

# Sinusoidal model

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## Description of the sinusoidal model

The observations along the tusk are denoted  $Y_i$  for  $i = 1, \dots, n$ , with the corresponding position along the tusk denoted  $x_i$ . The model is the following

$$Y_i = f(x_i, \varphi) + \varepsilon_i$$

with  $\varepsilon_i$  a random noise assumed to be normally distributed with mean 0 and variance  $\omega^2$ . The regression function is a periodic sinusoidal function

$$f(x, \varphi) = A \sin(g(x) + b) + B \sin(2g(x) + 2b + \pi/2)$$

with function  $g$  defined as

$$g(x) = ax + \xi_x$$

and finally  $\xi_x$  is assumed to be a random Ornstein-Uhlenbeck process

$$d\xi_x = -\beta \xi_x dx + \sigma dW_x$$

The objective is to estimate the parameters  $\varphi = (A, B, a, b)$ ;  $\psi = e^{\beta \Delta}$  where  $\Delta$  is the step size between two observations and  $\gamma^2 = \sigma^2/\beta$ .

## Simulation of trajectories

Let us start with some simulations.

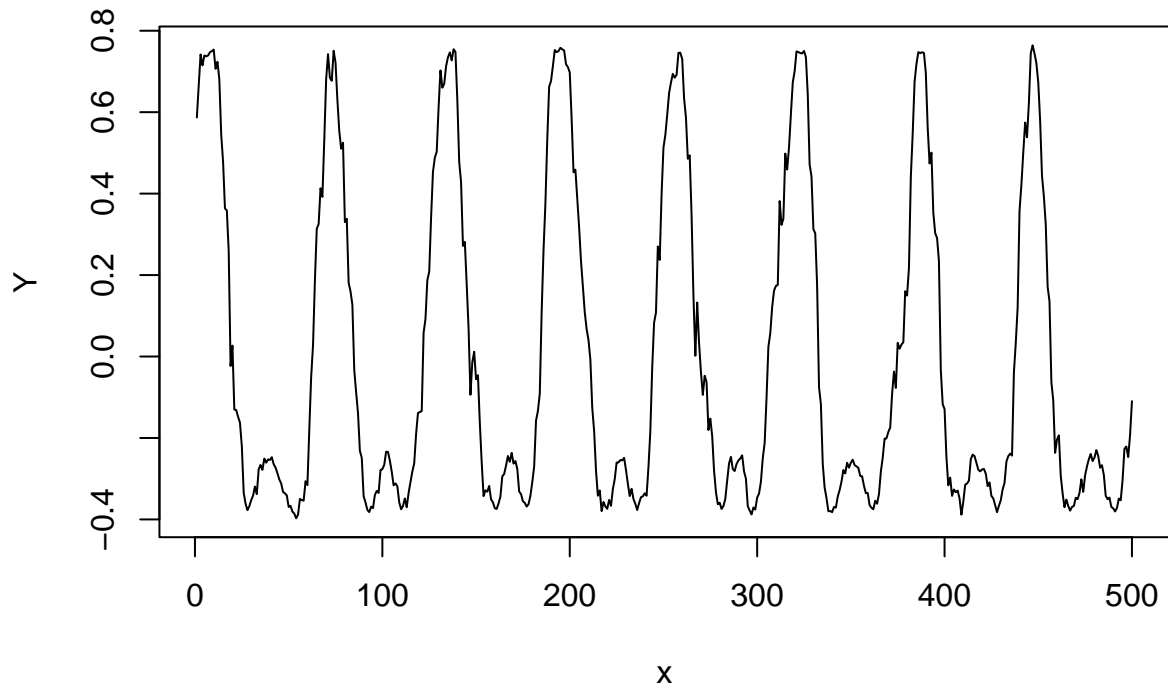
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# parameters
A = 1/2
B = -1/4
b = 1
a = 0.1
beta = 0.05
sigma = 0.1
omega = 0.01

# simulations
n = 500
x = 1:n
delta = 1
psi = exp(-delta*beta)
gamma = sigma/sqrt(2*beta)*sqrt(1-psi^2)
xi = rep(0,n)
```

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for (i in 2:n){
  xi[i] = xi[i-1]*psi + rnorm(1,0, gamma)
}
gx = a*x+xi
fx = A*sin(gx+b) + B*sin(2*gx + 2*b + pi/2)
Y = fx + rnorm(n,0,omega)
plot(x,Y,type = "l")

```



## Estimation with the EM algorithm

The EM algorithm is based on the complete log-likelihood of the model. The solution of the hidden process  $\xi_x$  is

$$\xi_{x+\delta} = \xi_x e^{-\beta\Delta} + \int_x^{x+\Delta} \sigma e^{\beta(s-x)} dW_s$$

such that the transition density is

$$p(\xi_{x+\delta}|\xi_x) = \mathcal{N}(\xi_x e^{-\beta\Delta}, \frac{\sigma^2}{2\beta}(1 - e^{-2\beta\Delta}))$$

The complete log-likelihood is thus

$$\begin{aligned}
\log L(Y, \xi, \theta) &= \sum_{i=1}^n \log p(Y_i | \xi_i) + \sum_{i=1}^n \log p(\xi_i | \xi_{i-1}) + \log p(\xi_1) \\
&= - \sum_{i=1}^n \frac{(Y_i - f(x_i, \varphi))^2}{2\omega^2} - \frac{n}{2} \log(\omega^2) \\
&\quad - \sum_{i=1}^n \frac{(\xi_i - \xi_{i-1} e^{-\beta \Delta})^2}{\frac{\sigma^2}{\beta} (1 - e^{-2\beta \Delta})} - \frac{n}{2} \log\left(\frac{\sigma^2}{\beta} (1 - e^{-2\beta \Delta})\right)
\end{aligned}$$

The EM algorithm proceeds at iteration  $k$  with the two following steps, given the current value of the parameters  $\theta^k$

- E step: calculation of  $Q(\theta, \theta^k)$
- M step: update of the parameters  $\theta^{k+1} = \arg \max_{\theta} Q(\theta, \theta^k)$

**E step** The condition distribution  $p(\xi | Y; \theta^k)$  is not explicit because the regression function is not linear. We should proceed with a MCMC algorithm to sample from this distribution. This will lead to a stochastic version of the EM algorithm, namely the SAEM algorithm.

**M step** We need the sufficient statistics to update the algorithm.

To update  $\omega^2$ , the statistic is

$$S_1(\xi_i) = \frac{1}{n} \sum_{i=1}^n (Y_i - f(x_i(\xi_i), \varphi))^2$$

To update  $\phi = (A, B, a, b)$ , the statistic is

$$S_2(\xi_i) = \sum_{i=1}^n \partial_{\varphi} f(x_i(\xi_i), \varphi) (y_i - f(x_i(\xi_i), \varphi))$$

For  $\gamma^2 = \sigma^2 / (2\beta)$ , the statistic is

$$S_3(\xi_i) = \frac{1}{n} \sum_{i=1}^n (\xi_i - \xi_{i-1} \psi)^2$$

To update  $\psi$ , we need to statistics

$$S_4(\xi) = \sum_{i=1}^n \xi_i \xi_{i-1}$$

and

$$S_5(\xi) = \sum_{i=1}^n (\xi_i^2 + \xi_{i-1}^2)$$

**SAEM algorithm** The steps of the SAEM algorithm are

- E step: simulation of a new trajectory  $\xi^k$  with a MCMC algorithm targeting  $p(\xi | Y; \theta^k)$  as stationary distribution
- SA step: stochastic approximation of the sufficient statistics

$$s^k = s^{k-1} + (1 - \alpha_k)(S(\xi^k) - s^{k-1})$$

- M step: update of  $\theta^k$  using the sufficient statistics  $s^k$