

3.1)

$$\text{a) } A_{ij} = P(X_{T+1} = j \mid X_T = i)$$

$$P(X_{T+1} \mid X_i) = \sum_{m_T}^m P(X_{T+1}, X_T = m_T \mid X_i) \quad \text{marg.}$$

$$= \underbrace{\sum_{m_2} \sum_{m_3} \dots \sum_{m_{T-1}}}_{T-1} P(X_{T+1}, X_T, \dots, X_2 \mid X_1)$$

$$= \underbrace{\sum_{m_2} \sum_{m_3} \dots \sum_{m_{T-1}}}_{T-1} P(X_{T+1} \mid X_T, X_{T-1}, \dots, X_1) \cdot$$

$$P(X_T \mid X_{T-1}, X_{T-2}, \dots, X_1).$$

⋮

$$P(X_2 \mid X_1)$$

$$= \underbrace{\sum_{m_2} \sum_{m_3} \dots \sum_{m_{T-1}}}_{T-1} P(X_{T+1} \mid X_T) P(X_T \mid X_{T-1}) \dots P(X_2 \mid X_1)$$

$$= \underbrace{\sum_{m_2} \sum_{m_3} \dots \sum_{m_{T-1}}}_{T-1} A_{i, m_T} A_{m_T, m_{T-1}} \dots A_{m_2, j} \quad \text{(i)}$$

For matrix multiplication:-

$$C_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

for 2 matrices.

If they're the same matrices

$$\Rightarrow b_{ij} = \sum_{k=1}^n a_{ik} a_{kj} \quad [B = A^2]$$

Similarly, for 3 matrices

$$B_{ij} = \sum_{k_1}^n \sum_{k_2}^n \alpha_{ik_1} \alpha_{k_1 k_2} \alpha_{k_2 j} \quad [B = A^3]$$

Thus, can be generalized for  $m$  matrices:-

$$B_{ij} = \sum_{k_1}^n \sum_{k_2}^n \dots \sum_{k_{m-1}}^n \alpha_{ik_1} \alpha_{k_1 k_2} \dots \alpha_{k_{m-1} j} \quad [B = A^m]$$

Thus, ...  $ij$  equates to

$$\sum_{m_2} \sum_{m_3} \dots \sum_{m_T} A_{ijm_T} A_{m_T m_{T-1}} \dots A_{m_2 j} = [A_{ij}^t]$$

$$\Rightarrow \boxed{P(X_{t+1} = j | X_t = i) = [A_{ij}^t]}$$

Using induction:-

• Base case :-  $t=1$

$$P(X_{t+1}=j | X_t=i) = [A^t]_{ij}$$

$$\Rightarrow P(X_2=j | X_1=i) = A_{ij}$$

which is true, since we're given

$$P(X_{t+1}=j | X_t=i) = A_{ij}$$

• Assuming, the statement is true for ' $t-1$ '

$$\Rightarrow P(X_t=j | X_1=i) = [A^{t-1}]_{ij}$$

$\Rightarrow$  For ' $t$ ' we have :-

$$\begin{aligned} P(X_{t+1}=j | X_t=i) &= \sum_k^m P(X_{t+1}=j, X_t=k | X_1=i) \\ &= \sum_k^m P(X_{t+1}=j | X_t=k, X_1=i) P(X_t=k | X_1=i) \\ &= \sum_k P(X_{t+1}=j | X_t=k) P(X_t=k | X_1=i) \end{aligned}$$

d-separation case 1

$$= \sum_k A_{ik} A_{kj}$$

$$\boxed{P(X_{t+1}=j | X_t=i) = [A^t]_{ij}}$$

$$b) P(X_2 | X_1) = A_{ij}$$

$$P(X_3 | X_1) = \sum_m A_{im} A_{mj}$$

For calculating  $[A^2]_{ij}$ , we will require  $m$  iterations.

But, to calculate  $[A^2]_{j,m}$  for  $m \in \{1, \dots, n\}$

we will repeat this process ' $m$ ' times

2) Asymptotic complexity =  $\Theta(m^2)$

$$P(X_4 | X_1) = \sum_m [A^2]_{im} A_{mj} \quad O(m^2)$$

$$P(X_{T+1} | X_t) = \sum_m [A^{t-1}]_{im} A_{mj}$$

$\Rightarrow$  Total asymptotic complexity =  $O(m^2t)$

C)

Since,

$$P(X_{t+1} = j | X_t = i) = [A^*]_{ij}$$

Now, similar to the concept of binary numbers, we can represent any number  $t$  as a sum of  $2^i$ .

e.g.

$$4 = 100 = 1 \times 2^2 + 0 \times 2^1 + 0 \times 2^0$$

thus, in general if  $t_{10}$  &  $t_2$  represent decimal and binary representation of  $t$ ,

$$\Rightarrow t_{10} = \sum_{i=0}^{\log_2 t_{10}} t_2[i] \cdot 2^i$$

$$\Rightarrow t_{10} = \sum_{i=0}^{\log_2 t_{10}} [t_2]_i \cdot 2^i$$

where,  $[t_2]_i$  represents  $i^{\text{th}}$  least significant bit.

$\Rightarrow$  We can split the matrix multiplication  $A^t$  into  $\log_2 t$  parts :-

$$A^{t_{10}} = \prod_{i=0}^{\log_2 t_{10}} [t_2]_i \cdot A^i$$

$\Rightarrow$  Since complexity of matrix multiplication is  $O(m^3)$

$\Rightarrow$  Total asymptotic complexity =  $O(m^3 \log_2 t)$

$$\begin{aligned}
 \textcircled{a}) \quad P(X_t=j | X_1=i) &= \sum_k P(X_t=j, X_{t+1}=k | X_1=i) \\
 &\stackrel{\text{(marg)}}{=} \sum_k P(X_{t+1}=k | X_t=j) P(X_t=j | X_1=i) \\
 &\stackrel{\text{(P.R.)}}{=} \sum_k A_{jk} [A^{t-1}]_{ij} \quad (\text{From (a)})
 \end{aligned}$$

- $\Rightarrow$  Each element in the row of  $A$  needs to be multiplied by each column of  $A^{t-1}$ ; but since  $s \ll m$
- $\Rightarrow$  Only  $s$  rows will strictly be used.
- $\Rightarrow$  ~~Asympt~~
- $\Rightarrow$  Complexity of this step will be  $O(sm)$ 
  - $\because$  this is repeated  $t-1$  times
  - $\Rightarrow$  asymptotic complexity of the calculation is  $O(smt)$

$$\textcircled{c}) P(X_t = i | X_{t+1} = j) =$$

$$\frac{P(X_{t+1} = j | X_t = i) P(X_t = i)}{P(X_{t+1} = j)}$$

(Bayes)

$$\Rightarrow \frac{P(X_{t+1} = j | X_t = i) P(X_t = i)}{\sum_{k_1} \dots \sum_{k_t} P(X_{t+1}, X_t, \dots, X_1)}$$

$$\Rightarrow \frac{[A^t]_{ij} P(X_t = i)}{\sum_{k_1} \dots \sum_{k_t} P(X_{t+1} | X_t) P(X_t | X_{t-1}) \dots P(X_2 | X_1) P(X_1)}$$

$$\Rightarrow \frac{[A^t]_{ij} P(X_t = i)}{\sum_{k_1} [A^t]_{k,j} P(X_t = k)}$$

$$\Rightarrow \boxed{P(X_t = i | X_{t+1} = j) = \frac{[A^t]_{ij} P(X_t = i)}{\sum_k [A^t]_{kj} P(X_t = k)}}$$

3.2

$$a) P(Y_1 = y_1 | X_1 = x_1)$$

$$= \sum_{x_2} P(Y_1, X_2 = x_2 | X_1)$$

marg.

$$= \sum_{x_2} P(Y_1 | X_1, X_2 = x_2) P(X_2 = x_2 | X_1)$$

[P.R.]

$$= \sum_{x_2} P(Y_1 | X_1, X_2 = x_2) P(X_2 = x_2)$$

marginal  
independence

$$b) P(Y_1) = \sum_{x_1} \sum_{x_2} P(Y_1, X_1 = x_1, X_2 = x_2)$$

[marg]

$$= \sum_{x_1} \sum_{x_2} P(Y_1 | X_1 = x_1, X_2 = x_2) P(X_2 = x_2 | X_1 = x_1)$$

$$\times P(X_1 = x_1)$$

[P.R.]

$$= \sum_{x_1} \sum_{x_2} P(Y_1 | x_1, x_2) P(x_2) P(x_1)$$

marginal  
independence

$$c) P(X_n | Y_1, Y_2, \dots, Y_{n-1})$$

Given the evidence set  $E = \emptyset$  and using  $Y_n$  as the sink node for rule-3 of d-separation

$$P(X_n | Y_1, Y_2, \dots, Y_{n-1}) = P(X_n)$$

$$d) P(Y_n | X_n, Y_1, Y_2, \dots, Y_{n-1})$$

$$\Rightarrow \sum_{X_{n-1}} P(Y_n, X_{n-1} | X_n, Y_1, Y_2, \dots, Y_{n-1})$$

$$\Rightarrow \sum_{X_{n-1}} P(Y_n | X_n, X_{n-1}, Y_1, Y_2, \dots, Y_{n-1})$$

$$P(X_{n-1} | Y_1, Y_2, \dots, Y_{n-1}, X_n)$$

$$P(X_{n-1} | X_n \perp\!\!\!\perp Y_1, Y_2, \dots, Y_{n-1})$$

$$P(X_{n-1} | X_n, Y_1, Y_2, \dots, Y_{n-1})$$

$$= P(X_{n-1} | Y_1, Y_2, \dots, Y_{n-1})$$

rule-3  
d-separation

$$P(Y_n | X_n, X_{n-1}, Y_1, Y_2, \dots, Y_{n-1})$$

$$= P(Y_n | X_n, X_{n-1}, Y_1, Y_2, \dots, Y_{n-1})$$

rule - 2  
d-separation

$$\Rightarrow \sum_{Y_{n-1}} P(Y_n | X_n, X_{n-1}, Y_1, \dots Y_{n-1}) P(X_{n-1} | Y_1, \dots Y_{n-1}, X_n)$$

$$= \left[ \sum_{Y_{n-1}} P(Y_n | X_n, X_{n-1}) P(X_{n-1} | Y_1, \dots Y_{n-1}) \right]$$

e)  $P(Y_n | Y_1, \dots Y_{n-1})$

$$= \sum_{X_{n-1}} P(Y_n, X_{n-1} | Y_1, \dots Y_{n-1}) \quad \boxed{\text{marg}}$$

$$= \sum_{X_{n-1}} P(Y_n | X_{n-1}, Y_1, \dots Y_{n-1}) P(X_{n-1} | Y_1, \dots Y_{n-1}) \quad \boxed{\text{P.R}}$$

$$= \sum_{X_{n-1}} P(Y_n | X_{n-1}) P(X_{n-1} | Y_1, \dots Y_{n-1})$$

$$= \sum_{X_{n-1}} \sum_{X_n} P(Y_n, X_n | X_{n-1}) P(X_{n-1} | Y_1, \dots Y_{n-1})$$

$$= \sum_{X_{n-1}} \sum_{X_n} P(Y_n | X_{n-1}, X_n) P(X_n | X_{n-1}).$$

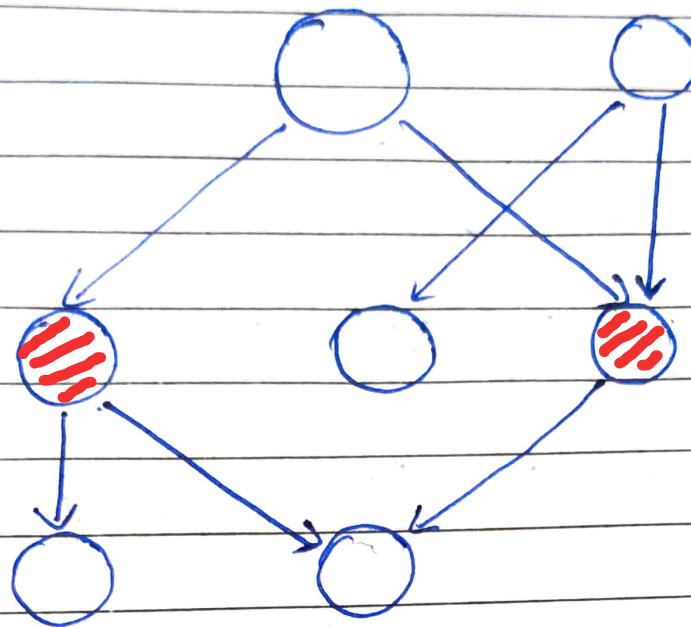
$$P(X_{n-1} | Y_1, \dots Y_{n-1})$$

$$= \sum_{X_{n-1}} \sum_{X_n} P(Y_n | X_{n-1}, X_n) P(X_n) P(X_{n-1} | Y_1, \dots Y_{n-1})$$

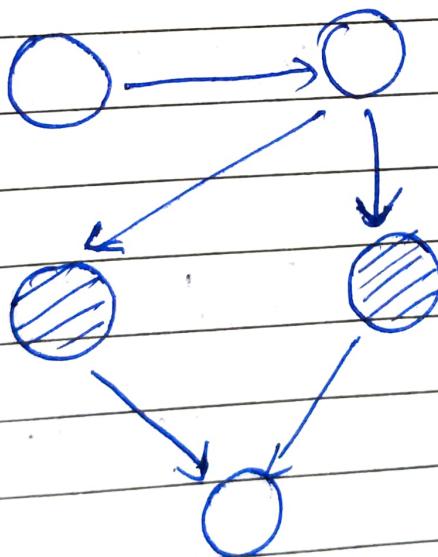
3.3

a) Polytree

b)



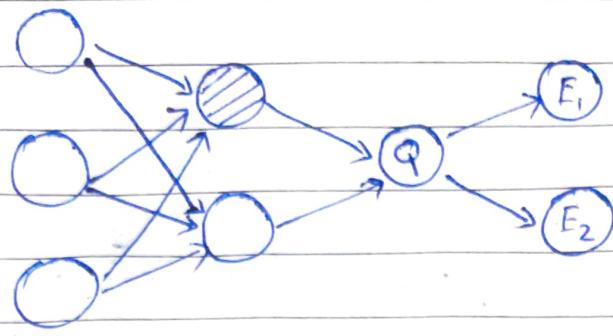
c)



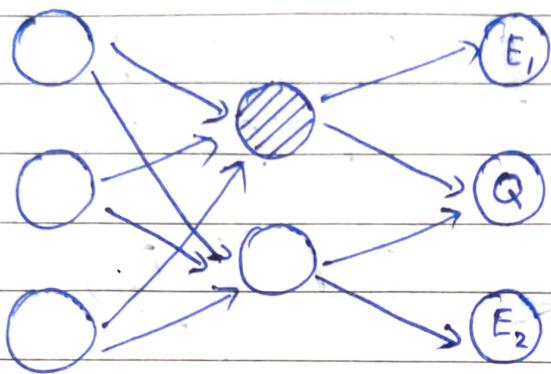
d) Polytree

e) Polytree

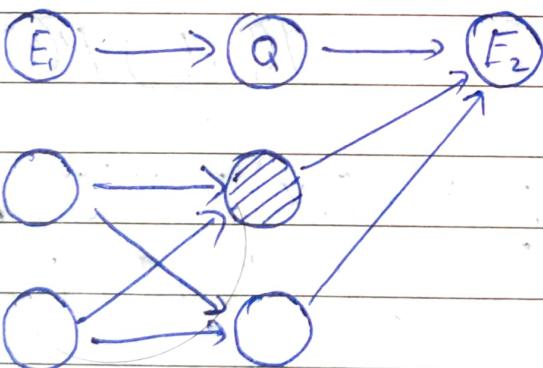
3.4



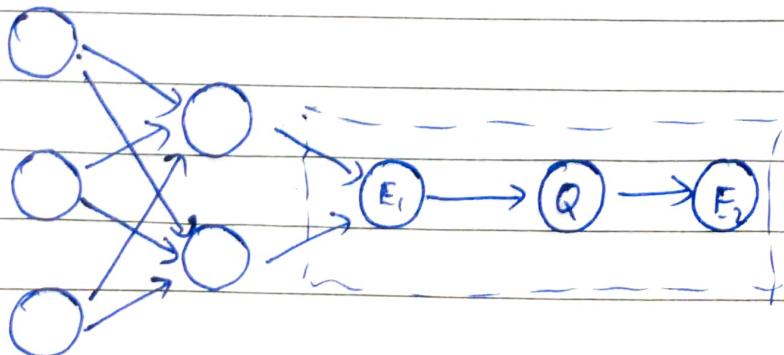
Q's parents  
belong to  
loopy network



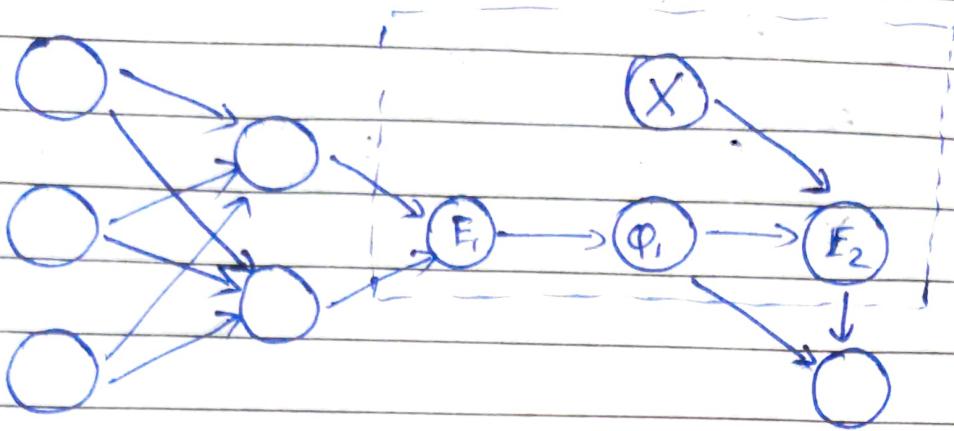
Q's parents  
belong to loopy  
network.



Q's siblings belong  
in a loopy network



E<sub>1</sub> & E<sub>2</sub>  
are Q's  
markov  
blanket.



$$\begin{aligned}
 P(\Phi | E_1, E_2) &= \frac{P(E_2 | \Phi, E_1) P(\Phi | E_1)}{P(E_2 | E_1)} \\
 &= \frac{P(E_2 | \Phi) P(\Phi | E_1)}{\sum_{\alpha} P(E_2, \alpha | E_1) P(\alpha | E_1)} \\
 &= \frac{\sum_x P(E_2, x | \Phi) P(\Phi | E_1)}{\sum_{\alpha} P(E_2 | \Phi, E_1) P(\Phi | E_1)} \\
 &= \frac{\sum_n P(E_2 | \Phi, x) P(x | \Phi) P(\Phi | E_1)}{\sum_{\alpha} P(E_2 | \Phi) P(\Phi | E_1)} \\
 &= \frac{\sum_n P(E_2 | \Phi, x) P(x) P(\Phi | E_1)}{\sum_{\alpha} \sum_n P(E_2 | \Phi, x) P(x) P(\Phi | E_1)}
 \end{aligned}$$

Thus, we can calculate the probability without using children of  $\Phi$ , &  $E_2$

3.5

<u>Y</u>	<u><math>P(Y X=0)</math></u>	<u><math>P(Y X=1)</math></u>
1	0.09375	0.09375
2	0.28125	0.09375
3	0.09375	0.03125
4	0.03125	0.28125
5	0.28125	0.03125
6	0.09375	0.28125
7	0.03125	0.09375
8	0.09375	0.09375

$$P(Y|X) = P(Y_1|X)P(Y_2|X)P(Y_3|X)$$

<u>Y</u>	<u><math>P(Z_1=1 Y)</math></u>	<u><math>P(Z_2=1 Y)</math></u>
1	0.9	0.1
2	0.8	0.2
3	0.7	0.3
4	0.6	0.4
5	0.5	0.5
6	0.4	0.6
7	0.3	0.7
8	0.2	0.8

$$P(Z|Y) = P(Z|Y_1, Y_2, Y_3)$$

$$\frac{3.6}{a)} P(Z|B_1, B_2, B_3, \dots, B_n) = \left(\frac{1-\alpha}{1+\alpha}\right) \alpha^{|z-f(B)|}$$

$$\sum_z P(z|B_1, \dots, B_n) = \sum_z \left(\frac{1-\alpha}{1+\alpha}\right) \alpha^{|z-f(B)|}$$

$\forall z \in [-\infty, \infty]$

$$\Rightarrow \left(\frac{1-\alpha}{1+\alpha}\right) \sum_z \alpha^{|z-f(B)|}$$

$$\text{let } K = |z-f(B)| \Rightarrow K=0 \text{ for } z=f(B)$$

$$\Rightarrow \left(\frac{1-\alpha}{1+\alpha}\right) \left(1 + 2 \sum_k \alpha^k\right) \quad \forall k \in [1, \infty]$$

$$\because 0 < \alpha < 1$$

The sum of the geometric series is:

$$\sum_k \alpha^k = \frac{\alpha}{1-\alpha}$$

$$\Rightarrow \left(\frac{1-\alpha}{1+\alpha}\right) \left(1 + \frac{2 \times \alpha}{1-\alpha}\right) = \left(\frac{1-\alpha}{1+\alpha}\right) \left(\frac{1+\alpha}{1-\alpha}\right) = 1$$

$$\Rightarrow \boxed{\sum_z P(z|B_1, \dots, B_n) = 1}$$

## 3.6

In [2]:

```
import random
import matplotlib.pyplot as plt
```

In [3]:

```
def P_B_i():
    num = random.random()
    if num < 0.5:
        return 0
    else:
        return 1
```

In [4]:

```
def f_B(B, n):
    num = 0
    for i in range(n):
        num = num + (B[i] * pow(2, i))
    return num
```

In [5]:

```
def P_Z_B(Z, B, n, alpha):
    result1 = pow(alpha, abs(Z - f_B(B, n)))
    const = ((1 - alpha)/(1 + alpha))
    result = const * result1
    return result
```

In [6]:

```
def indicator(x, x_):
    if x == x_:
        return 1
    return 0
```

In [1]:

```
def likelihood_estimation(targetBit, iterations):
    numerator = 0
    denominator = 0
    estimate = []
    for i in range(iterations):
        for bit in range(n):
            B[bit] = P_B_i()

        likelihood_weight = P_Z_B(Z, B, n, alpha)
        numerator = numerator + (indicator(B[targetBit], 1) * likelihood_weight)
        denominator = denominator + likelihood_weight
        estimate.append(numerator/denominator)

    return estimate
```

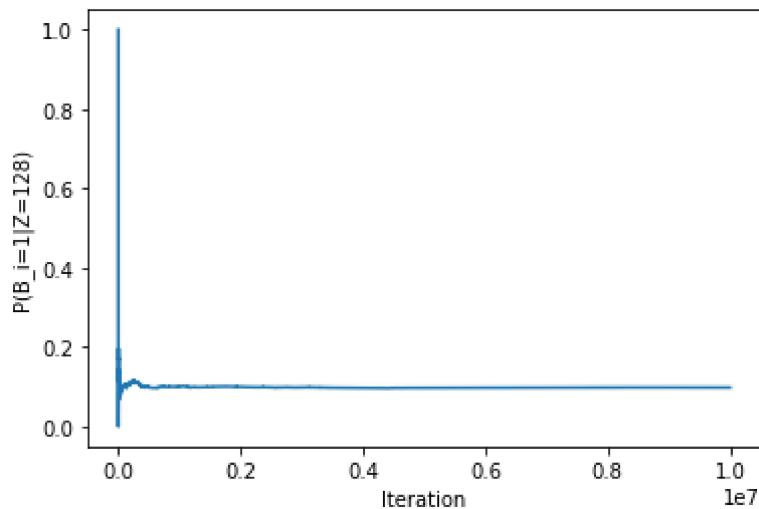
In [23]:

```
n = 10
B = [0 for i in range(n)]
Z = 128
alpha = 0.1
iterations = 10000000
```

i = 2

In [33]:

```
estimates = likelihood_estimation(1, iterations)
plt.plot(estimates)
plt.ylabel('P(B_{i=1}|Z=128)'.format(2))
plt.xlabel('Iteration')
plt.show()
```



In [ ]:

In [34]:

```
estimates[-1]
```

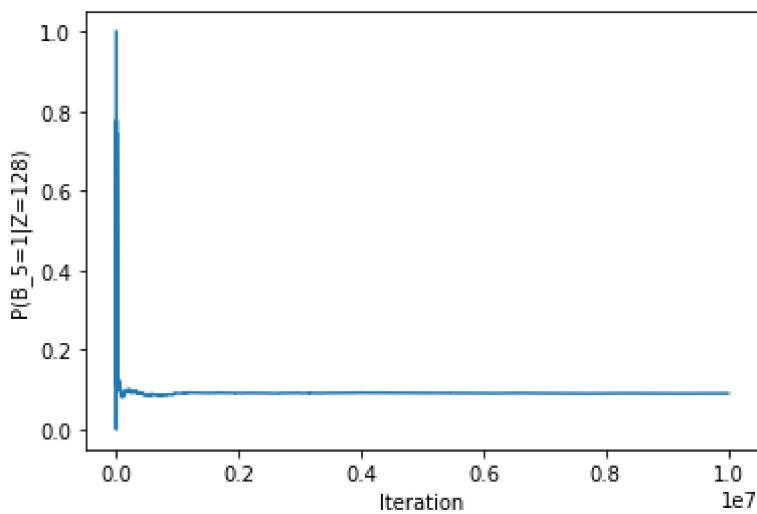
Out[34]:

0.09816876389177609

i = 5

In [40]:

```
estimates = likelihood_estimation(4, iterations)
plt.plot(estimates)
plt.ylabel('P(B_{}=1|Z=128)'.format(5))
plt.xlabel('Iteration')
plt.show()
```



In [41]:

```
estimates[-1]
```

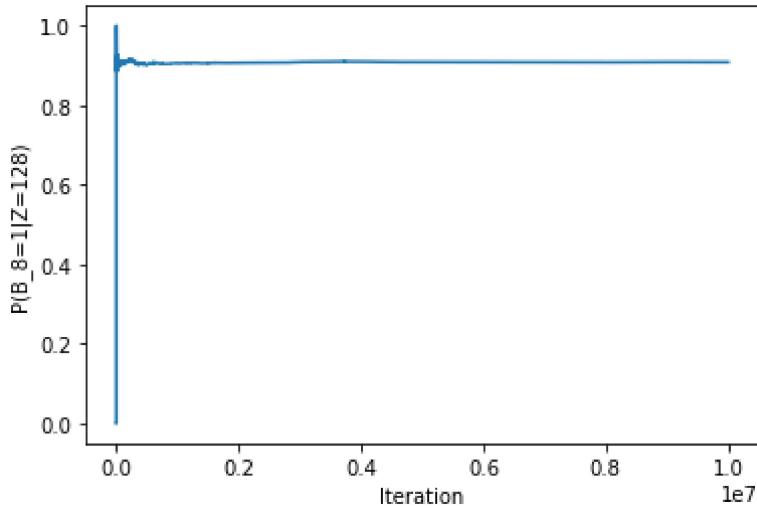
Out[41]:

0.09019225688900386

i = 8

In [43]:

```
estimates = likelihood_estimation(7, iterations)
plt.plot(estimates)
plt.ylabel('P(B_{}=1|Z=128)'.format(8))
plt.xlabel('Iteration')
plt.show()
```



In [44]:

```
estimates[-1]
```

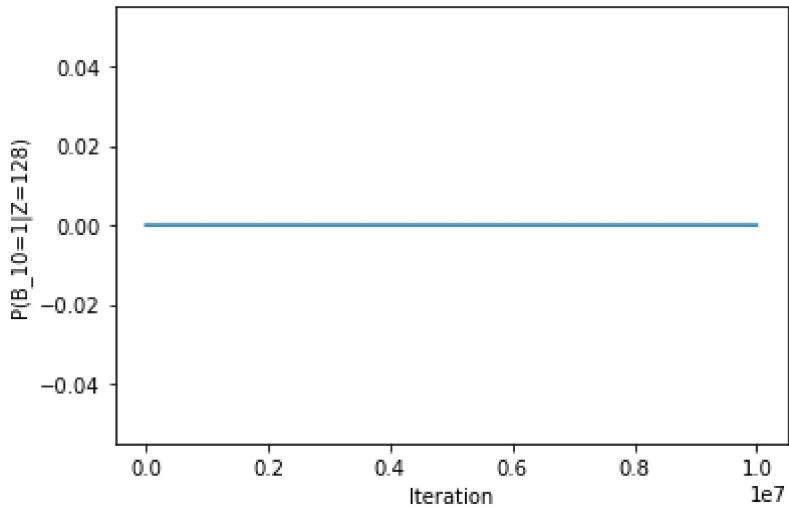
Out[44]:

0.9082078987581559

**i = 10**

In [50]:

```
estimates = likelihood_estimation(9, iterations)
plt.plot(estimates)
plt.ylabel('P(B_{10}=1|Z=128)'.format(10))
plt.xlabel('Iteration')
plt.show()
```



In [51]:

```
estimates[-1]
```

Out[51]:

0.0

3.7

$$\text{a) } P(B|A, C, D)$$

$$= \frac{P(D|A, B, C) P(B|A, C)}{P(D|A, C)}$$

Bayes rule

We know everything with respect to  $D$  instead of  $B$ , thus we use bayes rule to infer  $P(D|Pa(D))$  instead

$$= \frac{P(D|B, C) P(B|A)}{P(D|A, C)}$$

rule-1 & rule 3  
of D-separation

$$= \frac{P(D|B, C) P(B|A)}{\sum_b P(D, B|A, C)}$$

marginalization

Since we want to introduce independence between  $D$  &  $A$  using  $B$

$$= \frac{P(D|B, C) P(B|A)}{\sum_b P(D|A, B, C) P(B|A, C)}$$

Product Rule

$$= \frac{P(D|B, C) P(B|A)}{\sum_b P(D|B, C) P(B|A)}$$

rule-1 & rule-3  
of d-separation

$$\begin{aligned}
 b) \quad & P(B | A, C, D, E, F) \\
 = & P(B | A, C, D, E) \quad \text{rule-2} \\
 = & P(B | A, C, D) \quad \begin{array}{l} \text{d-separation} \\ \text{rule-3 of} \\ \text{d-separation.} \end{array}
 \end{aligned}$$

This is the same calculation that we did in part (a)

$$\Rightarrow P(B | A, C, D, E, F) = \frac{P(D | B, C) P(B | A)}{\sum_{\bar{D}} P(\bar{D} | B, C) P(\bar{B} | A)}$$

$$c) \quad P(B, E, F | A, C, D)$$

$$= P(B | A, C, D, E, F) P(E | A, C, D, F) P(F | A, C, D)$$

P.R

$$= P(B | A, C, D) P(E | A, C, D, F) P(F | A, C, D)$$

From (b)

$$= P(B | A, C, D) P(E | C) P(F | A)$$

rule-2 of d-separation.

$$\Rightarrow P(B, E, F | A, C, D) = P(B | A, C, D) P(E | C) P(F | A)$$

3.8

$$a) P(\Phi = q_1 | E = e) \approx \frac{\sum_{i=1}^T I(q_1, q_{1,i}) P(E_i = e_i | Y = y_i, Z = z_i)}{\sum_{i=1}^T P(E_i = e_i | Y = y_i, Z = z_i)}$$

$$b) P(\Phi_1 = q_1, \Phi_2 = q_2 | E_1 = e_1, E_2 = e_2)$$

$$\approx \frac{\sum_{i=1}^T I(q_1, a_{1,i}) I(q_2, a_{2,i}) P(E_1 = e_1 | \Phi_1 = q_{1,i}, X = x_i) \times P(E_2 = e_2 | E_1 = e_1, Z = z_i)}{\sum_{i=1}^T P(E_1 = e_1 | \Phi_1 = q_{1,i}, X = x_i) P(E_2 = e_2 | E_1 = e_1, Z = z_i)}$$