# Deforestation Challenge

(WebNOVA II Hackathon)



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### Introduction

Globally from 2001 to 2023, 22% of tree cover loss occurred in areas where the dominant drivers of loss resulted in deforestation.

Deforestation is a pressing concern, but with access to satellite imagery and the ability to map changes over time, we have a powerful tool to take actionable steps towards a solution.



• The code utilizes a change detection algorithm to identify changes in vegetation or land cover between two satellite images. The algorithm uses Principal Component Analysis (PCA) and K-means clustering to detect changes

```
def find FVS(EVS, diff image, mean vec, new):
   i = 2
   feature vector set = []
   while i < new[0] - 2:
       i = 2
       while j < new[1] - 2:
           block = diff_image[i-2:i+3, j-2:j+3]
           feature = block.flatten()
           feature vector set.append(feature)
           j = j+1
       i = i+1
   FVS = np.dot(feature vector set, EVS)
   FVS = FVS - mean vec
   print("\nfeature vector space size", FVS.shape)
   print("loop 2 done ")
   return FVS
```

```
return least_index, change_map,output
lef find vector_set(diff_image, new_size):
  i = 0
 j = 0
  vector_set = np.zeros((int(new_size[0] * new_size[1] / 25), 75))
  while i < vector_set.shape[0]:</pre>
      while j < new_size[0]:
         while k < new_size[1]:
             block = diff image[j:j+5, k:k+5]
             feature = block.ravel()
             vector_set[i, :] = feature
             k = k + 5
         j = j + 5
     i = i + 1
  mean_vec = np.mean(vector_set, axis = 0)
  vector_set = vector_set - mean_vec
  print("loop 1 done ")
   return vector_set, mean_vec
```

ef clustering(FVS, components, new):

output = kmeans.predict(FVS)

least index = min(count, key = count.get)

change\_map = np.reshape(output,(new[0] - 4, new[1] - 4))

count = Counter(output)

print("loop 3 done ")

print("line0")

print("line1")

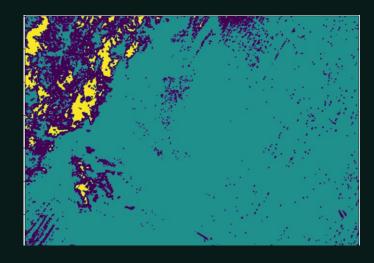
kmeans.fit(FVS)

print("line2")

- kmeans = KMeans(components, verbose = 0,n init=10) The code can be broken down into several parts:
  - find\_vector\_set: takes the diff image and its size as input and returns the vector set and mean vector
  - find\_FVS:function finds the Feature Vector Space(FVS) for the diff image
  - clustering: applies K-means clustering to FVS

### Result

• The output of the code is an image showing the detected changes between the two input images. The color scheme in the output image represents diff clusters identified by the K-means algorithm



• The meaning of the color is determined by the clustering results of the K-means algorithm in each run. You can use the average pixel value of each cluster to interpret what kind of changes each color represents

## Thank you

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