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ASSIGNMENT 1

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Download all latex-tikz codes from

https://github.com/vaibhavchhabra25/EE3900-course/blob/main/GATE_Assignment-1/main.tex

1 Problem

(EC 2017-Q.33) Consider an LTI system with magnitude response

$$|H(f)| = \begin{cases} 1 - \frac{|f|}{20}, & |f| \le 20\\ 0, & |f| > 20 \end{cases}$$

and phase response

$$arg H(f) = -2f$$

If the input to the system is

$$x(t) = 8\cos\left(20\pi t + \frac{\pi}{4}\right) + 16\sin\left(40\pi t + \frac{\pi}{8}\right)$$
$$+24\cos\left(80\pi t + \frac{\pi}{16}\right)$$

then what is the average power of the output signal y(t).

2 Solution

$$A \sin(\omega_0 t + \phi) \longrightarrow H(\omega) \text{ LTI} \longrightarrow A|H(\omega_0)|\sin(\omega_0 t + \phi + \angle H(\omega_0))$$

$$A \cos(\omega_0 t + \phi) \longrightarrow A|H(\omega_0)|\cos(\omega_0 t + \phi + \angle H(\omega_0))$$

Fig. 0: Output of LTI

1) For input signal $8\cos\left(20\pi t + \frac{\pi}{4}\right)$,

$$f_1 = 20\pi/2\pi = 10$$
Hz (2.0.1)

Since $|f_1| \leq 20$,

$$|H(f_1)| = 1 - \frac{10}{20} = \frac{1}{2}$$
 (2.0.2)

Also,

$$\arg H(f_1) = -2f_1 = -20 \tag{2.0.3}$$

So, the output signal $y_1(t)$ is

$$y_1(t) = \left(8 \times \frac{1}{2}\right) \cos\left(20\pi t + \frac{\pi}{4} - 20\right)$$
(2.0.4)

$$\implies y_1(t) = 4\cos\left(20\pi t + \frac{\pi}{4} - 20\right) \quad (2.0.5)$$

2) For input signal $16 \sin \left(40\pi t + \frac{\pi}{8}\right)$,

$$f_2 = 40\pi/2\pi = 20$$
Hz (2.0.6)

Since $|f_2| \le 20$,

$$|H(f_2)| = 1 - \frac{20}{20} = 0$$
 (2.0.7)

So, the output signal $y_2(t) = 0$.

3) For input signal $24\cos\left(80\pi t + \frac{\pi}{16}\right)$,

$$f_3 = 80\pi/2\pi = 40$$
Hz (2.0.8)

Since $|f_3| > 20$,

$$|H(f_3)| = 0 (2.0.9)$$

So, the output signal $y_3(t) = 0$. So, the total output signal is

$$y(t) = y_1(t) + y_2(t) + y_3(t)$$
 (2.0.10)

$$\implies y(t) = 4\cos\left(20\pi t + \frac{\pi}{4} - 20\right)$$
 (2.0.11)

Average power of this output signal

$$P_{y(t)} = \frac{4^2}{2} = 8W {(2.0.12)}$$