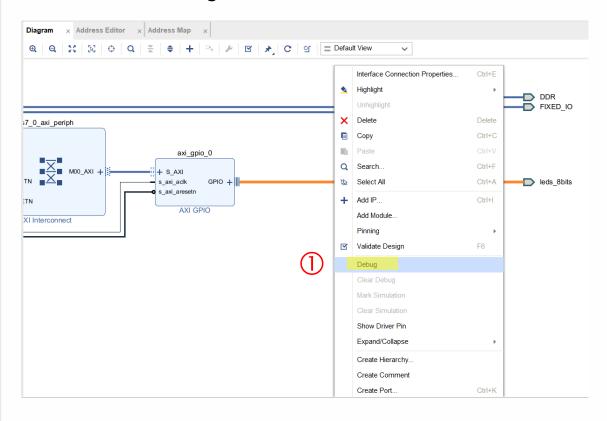


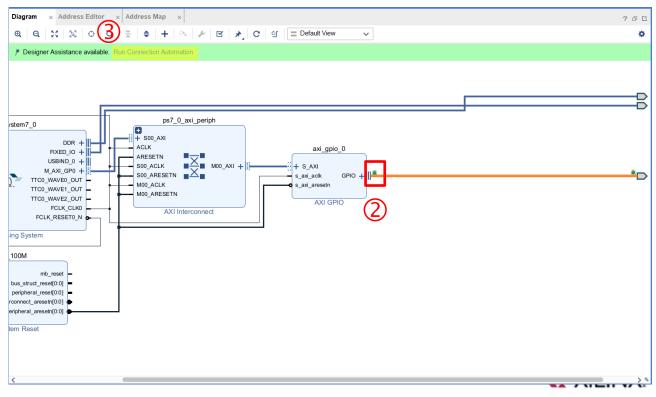
Block Design



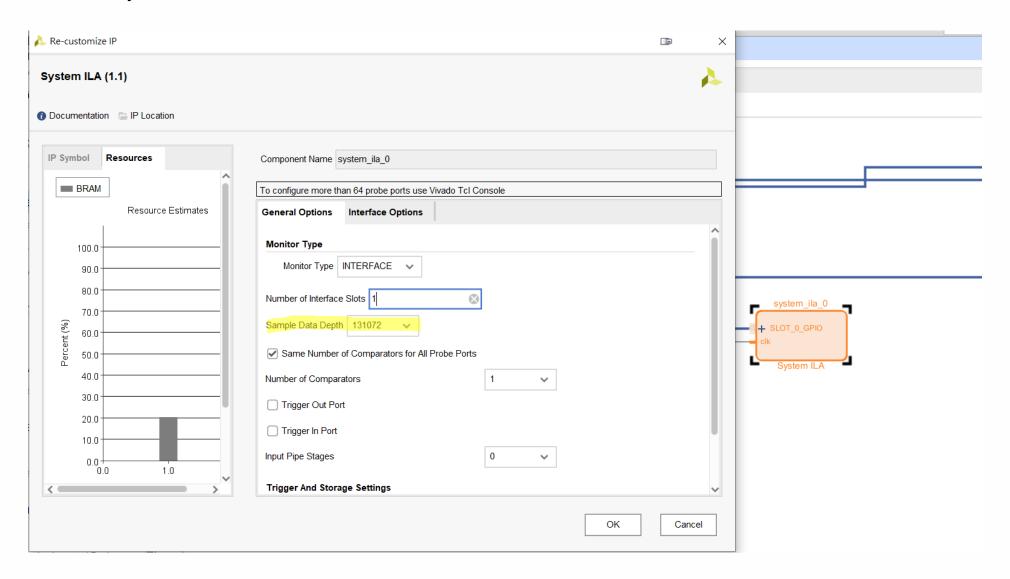


Block Design





Re-customize System ILA





## **Vitis Part**

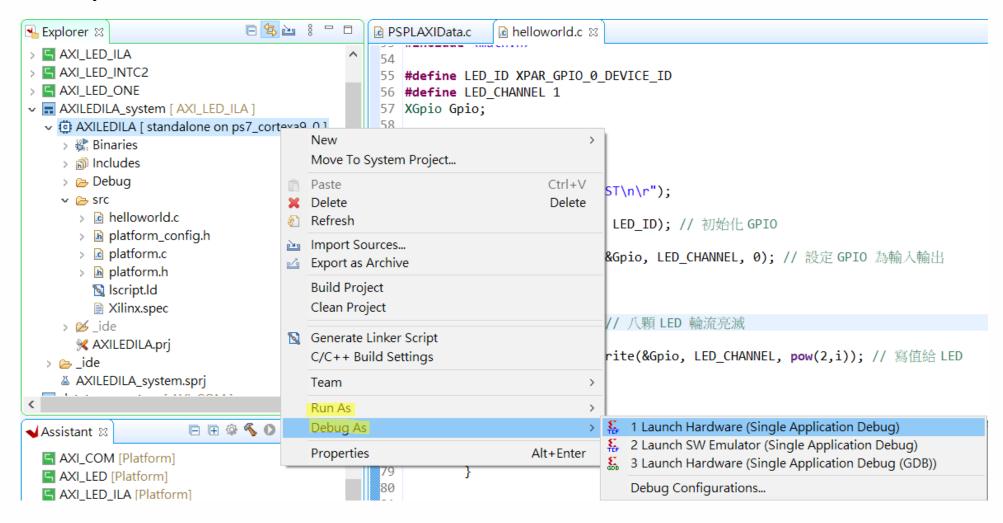


Open Vitis to review the code

```
    PSPLAXIData.c 
    □ helloworld.c 
    □
41 . I NAVI IILE DANN VAIE
43 * uartns550 9600
44 * uartlite Configurable only in HW design
45 * ps7 uart 115200 (configured by bootrom/bsp)
48 #include <stdio.h>
49 #include "platform.h"
50 #include "xil_printf.h"
51 #include "xgpio.h"
52 #include "sleep.h"
53 #include <math.h>
55 #define LED_ID XPAR_GPIO_0_DEVICE_ID
56 #define LED CHANNEL 1
57 XGpio Gpio;
59@ int main(void){
      int i=0;
      xil_printf("GPIO LED TEST\n\r");
                                                                                              若在 Vivado 中有設定 GPIO 為 All input/All output
      XGpio_Initialize(&Gpio, LED_ID); // 初始化 GPIO
      XGpio SetDataDirection(&Gpio, LED CHANNEL, 0); // 設定 GPIO 為輸入輸出
                                                                                              的話,此處的 SetDataDirection 則無需撰寫與加入
      while (1) {
         for(i=7;i>-1;--i){ // 八顆 LED 輪流亮滅
             XGpio_DiscreteWrite(&Gpio, LED_CHANNEL, pow(2,i)); // 寫值給 LED
             usleep(100);
             XGpio_DiscreteClear(&Gpio, LED_CHANNEL, pow(2,i)); // 等於 XGpio_DiscreteWrite(&Gpio,LED_CHANNEL,0x00),即全清零
             usleep(100);
      return 0;
85
```



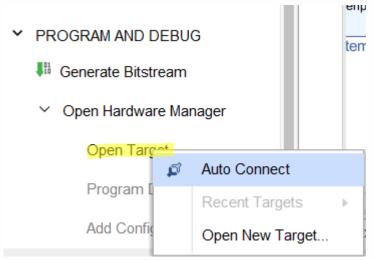
Build the Project and Run

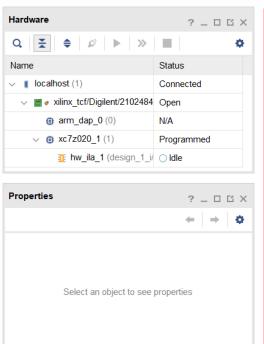


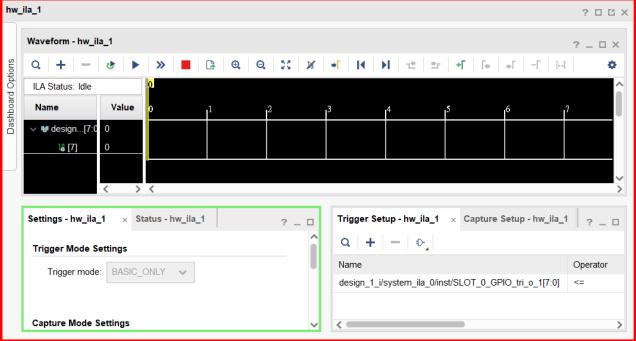


# **Vivado Part**

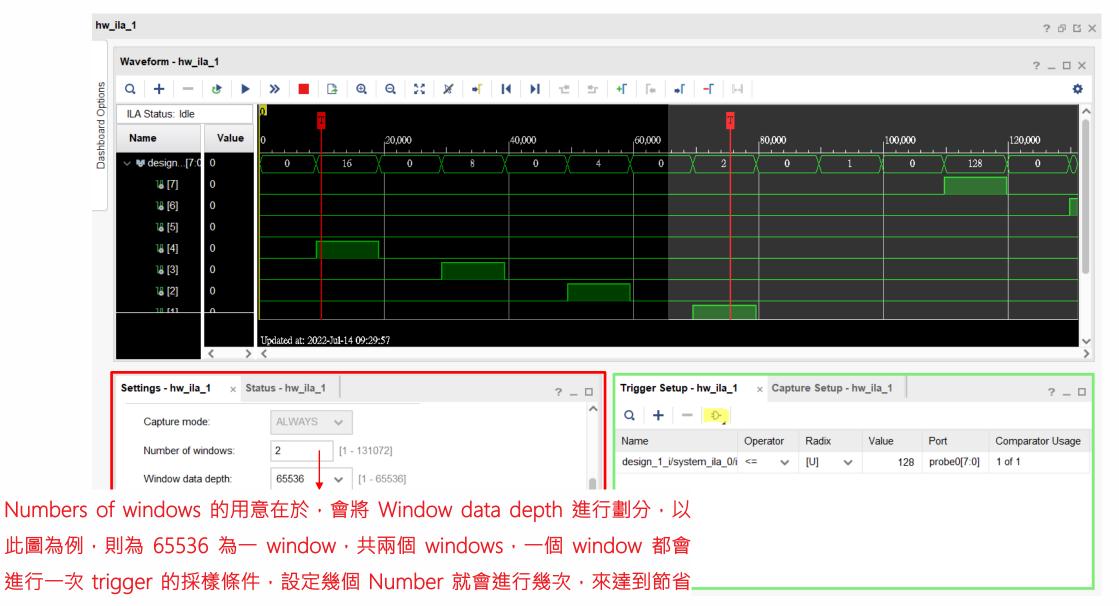




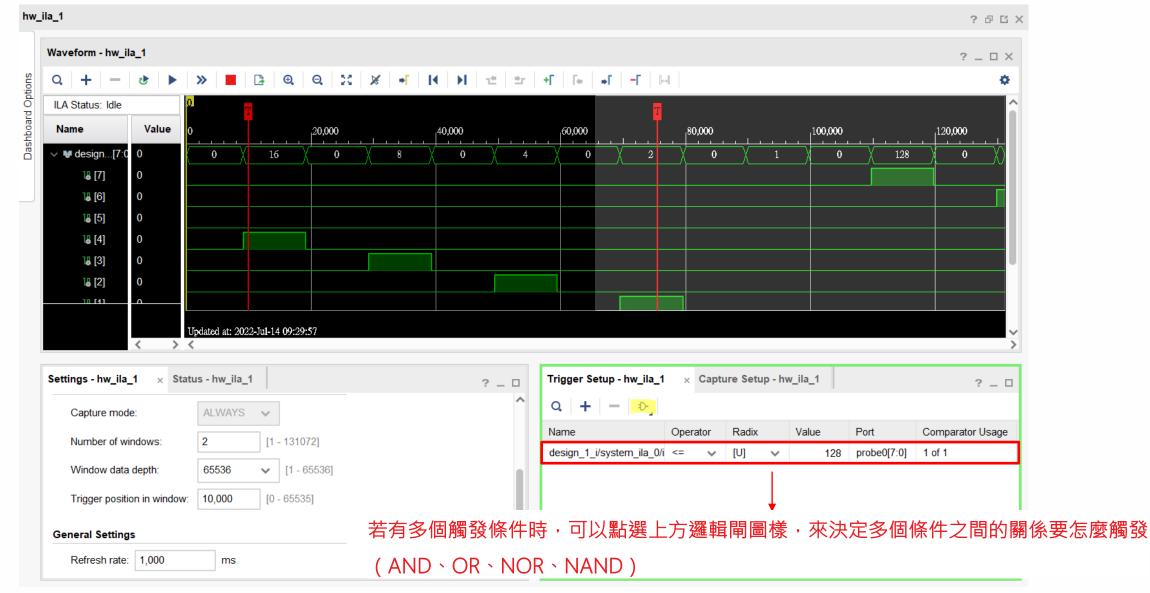




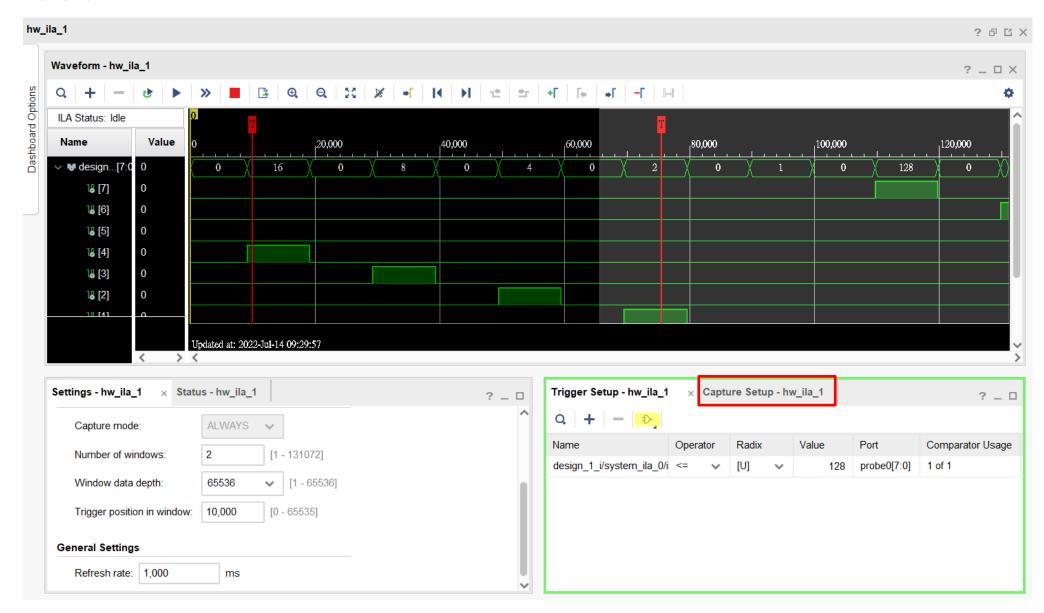
多次人工除錯的時間













Capture Setup

可以當作一種觸發條件,與 trigger 進行連動而不會使用到針腳以節省資源



# Thank you very much for your attention!



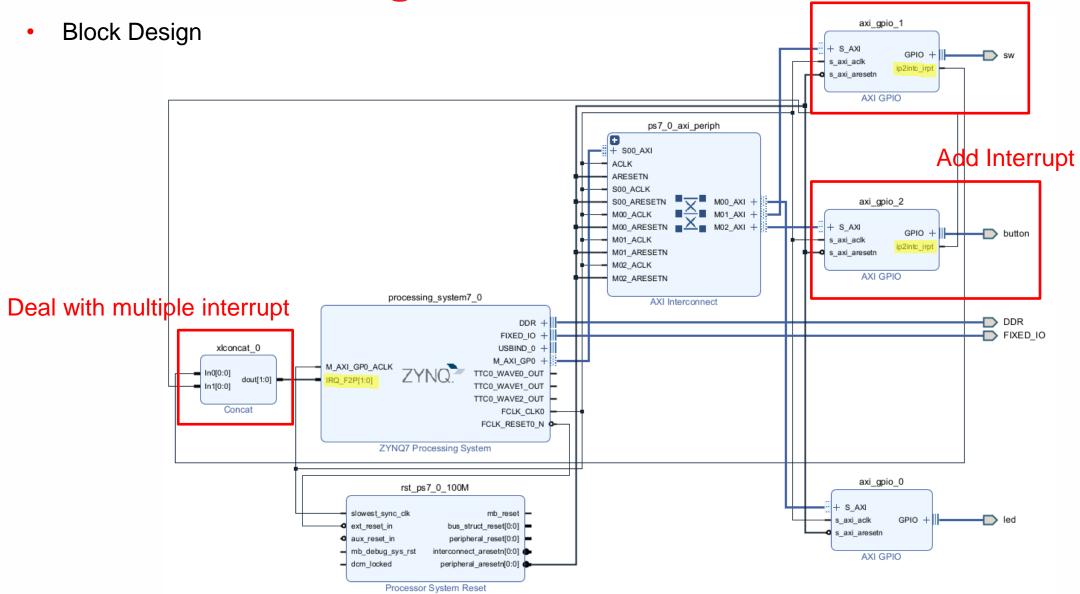
# Appendix: Use Interrupt to Control AXI GPIO (Through PS GIC)



# **Vivado Part**

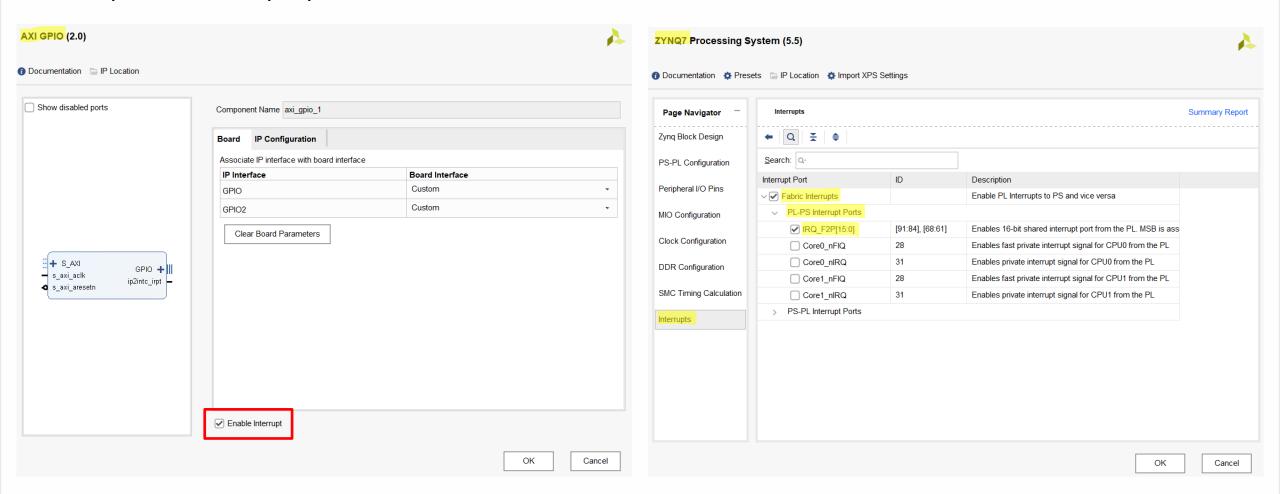


Add Interrupt





Open the Interrupt option



◆ If your AXI GPIO is customized, you need to do I/O planning manually.



## **Vitis Part**



Open Vitis to review the code

```
47
 48 #include <stdio.h>
 49 #include "platform.h"
 50 #include "xil_printf.h"
 51
 52 #include "xparameters.h"
 53 #include "xgpio.h"
 54 #include "xscugic.h"
 55 #include "xil exception.h"
 56 #include "xil printf.h"
 58 // Parameter Definitions
 59 #define INTC_DEVICE_ID XPAR_SCUGIC_SINGLE_DEVICE_ID
 61 #define INTC_GPIO_INTERRUPT_ID_SW XPAR_FABRIC_AXI_GPIO_1_IP2INTC_IRPT_INTR
 62 #define INTC_GPIO_INTERRUPT_ID_BTN XPAR_FABRIC_AXI_GPIO_2_IP2INTC_IRPT_INTR
 64 #define SWS DEVICE ID XPAR AXI GPIO 1 DEVICE ID
 65 #define BTNS_DEVICE_ID XPAR_AXI_GPIO_2_DEVICE_ID
 66 #define LEDS DEVICE ID XPAR AXI GPIO 0 DEVICE ID
 68 #define SW INT CHANNEL 1
 69 #define BTN_INT_CHANNEL 1
 71 XGpio LEDInst, BTNInst, SWInst; // Struct
 72 XScuGic INTCInst;
 73 static int led data;
74 static int btn_value;
75 static int sw value;
 76 int counter_BTN = 1; //add or minus
 77 int max = 3;
 79 // Prototype Functions
 80 static void BTN_Intr_Handler(void *baseaddr_p);
                                                          //interrupt behavior
 81 static int BTN_InterruptSystemSetup(XScuGic *XScuGicInstancePtr);
 82 static int BTN_IntcInitFunction(u16 DeviceID, XGpio *GpioInstancePtr);
 84 static void SW_Intr_Handler(void *baseaddr p);
                                                          //interrupt behavior
 85 static int SW_InterruptSystemSetup(XScuGic *XScuGicInstancePtr);
 86 static int SW_IntcInitFunction(u16 DeviceID, XGpio *GpioInstancePtr);
 88 void BTN_Intr_Handler(void *InstancePtr){
        XGpio InterruptDisable(&BTNInst, BTN INT CHANNEL);
        if((XGpio_InterruptGetStatus(&BTNInst) & BTN_INT_CHANNEL) != BTN_INT_CHANNEL){
```



Result



