	F. VAGHDEVI PRAVEEN 8051 PROGRAMS
USN:	1/3/V1/4C & 1 + 3
SIGNA.	TURE: Plaghdevic LAB-1
	LAB!
11	Derive a Stepper motor interface to stotate the
	Merive a Stepper motor interpretarion of Steps. Introduce motor in Anti-Clockwise by N Steps. Introduce
	suitable delay between Successive Steps.
	0
	# include < Stdip.h>
	# include < 9reg 51.h>
	char xdata port at Oxe803;
	char xdata porta_at_0xe800;
	charidata acc at 1)x30;
	OLIO CO MORIAN REFLOREN THE ROTATION OF THE STEPPE
	3 MOTOR
-	interior de la constitución de l
-	int j;
101 112	for (j=0; j<800; j++)
<del></del>	7 }
	void main ()
<b></b>	void main ()
	10 00 00 00 00 00
-	POTE = DX80; 1/ CONFIGURE ALL THE PORTS OF 8255 AS
	DUTPUT PORT
	while (1)
	}
	ace = DXII;
<u> </u>	porta = acc;
	delay (); min man me his.
	acc = 0x44;
	porta = acc;
	delay ();
	acc = 0x88;
	porta = acc;
	delay ();
	2 1
	7