# XCS229i Problem Set 1 (Written)

#### Vaibhav Kulkarni

**TOTAL POINTS** 

### 24 / 27

**QUESTION 1** 

## Convexity of GLMs 18 pts

#### 1.1 a 6 / 6

- $\sqrt{+3}$  pts \*\*Proof portion: \*\*Proof successfully arrives at \$\$E[Y;\eta] = \frac{\partial}{\partial} \eta} a(\eta)\$\$
- + **1.5 pts** \*\*Proof portion:\*\* Proof attempts to arrive at \$\$E[Y;\eta] = \frac{\partial}{\partial} \eta} a(\eta)\$\$
- √ + 3 pts \*\*Math and Process:\*\* No broad
  assumptions or leaps in logic or mathematical errors
- + 2 pts \*\*Math and Process: \*\*Minor assumptions and/or leaps in logic and/or mathematical errors
- + 1 pts \*\*Math and Process: \*\*Major assumptions and/or leaps in logic and/or mathematical errors
  - + 0 pts No proof included

#### 1.2 b 6 / 6

- √ + 3 pts \*\*Proof Portion:\*\* Proof correctly shows \$\$Var(Y; \eta) = \frac{\partial^2}{\partial \eta^2} a(\eta)\$\$
- + 1.5 pts \*\*Proof Portion: \*\*Proof attempts to arrive
  at \$\$Var(Y; \eta) = \frac{\partial^2}{\partial \eta^2}
  a(\eta)\$\$
- √ + 3 pts \*\*Math and Process:\*\* No broad
  assumptions or leaps in logic or mathematical errors
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- + 1 pts \*\*Math and Process:\*\* Major assumptions and/or leaps in logic and/or mathematical errors
  - + 0 pts No proof included

## 1.3 C 4 / 6

- √ + 2 pts \*\*Loss Function:\*\* Correct calculation for loss function \$\$I(\theta)\$\$
- + 1 pts \*\*Loss Function:\*\* Attempts to calculate for loss function \$\$I(\theta)\$\$

- + 2 pts \*\*Gradient of Loss\*\*: Correct calculation for gradient of loss function \$\$\nabla\_\theta |\theta\$\$
- √ + 1 pts \*\*Gradient of Loss:\*\* Attempts to calculate gradient of loss function \$\$\nabla\_\theta |\theta\$\$
- + 2 pts \*\*Hessian:\*\* Correct calculation of Hessian to show its PSD  $\$  \above 1 (\theta^2 I (\theta) \$\$
  - + 0 pts Proof not included
- $\checkmark$  + 1 pts \*\*Hessian:\*\* Attempts to calculate Hessian to show its PSD \$\$\nabla\_\theta^2 I (\theta)\$\$
  - + 2 pts Has intermediate steps.
- + 1 pts Some intermediate steps and attempt at PSD. Please check solutions.
  - 1 pts Some mathematical errors.

### QUESTION 2

## Linear Regression: Linear in What? 9 pts

#### 2.1 a 5 / 5

- $\checkmark$  + 1.5 pts \*\*Objective Function:\*\* Correct value for \$\$J(\theta)\$\$
- + **0.5 pts** \*\*Object Function:\*\* Attempt to derive correct value for \$\$J(\theta)\$\$
- √ + 2 pts \*\*Gradient: \*\* Correct differentiation of \$\$\nabla\_\theta J(\theta)\$\$
- + 1 pts \*\*Gradient:\*\* Attempt to differentiate \$\$\nabla\_\theta J(\theta)\$\$
- √ + 1.5 pts \*\*Update Rule:\*\* Correct reduction the gradient descent update rule \$\$\theta := \theta -\alpha \nabla\_\theta J(\theta)\$\$
- + **0.5 pts** \*\*Update Rule:\*\* Attempt to reduce gradient descent update rule \$\$\theta := \theta \alpha \nabla\_\theta J(\theta)\$\$
- **0.5 pts** There should be no phi(x) notion, h\_theta(x) means that.
- + **0.5 pts** Attempt to create update rule. You should be using gradient, not Hessian.

### + 0 pts Not done

## 2.2 d 1/1

- $\sqrt{+1}$  pts Commentary that a higher degree polynomial fits the data better.
  - + O pts Blank
- **0.25 pts** Incorrect statement (e.g. not significantly differentiating k=20 with lower order fits)

## 2.3 f 1/1

- √ + 1 pts Comment on two of the three observations:
- (1) better fit to the data, (2) robustness, or (3) numerical instability.
  - + O pts Blank

### 2.4 h 2/2

- $\checkmark$  + 2 pts Comment on numerical instability with high degree polynomials or poor fit with small data.
  - + O pts Blank

#### QUESTION 3

- 3 On Time / Late Penalty -1/0
  - + 0 pts Correct
  - 1 Point adjustment
    - Late submission, -1 point per day

This handout includes space for every question that requires a written response. Please feel free to use it to handwrite your solutions (legibly, please). If you choose to typeset your solutions, the README.md for this assignment includes instructions to regenerate this handout with your typeset LATEX solutions.

## 1.a

Lets start with the definition that integral of density function is equal to 1 over the entire space:

$$\int p(y;\eta)dy = 1$$

Applying same to exponential family distribution and trying to find out  $a(\eta)$ :

$$\int p(y;\eta)dy = \int b(y) \exp(\eta y - a(\eta))dy = 1$$
 i.e  $\int b(y) \exp(\eta y - a(\eta))dy = 1$ 

We can rewrite this as:

$$\exp(-a(\eta)) \int b(y) \exp(\eta y) dy = 1$$
$$\exp(a(\eta)) = \int b(y) \exp(\eta y) dy$$
$$a(\eta) = \log \int b(y) \exp(\eta y) dy$$

Lets take derivative of  $a(\eta)$  with respect to  $\eta$  and apply hint provided in 1.a

$$\frac{\partial a(\eta)}{\partial \eta} = \frac{\partial}{\partial(\eta)} \log \int b(y) \exp(\eta y) dy$$

$$= \frac{\int y b(y) \exp(\eta y) dy}{\int b(y) \exp(\eta y) dy}$$

As per pervious steps we can replace denominator with  $\exp a(\eta)$ 

$$= \frac{\int yb(y) \exp(\eta y)dy}{\exp a(\eta)}$$

$$= \int yb(y) \exp(\eta y - a(\eta))dy = E[Y; \eta]$$

This proves that the first derivate of  $a(\eta)$  w.r.t  $\eta$  is equivalent to the mean of exponentail family distribution

## 1.1 a 6 / 6

- √ + 3 pts \*\*Proof portion: \*\*Proof successfully arrives at \$\$E[Y;\eta] = \frac{\partial}{\partial} \eta} a(\eta)\$\$
  - + **1.5 pts** \*\*Proof portion:\*\* Proof attempts to arrive at \$\$E[Y;\eta] = \frac{\partial}{\partial} \eta} a(\eta)\$\$
- √ + 3 pts \*\*Math and Process:\*\* No broad assumptions or leaps in logic or mathematical errors
  - + 2 pts \*\*Math and Process: \*\*Minor assumptions and/or leaps in logic and/or mathematical errors
  - + 1 pts \*\*Math and Process: \*\*Major assumptions and/or leaps in logic and/or mathematical errors
  - + 0 pts No proof included

## 1.b

Lets startby computing second derivative of  $a(\eta)$  w.r.t  $\eta$  using defintion computed in previous answer 1.a

$$\frac{\partial^2 a(\eta)}{\partial \eta^2} = \frac{\partial}{\partial(\eta)} \int y b(y) \exp(\eta y - a(\eta)) dy$$

$$= \int y b(y) \exp(\eta y - a(\eta)) (y - a'(\eta)) dy$$

$$= \int p(y; \eta) y^2 dy - a'(\eta) \int p(y; \eta) y dy$$

$$= E[Y^2; \eta] - E[Y; \eta] E[Y; \eta]$$

$$= Var[Y; \eta]$$

This shows that the variance of an exponential family distribution is the second derivative of the log-partition function w.r.t. the natural parameter.

## 1.2 b 6 / 6

- $\sqrt{+3}$  pts \*\*Proof Portion:\*\* Proof correctly shows \$\$Var(Y; \eta) = \frac{\partial^2}{\partial \eta^2} a(\eta)\$\$
  - + 1.5 pts \*\*Proof Portion: \*\*Proof attempts to arrive at \$\$Var(Y; \eta) = \frac{\partial^2}{\partial \eta^2} a(\eta)\$\$
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  - + 1 pts \*\*Math and Process:\*\* Major assumptions and/or leaps in logic and/or mathematical errors
  - + 0 pts No proof included

## 1.c

Lets start with definition of negative log likelyhood  $NLL = -log(p(y; \eta))$ 

$$= -log(b(y) \exp(\eta y - a(\eta)))$$

$$= -(log(b(y)) + log(\exp(\eta y - a(\eta))))$$

This can be rewritten as

$$= -(log(b(y)) + (\eta y - a(\eta)))$$
  
$$= -(log(b(y)) + (\theta^T xy - a(\theta^T x)))$$

Now lets take hessian of the NLL wrt to  $\theta$  :

$$\begin{split} & \nabla_{\theta}^2(NLL) = \nabla_{\theta}^2(-(log(b(y)) + (\theta^Txy - a(\theta^Tx)))) \\ & = \nabla_{\theta}^2(-(\theta^Txy - a(\theta^Tx))) \end{split}$$

The second order derivative of  $-(\theta^T xy)$  w.r.t  $\theta$  is equal to 0, so:

$$= \nabla^2_{\boldsymbol{\theta}}(a(\boldsymbol{\theta}^T \boldsymbol{x}))$$

$$= Var(Y; \eta)$$

As variance of any probability distribution is non negative and therefore the Hessian of GLM's NLL loss is PSD, and hence convex.

#### 1.3 C 4 / 6

- √ + 2 pts \*\*Loss Function:\*\* Correct calculation for loss function \$\$I(\theta)\$\$
  - + 1 pts \*\*Loss Function:\*\* Attempts to calculate for loss function \$\$I(\theta)\$\$
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  - + 2 pts \*\*Hessian: \*\* Correct calculation of Hessian to show its PSD \$\$\nabla\_\theta^2 | (\theta)\$\$
  - + **0 pts** Proof not included
- √ + 1 pts \*\*Hessian:\*\* Attempts to calculate Hessian to show its PSD \$\$\nabla\_\theta^2 I (\theta)\$\$
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  - + 1 pts Some intermediate steps and attempt at PSD. Please check solutions.
  - **1 pts** Some mathematical errors.

2.a

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} (h_{\theta}(\hat{x}^{(i)} - y^{(i)})^{2}.$$

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Differentiating this objective, we get:

$$\nabla_{\theta} J(\theta) = \frac{\partial}{\partial \theta_j} \frac{1}{2} (h_{\theta}(\hat{x}) - y)^2 = (h_{\theta}(\hat{x}) - y) x_j$$

The gradient descent update rule is

$$\theta := \theta - \lambda \nabla_{\theta} J(\theta)$$

which reduces here to:  $\theta := \theta - \lambda (h_{\theta}(\hat{x}) - y) x_j$  Rearranging terms and in general for i  $\theta := \theta + \lambda (y^{(i)} - h_{\theta}(\hat{x}^{(i)})) \hat{x}_j^{(i)}$ 

#### 2.1 a 5 / 5

- √ + 1.5 pts \*\*Objective Function:\*\* Correct value for \$\$J(\theta)\$\$
  - + 0.5 pts \*\*Object Function:\*\* Attempt to derive correct value for \$\$J(\theta)\$\$
- √ + 2 pts \*\*Gradient: \*\* Correct differentiation of \$\$\nabla\_\theta J(\theta)\$\$
  - + 1 pts \*\*Gradient:\*\* Attempt to differentiate \$\$\nabla\_\theta J(\theta)\$\$
- $\checkmark$  + 1.5 pts \*\*Update Rule:\*\* Correct reduction the gradient descent update rule \$\$\theta := \theta \alpha \nabla\_\theta J(\theta)\$\$
- + **0.5 pts** \*\*Update Rule:\*\* Attempt to reduce gradient descent update rule \$\$\theta := \theta \alpha \nabla\_\theta J(\theta)\$\$
  - **0.5 pts** There should be no phi(x) notion, h\_theta(x) means that.
  - + **0.5 pts** Attempt to create update rule. You should be using gradient, not Hessian.
  - + 0 pts Not done

# 2.d

For k=1 (or 2) the fit is almost a straight line

For k=3 the fit starts to show the sin wave pattern

For k=5,10 the fit is more natural to data points and is closer also

For k=20 the curve passes through most of the points and also start showing signs of overfitting as we can see some curvatures beyond the given point.

So as k increases fit is passing through more and more points and tends to overfitting.

## 2.2 d 1/1

- $\sqrt{+1}$  pts Commentary that a higher degree polynomial fits the data better.
  - + 0 pts Blank
  - **0.25 pts** Incorrect statement (e.g. not significantly differentiating k=20 with lower order fits)

# 2.f

Compared to 2.c we can see the fitted model taking a sin wave pattern. This is even true for low values of k like 1 or 2. The reason for this is that the training data is also created using sin function. After adding a  $\sin(x)$  to the polynomial regression even for low value of x we get good fit as compared to 2.c

# 2.3 f 1/1

 $\checkmark$  + 1 pts Comment on two of the three observations: (1) better fit to the data, (2) robustness, or (3) numerical instability.

+ O pts Blank

# 2.h

As the training dataset is small the fitting of the training dataset changes with K as follows:

For polynomial regression,

For lower values of K (= 1 or 2) the fit is not going over any data point

For K (=3,5) fit is closer to training data point or passes through some of the training data points and is more natural

But as K increases(10,20) we can see overfitting i.e the long curves in sin wave

For polynomial and sinusoidal features,

Fitting of the data is more natural even with lower values of K like 1,2,3,5

But as K increases we can see overfitting

## 2.4 h 2 / 2

 $\checkmark$  + 2 pts Comment on numerical instability with high degree polynomials or poor fit with small data.

+ 0 pts Blank

# 3 On Time / Late Penalty -1/0

- + 0 pts Correct
- 1 Point adjustment
  - Late submission, -1 point per day