















<b>CONTACT INFORMATION</b>	<ul style="list-style-type: none"> <li>▪ <b>Email:</b> <a href="mailto:vaghat@seas.upenn.edu">vaghat@seas.upenn.edu</a> </li> <li>▪ Webpage  / Google Scholar  / LinkedIn <a href="#">in</a> / Twitter  / Github </li> </ul>
<b>RESEARCH INTERESTS</b>	Computer Vision, Robotics, Geometric Deep Learning, Equivariant representations, Optimization on Manifolds, Generative Models, Differential Geometry, AI for Science and Engineering
<b>EDUCATION</b>	<div> <div data-bbox="373 422 781 443">University Of Pennsylvania (UPenn)</div> <div data-bbox="1349 422 1458 443">Sep 2018-</div> <ul style="list-style-type: none"> <li>▪ <b>PhD</b> in Computer and Information Science <ul style="list-style-type: none"> <li>• Specialization: Geometric Deep Learning, Computer Vision</li> <li>• Advisor: Kostas Daniilidis </li> </ul> </li> <li>▪ <b>Master</b> in Statistics and Data Science (Wharton) <div data-bbox="1349 548 1458 569">Jan 2023-</div> <ul style="list-style-type: none"> <li>• <b>Current GPA:</b> 4.00/4.00</li> <li>• Relevant Coursework: Statistical Machine Learning, High-dimensional Statistics, Time-Series Forecasting, Stochastic Processes, Conformal Prediction</li> </ul> </li> <li>▪ <b>Master of Engineering</b> in Robotics (GRASP Laboratory) <div data-bbox="1240 663 1458 684">Sep 2020- Dec 2022</div> <ul style="list-style-type: none"> <li>• <b>GPA:</b> 4.00/4.00</li> <li>• Relevant Coursework: Convex Optimization, Learning in Robotics, Machine Perception, Advanced Machine Perception, Principles of Deep Learning, Theory of Computation</li> </ul> </li> </ul> <div> <div data-bbox="373 779 1013 800">National Technical University of Athens (NTUA), Greece</div> <div data-bbox="1240 779 1458 800">Sep 2012- Sep 2018</div> <ul style="list-style-type: none"> <li>▪ <b>BSc &amp; MSc</b> in Electrical and Computer Engineering (5-year joint degree; 300 ECTS) <ul style="list-style-type: none"> <li>• <b>GPA:</b> 9.58/10.0 (top 1% among graduate class of 341 students; highest honors)</li> <li>• <b>Major GPA:</b> 9.64/10.0 (top 1%) Specialization: Computer Science</li> <li>• Relevant Coursework: Computer Vision, Stochastic Processes, Pattern Recognition, Deep Learning, Advanced Algorithms, Algorithmic Machine Learning, Spectral Graph Theory, Social Network Analysis</li> <li>• Undergraduate Thesis: “<i>Spectral Graph Methods with Applications in Computer Vision</i>”  (Greek)</li> <li>• Advisor: Petros Maragos </li> </ul> </li> </ul> </div> </div>
<b>PUBLICATIONS</b>	<ul style="list-style-type: none"> <li>▪ EqNIO: Subequivariant Neural Inertial Odometry. Royina Karegoudra Jayanth, Yinshuang Xu, Ziyun Wang, Evangelos Chatzipantazis, Daniel Gehrig, Kostas Daniilidis.  (Under Review)</li> <li>▪ BiEquiFormer: Bi-Equivariant Representations for Global Point Cloud Registration. Stefanos Pertigkiozoglou*, Evangelos Chatzipantazis*, Kostas Daniilidis.  (Under Review)</li> <li>▪ Improving Equivariant Model Training via Constraint Relaxation, Stefanos Pertigkiozoglou*, Evangelos Chatzipantazis*, Shubhendu Trivedi, Kostas Daniilidis.  NeurIPS 2024.</li> <li>▪ <b>(Best Student Paper)</b> Structural Risk Minimization for Learning Nonlinear Dynamics, Charis Stamouli, Evangelos Chatzipantazis, George J Pappas.  ACC 2024.</li> <li>▪ SE(3)-Equivariant Attention Networks for Shape Reconstruction in Function Space, E.Chatzipantazis*, S.Pertigkiozoglou*, E.Dobriban, K.Daniilidis.   ICLR 2023.</li> <li>▪ <b>(Outstanding Paper)</b> Graph Neural Networks for Multi-Robot Active Information Acquisition. M.Tzes, N.Bousias, E.Chatzipantazis, G.Pappas.   ICRA 2023.</li> <li>▪ Learning Augmentation Distributions Using Transformed Risk Minimization, E.Chatzipantazis*, S.Pertigkiozoglou*, K.Daniilidis, E.Dobriban.  TMLR 2023.</li> <li>▪ Unsupervised Monocular Depth and Latent Structure, K.Chaney*, B.Bucher*, E.Chatzipantazis, J.Shi, K.Daniilidis. CVPR Workshop on 3D Scene Understanding for Vision, and Robotics 2019.</li> </ul>

PROFESSIONAL  
EXPERIENCE

▪ **(Boston Dynamics) AI Institute**

- *Research Intern.*


Jun 2024-

- Designed a novel policy learning algorithm for robotic manipulation tasks that exploits advanced perception representations to produce fast and robust multimodal policies.
- Supervisor: Robert Platt , Robin Walters .

▪ **University of Pennsylvania (UPenn)**

- *Graduate Research Assistant, GRASP Lab, UPenn.*



Sep 2018-

- Conceptualized and implemented an equivariant attention-based neural network for point cloud reconstruction and improved the state-of-the-art by a large margin while achieving zero-shot generalization to real scenes.
- Conceptualized a mathematical framework for automatic discovery of symmetries in data and implemented a modular and efficient algorithm for recovering and applying useful augmentations while training large neural networks for vision tasks.
- Implemented a deep network for monocular depth estimation and fused it with IMU measurements using a MSCKF for vision and inertial odometry.
- Supervisor: Kostas Daniilidis 

- *Teaching Assistant CIS700: Advanced Topics in Geometric Deep Learning,*




Spring 2024

- Lectures on Equivariant Deep Learning: See [notes](#) on derivation of harmonic networks from steerability constraints.


- Professor: Kostas Daniilidis , Jean Gallier 

- *Teaching Assistant CIS680: Advanced Machine Perception,*

Spring 2019

- MaskRCNN implementation from scratch on a newly curated COCO dataset: : (, ).

- Website 

- Professor: Jianbo Shi 

- *Teaching Assistant ESE546: Principles of Deep Learning,*

Spring 2019, 2020


- Co-authored course material in PAC-learning ([Chapter 13](#)) and [Markov Chains](#).

- Class Notes 

- Professor: Pratik Chaudhari 

- *Teaching Assistant ESE650: Learning in Robotics,*

Fall 2019

- Designed assignment on Partially Observable Markov Decision Processes (POMDP) and developed a novel fusion of Multi State Constraint Kalman Filter with deep depth estimators .

- Professor: Kostas Daniilidis 






▪ **National Technical University of Athens,**

Sep 2017- Sep 2018

- *Undergraduate Research Assistant, Computer Vision and Signal Processing (CVSP) Lab.*

- Scaled up spectral graph algorithms for image segmentation and extended previous methods by incorporating user-defined hard constraints.

- Supervisor: Petros Maragos 

<b>HONORS&amp; AWARDS</b>	▪ <b>Best Student Paper Award</b> ACC 2024. Paper: <a href="#">Structural Risk Minimization for Learning Nonlinear Dynamics</a>
	▪ <b>Outstanding Paper Award in Multi-Robot Systems</b> ICRA 2023. Paper: <a href="#">Graph Neural Networks for Multi-Robot Active Information Acquisition</a> .
	▪ <b>Gerondelis Foundation Graduate Scholarship</b> 2022. Awarded for academic excellence to support Ph.D. Studies.
	▪ <b>Thomaideion Award</b> 2016, 2018. Awarded for highest grade among all students of Electrical and Computer Engineering in academic years 2015-2016 and 2017-2018.
	▪ <b>Kritikos Award</b> 2017. Awarded for highest grade in all courses of Mathematics among fellow students for the academic year 2016-2017.
	▪ <b>Papakyriakopoulos Award</b> 2016. Awarded for highest grade in all courses of Mathematics among fellow students for years 2015-2016.
	▪ <b>"The Great Moment of Education" Eurobank EFG Award</b> 2012. Ranking 1st among fellow students in high school in the National Qualification Exams, 2012.
<b>ACADEMIC SERVICE</b>	▪ <b>Organizer</b> of IROS 2024 Workshop on <i>Equivariant Robotics: The Role of Symmetry Across Perception, Estimation, and Control</i> <a href="#">Website</a> 
	▪ <b>Invited Speaker</b> in CVPR 2024 workshop on <i>Equivariant Vision: From Theory to Practice</i> : Talk on practical and theoretical aspects of equivariant deep learning. <a href="#">Website</a>  , <a href="#">Slides</a>  .
	▪ Machine Learning Conference Reviewer: ICML 2022,2023,2024, NeurIPS 2022,2023,2024.
	▪ Computer Vision Conference Reviewer: ICCV 2023.
	▪ Robotics Conference Reviewer: ICRA 2023.
<b>LANGUAGES</b>	<b>Greek:</b> Native language. <b>English:</b> fluent. <b>French:</b> novice
<b>TECHNICAL SKILLS</b>	▪ <b>Programming Languages</b> <ul style="list-style-type: none"> <li>• Current Frequent Use: Python</li> <li>• Past Frequent Use: C, C++, Java, Prolog, SMLNJ, MATLAB, HTML5, Javascript, PHP, mySQL</li> </ul>
	▪ <b>Other Programming Skills</b> <ul style="list-style-type: none"> <li>• PyTorch, Parallel &amp; GPU Programming , Github, <math>\text{\LaTeX}</math>, Unix Kernel programming, bash scripting</li> </ul>
<b>OTHER INTERESTS</b>	Competitive Swimming (7 years), Water Polo (3 years), Tennis (3 years), Guitar(self-taught)
<b>REFERENCES (UPON REQUEST)</b>	<b>Kostas Daniilidis</b> Ruth Yalom Stone Professor UPenn 
	<b>Edgar Dobriban</b> Associate Professor of Statistics and Data Science Wharton 
	<b>Pratik Chaudhari</b> Assistant Professor UPenn 