

This handout includes space for every question that requires a written response. Please feel free to use it to handwrite your solutions (legibly, please). If you choose to typeset your solutions, the `README.md` for this assignment includes instructions to regenerate this handout with your typeset \LaTeX solutions.

1.a

Lets start with the definition that integral of density function is equal to 1 over the entire space:

$$\int p(y; \eta) dy = 1$$

Applying same to exponential family distribution and trying to find out $a(\eta)$:

$$\int p(y; \eta) dy = \int b(y) \exp(\eta y - a(\eta)) dy = 1 \text{ i.e}$$

$$\int b(y) \exp(\eta y - a(\eta)) dy = 1$$

We can rewrite this as:

$$\exp(-a(\eta)) \int b(y) \exp(\eta y) dy = 1$$

$$\exp(a(\eta)) = \int b(y) \exp(\eta y) dy$$

$$a(\eta) = \log \int b(y) \exp(\eta y) dy$$

Lets take derivative of $a(\eta)$ with respect to η and apply hint provided in

1.a

$$\frac{\partial a(\eta)}{\partial \eta} = \frac{\partial}{\partial (\eta)} \log \int b(y) \exp(\eta y) dy$$

$$= \frac{\int y b(y) \exp(\eta y) dy}{\int b(y) \exp(\eta y) dy}$$

As per pervious steps we can replace denominator with $\exp a(\eta)$

$$= \frac{\int y b(y) \exp(\eta y) dy}{\exp a(\eta)}$$

$$= \int y b(y) \exp(\eta y - a(\eta)) dy = E[Y; \eta]$$

This proves that the first derivate of $a(\eta)$ w.r.t η is equivalent to the mean of exponentail family distribution

1.b

Lets startby computing second derivative of $a(\eta)$ w.r.t η using defintion computed in previous answer 1.a

$$\frac{\partial^2 a(\eta)}{\partial \eta^2} = \frac{\partial}{\partial (\eta)} \int y b(y) \exp(\eta y - a(\eta)) dy$$

$$= \int y b(y) \exp(\eta y - a(\eta)) (y - a'(\eta)) dy$$

$$= \int p(y; \eta) y^2 dy - a'(\eta) \int p(y; \eta) y dy$$

$$= E[Y^2; \eta] - E[Y; \eta] E[Y; \eta]$$

$$= Var[Y; \eta]$$

This shows that the variance of an exponential family distribution is the second derivative of the log-partition function w.r.t. the natural parameter.

1.c

$$\begin{aligned}
& \text{Let's start with definition of negative log likelihood } NLL = -\log(p(y; \eta)) \\
& = -\log(b(y) \exp(\eta y - a(\eta))) \\
& = -(\log(b(y)) + \log(\exp(\eta y - a(\eta))))
\end{aligned}$$

This can be rewritten as

$$\begin{aligned}
& = -(\log(b(y)) + (\eta y - a(\eta))) \\
& = -(\log(b(y)) + (\theta^T x y - a(\theta^T x)))
\end{aligned}$$

Now let's take hessian of the NLL wrt to θ :

$$\begin{aligned}
\nabla_{\theta}^2(NLL) & = \nabla_{\theta}^2(-(\log(b(y)) + (\theta^T x y - a(\theta^T x)))) \\
& = \nabla_{\theta}^2(-(\theta^T x y - a(\theta^T x)))
\end{aligned}$$

The second order derivative of $-(\theta^T x y)$ w.r.t θ is equal to 0, so:

$$\begin{aligned}
& = \nabla_{\theta}^2(a(\theta^T x)) \\
& = \text{Var}(Y; \eta)
\end{aligned}$$

As variance of any probability distribution is non negative and therefore the Hessian of GLM's NLL loss is PSD, and hence convex.

2.a

$$J(\theta) = \frac{1}{2} \sum_{i=1}^n (h_{\theta}(\hat{x}^{(i)}) - y^{(i)})^2.$$

Differentiating this objective, we get:

$$\begin{aligned} \nabla_{\theta} J(\theta) &= \\ \frac{\partial}{\partial \theta_j} \frac{1}{2} (h_{\theta}(\hat{x}) - y)^2 &= \\ (h_{\theta}(\hat{x}) - y) x_j \end{aligned}$$

The gradient descent update rule is

$$\theta := \theta - \lambda \nabla_{\theta} J(\theta)$$

which reduces here to:

$$\theta := \theta - \lambda (h_{\theta}(\hat{x}) - y) x_j$$

Rearranging terms and in general for i

$$\theta := \theta + \lambda (y^{(i)} - h_{\theta}(\hat{x}^{(i)})) \hat{x}_j^{(i)}$$

2.d

For $k=1$ (or 2) the fit is almost a straight line

For $k=3$ the fit starts to show the sin wave pattern

For $k=5,10$ the fit is more natural to data points and is closer also

For $k=20$ the curve passes through most of the points and also start showing signs of overfitting as we can see some curvatures beyond the given point.

So as k increases fit is passing through more and more points and tends to overfitting.

2.f

Compared to 2.c we can see the fitted model taking a sin wave pattern.

This is even true for low values of k like 1 or 2.

The reason for this is that the training data is also created using sin function.

After adding a $\sin(x)$ to the polynomial regression even for low value of x we get good fit as compared to 2.c

2.h

As the training dataset is small the fitting of the training dataset changes with K as follows:

For polynomial regression,

For lower values of K ($= 1$ or 2) the fit is not going over any data point

For K ($= 3, 5$) fit is closer to training data point or passes through some of the training data points and is more natural

But as K increases ($10, 20$) we can see overfitting i.e the long curves in sin wave

For polynomial and sinusoidal features,

Fitting of the data is more natural even with lower values of K like $1, 2, 3, 5$

But as K increases we can see overfitting