

# EV BATTERY DEGRADATION PREDICTION

Using Machine Learning

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# INTRODUCTION

## IMPORTANCE OF EV BATTERY HEALTH

Battery health plays a crucial role in determining the performance, range, and lifespan of electric vehicles.

## CHALLENGES IN MANUAL ESTIMATION

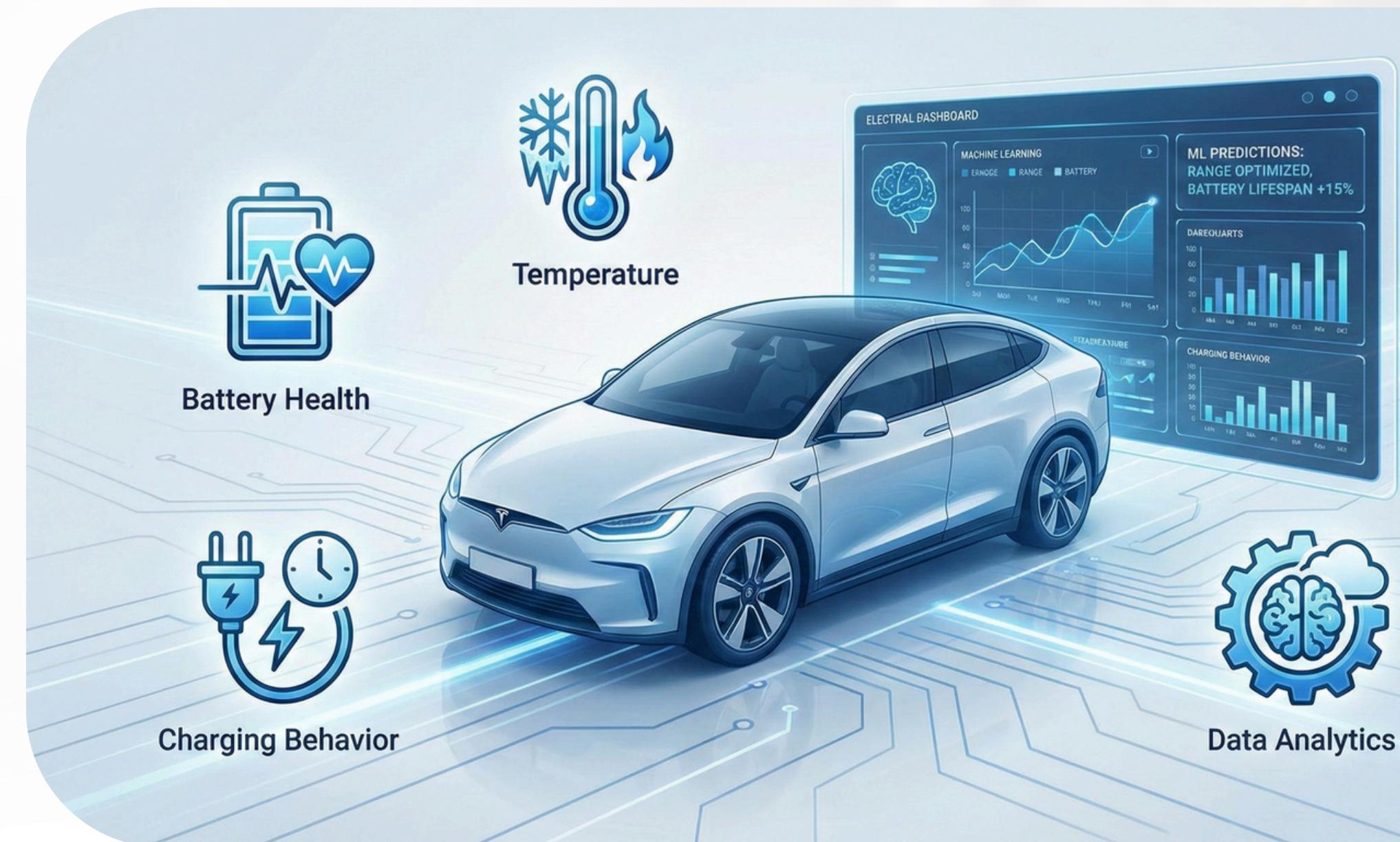
Battery degradation cannot be accurately estimated manually as it depends on multiple factors like usage, temperature, and charging behavior.

## ROLE OF MACHINE LEARNING

Machine learning models can analyze complex patterns in EV usage data and accurately predict battery degradation.

## PROJECT GOAL

The goal of this project is to predict EV battery degradation percentage using usage and environmental factors to help improve battery management and planning.



# DATASET OVERVIEW

## KEY FEATURES

### Vehicle Information

These features describe the vehicle's physical and age-related characteristics.

- Vehicle Age (Years)
- Battery Capacity (kWh)

### Usage & Charging Patterns

These features represent how the vehicle is used daily, similar to lifestyle habits in humans.

- Daily Usage (km)
- Total Distance Driven (km)
- Charge Cycles
- Fast Charging Percentage (%)

### Environmental Conditions

These features represent external conditions affecting battery health.

- Average Operating Temperature (°C)

## DATASET SOURCE

- The dataset is synthetically generated but logically designed to simulate real-world EV usage scenarios.
- Feature relationships are based on known EV battery aging principles.

## TARGET VARIABLE

- Battery Degradation (%) – Represents the percentage of battery health loss over time.

# DATA PREPROCESSING

## 1. Handling Missing Values

- Checked and handled missing values to ensure data completeness.

## 2. Feature Selection

- Relevant features related to EV usage and battery stress were selected.

## 3. Outlier Detection

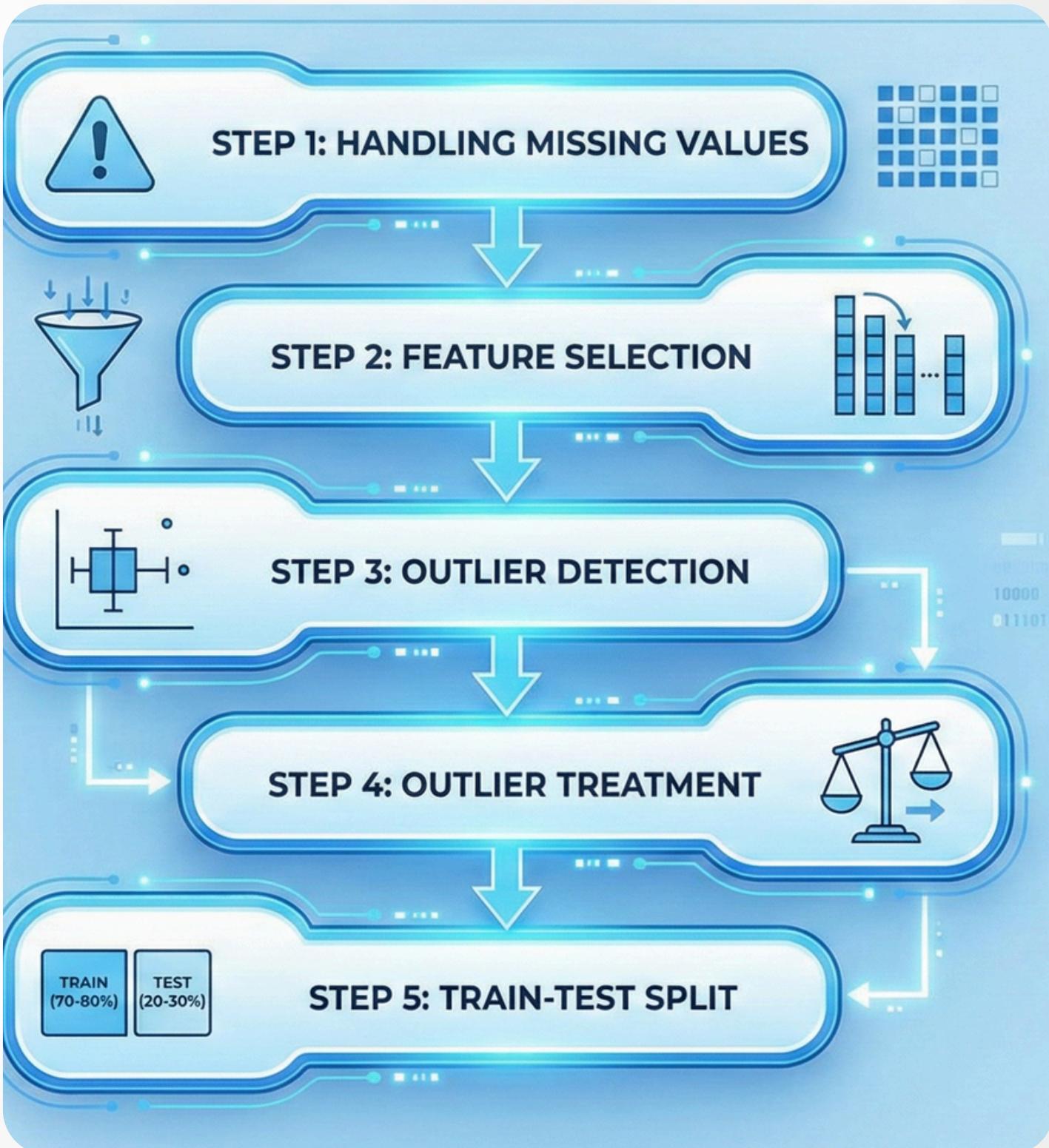
- Boxplots were used to identify extreme values in the dataset.

## 4. Outlier Treatment

- Outliers were detected using boxplots and treated using the IQR method to improve model robustness and reduce noise.

## 5. Train-Test Split

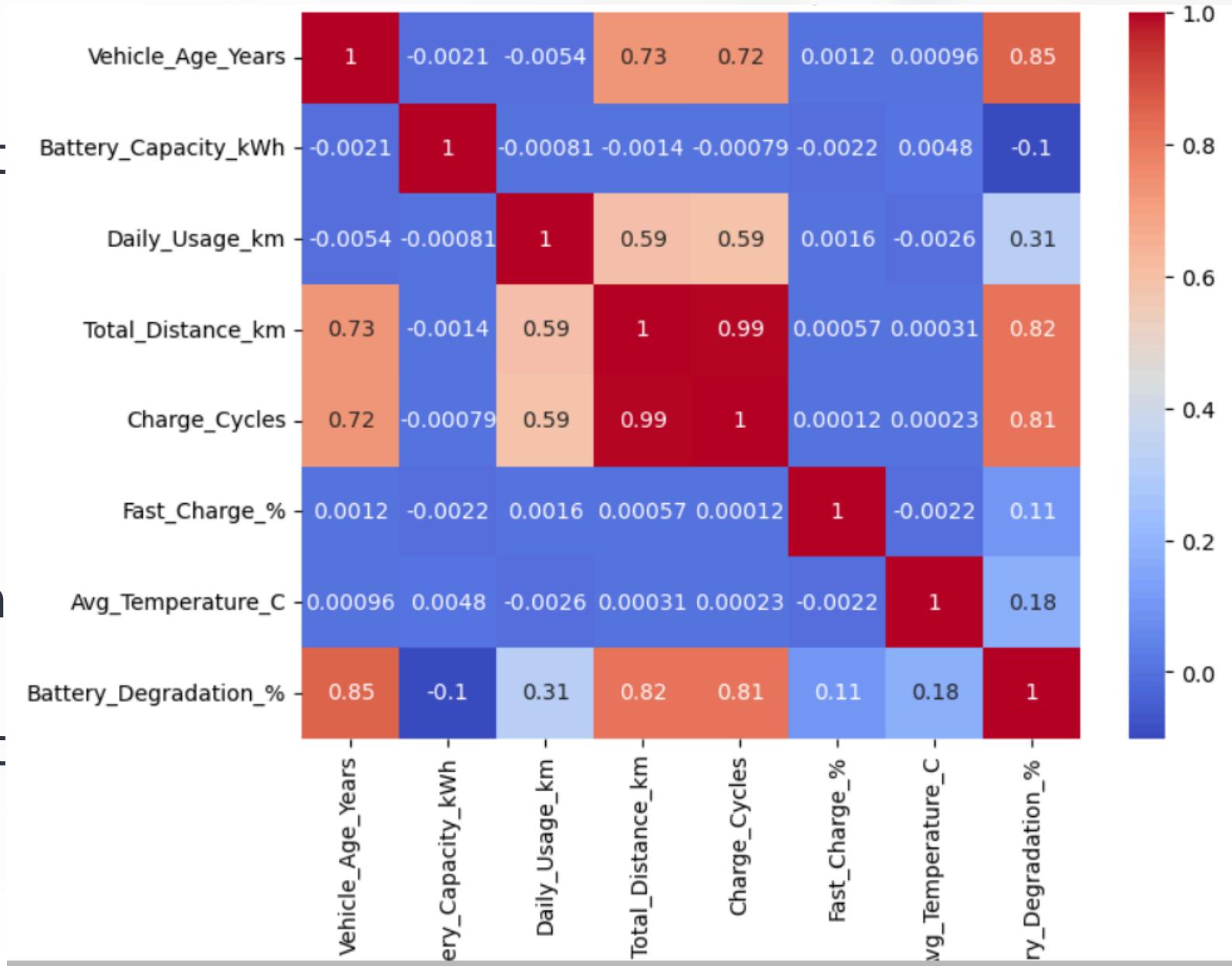
- Dataset was split into 80% training data and 20% testing data.



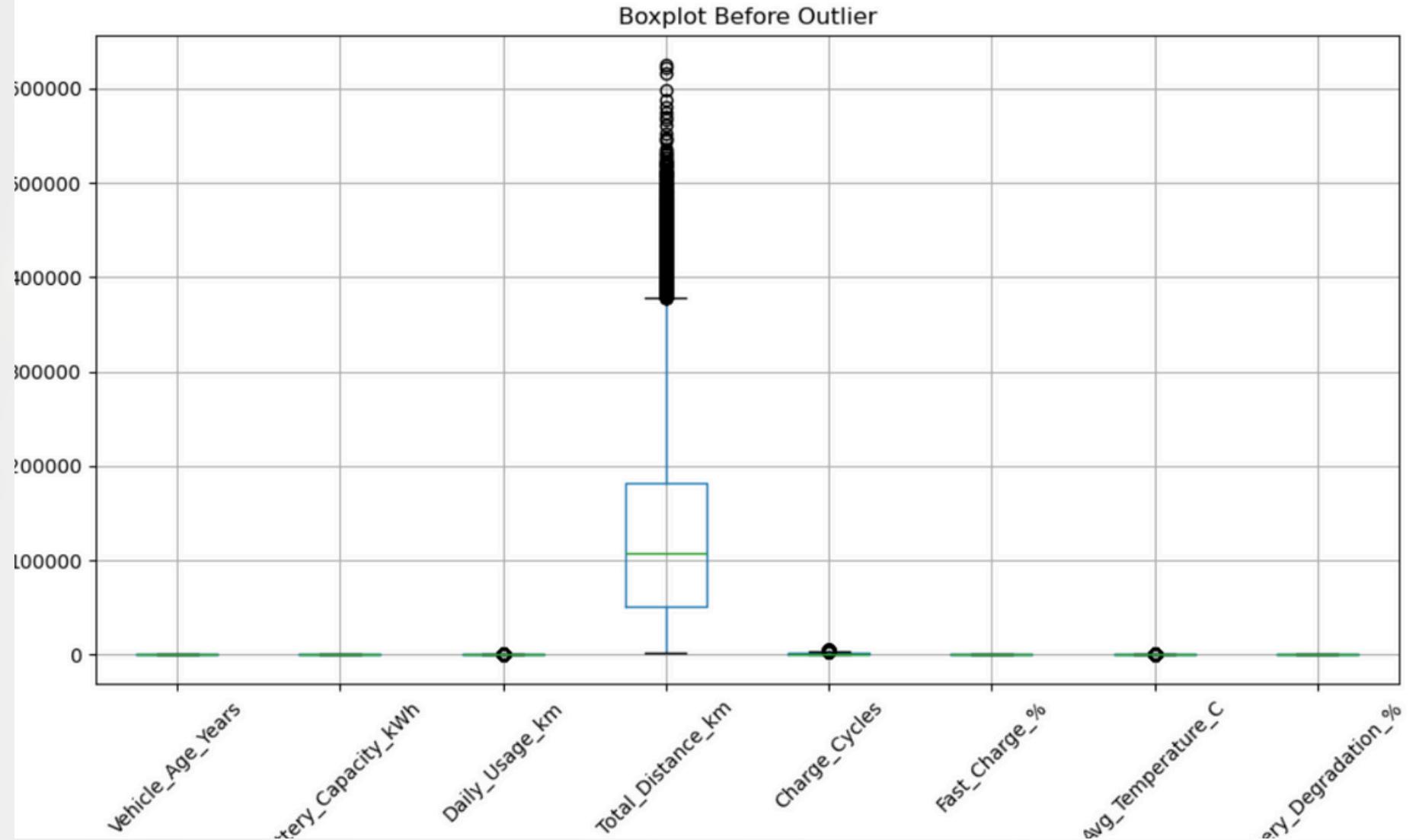
# VISUALIZATIONS & INSIGHTS

## CORELATION HEAT MAP

- Used to analyze the relationship between input features and battery degradation.
- Strong positive correlation observed with:
  - Vehicle Age
  - Total Distance Driven
  - Charge Cycles
- Battery Capacity shows a weak negative correlation with degradation.
- Correlation analysis helped identify the most influential features before model training.

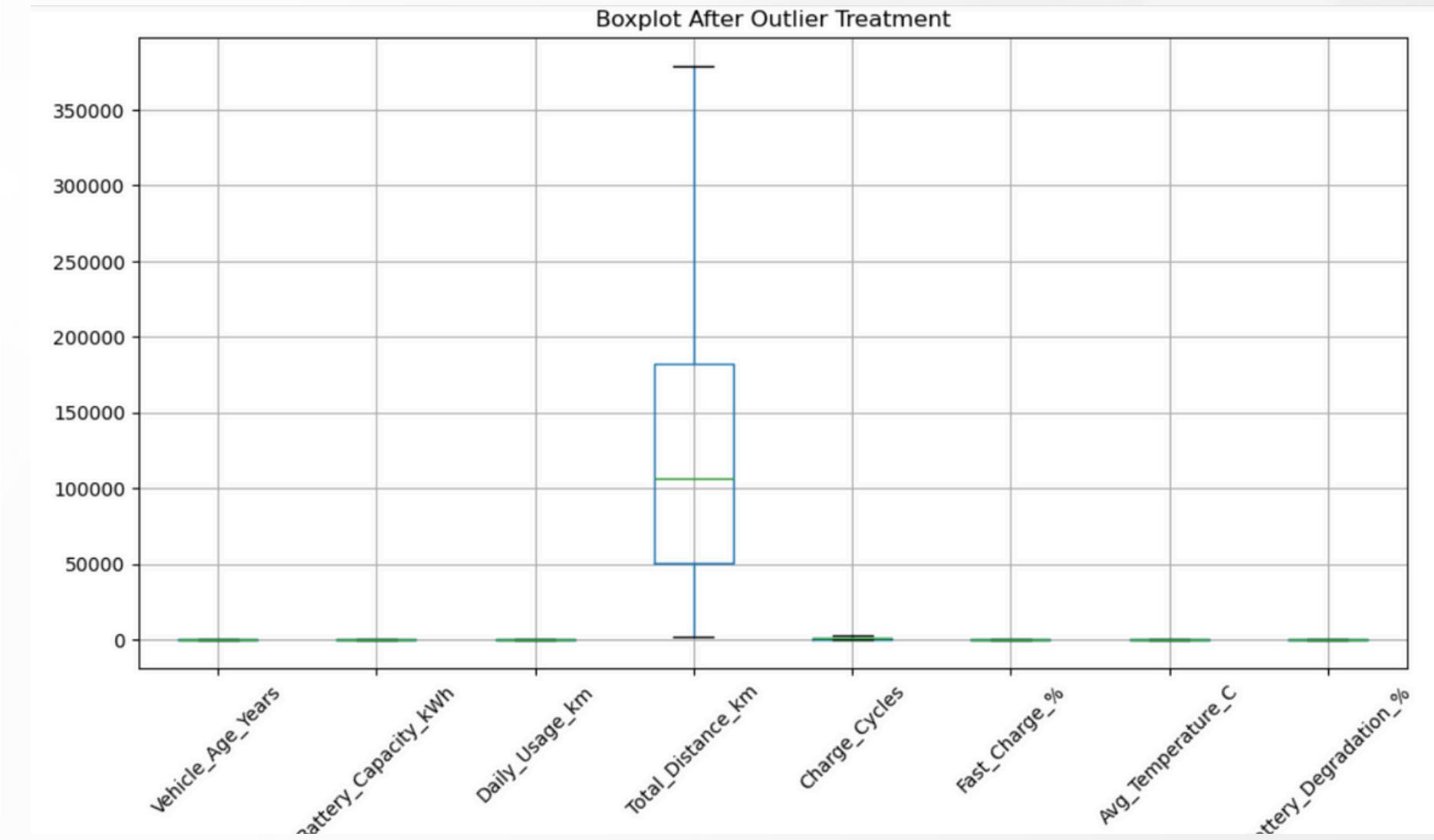


## BOXPLOT – BEFORE OUTLIER TREATMENT



- Identified extreme values in:
  - Total Distance
  - Charge Cycles
  - Battery Degradation
- These outliers represent heavy EV usage patterns.

## BOXPLOT – AFTER OUTLIER TREATMENT



- Outliers were treated using the IQR method.
- Data distribution became more stable and realistic.
- Important usage patterns were retained without removing valid data.

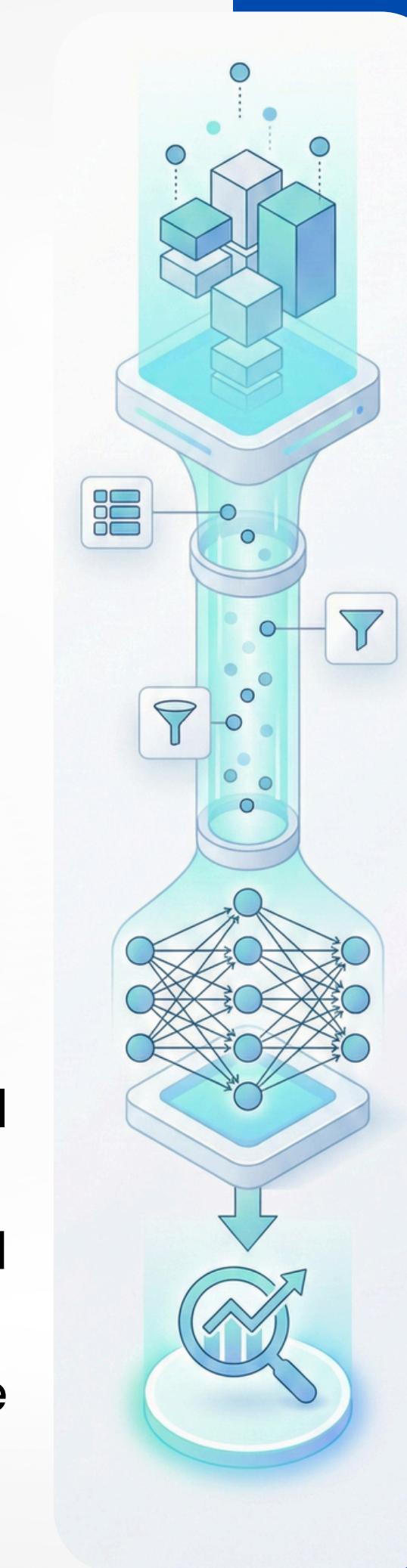
# MODEL SELECTION

## 1. Multiple Regression Models Tested

- Linear Regression
- Decision Tree Regressor
- Random Forest Regressor
- KNN Regressor
- AdaBoost Regressor
- Gradient Boosting Regressor

## 2. Train-Test Split

- Used to evaluate initial model performance on unseen data.
- Dataset split into 80% training and 20% testing.
- Helps evaluate model performance and avoid overfitting.



## 3. K-Fold Cross Validation

- 5-Fold Cross Validation was applied to ensure model stability and reduce dependency on a single data split.

## 4. Hyperparameter Tuning

- GridSearchCV was used to optimize Random Forest parameters such as number of trees and tree depth to prevent overfitting.

## 5. Best Performing Model

- Random Forest Regressor achieved the highest and most consistent  $R^2$  score across both test data and cross-validation.

# MODEL RESULTS & PERFORMANCE EVALUATION

## EVALUATION METRICS USED

- R<sup>2</sup> Score – Measures how well the model explains variance in battery degradation
- MSE (Mean Squared Error) – Measures average squared prediction error
- RMSE (Root Mean Squared Error) – Indicates prediction stability and penalizes large errors

Model	R2 Score
2	Random Forest 0.985775
5	Gradient Boosting 0.982644
1	Decision Tree 0.968117
4	AdaBoost 0.933380
0	Linear Regression 0.885688
3	KNN 0.875885

## K-FOLD CROSS VALIDATION

- 5-Fold Cross Validation applied
- Ensures model stability and avoids bias due to single train-test split
- Performance evaluated across multiple data partitions

## BEST MODEL SELECTION

- Random Forest Regressor
- Achieved:
  - Highest Mean R<sup>2</sup> Score
  - Lowest RMSE
- Selected as the final model for prediction and deployment

# PREDICTION EXAMPLE & **MODEL DEPLOYMENT**

## **Prediction Example**

Input Values Provided to the Model:

- Vehicle Age: 4.3 years
- Battery Capacity: 30 kWh
- Daily Usage: 60 km
- Total Distance Driven: 82,000 km
- Charge Cycles: 720
- Fast Charging Usage: 30%
- Average Temperature: 32°C

## **Predicted Output**

Predicted Battery Degradation:

- $\approx 28.5\%$

This indicates moderate battery wear due to frequent charging and usage.

## **Model Deployment**

- The trained Random Forest model was saved using Joblib.
- A Streamlit web application was developed for deployment.
- Users can input EV usage details and get real-time battery degradation predictions.

The deployed model enables users to estimate EV battery health and make informed decisions regarding battery maintenance and replacement.

# CONCLUSION & FUTURE SCOPE

## Conclusion

- The project successfully predicts EV battery degradation using machine learning.
- Exploratory Data Analysis identified key factors affecting battery health.
- Outlier treatment improved data quality and model stability.
- Multiple regression models were evaluated.
- Random Forest Regressor performed best with high R<sup>2</sup> score and low error.
- The final model was deployed using Streamlit for real-time prediction.

## Future Scope

- Use real-world EV data instead of synthetic data.
- Apply advanced hyperparameter tuning techniques.
- Extend the model to time-series battery degradation prediction.
- Deploy as a mobile or cloud-based application.
- Integrate with EV battery management systems.

## Key Takeaways

- Battery degradation increases with:
  - Vehicle age
  - Charge cycles
  - Frequent fast charging
  - High operating temperature
- Ensemble models outperform simple regression models for this problem.

thank  
you

