

Exam III

Name: _____

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There are four equally weighted partial credit questions. Please show all your work for full credit; displaying only the final answer will earn you very little, if anything.

Very important: throughout this exam, wherever they appear, $\alpha =$ $\beta =$ $\gamma =$

1. Consider the linear system

$$\begin{cases} -x_1 + 4x_2 + 2x_3 = 3\alpha - 5\beta + 2\gamma \\ 2x_1 + x_2 + 5x_3 = 3\alpha + \beta + 5\gamma \\ 3x_1 - x_2 + x_3 = 2\alpha + 4\beta + \gamma \end{cases}$$

(a) Solve the system using Gaussian elimination.

Augmented Matrix

$$\left[\begin{array}{ccc|c} -1 & 4 & 2 & 3\alpha - 5\beta + 2\gamma \\ 2 & 1 & 5 & 3\alpha + \beta + 5\gamma \\ 3 & -1 & 1 & 2\alpha + 4\beta + \gamma \end{array} \right] \begin{array}{l} R_2^{\text{new}} = R_2^{\text{old}} + 2R_1 \\ R_3^{\text{new}} = R_3^{\text{old}} + 3R_1 \end{array}$$

$$\left[\begin{array}{ccc|c} -1 & 4 & 2 & 3\alpha - 5\beta + 2\gamma \\ 0 & 9 & 9 & 9\alpha - 9\beta + 9\gamma \\ 0 & 11 & 7 & 11\alpha - 11\beta + 7\gamma \end{array} \right] \begin{array}{l} R_2^{\text{new}} = R_2^{\text{old}} \div 9 \\ R_3^{\text{new}} = R_3^{\text{old}} - 11R_2 \end{array}$$

$$\left[\begin{array}{ccc|c} -1 & 4 & 2 & 3\alpha - 5\beta + 2\gamma \\ 0 & 1 & 1 & \alpha - \beta + \gamma \\ 0 & 11 & 7 & 11\alpha - 11\beta + 7\gamma \end{array} \right] \begin{array}{l} R_3^{\text{new}} = R_3^{\text{old}} - 11R_2 \end{array}$$

$$\left[\begin{array}{ccc|c} -1 & 4 & 2 & 3\alpha - 5\beta + 2\gamma \\ 0 & 1 & 1 & \alpha - \beta + \gamma \\ 0 & 0 & -4 & -4\gamma \end{array} \right] \Rightarrow \begin{cases} -x_1 + 4x_2 + 2x_3 = 3\alpha - 5\beta + 2\gamma \\ x_2 + x_3 = \alpha - \beta + \gamma \\ -4x_3 = -4\gamma \end{cases}$$

Back substitution \Rightarrow

Answer : $x_1 = \alpha + \beta$, $x_2 = \alpha - \beta$, $x_3 = \gamma$ 3pts

(b) Write out the **individual components** of Jacobi iteration equations for solving the system. Then, starting

with the initial vector $x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, perform two iterations (i.e., find $x^{(2)}$).

$$\begin{cases} x_1^{(k+1)} = -3\alpha + 5\beta - 2\gamma + 4x_2^{(k)} + 2x_3^{(k)} \\ x_2^{(k+1)} = 3\alpha + \beta + 5\gamma - 2x_1^{(k)} - 5x_3^{(k)} \\ x_3^{(k+1)} = 2\alpha + 4\beta + \gamma - 3x_1^{(k)} + x_2^{(k)} \end{cases}$$

$$\begin{cases} x_1^{(1)} = -3\alpha + 5\beta - 2\gamma \\ x_2^{(1)} = 3\alpha + \beta + 5\gamma \\ x_3^{(1)} = 2\alpha + 4\beta + \gamma \end{cases} \quad \begin{cases} x_1^{(2)} = \dots \\ x_2^{(2)} = \dots \\ x_3^{(2)} = \dots \end{cases}$$

→ 3.5 pts

(c) Write out the **individual components** of Gauss-Seidel iteration equations for solving the system. Then,

starting with the initial vector $x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, perform two iterations (i.e., find $x^{(2)}$).

$$\begin{cases} x_1^{(k+1)} = -3\alpha + 5\beta - 2\gamma + 4x_2^{(k)} + 2x_3^{(k)} \\ x_2^{(k+1)} = 3\alpha + \beta + 5\gamma - 2x_1^{(k+1)} - 5x_3^{(k)} \\ x_3^{(k+1)} = 2\alpha + 4\beta + \gamma - 3x_1^{(k+1)} + x_2^{(k+1)} \end{cases}$$

3.5 pts.

$$\begin{cases} x_1^{(1)} = -3\alpha + 5\beta - 2\gamma \\ x_2^{(1)} = 3\alpha + \beta + 5\gamma + 6\alpha - 10\beta + 4\gamma = 9\alpha - 9\beta + 9\gamma \\ x_3^{(1)} = 2\alpha + 4\beta + \gamma + 9\alpha - 15\beta + 6\gamma + 9\alpha - 9\beta + 9\gamma \\ \quad = 20\alpha - 20\beta + 16\gamma \end{cases} \quad \begin{cases} x_1^{(2)} = \dots \\ x_2^{(2)} = \dots \\ x_3^{(2)} = \dots \end{cases}$$

2. Let

$$A = \begin{bmatrix} -12 & a+b & c & \alpha \\ -a & -1 & c & \beta \\ b & b+c & 12 & -a \\ \gamma & b & c & 30 \end{bmatrix}.$$

Find a , b , and c **nonnegative numbers**, or conclude that there is no such triple of numbers, such that the circles in the Gerschgorin Theorem will form a chain of four tangent circles with **mutually disjoint interiors**.

$$C_1 = \{z \in \mathbb{C} : |z + 12| \leq r_1 = a + b + c + \alpha\}$$

$$C_2 = \{z \in \mathbb{C} : |z + 1| \leq r_2 = a + c + \beta\}$$

$$C_3 = \{z \in \mathbb{C} : |z - 12| \leq r_3 = a + 2b + c\}$$

$$C_4 = \{z \in \mathbb{C} : |z - 30| \leq r_4 = b + c + \gamma\}$$



2 pts.

4 pts. $\begin{cases} r_1 + r_2 = 11 \\ r_2 + r_3 = 13 \\ r_3 + r_4 = 18 \end{cases} \Leftrightarrow \begin{cases} 2a + b + 2c = 11 - \alpha - \beta \\ 2a + 2b + 2c = 13 - \beta \\ a + 3b + 2c = 18 - \gamma \end{cases}$

$\Rightarrow \begin{cases} a = \dots \\ b = \dots \\ c = \dots \end{cases} \left. \begin{array}{l} 3 \text{ pts} \\ \Rightarrow \text{Conclusion} \end{array} \right\} \rightarrow 1 \text{ pt.}$

3. Let $A = \begin{bmatrix} \alpha & \beta^2 \\ \gamma^2 & \alpha \end{bmatrix}$.

(a) Find all eigenpairs (that is, the eigenvalues and corresponding eigenvectors) of the matrix

$$p(B) = \beta^2 \gamma^2 B^2 - \beta \gamma B + \alpha I_2, \text{ where } B = (A - \alpha I_2)^{-1},$$

without calculating B or $p(B)$.

$$P_A(\lambda) = \begin{vmatrix} \alpha - \lambda & \beta^2 \\ \gamma^2 & \alpha - \lambda \end{vmatrix} = (\alpha - \lambda)^2 - \beta^2 \gamma^2 = 0 \Rightarrow \lambda = \alpha \pm \beta \gamma \quad \rightarrow 1 \text{ pt}$$

$$\boxed{\lambda_1 = \alpha - \beta \gamma} : \text{Null}(A - (\alpha - \beta \gamma)I_2) = E_{\lambda_1} \quad \rightarrow 2 \text{ pts}$$

$$\begin{bmatrix} \beta \gamma & \beta^2 & 0 \\ \gamma^2 & \beta \gamma & 0 \end{bmatrix} \xrightarrow[R_2^{\text{new}} = \frac{1}{\gamma} R_2^{\text{old}}]{R_1^{\text{new}} = \frac{1}{\beta} R_1^{\text{old}}} \begin{bmatrix} \gamma & \beta & 0 \\ \gamma & \beta & 0 \end{bmatrix} \xrightarrow{R_2^{\text{new}} = R_2^{\text{old}} - R_1} \begin{bmatrix} \gamma & \beta & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{cases} \gamma x_1 + \beta x_2 = 0 \\ x_2 = \text{free variable} \end{cases} \Rightarrow \begin{cases} x_1 = -\frac{\beta}{\gamma} x_2 \\ x_2 = \text{free} \end{cases} \Rightarrow E_{\lambda_1} = \text{Span} \left\{ \begin{bmatrix} -\beta/\gamma \\ 1 \end{bmatrix} \right\} \quad \rightarrow 2 \text{ pts}$$

$$\boxed{\lambda_2 = \alpha + \beta \gamma} : E_{\lambda_2} = \text{Null}(A - (\alpha + \beta \gamma)I_2) = \text{Span} \left\{ \begin{bmatrix} \beta/\gamma \\ 1 \end{bmatrix} \right\}$$

Eigenpairs of A : $(\alpha - \beta \gamma, c \begin{bmatrix} -\beta/\gamma \\ 1 \end{bmatrix})$; $(\alpha + \beta \gamma, c \begin{bmatrix} \beta/\gamma \\ 1 \end{bmatrix})$; $c \neq 0$

Eigenpairs of B : $(\frac{1}{-\beta \gamma}, c \begin{bmatrix} -\beta/\gamma \\ 1 \end{bmatrix})$; $(\frac{1}{\beta \gamma}, c \begin{bmatrix} \beta/\gamma \\ 1 \end{bmatrix})$; $c \neq 0$

Eigenpairs of $p(B)$: $(p(\frac{1}{-\beta \gamma}), c \begin{bmatrix} -\beta/\gamma \\ 1 \end{bmatrix})$; $(p(\frac{1}{\beta \gamma}), c \begin{bmatrix} \beta/\gamma \\ 1 \end{bmatrix})$; $c \neq 0$

where $p(x) = \beta^2 \gamma^2 x^2 - \beta \gamma x + \alpha$

$$p(\frac{1}{-\beta \gamma}) = 1 + 1 + \alpha = \alpha + 2 \quad ; \quad p(\frac{1}{\beta \gamma}) = 1 - 1 + \alpha = \alpha.$$

$\rightarrow 2 \text{ pts}$

(b) If $\mathbf{x}^{(0)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, perform two iterations (i.e., find m_2 and $\mathbf{x}^{(2)}$) of the power method for A .

$$\vec{z}^{(0)} = A \vec{x}^{(0)} = \begin{bmatrix} \alpha & \beta^2 \\ \gamma^2 & \alpha \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \alpha + \beta^2 \\ \gamma^2 + \alpha \end{bmatrix}$$

$$m_1 = \max \{ \alpha + \beta^2, \gamma^2 + \alpha \}$$

$$\vec{x}_1^{(1)} = \frac{1}{m_1} \begin{bmatrix} \alpha + \beta^2 \\ \gamma^2 + \alpha \end{bmatrix}$$

$$\vec{z}^{(1)} = A \vec{x}^{(1)} = \frac{1}{m_1} \begin{bmatrix} \alpha & \beta^2 \\ \gamma^2 & \alpha \end{bmatrix} \begin{bmatrix} \alpha + \beta^2 \\ \gamma^2 + \alpha \end{bmatrix} = \dots$$

$$m_2 = \max \{ \dots, \dots \}$$

$$\vec{x}^{(2)} = \frac{1}{m_2} \vec{z}^{(1)} = \dots$$

1.5 pts.

1.5 pts.

4. A radar was used to record the speed of an object during the first 3 seconds of motion (see the table below).

Time t (sec)	0	1	2	3
v (m/sec)	0	α	$\alpha + \beta$	$\alpha + \beta + \gamma$

(a) Construct the divided difference table for the data set, and then write out the Newton form of the interpolating polynomial. Use the resulting polynomial to approximate the value of $v(1.5)$.

$$\begin{array}{lcl}
 0 & \boxed{0} = a_0 & \\
 1 & \alpha & \boxed{\alpha} = a_1 \\
 2 & \alpha + \beta & \boxed{\frac{\beta - \alpha}{2}} = a_2 \\
 3 & \alpha + \beta + \gamma & \boxed{\frac{\gamma - 2\beta + \alpha}{6}} = a_3
 \end{array}$$

} 4 pts.

$$P_N(t) = 0 + \alpha t + \frac{\beta - \alpha}{2} t(t-1) + \frac{\gamma - 2\beta + \alpha}{6} t(t-1)(t-2)$$

$$v(1.5) \simeq p(1.5) = \dots$$

→ 0.5 pts.

(b) Construct the Lagrange form of the interpolating polynomial. Use the resulting polynomial to approximate the value of $v(1.5)$; it should be the same as in part (a) (why?).

$$\begin{aligned}
 P_L(t) &= 0 \cdot \frac{(t-1)(t-2)(t-3)}{(0-1)(0-2)(0-3)} + \alpha \frac{(t-0)(t-2)(t-3)}{(1-0)(1-2)(1-3)} \\
 &\quad + (\alpha+\beta) \frac{(t-0)(t-1)(t-3)}{(2-0)(2-1)(2-3)} + (\alpha+\beta+\gamma) \frac{(t-0)(t-1)(t-2)}{(3-0)(3-1)(3-2)} \\
 &= \frac{\alpha}{2} t(t-2)(t-3) + \frac{\alpha+\beta}{-2} t(t-1)(t-3) \\
 &\quad + \frac{\alpha+\beta+\gamma}{6} t(t-1)(t-2)
 \end{aligned}$$

$$v(1.5) \simeq P_L(1.5) = \dots$$

→ 0.5 pts.

$v(1.5)$ is approximated by the same value in (a) and (b) because $P_N(t)$ and $P_L(t)$ are just different forms of the same interpolating polynomial.

↓ 1 pt.

1	2	3	4	Total