MicroCAT C-T (P optional) Recorder (Inductive Modem)



SUMMARY

- Conductivity, Temperature, and (optional) Pressure, at user-programmable intervals (6 seconds to 6 hours).
- Inductive Modem (IM) interface, internal memory, and internal batteries.
- Expendable anti-foulant devices for bio-fouling protection.
- Depths to 350 meters (ShallowCAT plastic housing) or 7000 meters (titanium housing).
- Sea-Bird's field-proven MicroCAT family, with more than 8000 instruments deployed since 1997.

DESCRIPTION

The SBE 37-IM MicroCAT is a high-accuracy conductivity and temperature sensor/recorder (pressure optional) with internal battery, non-volatile memory, and built-in Inductive **M**odem.

The Inductive Modem (IM) system provides reliable, low-cost, real-time data transmission for up to 100 IM-enabled instruments using plastic-coated wire rope (typically 3 x 19 galvanized steel) as both the transmission line and mooring tension member. IM instruments clamp anywhere along the rugged mooring wire. Expensive and potentially unreliable multi-conductor electrical cables with fixed-position underwater connectors are not required. IM moorings are easily reconfigured for changing deployments (positions changed or instruments added or removed), by sliding and re-clamping instruments on the cable. IM systems are much less expensive and more power-efficient than acoustic modems, and offer reliable communication over greater distances.

In a typical mooring, an Inductive Modem Module (IMM) or Surface Inductive Modem (SIM) housed in the buoy communicates with underwater IM $\,$

instruments and is interfaced to a computer or data logger via an RS-232 serial port. The computer or data logger (not supplied by Sea-Bird) is programmed to poll each IM instrument on the mooring for its data, and send the files to a telemetry transmitter (satellite link, cell phone, RF modem, etc.). The MicroCAT saves data in memory for upload after recovery, providing a data backup if real-time telemetry is interrupted.



SENSORS AND INTERFACE ELECTRONICS

The MicroCAT retains the temperature and conductivity sensors used in our time-proven SeaCAT and SeaCAT plus products. Calibration coefficients are stored in EEPROM, allowing the MicroCAT to transmit data in engineering units. Our unique internal-field conductivity cell permits the use of expendable anti-foulant devices. The aged and pressure-protected thermistor has a long history of exceptional accuracy and stability.

Temperature is acquired by applying an AC excitation to a hermetically sealed VISHAY reference resistor and an ultra-stable aged thermistor (drift rate typically less than 0.002 °C per year). The ratio of thermistor resistance to reference resistance is determined by a 24-bit A/D converter; this A/D also processes the pressure sensor signal. Conductivity is acquired using an ultra-precision Wien-Bridge oscillator.

The optional strain-gauge pressure sensor is available in eight ranges, to a maximum depth of 7000 meters. Compensation of the temperature influence on pressure offset and scale is performed by the MicroCAT's CPU.

OPERATING MODES

User-selectable operating modes include:

- Polled On command, MicroCAT takes one sample and transmits the data.
- Autonomous MicroCAT samples autonomously at pre-programmed intervals, storing the data in memory.
- Combo or Averaging Sampling MicroCAT samples autonomously at pre-programmed intervals, storing data in memory, and the IMM/SIM can request the last stored data or the average of the samples acquired since its last request.



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SOFTWARE

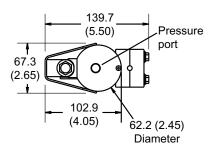
The MicroCAT is supplied with a powerful Windows 2000/XP software package, Seasoft® V2, which includes:

- SeatermV2[©] terminal program for easy communication and data retrieval.
- SBE Data Processing® programs for calculation, display, and plotting of conductivity, temperature, pressure (optional), and derived variables such as salinity and sound velocity.

DATA STORAGE AND BATTERY ENDURANCE

Temperature and conductivity are stored 6 bytes/sample, time 4 bytes/sample, and optional pressure 5 bytes/sample; memory capacity is in excess of 530,000 samples. The MicroCAT is powered by a 10.6 Amp-hour (nominal) battery pack consisting of twelve AA lithium batteries (Saft LS14500) which, when removed from the MicroCAT, can be shipped via commercial aircraft. The pack provides sufficient internal battery capacity for more than 300,000 samples for a typical sampling scheme.

Dimensions in mm (inches)



SPECIFICATIONS

Measurement Range

Conductivity: 0 - 7 S/m (0 - 70 mS/cm)

Temperature: -5 to 35 °C

Optional Pressure: 20/100/350/600/1000/2000/3500/7000 m

(meters of deployment depth capability)

Initial Accuracy

Conductivity: ± 0.0003 S/m (0.003 mS/cm)

Temperature: ± 0.002 °C

Optional Pressure: ± 0.1% of full scale range

Typical Stability

Conductivity: 0.0003 S/m (0.003 mS/cm) per month

Temperature: 0.0002 °C per month

Optional Pressure: 0.05% of full scale range per year

Resolution

Conductivity: 0.00001 S/m (0.0001 mS/cm)

Temperature: 0.0001 °C

Optional Pressure: 0.002% of full scale range

Clock Accuracy 5 seconds/month

Power Supply 10.6 Amp-hour (nominal) battery pack

Quiescent Current120 microAmpsCommunications Current2.5 milliAmps

Communications Time 0.5 seconds/sample

Acquisition Current 13 milliAmps

Acquisition Time 1.8 - 2.6 seconds/sample, dependent on sampling

mode and inclusion of pressure sensor

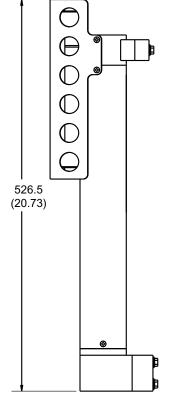
Housing, Depth Rating, & Weight (with standard mooring guide & clamp, without pressure)

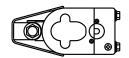
Standard Titanium housing; 7000 m (23,000 ft)

Weight in air: 4.0 kg (8.8 lbs)
Weight in water 2.4 kg (5.3 lbs)
Plastic bousing: 350 m (1150 ft)

Optional ShallowCAT Plastic housing; 350 m (1150 ft)

Weight in air: 2.9 kg (6.4 lbs)
Weight in water 1.3 kg (2.9 lbs)





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