

Some stochastic models in ecology

Adeline Leclercq Samson (Grenoble, France)

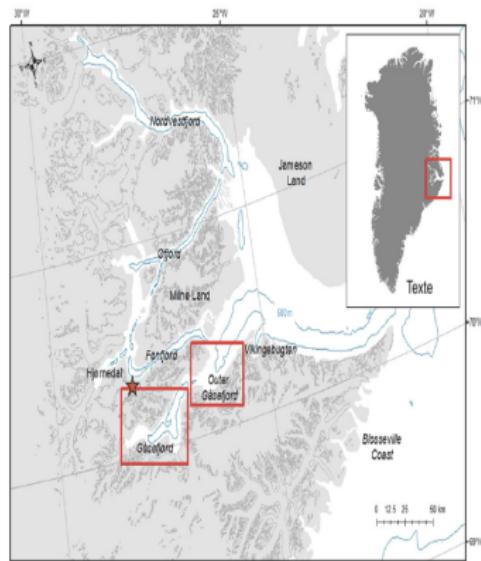
Joint work with

E. Buckwar (Linz), S. Ditlevsen (Copenhagen), M.P. Heide-Jørgensen (Copenhagen),
A. Melnykova (Avignon), P. Pilipovic (Copenhagen), M. Tamborrino (Warwick),
O. Tervo (Copenhagen), I. Tubikanec (Linz)



Outline of the talk

- **1. Climate change in Greenland**
 - ▶ Effect on endemic whales
 - ▶ Design of experimental data
- **2. Sound data**
 - ▶ Point process
 - ▶ Mediation effect of depth
- **3. Spatial data**
 - ▶ Hypoelliptic diffusion
 - ▶ Numerical scheme and statistical inference

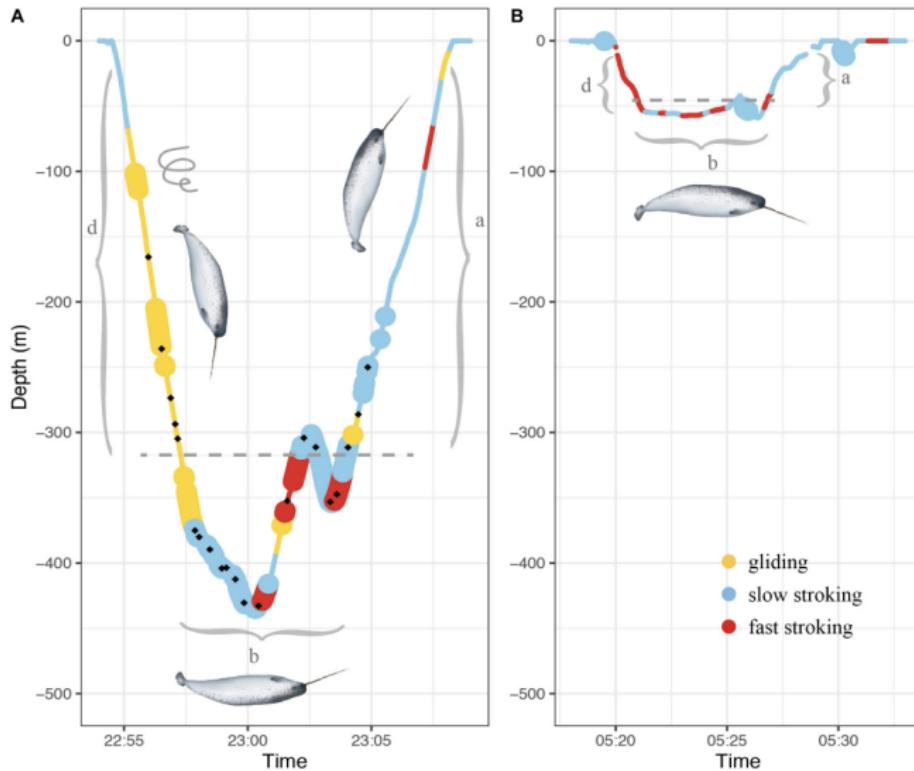


1. Climate change: a danger for the narwhals?

- Ice melt
- Decrease of sea ice coverage
- Increase of anthropogenic activities, of mining activities
- Reactions of narwhals to noise and human presence?



Narwhal dive



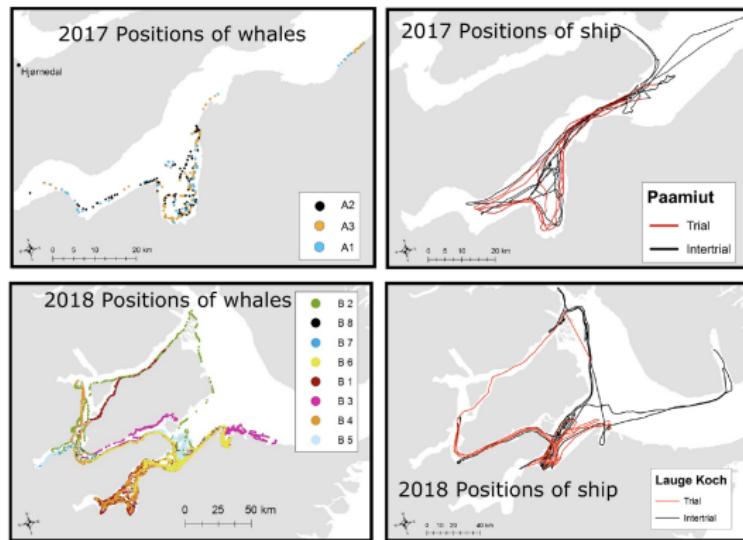
Foraging V dive (A) and Non-foraging U dive (B), Buzzes (black dots)

Experimental design

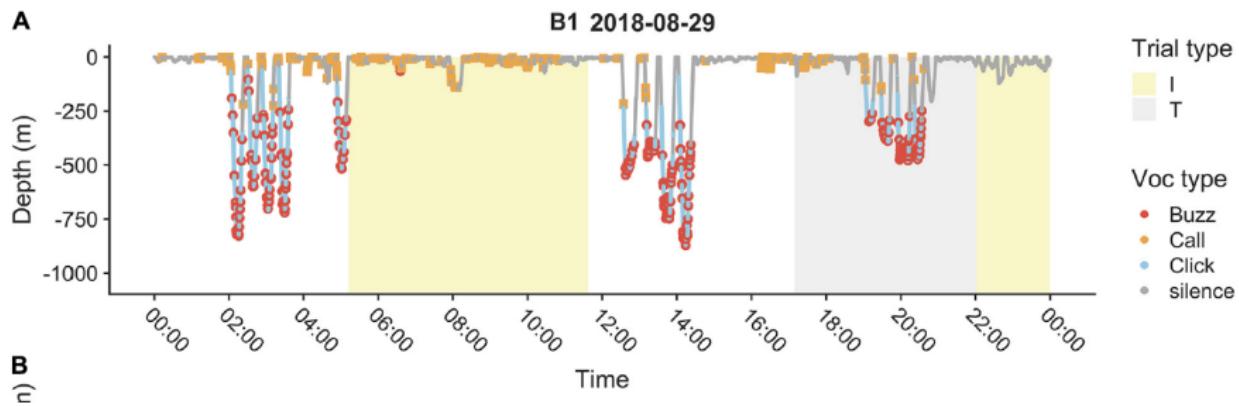
- 16 animals
- Instrumented with satellite tags and Acousonde acoustic-behavioral recorders
- Exposition to airgun pulses and vessel sounds
 - ▶ Pre exposure
 - ▶ Trials: airgun and ship-noise
 - ▶ Intertrial: only ship-noise
 - ▶ Post exposure

Recorded data

- Data recorded each second
- Sound (click/buzz)
- Depth
- Position of whales
- Position of ship
- Stroke
- Accelerometer



2. Sound data



Sound analysis: definition

Point process

- T_j , the time of the j th sound emitted by the animal
- $T_0 = 0 < T_1 < T_2 < \dots$
- $T_n \rightarrow \infty$ when $n \rightarrow \infty$ (no accumulation)

Count process

- $N(t)$ the number of sounds emitted in the interval $]0; t]$
- $(N(t))_{t \in \mathbb{R}^+}$ is a stochastic process at continuous time
 - ▶ $N(0) = 0$
 - ▶ $N(b) - N(a)$ is the number of sounds emitted in the interval $]a; b]$

Poisson process

A **Poisson process** is a count process $(N(t))_{t \in \mathbb{R}^+}$ such that

- $N(0) = 0$
- For all $0 \leq t_1 \leq t_2 \leq \dots \leq t_k$ the variables $N(t_{j+1}) - N(t_j)$ are independent
- For all $(s, t) \in \mathbb{R}_+^2$, $N(s + t) - N(s)$ follows a Poisson distribution of parameter λt :

$$\mathbb{P}(N(s + t) - N(s) = k) = e^{\lambda t} \frac{(\lambda t)^k}{k!}$$

Thus

- $\mathbb{P}(N(t) = k) = e^{\lambda t} \frac{(\lambda t)^k}{k!}$
- $\mathbb{E}(N(t)) = \lambda t$

Non homogeneous Poisson process

Let $\lambda(t)$ an integrable function. $(N(t))_{t \in \mathbb{R}^+}$ is a **nonhomogeneous Poisson process** with **rate** or **intensity** $\lambda(t)$ if

- $N(0) = 0$
- For all $0 \leq t_1 \leq t_2 \leq \dots \leq t_k$ the variables $N(t_{j+1}) - N(t_j)$ are independent
- For all $(t, s) \in \mathbb{R}_+^2$, $N(s+t) - N(s)$ follows a Poisson distribution of parameter $\int_t^{t+s} \lambda(u)du$:

$$N(s+t) - N(s) \sim \text{Poisson} \left(\int_t^{t+s} \lambda(u)du \right)$$

Thus

- $\mathbb{P}(N(t + \Delta) - N(t) = 0) = 1 - \lambda(t)\Delta + o(\Delta)$
- $\mathbb{P}(N(t + \Delta) - N(t) = 1) = \lambda(t)\Delta + o(\Delta)$
- $\mathbb{P}(N(t + \Delta) - N(t) \geq 2) = o(\Delta)$

If the time interval $[t, t + \Delta[$ is small:

- the probability of a single event is approximately $\lambda(t)\Delta$
- the probability of more than 1 event is negligible

Simplification of the process:

- $Y(t) := N(t + \Delta) - N(t)$ takes value 0 or 1
- Bernoulli distribution with $\mathbb{E}(Y(t)) = \mathbb{P}(Y(t) = 1) = \lambda(t)\Delta$

Inclusion of covariates

To ensure the positivity of the intensity, we consider the log link:

$$\log \lambda(t, Z(t)) = \gamma_0 + \gamma_1 D(t) + \gamma_2 X(t) = \gamma^t Z(t)$$

with

- $D(t)$: Depth
- $X(t)$: Exposure level of seismic activity = 1/distance to ship
- $Z(t) = (1, D(t), X(t))$ vector of covariates

Estimation by maximum likelihood for iid sample Y_1, \dots, Y_n :

$$L(\gamma | Y, Z) = \prod_{j=1}^n e^{-\lambda(t_j, Z_j)} \frac{\lambda^{Y_j}}{Y_j!}$$

Maximisation of the log-likelihood

$$\ell(\gamma | Y, Z) = \sum_{j=1}^n (Y_j \gamma^t Z_j - e^{\gamma^t Z_j})$$

To include variability between individuals (random effects)

Covariance between observations of a given individual:

$$\log \lambda(t|b_i, Z(t)) = \gamma_0 + b_i + \gamma_1 D(t) + \gamma_2 X(t) = b_i + \gamma^t Z(t)$$

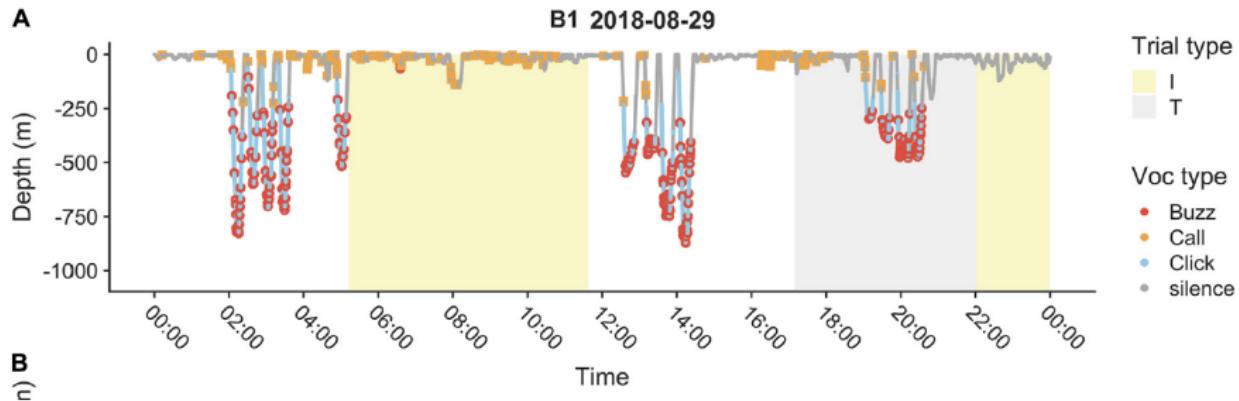
with

- b_i random effect of individual i
- $b_i \sim \mathcal{N}(0, \omega^2)$

Estimation by maximum likelihood for iid sample of animal i : Y_{i1}, \dots, Y_{in_i}

$$L(\gamma|Y, Z) = \int p(Y_i|Z_i, b_i, \gamma) p(b_i, \omega^2) db_i$$

Non independence of observations



- When buzzes start to be emitted, a whole sequence of buzzes is emitted
 - Dependence of the emission between observations of a given animal
- Intensity should depend on the past and thus be a random variable

Poisson model with random intensity function

Non homogeneous Poisson model with random intensity function

- \mathcal{F}_t denotes the filtration of the process up to time t
- $\lambda(t)$ is a random variable whose value is determined by \mathcal{F}_t such that
 - ▶ $\mathbb{P}(N(t + \Delta) - N(t) = 1 | \mathcal{F}_t) = \lambda(t)\Delta + o(\Delta)$
 - ▶ $\mathbb{P}(N(t + \Delta) - N(t) \geq 2 | \mathcal{F}_t) = o(\Delta)$

Example: Hawkes process

$$\lambda(t) = \lambda + \sum_{j=1}^{N(t)} M_j e^{-\alpha(t - T_j)}$$

To ensure a positive intensity:

$$\log \lambda(t) = \lambda + \sum_{j=1}^{N(t)} M_j e^{-\alpha(t-T_j)}$$

With covariates and random effects:

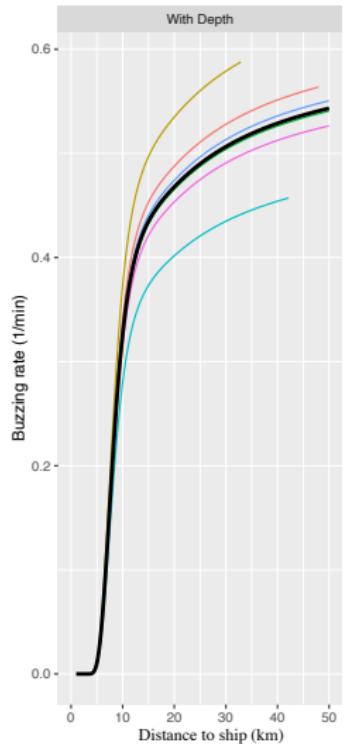
$$\log \lambda(t) = \lambda + b_i + \sum_{j=1}^{N(t)} M_j e^{-\alpha(t-T_{ij})} + \gamma_1 D_i(t) + \gamma_2 X_i(t)$$

with

- $D(t)$: Depth
- $X(t)$: Exposure level of seismic activity = 1/distance to ship

Estimation: two steps to estimate the auto-regressive memory and then the other effects

Estimated buzzing rate



- Variability between individuals
- When ship is close, no buzz
- Buzzing rate without exposure = $0.55/\text{min}$

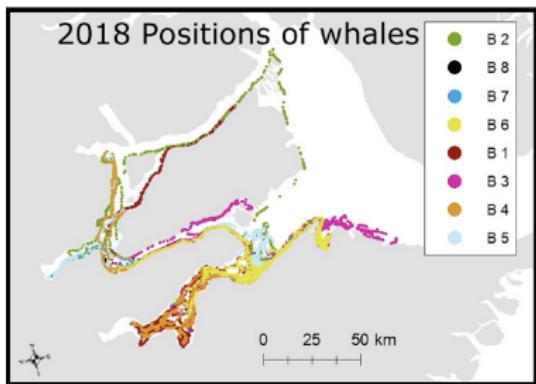
Still to be done

- Estimation of the mediation effect of Depth:
 - ▶ Exposure causes animal to dive less
 - ▶ Less dives make animals produce less sounds
 - ▶ What is the direct of Exposure and its indirect effect through Depth?
 - ▶ Is Depth a mediation factor?
- Hawkes process instead of the Poisson model
 - ▶ Non-parametric intensity
 - ▶ Random effects
 - ▶ Mediation

3. Spatial position data

Do animals adapt their position due to

- anthropogenic activities?
- warming of ocean temperatures?



Stochastic model of animal movement

[Blackwell 1997, Brillinger et al 2002, Preisler et al 2004, Hooten et al 2010, Michelot et al 2019, Gloaguen et al 2018]

Stochastic Differential Equation (SDE) to describe the dynamic of the position:

- X_t position at time t
- SDE on the position X_t

$$dX_t = b(X_t, \theta)dt + \Sigma(X_t, t)dW_t$$

- The drift $b(x, \theta)$ models the direction preference depending on position x
- The diffusion coefficient $\Sigma(X_t, t)$ models the variability around the mean

A first SDE

Ornstein-Uhlenbeck process

$$dX_t = -\beta(X_t - \mu)dt + \Sigma dW_t$$

Solution obtained by the Ito lemma applied to the function $f(X_t, t) = X_t e^{\beta t}$

$$\begin{aligned} df(X_t, t) &= \beta X_t e^{\beta t} dt + e^{\beta t} dX_t \\ &= e^{\beta t} \beta \mu dt + \Sigma e^{\beta t} dW_t \end{aligned}$$

Integration from 0 to t

$$X_t e^{\beta t} = X_0 + \int_0^t e^{\beta s} \beta \mu ds + \int_0^t \Sigma e^{\beta s} dW_s$$

Thus

$$X_t = X_0 e^{-\beta t} + \mu(1 - e^{-\beta t}) + \int_0^t \Sigma e^{\beta(s-t)} dW_s$$

The moments of the Ornstein-Uhlenbeck process are

- $\mathbb{E}(X_t) = X_0 e^{-\beta t} + \mu(1 - e^{-\beta t})$
- $Cov(X_s, X_t) = \frac{\sigma^2}{2\beta} e^{-\beta(s+t)} (e^{2\beta(s+t)} - 1)$
- $Var(X_t) = \frac{\sigma^2}{2\beta} (1 - e^{-2\beta t})$

Parameter estimation

Transition density

$$X_{t+\Delta}|X_t \sim \mathcal{N} \left(X_t e^{-\Delta} + \mu(1 - e^{-\beta\Delta}), \frac{\sigma^2}{2\beta}(1 - e^{-2\beta\Delta}) \right)$$

Likelihood

$$L(\beta, \mu, \sigma^2) = \prod_{j=1}^n p(X_{t_{j+1}}|X_{t_j})$$

Maximum Likelihood Estimator

$$\begin{aligned}\widehat{e^{-\beta\Delta}} &= \frac{\sum_j X_j X_{j-1}/n - \sum_i X_i/n \sum_i X_{i-1}/n}{\sum_i X_{i-1}^2/n - (\sum_i X_{i-1}/n)^2} \\ \hat{\mu} &= \frac{\sum_j (X_j - \widehat{e^{-\beta\Delta}} X_{j-1})}{1 - \widehat{e^{-\beta\Delta}}}\end{aligned}$$

More complex SDE for movement ecology

- **SDE on the velocity** $V_t \in \mathbb{R}^2$ [Hamiltonian models]

$$dX_t = V_t dt$$

$$dV_t = b(V_t, S_t, \theta) dt + \Sigma(V_t, t) dW_t$$

with S_t different spatial maps (temperature, depth, ice coverage, etc)

- ▶ Hypoelliptic system

- **Modeling Depth**

$$dX_t = b_X(X_t, S_t, D_t, \theta) dt + \Sigma(X_t, t) dW_t^1$$

$$dD_t = b_D(X_t, S_t, D_t, \theta) dt + \sigma_D dW_t^2$$

- ▶ Noise could be possibly degenerated ($\sigma_D = 0$)

Parametric estimation for multidimensionnal systems

Matricial notations $X_t \in \mathbb{R}^d$:

$$dX_t = b(X_t, \theta) + \Sigma dW_t$$

Difficult because

- Data: discrete observations $X_{10:n} = (X_{10}, \dots, X_{1n})$ at times $t_0 = 0 < t_1 = \Delta < \dots < t_n = n\Delta$
- No explicit transition density of the SDE except if b is linear
- Hypoellipticity: Σ is degenerated but X_t has a smooth density (noise propagates to \mathbb{R}^d)

Different strategies of inference

Based on simulation

- Exact simulation
- Approximated simulation with a numerical scheme
- Estimation methods based on simulation
 - ▶ ABC
 - ▶ Monte Carlo, Importance Sampling

Based on approximation of the transition density

- What is a "good" approximation? Depends on the properties of the numerical scheme
- Estimation methods based on approximation
 - ▶ Contrast estimator [Thieullen Samson 2012, Ditlevsen Samson 2019, Melnykova 2020]
 - ▶ MCMC
 - ▶ EM algorithm [Beskos et al 2005, Gloaguen et al 2018, Ditlevsen, Samson 2014, 2019]

Numerical approximation schemes

Expected properties of a numerical scheme

- Locally Lipschitz conditions on b
- Exact moments up to a certain order
- Mean-square convergence of order p for a step size Δ

$$\max_{t_i} \left(\mathbb{E} \left(\|X(t_i) - \tilde{X}(t_i)\|^2 \right) \right)^{1/2} \leq c\Delta^p$$

- Preservation of structural properties: hypoellipticity, ergodicity, amplitudes, frequencies, phases of oscillations

Some numerical schemes

Discretization with Euler-Maruyama

$$X_{i+1} = X_i + \Delta b(X_i) + \sqrt{\Delta \Sigma} \eta_i, \quad \eta_i \sim_{iid} \mathcal{N}(0, I)$$

- Not mean-square convergent
- Does not preserve ergodicity
- Does not preserve hypoellipticity

$$\text{Var}(X_{i+1}|X_i) = \sigma^2 \begin{pmatrix} 0 & 0 \\ 0 & \Delta \end{pmatrix}$$

Local linearization

[Ozaki 1989, Biscay et al. 1996, Jimenez et al 2015, Melnykova 2020]

Approximate the solution by the solution of an autonomous linear SDE

On each interval $[i\Delta, (i+1)\Delta[$,

$$d\tilde{X}_t = \left(b(\tilde{X}_i) + \partial_x b(\tilde{X}_i)(\tilde{X}_t - \tilde{X}_i) + \frac{1}{2}\sigma^2 \partial_c^2 b(\tilde{X}_i)(t - i\Delta) \right) + \Sigma dW_t$$

- Linear SDE → explicit solution
- 1-step hypoellipticity

$$\text{Cov}(\tilde{X}_{i+1} | \tilde{X}_i) = \sigma^2 \begin{pmatrix} \frac{\Delta^3}{3} \partial_c b_1^2 & \frac{\Delta^2}{2} \partial_c b_1 \\ \frac{\Delta^2}{2} \partial_c b_1 & \Delta \end{pmatrix}$$

- Mean-square convergent of order 1
- Does not preserve other structural properties (ergodicity, oscillations)

Numerical splitting scheme

[Buckwar, Samson, Tamborrino, Tubikanec, 2021; Ditlevsen, Pilipovic, Samson, 2022]

Introduction of two subsystems.

1. **Subsystem a:** Linear SDE with exact solution

$$dX_t^a = AX_t^a dt + \Sigma dW_t$$

2. **Subsystem b:** Non-linear (decoupled) ODE with (exact) solution

$$dX_t^b = N(X_t^b)dt$$

Numerical splitting schemes with time step Δ

- Lie-Trotter

$$\hat{X}^{LT} = X_\Delta^a \circ X_\Delta^b$$

- Strang

$$\hat{X}^S = X_{\Delta/2}^b \circ X_\Delta^a \circ X_{\Delta/2}^b$$

Properties of splitting schemes

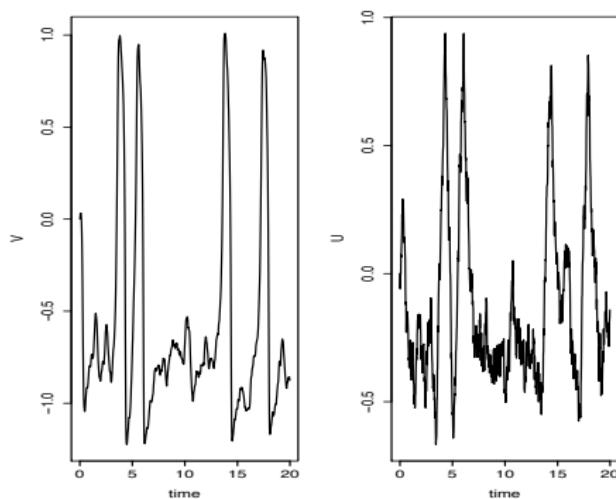
- Exact first moment up to Δ^3 , covariance matrix up to Δ^3
- Mean-square convergence with order 1
- Preservation of noise structure, 1-step hypoellipticity
- Preservation of Lyapounov structure
- Geometric ergodicity
- Transition density of the scheme highly non-linear -*i* difficult to exploit?

Example on the Fitzhugh-Nagumo model

[Lindner et al 1999, Gerstner and Kistler, 2002, Lindner et al 2004, Berglund and Gentz, 2006]

$$\begin{aligned} dV_t &= \frac{1}{\varepsilon}(V_t - V_t^3 - C_t - s)dt, \\ dC_t &= (\gamma V_t - C_t + \beta)dt + \sigma dW_t, \end{aligned}$$

- ε time scale separation
- s stimulus input
- β position of the fixed point
- γ duration of excitation



Splitting scheme on the FHN model

1. Subsystem a: Linear SDE

$$dX_t = \begin{pmatrix} 0 & -\frac{1}{\varepsilon} \\ \gamma & -1 \end{pmatrix} X_t dt + \Sigma dW_t$$

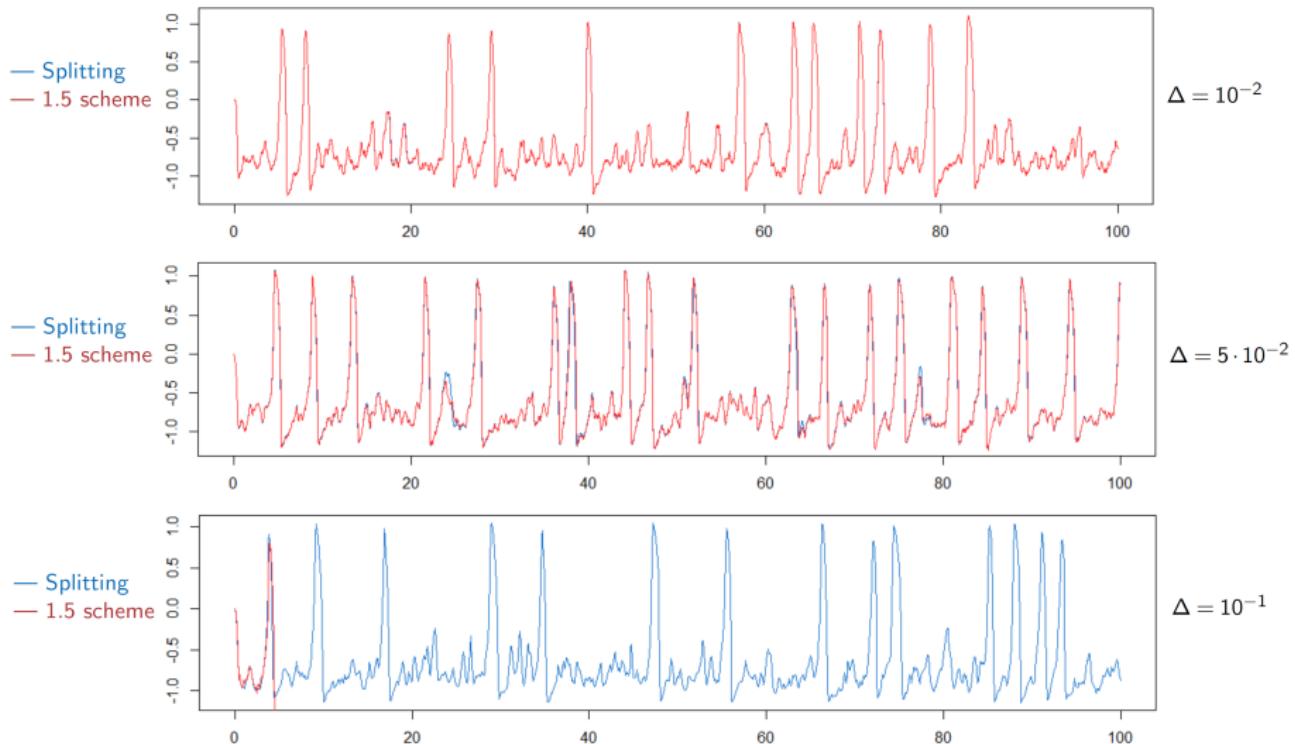
2. Subsystem b: Non-linear ODE

$$dX_t = \begin{pmatrix} \frac{1}{\varepsilon}(X_{1t} - X_{1t}^3) \\ \beta \end{pmatrix} dt$$

Explicit solution for both systems

Comparison of Splitting and Order 1.5 Strong Taylor Scheme

[Buckwar, Samson, Tamborrino, Tubikanec, 2021]



Estimation for elliptic SDE

$$dX_t = b(X_t, \theta)dt + \Sigma dW_t, \quad \Sigma = \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix}$$

Minimum contrast estimator [Genon-Catalot, Jacod, 1993; Kessler 1996; Pilipovic, Samson, Ditlevsen, 2022]

Set $\Gamma = \Sigma' \Sigma$.

$$\hat{\theta} = \arg \min_{\theta \in \Theta} \left(\sum_{i=1}^{n-1} (X_{i+1} - X_i - \Delta b(X_i, \theta))' \Gamma^{-1} (X_{i+1} - X_i - \Delta b(X_i, \theta)) \right. \\ \left. + \sum_{i=1}^{n-1} \log \det \Gamma \right)$$

Rate of convergence specific to hypoelliptic systems

- $\hat{\theta}$ asymptotically normal at rate $\sqrt{n\Delta}$
- $\hat{\Gamma}$ asymptotically normal at rate \sqrt{n}

Estimation for hypoelliptic SDE

Constraints based on numerical approximations [Genon-Catalot, Jacod, 1993; Kessler 1996,

Ditlevsen, Samson, 2019, Melnykova 2020]

$$\hat{\theta} = \arg \min_{\mu \in \Theta} \left(\sum_{i=1}^{n-1} (X_{i+1} - X_i - \Delta \tilde{b}(X_i, \theta))' \Gamma^{-1} (X_{i+1} - X_i - \Delta \tilde{b}(X_i, \theta)) + \sum_{i=1}^{n-1} \log \det \Gamma \right)$$

Rate of convergence specific to hypoelliptic systems

- $\hat{\theta}_1$ asymptotically normal at rate $\sqrt{n/\Delta}$
- $\hat{\theta}_2$ asymptotically normal at rate $\sqrt{n\Delta}$
- $\hat{\Gamma}$ asymptotically normal at rate \sqrt{n}

Still to be done

- First numerical applications of contrast estimator based on splitting scheme are promising
- Extension to SDE with spatial covariates
 - ▶ numerical schemes?
 - ▶ asymptotic results of estimators?
- Modeling Depth together with the position to get a 3D system
 - ▶ where should we put noise?
 - ▶ can we test the presence of noise?

Perspectives

- Narwhals data are very rich
 - ▶ Time-dependent variables
 - ▶ Multi-dimensional analysis
 - ▶ Mediation effect
- Hypoelliptic SDE for movement/spatial data
 - ▶ Splitting schemes are promising
 - ▶ Adaptation to drift with gradient of potential

MERCI !