# **Support Vector Machines**

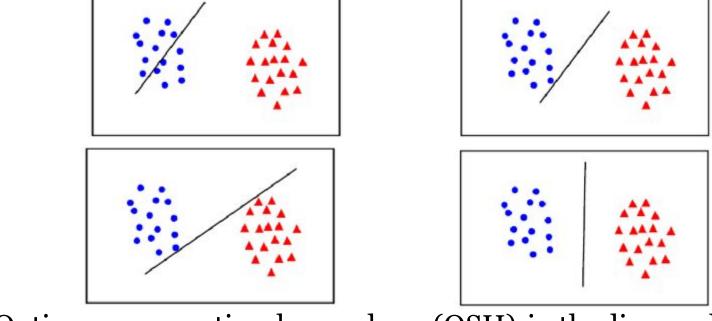


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### Optimum Separation Hyperplane

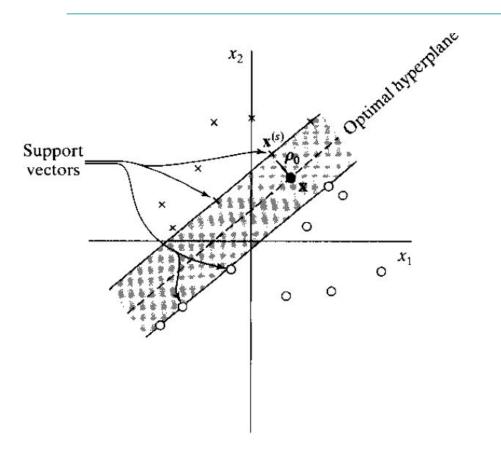




- Optimum separation hyperplane (OSH) is the linear classifier with the maximum margin for a given finite set of learning patterns.
- Better generalization!

#### Optimum Separation Hyperplane



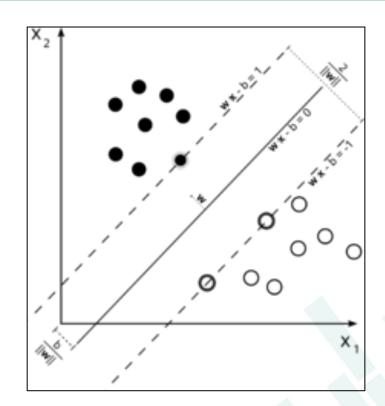


- *Margin of separation*: distance to the closest example
- For the optimal hyperplane
  - distance to the closest negative example = distance to the closest positive example
- The goal of SVM is to find the particular hyperplane for which the *margin of separation* is maximized.

#### **Support Vectors**



- Support vectors are the samples closest to the separating hyperplane
  - They are the most difficult patterns to classify.
- Optimal separation hyper-plane is completely defined by support vectors



## Optimal Hyperplane: Problem Formulation

- Training Set: D =  $\{(x_i, d_i); i = 1, 2, ..., n\}$
- Linearly Separable:
  - The Decision Boundary [Hyperplane]

$$\sum_{i=1}^{m} w_i x_i + b = W^T x + b = 0$$

Correct Classification

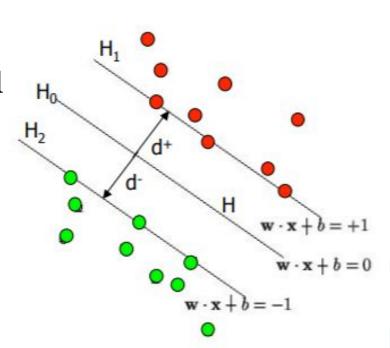
$$w^T x_i + b \ge 0; \forall y_i = +1$$
  
 $w^T x_i + b < 0; \forall y_i = -1$ 

- Infinitely many hyperplanes exist
  - Which is the optimal?

## Margin of Separation



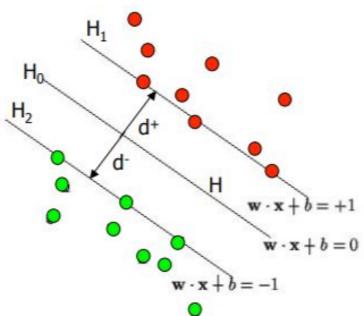
- NO training patterns exist between the two hyperplanes:
  - $\circ$  H<sub>1</sub>: wx + b = 1, y = 1
  - $\circ$  H<sub>2</sub>: wx + b = -1, y = -1
- The points on the planes H<sub>1</sub> and H<sub>2</sub> are the Support Vectors
- d+ = the shortest distance to the closest positive point
- d- = the shortest distance to the closest negative point
- The margin m of a separating hyperplane is (d+) + (d-)



## Maximizing the margin



- We want a classifier (linear separator) with as big a margin as possible.
- Distance from a point(x<sub>o</sub>,y<sub>o</sub>) to a
   Line Ax+By+c = o is
  - $\circ |Ax_0 + By_0 + c|/sqrt(A^2 + B^2)$
- The distance between  $H_o$  and  $H_1$  $\circ |w \cdot x + b|/||w|| = 1/||w||$
- The total distance *m* between H<sub>1</sub> and H<sub>2</sub>:
  - $\circ$   $2/\overline{||w||}$



## Quadratic Programming Problem

- When  $/\!/$  w  $/\!/$  =1 then m=2
- When  $/\!/ w/\!/ = 2$  then m=1
- When  $/\!/$  w  $/\!/$  =4 then m=1/2
- The bigger the norm is, the smaller the margin become.
- Maximize 2/ || w || Minimize || w || /2
  - $\circ = Minimize \frac{1}{2} \| \mathbf{w} \|^2$
- Minimize  $f: \frac{1}{2}||w||^2$  s.t.  $g: y_i[w \cdot x_i + b] > = 1$
- This is a constrained optimization problem
- It can be solved by the Lagrangian multiplier method
  - o Because it is quadratic, the surface is a paraboloid, with just a single global minimum

#### SVM: Constrained Optimization Problem



- Given the training sample  $\{(x_i, y_i)\}_{i=1}^n$ , find the optimum values of the weight vector **w** and bias **b** such that they satisfy the constraints
  - $0 \quad y_i^*(\mathbf{w}^T\mathbf{x}_i + \mathbf{b}) >= 1, \ \forall \ i=1,2,...n$ 
    - Equality is true for support vector points and greater than condition holds true for non-support vector points.

and the weight vector **w** minimizes the cost function:

- $\Phi(\mathbf{w}) = \frac{1}{2} \| \mathbf{w} \|^2 = \mathbf{1}/2\mathbf{w}^T\mathbf{w}$
- Constraints are linear
- Cost function is convex

#### **Constrained Optimization**



- Lagrangian function: Constrained optimization can be solved through unconstrained optimization
  - $L(x,y,\alpha) = f(x,y) \alpha g(x,y)$ 
    - a: Lagrange multipliers
- *Solution:*  $\nabla L(x,y,\alpha) = o$ 
  - $\circ \quad \partial L(x,y,\alpha)/\partial x = 0$
  - $\circ \ \partial L(x,y,\alpha)/\partial y = 0$
  - $\circ \quad \partial L(x,y,\alpha)/\partial a = 0$

#### Lagrange Multiplier: Primal Form



- $J(w,b,\alpha) = \frac{1}{2} \mathbf{w}^{\mathsf{T}} \mathbf{w} \mathbf{\Sigma}_{i=1}^{\mathsf{n}} \alpha_{i} [y_{i}^{\mathsf{*}} (\mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} + b)]$ 
  - Inequality constraints -> equality constraints
  - $0 \quad J(w,b,\alpha) = \frac{1}{2} \mathbf{w}^{T} \mathbf{w} \sum_{i=1}^{n} \alpha_{i} [y_{i}^{*} (\mathbf{w}^{T} \mathbf{x}_{i} + b) 1]$
- Karush-Kuhn-Tucker Condition
- $\circ$  Multipliers that can assume non-zero values ( $\alpha > 0$ ), must satisfy following conditions:

## Lagrange Multiplier



- *Solution:*  $\nabla L(x,y,\alpha) = o$ 
  - Conditions of optimality

    - $\blacksquare$   $\partial J(\mathbf{w}, b, \alpha)/\partial b = o$
- $J(w,b,\alpha) = \frac{1}{2} \mathbf{w}^{T} \mathbf{w} \mathbf{\Sigma}_{i=1}^{n} \alpha_{i} [y_{i}^{*} (\mathbf{w}^{T} \mathbf{x}_{i} + b) 1]$
- $0 \quad \frac{1}{2} \mathbf{w.w} \mathbf{\Sigma}^{n}_{i=1} \alpha_{i} y_{i} \mathbf{w.x}_{i} \mathbf{\Sigma}^{n}_{i=1} \alpha_{i} y_{i} b + \mathbf{\Sigma}^{N}_{i=1} \alpha_{i}$
- $\mathbf{w} = \sum_{i=1}^{n} \alpha_i y_i \mathbf{x_i} \dots (\mathbf{A})$
- $\sum_{i=1}^{n} \alpha_i y_i = 0$  ....(B)

### Duality theorem (Bertsekas, 1995)



- If the primal problem has an optimal solution, the dual problem also has an optimal solution, and the corresponding optimal values are equal.
  - $\Phi(\mathbf{w}_{\alpha}) = J(\mathbf{w}_{\alpha}, b_{\alpha}, \alpha_{\alpha}) = \min J(\mathbf{w}, \mathbf{b}, \alpha)$
- Applying (B) and then (A) to Lagrangian equation:
  - $0 \quad J(w,b,\alpha) = \frac{1}{2} \mathbf{w.w} \mathbf{\Sigma}_{i=1}^{n} \alpha_i y_i \mathbf{w.x}_i + \mathbf{\Sigma}_{i=1}^{n} \alpha_i$
  - $O J(w,b,\alpha) = \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_i \alpha_j y_i y_j \mathbf{x_i x_j} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_i \alpha_j y_i y_j \mathbf{x_i x_j} + \sum_{i=1}^{n} \alpha_i \alpha_i \mathbf{x_i y_i y_i x_i x_j}$
  - $O(\alpha) = \sum_{i=1}^{N} \alpha_i \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_i \alpha_j y_i y_j x_i x_j$

#### Dual Problem



- Given the training sample  $\{(x_i, y_i\}_{i=1}^n$ , find the Lagrange multipliers that maximize the objective function
  - $Q(\alpha) = \sum_{i=1}^{N} \alpha_i 1/2 \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_j \alpha_j y_j y_j x_i x_j S.T.$ 

    - $\sum_{i=1}^{n} \alpha_i y_i = 0$
- Primal vs Dual
  - The dual problem is cast entirely in terms of the training data
- Objective: To find the lagrangian multipliers which maximizes the  $Q(\alpha)$ 
  - Some of the lagrangian multipliers will become zero
  - Some of the lagrangian multipliers will have high value

#### Interpretation



- Some of the lagrangian multipliers will have high value
  - Corresponding input training sample is a support vector
- Some of the lagrangian multipliers will become zero
  - Corresponding input training sample is not a support vector
- Some of the lagrangian multipliers might have very high value
  - Corresponding input training sample is an outlier

# Optimal weight and bias: Decision boundary

- Having determined the optimum Lagrangian multipliers, the optimum weight vector may be computed
  - $\circ$   $\mathbf{w}_{o} = \sum_{i=1}^{n_{s}} \alpha_{o,i} y_{i} \mathbf{x}_{i}$  $\circ$   $n_{s}$  is the number of support vectors for which the Lagrange multipliers are all non-zero
- Having obtained  $\mathbf{w}_{o}$ , the bias  $\mathbf{b}_{o}$  may be computed

   $\mathbf{b}_{o} = \mathbf{1} \mathbf{w}_{o}^{\mathsf{T}} \mathbf{x}^{(\mathbf{s})}$ ,  $\forall \mathbf{y}^{(\mathbf{s})} = \mathbf{1}$   $\mathbf{1} \sum_{i=1}^{N_{s}} \alpha_{o,i} \mathbf{y}_{i} \mathbf{x}_{i} \mathbf{x}^{(\mathbf{s})}$
- For a new sample z, calculate  $\mathbf{w}_{o}z + \mathbf{b}_{o}$ •  $\Sigma^{\text{Ns}} = \alpha_{o,i} y_{i} \mathbf{x}_{i} \mathbf{z}_{j} + (1 - \Sigma^{\text{ns}} = \alpha_{o,i} y_{i} \mathbf{x}_{i} \mathbf{x}^{(s)})$
- If the sign is positive, the sample z will belong the positive class, else the sample z will belong to the negative class.

## **Breakout Room Activity**



i	$x_i$	$y_i$	$lpha_i$	i	$x_i$	$y_i$	$\alpha_i$
1	(4,2.9)	1	0.414	6	(1.9,1.9)	-1	0
2	(4,4)	1	0	7	(3.5, 4)	1	0.018
3	(1,2.5)	-1	0	8	(0.5, 1.5)	-1	0
4	(2.5,1)	-1	1.18	9	(2,2.1)	-1	0.414
5	(4.9, 2.5)	1	0	10	(4.5, 2.5)	1	0

Consider the training data samples and the corresponding Lagrange multipliers learned from them, as given in the following table.

From the given table above, answer the following questions?

- What is the b for the SVM?
- 2. Identify the support vectors.
- 3. Compute w and classify the point (3,3).

#### References



- 1. <a href="https://www.svm-tutorial.com/2017/02/svms-overview-support-vector-machines/">https://www.svm-tutorial.com/2017/02/svms-overview-support-vector-machines/</a>
- 2. https://www.syncfusion.com/ebooks/support\_vector\_machines\_succin ctly/introduction
- 3. https://www.youtube.com/watch?v=b-Su6aVh5yo
- 4. Chapter 6, Neural Networks: A Comprehensive Foundation (2nd Edition) 2nd Edition by Simon Haykin





### Supplement: Scaling of weight vectors



- Distance from a point  $(x_0, y_0)$  to a Line Ax + By + c = 0 is
- $\circ |Ax_0 + By_0 + c|/sqrt(A^2 + B^2)$
- The distance between support vector point and H<sub>o</sub>
- $om = |\mathbf{w} \cdot \mathbf{x}_0 + \mathbf{b}| / ||\mathbf{w}||$
- III = |w•x₀+b|/||w||
   The geometric margin is clearly invariant to scaling of weight parameters because it is inherently normalized by the length of ||w||
- This means that we can impose any scaling constraint we wish on ||w|| without affecting the geometric margin.
- $\bullet \quad |\mathbf{w} \bullet \mathbf{x}_0 + \mathbf{b}| = \mathbf{m}^* ||\mathbf{w}||$
- By applying a proper scaling to the weights, the factor m\*
   ||w|| can always be made = 1