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REM VAL I Program to move 9 blocks from a conveyor onto a pallet
REM
REM Initialise PALLET and CON vectors and APP transform matrix to:
REM
REM     PALLET = (2000,2000,1000)  CON = (1000,1000,1000)
REM
REM           1 0 0  0
REM     APP =  0 1 0  0
REM           0 0 1 50
REM           0 0 0  1
REM
REM Absolute locations will be used so Robot position is immaterial
REM
REM Initialise PX and PY which will count the number of boxes
REM placed in each column and row respectively
SETI PX = 0
SETI PY = 1
    REM Move next block
10  GOSUB 100
    REM End of row?
    IF PX=3 THEN 20
        REM Redefine X co-ordinate of PALLET
        SHIFT PALLET BY 100,0,0
        GOTO 10
    REM End of column?
20  IF PY=3 THEN 200
    REM Reset row counter and increment column counter
    SETI PX=0
    SETI PY=PY+1
    REM Redefine X and Y co-ordinates of PALLET
    SHIFT PALLET BY -200,100,0
    GOTO 10
    REM
    REM SUBROUTINE TO MOVE A BLOCK FROM CONVEYOR TO PALLET
    REM
    REM Move to a point 50mm above CON using joint interpolation
100 APPRO CON,50
    REM Wait for the conveyor to position the next box if necessary
    WAIT CONRDY
    REM Move down to CON using straight line motion
    MOVES CON
    REM Grip a box - signal an error if no box present (indicated
    REM by the jaws of the gripper becoming less than 25mm apart)
    GRASP 25
    REM Move back 50mm - I.e. 50mm up
    DEPART 50
    REM Move to the product of the PALLET vector and APP transform
    REM using joint interpolation - I.e. 50mm above next position
    MOVE PALLET : APP
    REM Move down to PALLET using straight line motion
    MOVES PALLET
    REM Open the gripper (depositing a box)
    OPENI
    REM Move back 50mm
    DEPART 50
    REM Signal conveyor to move next box into position
    SIGNAL GOCON
    REM
    REM Increment row counter
    SETI PX=PX+1
    RETURN
200 STOP

```