

signals and systems

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Consider the state-space description of an LTI system with matrices

$$A = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix}, \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad C = [3 \quad -2], \quad D = 1$$

For the input, $\sin(\omega t)$, $\omega > 0$, the value of ω for which the steady-state output of the system will be zero, is _____ (Round off to the nearest integer).

solution:

$$A = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad C = [3 \quad -2] \quad D = [1]$$

transfer function given by $T.F = C(sI - A)^{-1}B + D$

$$[sI - A] = \begin{bmatrix} s & -1 \\ 1 & s+2 \end{bmatrix} \quad [sI - A]^{-1} = \begin{bmatrix} s & -1 \\ 1 & s+2 \end{bmatrix}^{-1}$$

$$[sI - A]^{-1} = \frac{1}{s(s+2)+1} \begin{bmatrix} s+2 & 1 \\ -1 & s \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$T.F = \begin{bmatrix} 3/s^2 + 2s + 1 & -2/s^2 + 2s + 1 \end{bmatrix} \begin{bmatrix} s+2 & 1 \\ -1 & s \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 1$$

$$T.F = \begin{bmatrix} 3/s^2 + 2s + 1 & -2/s^2 + 2s + 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 1$$

$$T.F = s^2 + 4 * 1/s^2 + 2s + 1$$

$$H(S) = T.F = s^2 + 4 * (\frac{1}{s^2 + 2s + 1})$$

$$s = j\omega$$

$$H(j\omega) = 4 - (\omega)^2 * (\frac{1}{1 + 2j\omega - (\omega)^2})$$

Steady state output of system is zero

$$4 - (\omega)^2 = 0$$

$$\omega = 2 \text{ rad/sec}$$