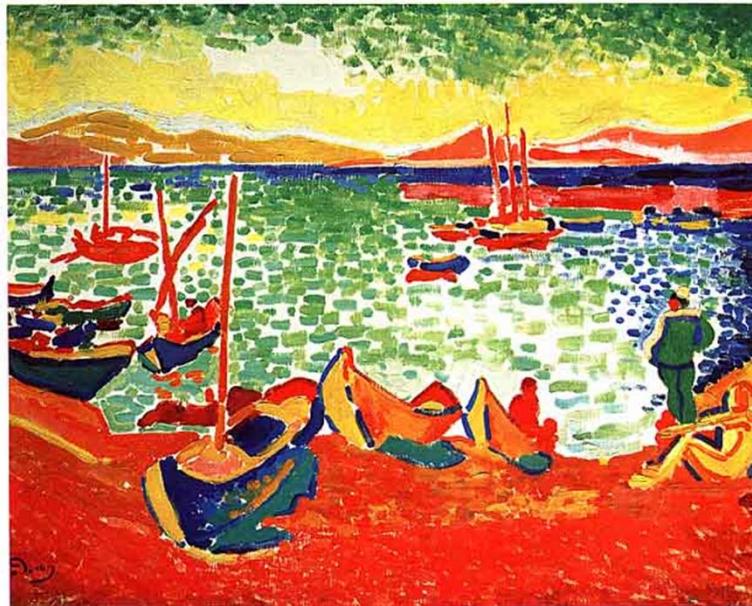


Colour



Colour

- Introduction
- Physical characteristics of colour
- Colour Spaces
- Applications & conclusions

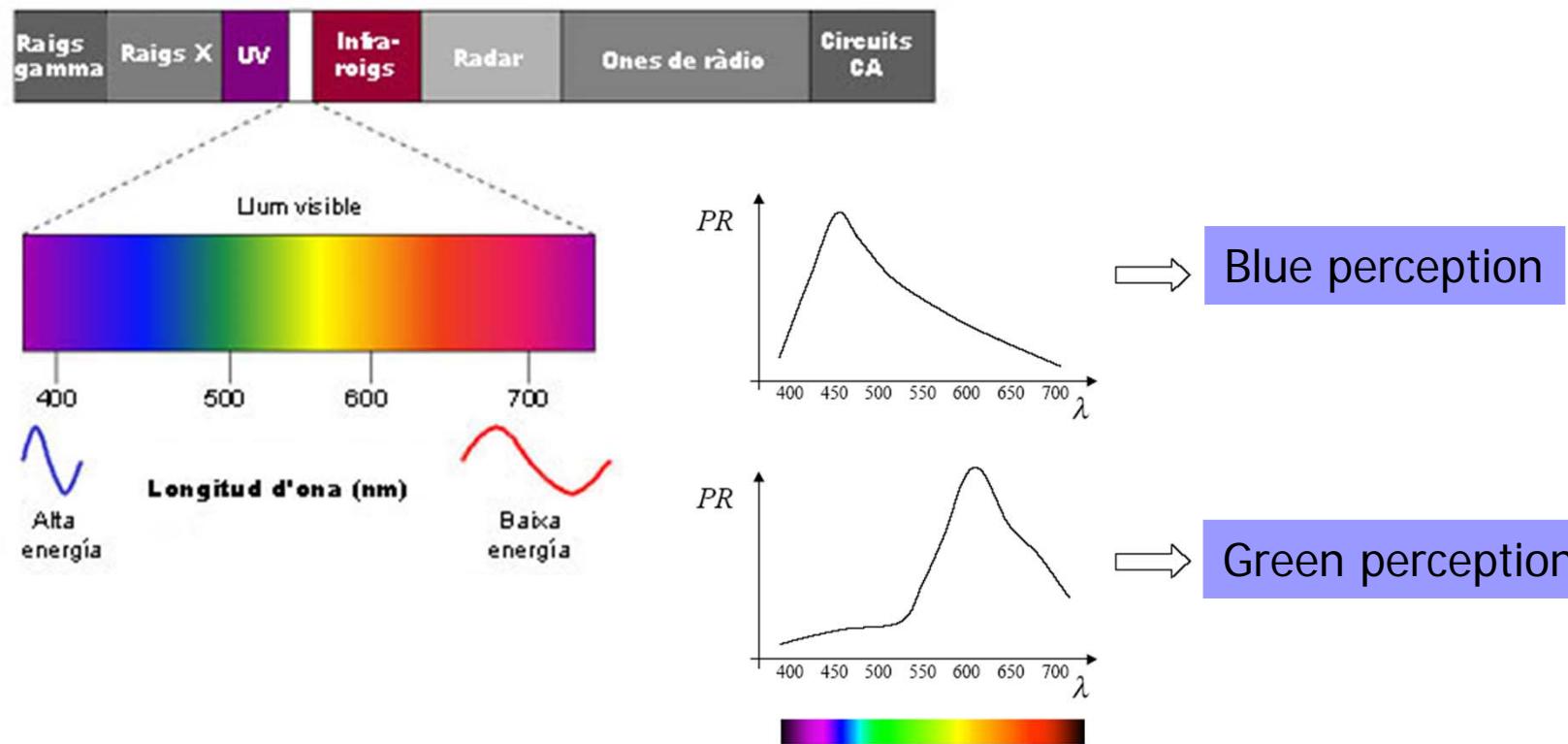
Introduction. Colour

- Is an important part of object perception
- However, is a complex phenomenon (difficult to characterize)
- It is related to the interaction of:
 - Light: spectral properties of the light source
 - Object: size, shape and texture (surface)
 - Observer: spectral sensitivity, lens, etc

Colour Physical characteristics

Visible spectra

- Electromagnetic spectra

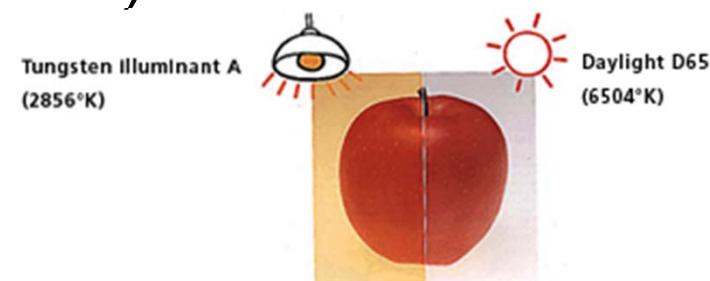


Physical stimulus. The Object

Illuminants

- Colour temperature (K). Temperature at which an ideal blackbody radiator emits radiation of the same colour as a given object
 - A measure of the spectral energy distribution of a light source
 - Low Temp: warm light (yellow/red) → Ex. sunset
 - High Temp: cold light (blue/white)

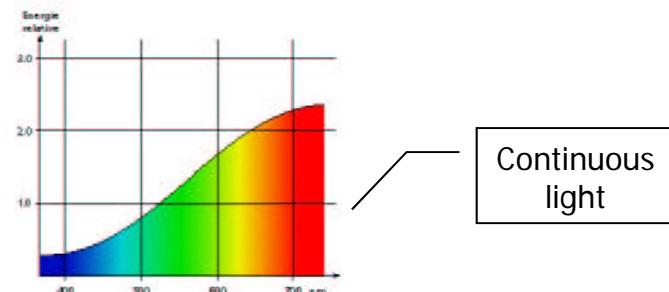
A	Standard bulb (2856 K)
C	Daylight without UV component (6750 K)
D65	Daylight with UV component (6500 K)
F11	Fluorescent lamp



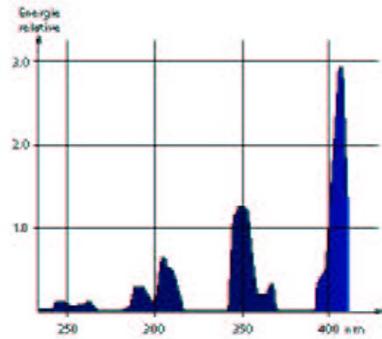
Physical stimulus. The Object

Light Sources

- Power spectra of a non continuous light source: concentrates emission in regions of the spectra
 - Causes distortions in the perception of the color of the objects

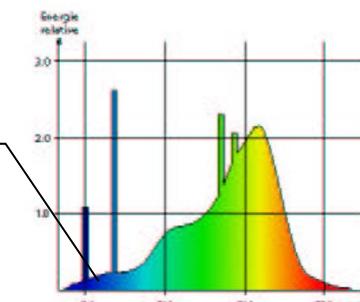


Continuous
light

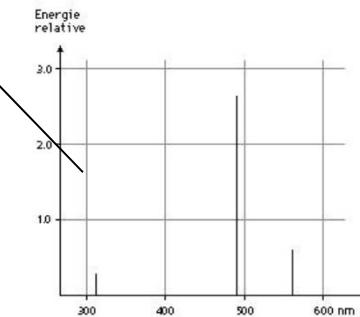


Non
continuous

Fluorescent



Laser



Physical stimulus. The Object

Colour rendering: variability of colour perception due to different light sources



Lumière du Jour D65



Illuminant A (Incandescent)



Blanc Froid Fluorescent

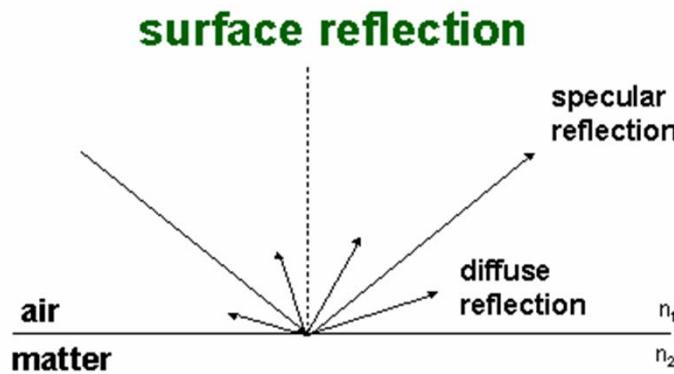


TL84

Physical stimulus. The Object

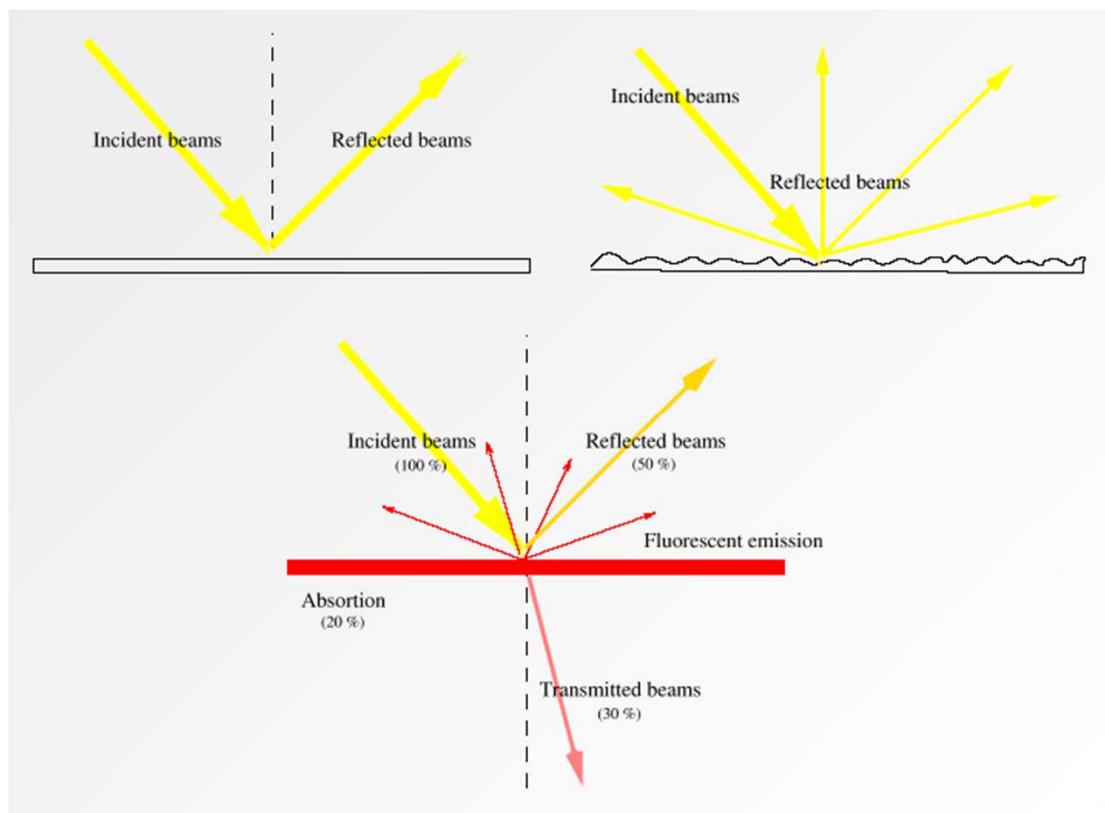
Effects of the surface

- Transmittance. Ratio between the transmitted and incident light in a surface
- Reflectance
 - Specular. The light is reflected with the same incidence angle with respect to the normal to the surface (eg. mirror)
 - Diffuse
- Absortion



Physical stimulus. The Object

Effects of the surface

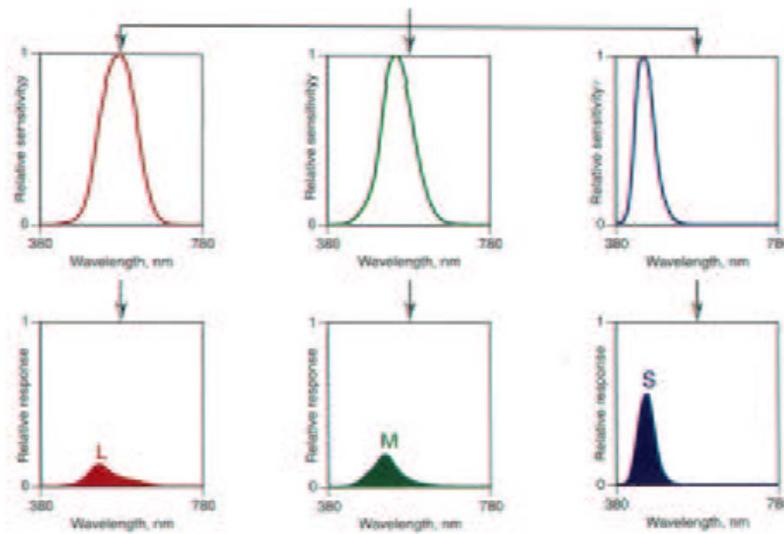


Colour perception

Which colour do we perceive?

Stimuli + Spectral sensitivity

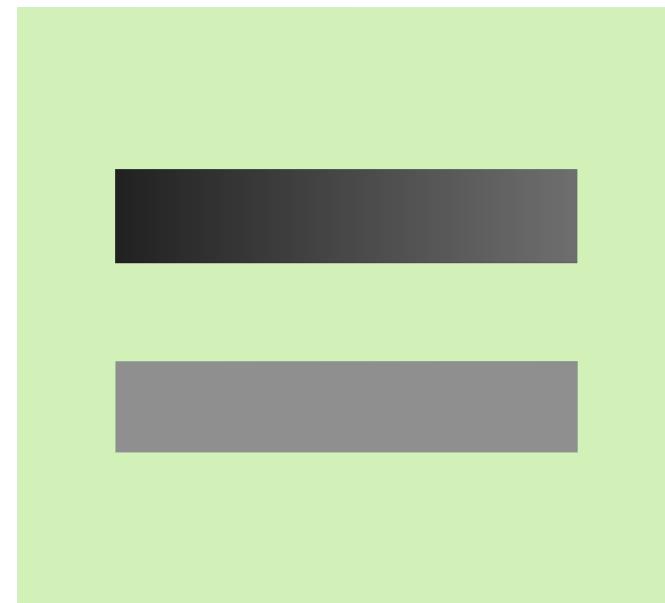
- Integration of the incident light for the 3 components
- **Tricromacy**



Colour perception

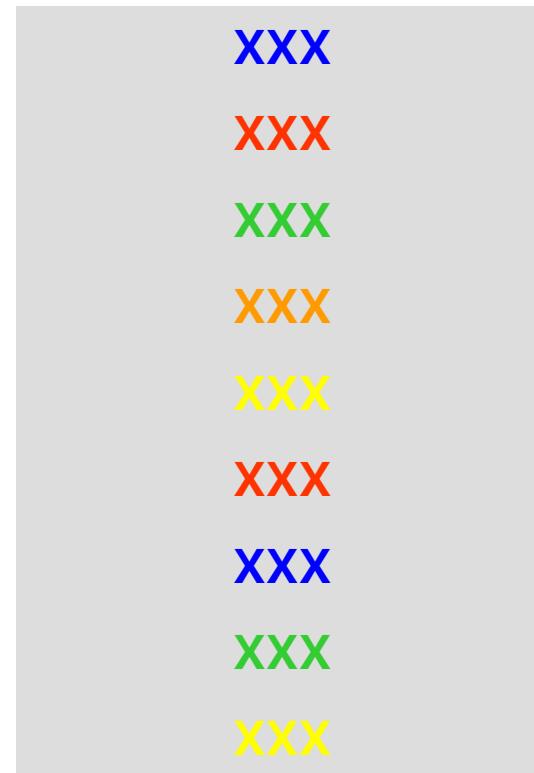
Receptive fields

- Contrast enhancement
- Constant illumination



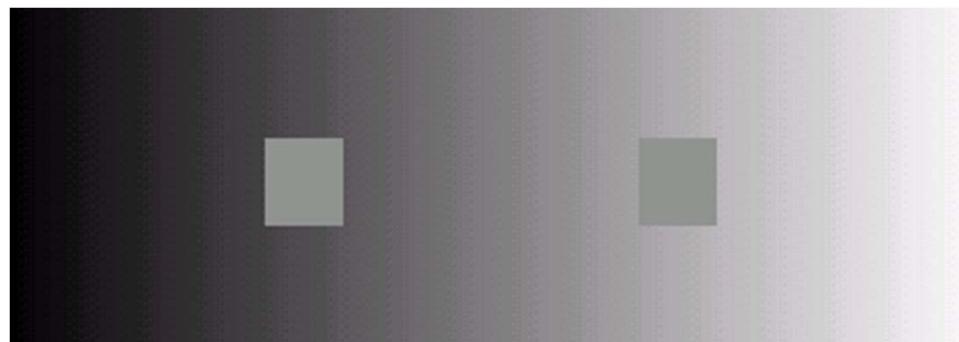
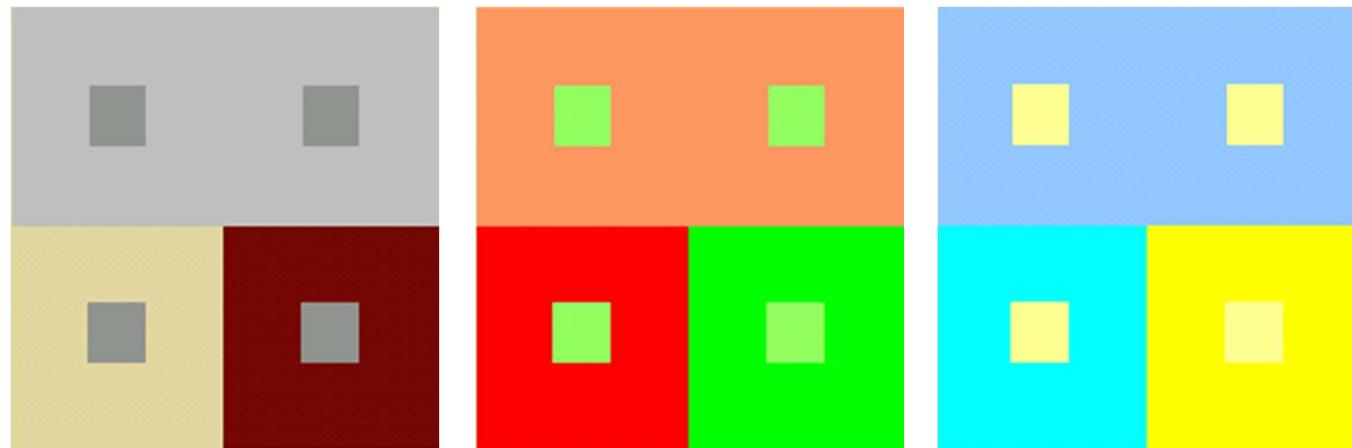
Colour perception

- **Stroop Effect** A demonstration of the reaction time of a task



Colour perception

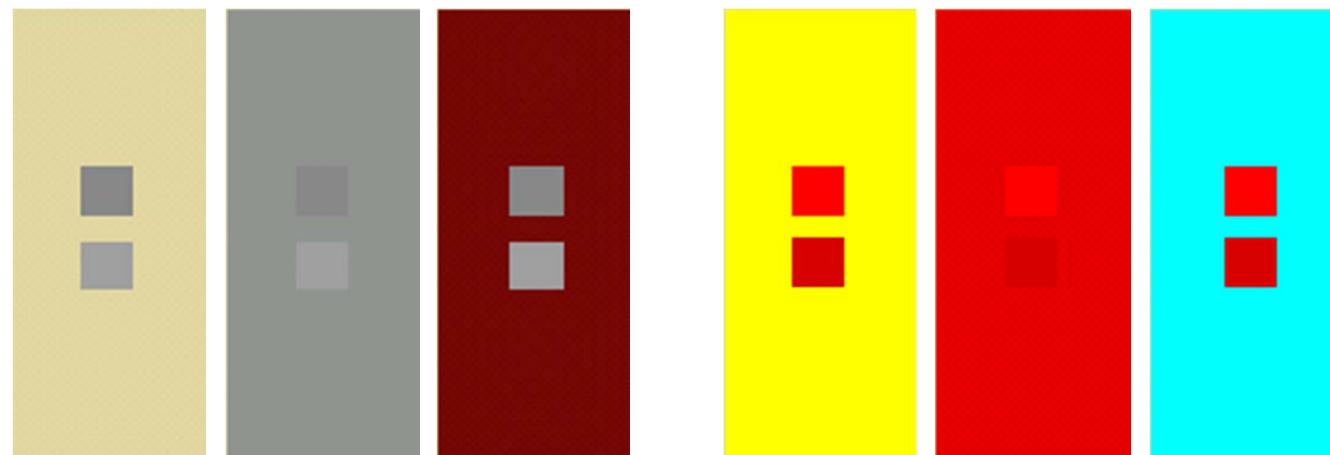
- **Simultaneous contrast** How the colours of two different objects affect each other



Colour perception

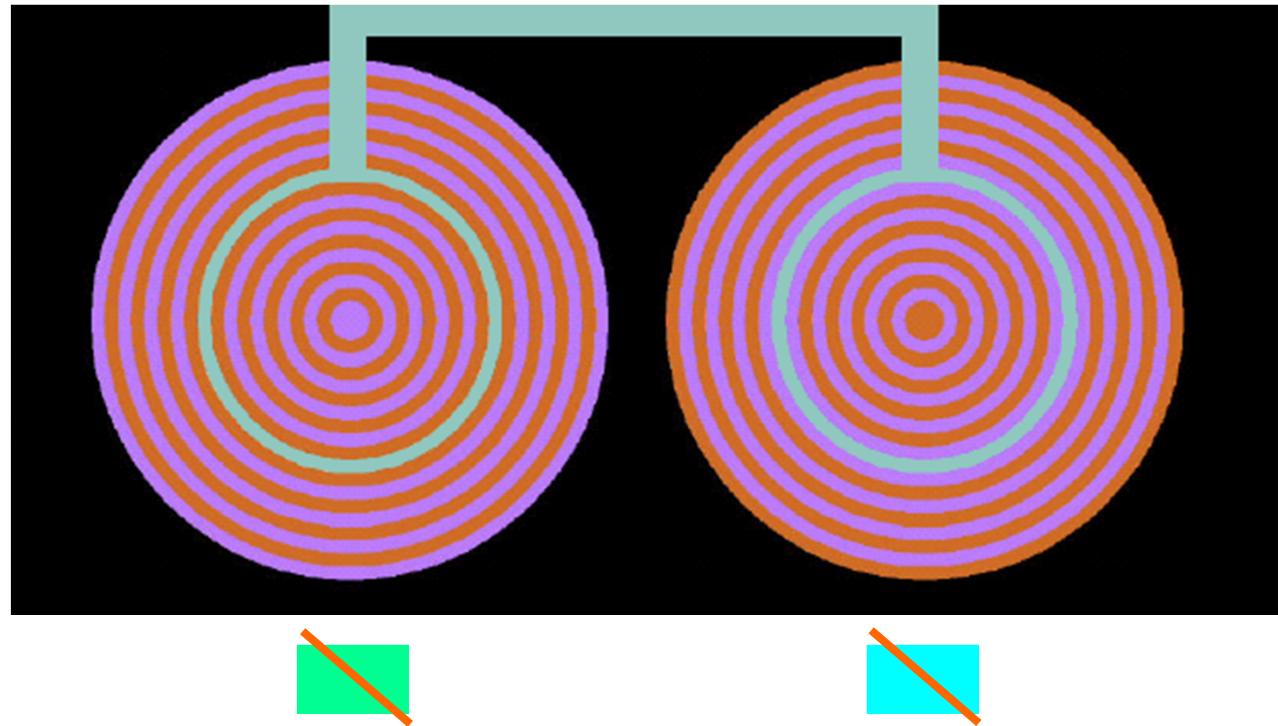
- **Crispening**

Colour discrimination is best for stimuli that are at or near the adaptation light and the discrimination worsens for stimuli that differ substantially from the adapting conditions

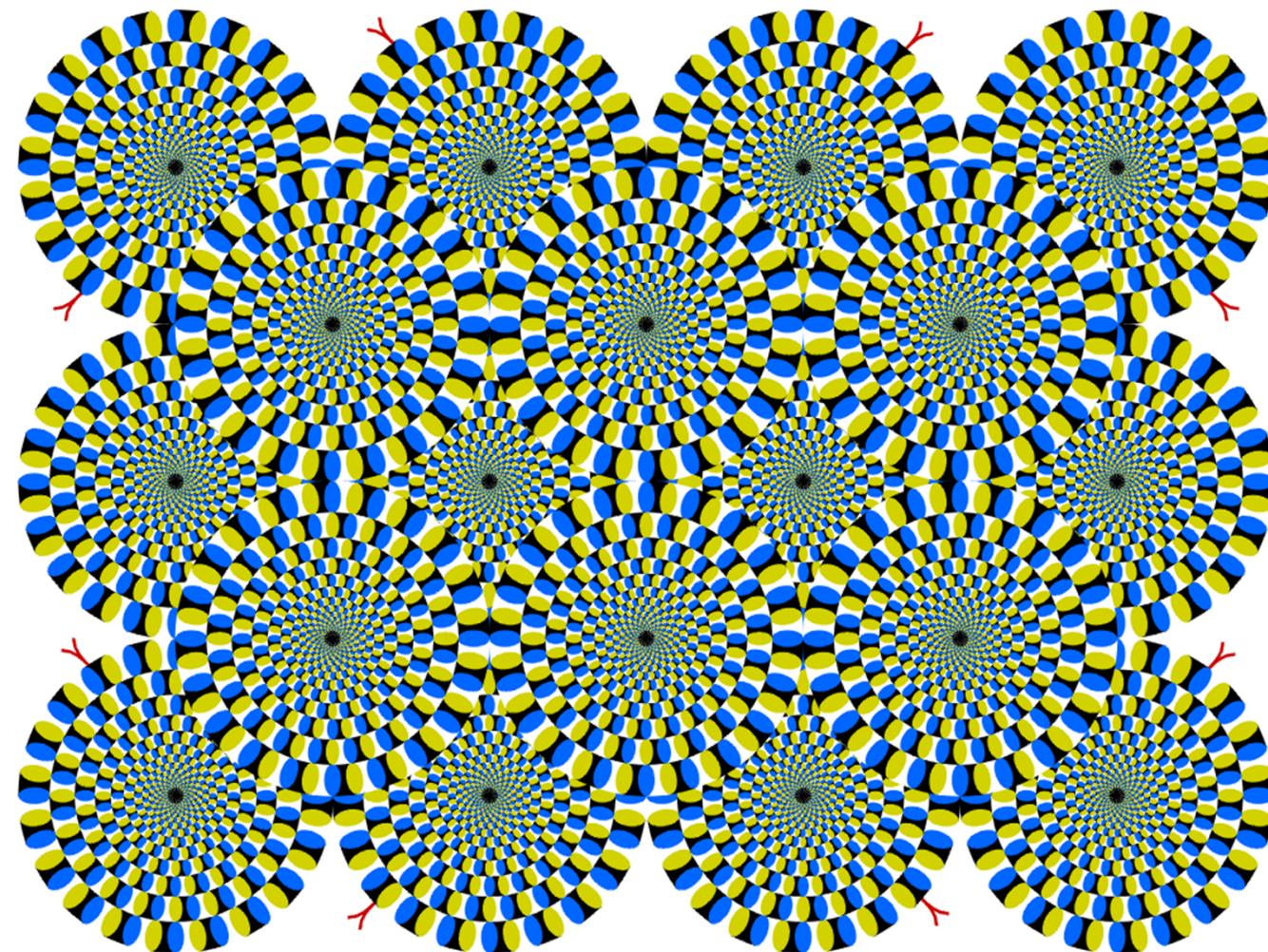


Colour perception

- Colour induction phenomena:



Colour perception



Colour perception



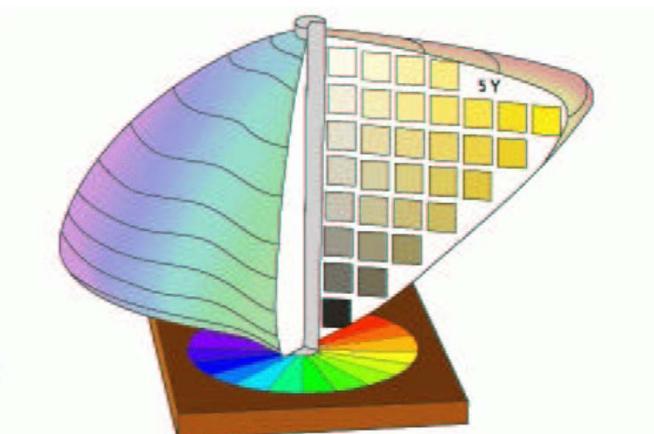
Colour perception



Colour description

Need of colour description

- Language labels: red, green, ...
- Hue, illumination and chromacity (saturation)
 - Hue: colour attribute
 - Luminosity: light component (from white to black) of a colour
 - Saturation: intensity of this colour (from grey to colour)



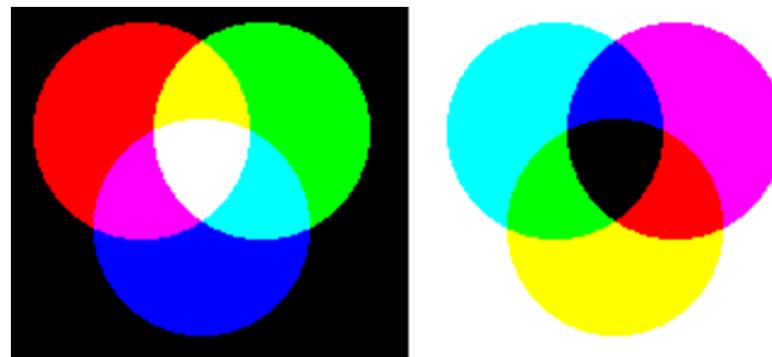
Colour spaces

Colour spaces

- 3 dimensional representations of colour
- Each point represents a different colour
- Classification based on
 - Visual human system (RGB, HIS)
 - Technical systems (colorimetry, xyz)
 - Image processing (Ohta, ...)
 - ...

Colour specification

- Colour models: additive vs subtractive



- Additive: RGB
 - Monitors, cameras
- Subtractive: CMY-K
 - Light absorption
 - Printing

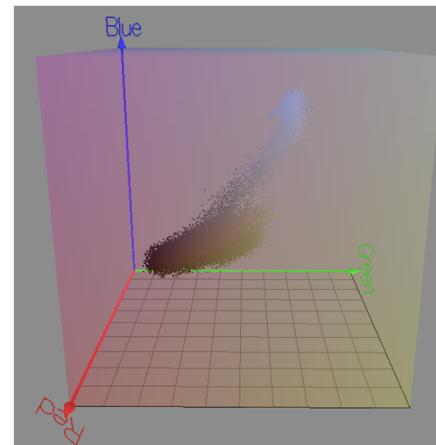
$$\begin{bmatrix} C \\ M \\ Y \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

Colour spaces

RGB

- Cube representation
- Intensity independence ($r+g+b=1$)

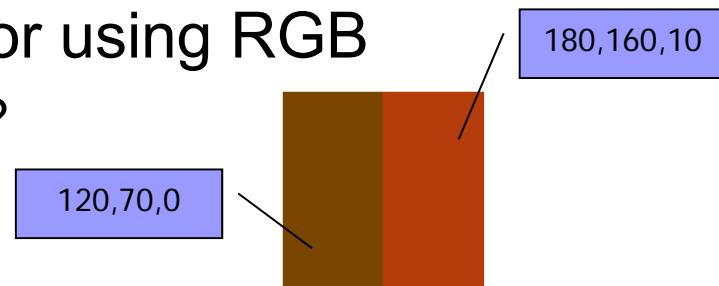
$$r = \frac{R}{R + G + B} \quad g = \frac{G}{R + G + B} \quad b = \frac{B}{R + G + B}$$



Colour spaces

RGB. Problems

- Not able to represent all colors that humans can perceive (ex. RGB monitors)
- Is not easy to express a color using RGB
 - What is RGB value for brown?
- Perceptually not lineal
 - A smaller distance between 2 points in RGB does not mean that are perceptually more similar than 2 points with a larger RGB distance



Colour spaces

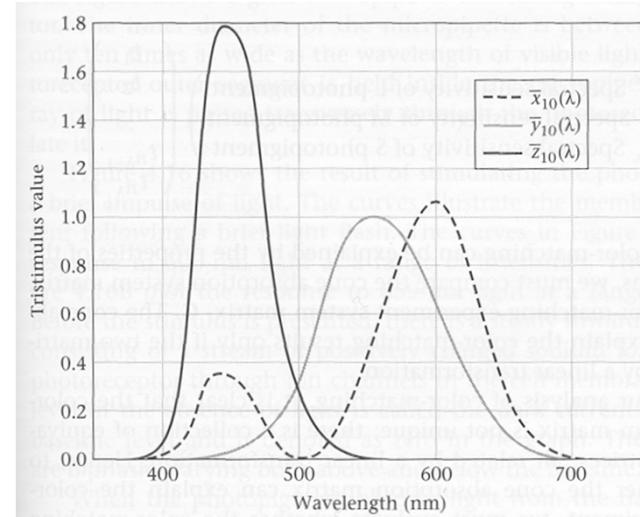
CIE XYZ (1931)

- Positive Color functions
- Origin: Technical developments

- Y component corresponds to intensity
- Conversion from RGB to XYZ considering an illuminant E

$$\begin{bmatrix} X \\ Y \\ Z \end{bmatrix} = \begin{bmatrix} 2.7690 & 1.7518 & 1.1300 \\ 1.0000 & 4.5907 & 0.0601 \\ 0.0000 & 0.0565 & 5.5943 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

$$\forall \lambda \quad E(\lambda) = 1$$



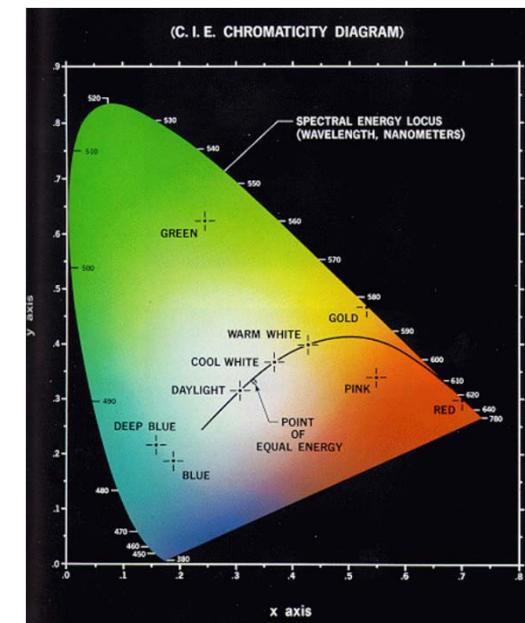
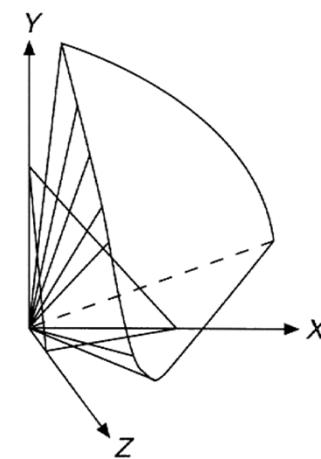
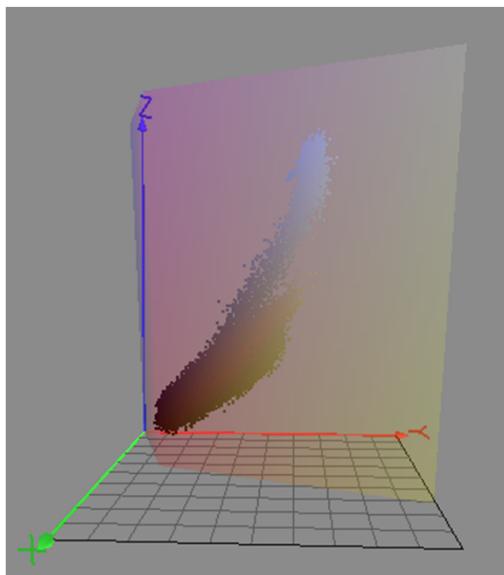
Colour spaces

CIE XYZ (1931)

- Cromacity image: projection X-Y

$$x = X / (X + Y + Z)$$

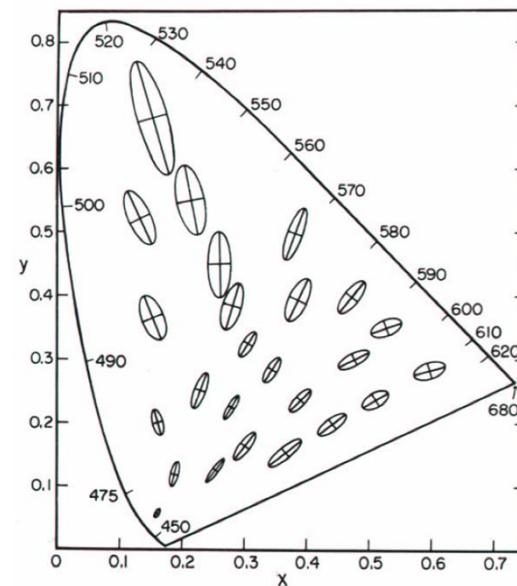
$$y = Y / (X + Y + Z)$$



Colour spaces

CIE XYZ (1931)

- Problem: no linearity with colour perception
- MacAdam Ellipses:
 - Each ellipse denotes colour matching of an observer
- Need of other colour spaces
 - CIELuv
 - CIELab



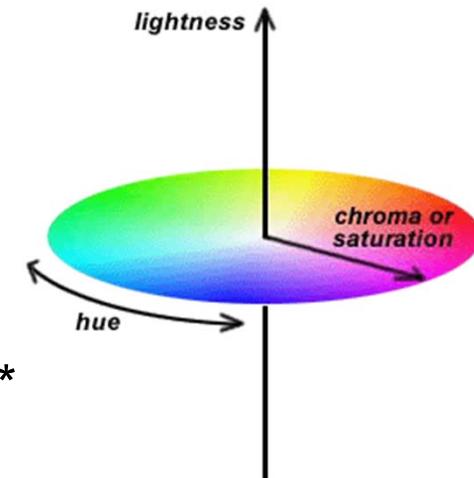
Colour spaces

CIELuv and CIELab

- Measure of light in *L (vertical axes)
- Planes with coordinates (u^*, v^*) or (a^*, b^*)
- Points far from *L axes represent colour
- Measure of cromacity C^* and Hue angle H^*

$$C_{uv}^* = \sqrt{u^{*2} + v^{*2}} \quad h_{uv} = \arctan\left(\frac{v^*}{u^*}\right)$$

$$C_{ab}^* = \sqrt{a^{*2} + b^{*2}} \quad h_{ab} = \arctan\left(\frac{b^*}{a^*}\right)$$

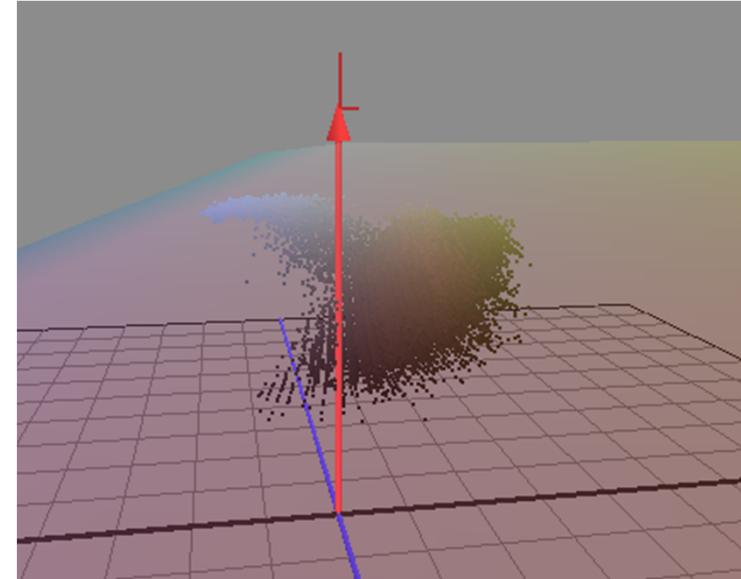
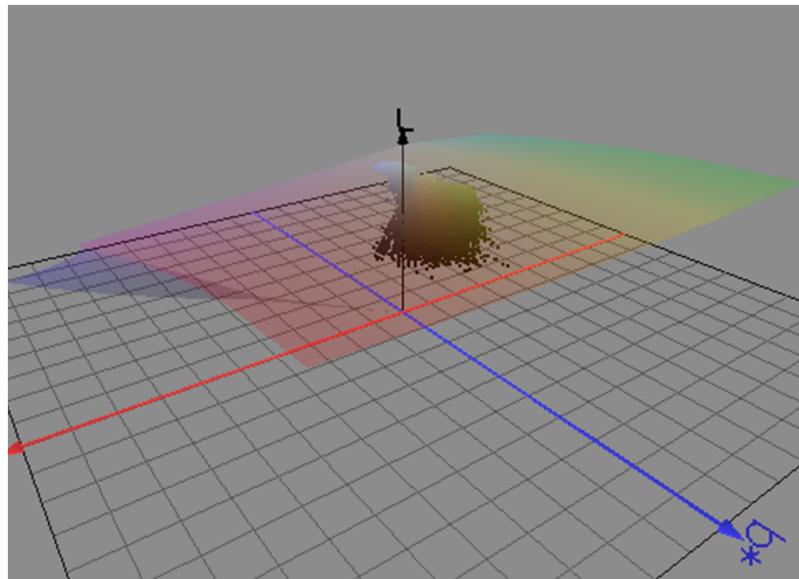


- Colour difference (lineal)

$$\Delta E = \sqrt{\Delta L^2 + \Delta a^2 + \Delta b^2} \quad \text{or} \quad \Delta E = \sqrt{\Delta L^2 + \Delta C_{ab}^{*2} + \Delta h_{ab}^2}$$

Colour spaces

CIELuv and CIELab



Perceptual Colour Spaces

HSI: Hue, Saturation and Intensity

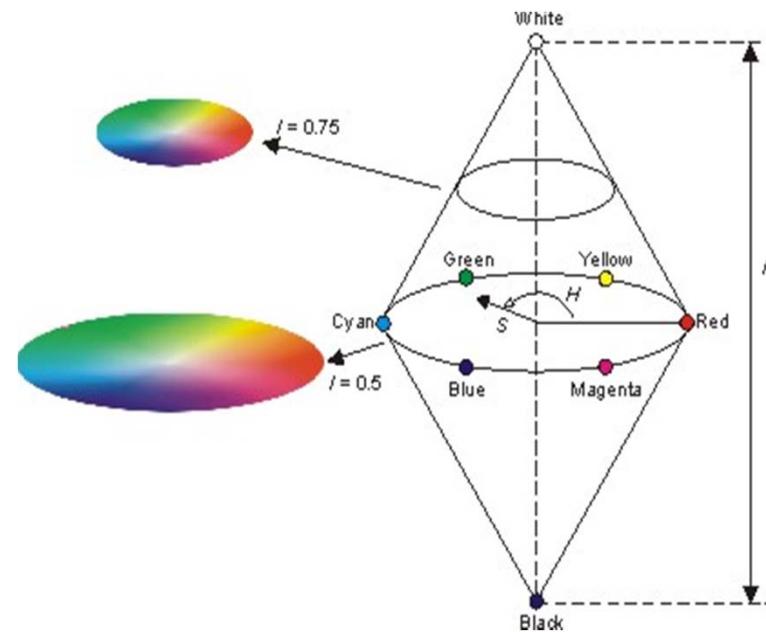
- Intensity: amount of light
- Hue: colour (main wavelength)
- Saturation: colour “purity”

$$I = 1/3(R+G+B)$$

$$S = 1 - \frac{\min(R, G, B)}{I}$$

$$H = \cos^{-1} \left\{ \frac{1/2[(R-G)+(R-B)]}{\sqrt{[(R-G)^2 + (R-B)(G-B)]}} \right\} \text{ if } B < G$$

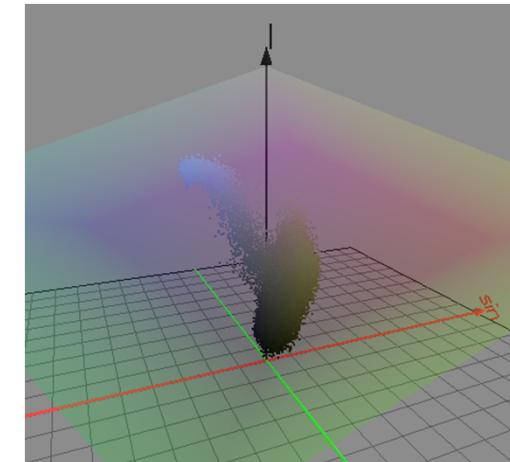
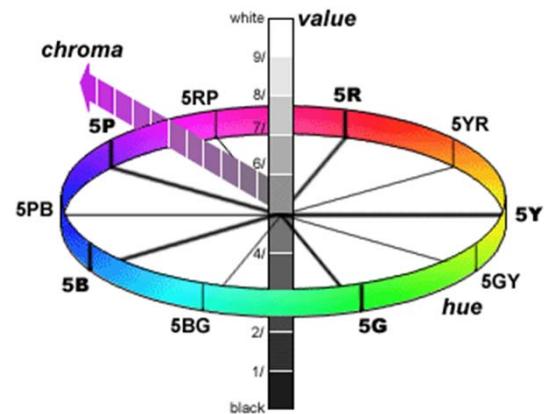
$$H = 360 - \cos^{-1} \left\{ \frac{1/2[(R-G)+(R-B)]}{\sqrt{[(R-G)^2 + (R-B)(G-B)]}} \right\} \text{ if } B > G$$



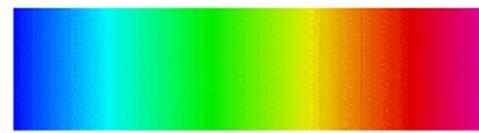
Perceptual Colour Spaces

HSI: Hue, Saturation and Intensity

- More similar to our colour perception
- Various Colour models based on HSI
 - (Munsell –red, yellow, green, blue, purple)



Perceptual Colour Spaces



Hue



Intensity



Saturation

Exemple:



Perceptual Colour Spaces

Espai HSV (Smith):

$$H = \begin{cases} 60 * (b' - g') & \text{if } R = \max(R, G, B) \\ 60 * (2 + r' - b') & \text{if } G = \max(R, G, B) \\ 60 * (4 + r' - g') & \text{if } B = \max(R, G, B) \end{cases}$$

$$S = \frac{\max(R, G, B) - \min(R, G, B)}{\max(R, G, B)}$$

$$V = \max(R, G, B)$$

$$r' = \frac{\max(R, G, B) - R}{\max(R, G, B) - \min(R, G, B)}$$

$$g' = \frac{\max(R, G, B) - G}{\max(R, G, B) - \min(R, G, B)}$$

$$b' = \frac{\max(R, G, B) - B}{\max(R, G, B) - \min(R, G, B)}$$

Espai HSV (Tenenbaum):

$$H = \arctan \left(\frac{\sqrt{3}(G - B)}{2R - G - B} \right) \quad V = \frac{R + G + B}{3}$$

$$S = 1 - 3 * \min \left(\frac{R}{R + G + B}, \frac{G}{R + G + B}, \frac{B}{R + G + B} \right)$$

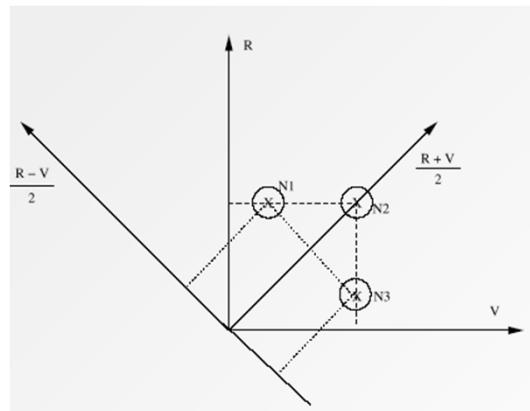
Non Correlated colour spaces

Non correlated

- There is a high correlation (0.78-0.90) between components in some colour spaces, mainly due to the luminosity/Intensity component
- In addition and except for the luminosity, components show little discriminant characteristics (small variance)



$X_1X_2X_3$ Space: Obtain new axes with more uncorrelated and discriminant data using the Karhunen-Loeve transform (KL)



Non Correlated colour spaces

$X_1 X_2 X_3$

Obtain discriminant colour features using the KL transform:

- Compute the covariance matrix of RGB, P matrix
- In general, for P_1, P_2, P_3 colour components

$$\mathbf{P} = \begin{bmatrix} var(P_1) & cov(P_1, P_2) & cov(P_1, P_3) \\ cov(P_1, P_2) & var(P_2) & cov(P_2, P_3) \\ cov(P_1, P_3) & cov(P_2, P_3) & var(P_3) \end{bmatrix}$$

- [Reminder] Variance and covariance of a random variable

$$P(i,j) = 1/N \sum_{k=1}^N (c_k^i - \bar{c}_i)(c_k^j - \bar{c}_j) \quad \text{if } i \neq j$$

$$P(i,i) = 1/N \sum_{k=1}^N (c_k^i - \bar{c}_i)^2$$

Non Correlated colour spaces

$X_1 X_2 X_3$

- KL transform:
 - Compute eigen values ($\lambda_1, \lambda_2, \lambda_3$) and eigen vectors ($\omega_1, \omega_2, \omega_3$) of the covariance matrix P (being $\lambda_1 > \lambda_2 > \lambda_3$)
 - Usually, from the principal axes of the eigen vectors:
 - ω_1 corresponds to the luminance component
 - ω_2, ω_3 corresponds to colour characteristics (usually just using ω_2 to represents the major colour distribution)

$$X_1 = \omega_1^1 P_1 + \omega_1^2 P_2 + \omega_1^3 P_3$$

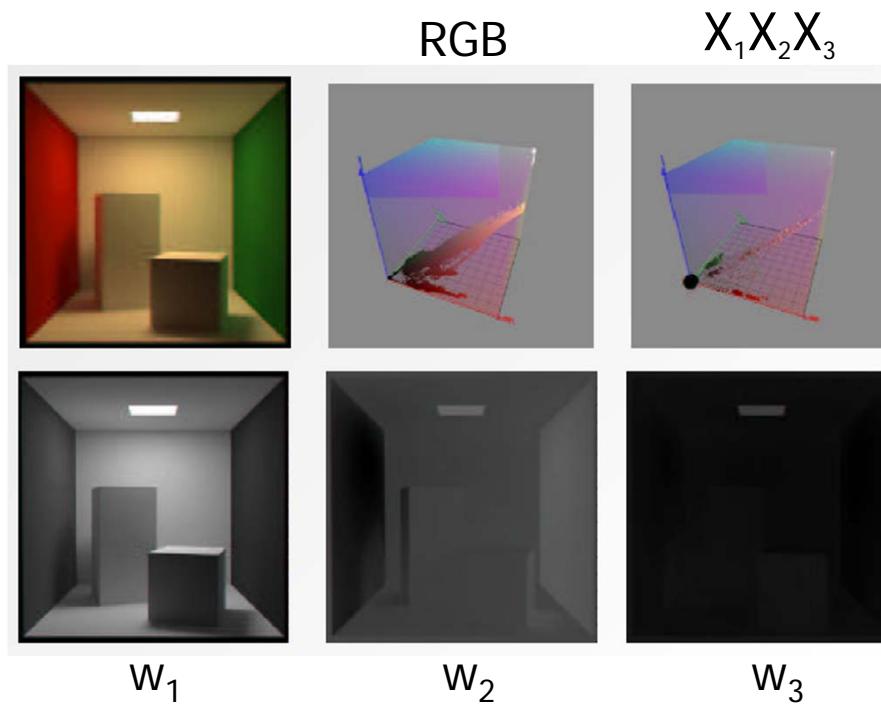
$$X_2 = \omega_2^1 P_1 + \omega_2^2 P_2 + \omega_2^3 P_3$$

$$X_3 = \omega_3^1 P_1 + \omega_3^2 P_2 + \omega_3^3 P_3$$

Non Correlated colour spaces

$X_1 X_2 X_3$: Example of a synthetic image: RGB & $X_1 X_2 X_3$ colour spaces

- W1: Luminosity
- W2: Differential colour between red and green
- W3: Remaining colour information



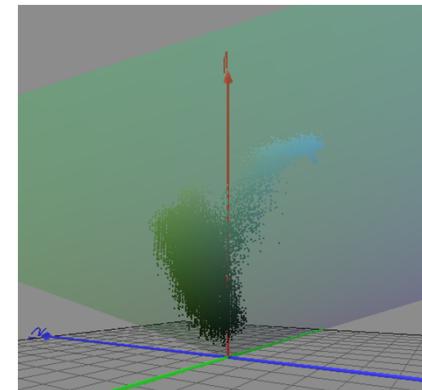
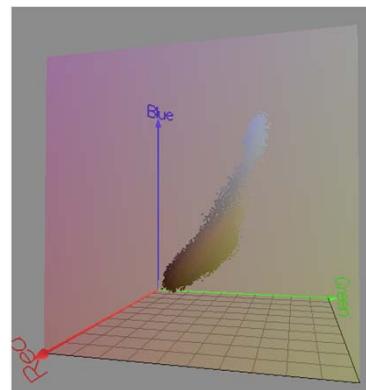
Non Correlated colour spaces

Ohta $I_1 I_2 I_3$

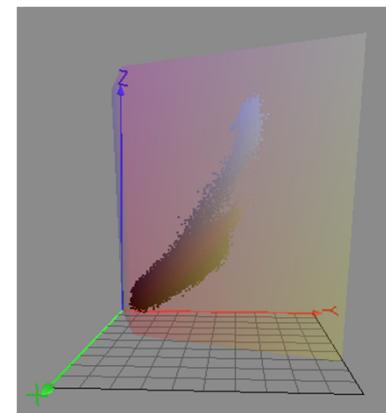
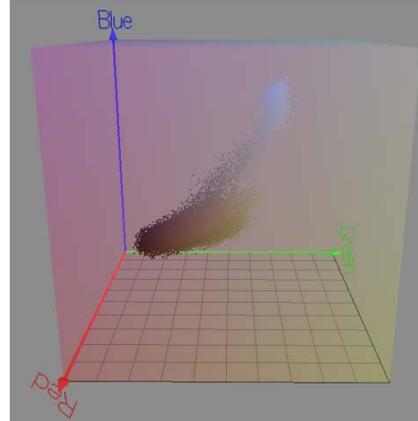
- The KL computation can be approximated by

$$\begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 1/3 & 1/3 & 1/3 \\ 1/2 & 0 & -1/2 \\ -1/4 & 1/2 & -1/4 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

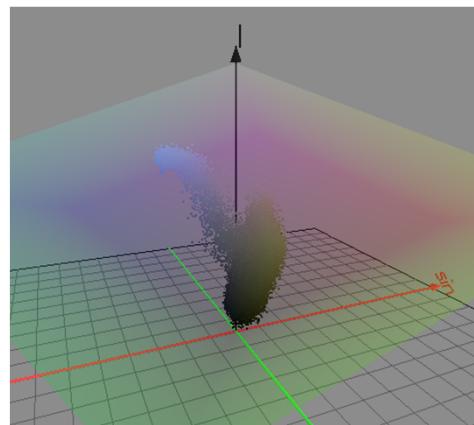
- Reduces the correlation of RGB
- Useful for compression and clustering applications



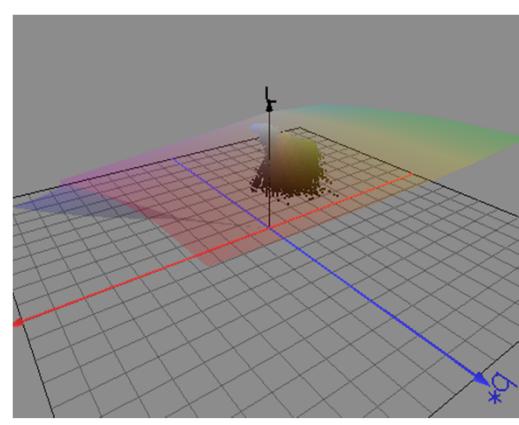
Which colour space?



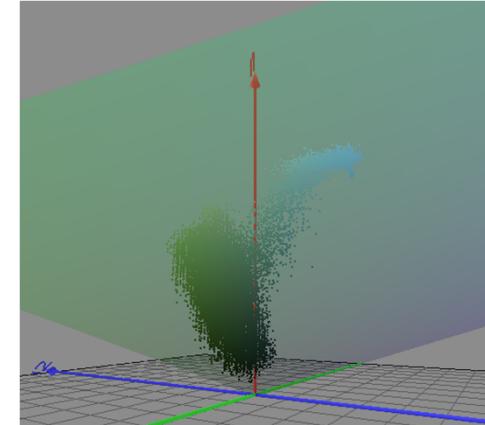
RGB



HSI

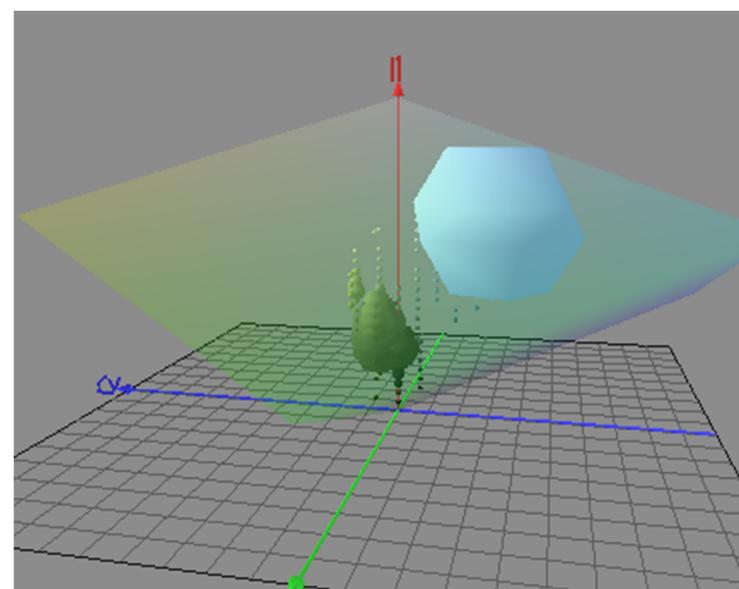
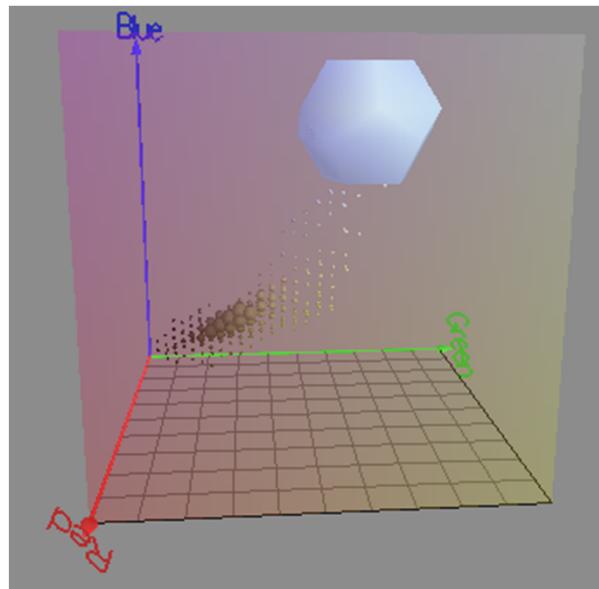


CIELUV



$I_1I_2I_3$

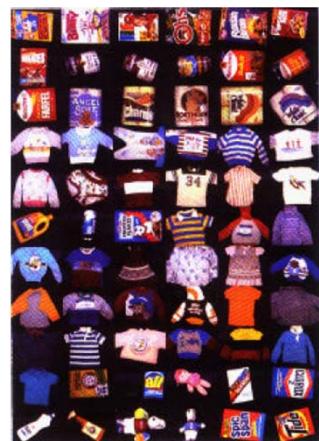
Which colour space?



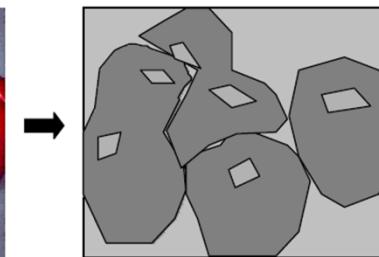
Applications

- Colour applications: along with shape and texture, colour will be used to characterise a region → first step for applications such as
 - Image segmentation and clustering
 - Compression and codification
 - Image recognition and understanding
 - Movement analysis...

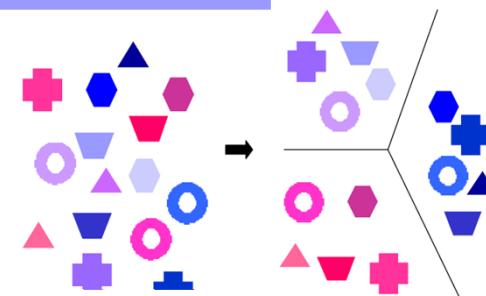
Recognition



Segmentation



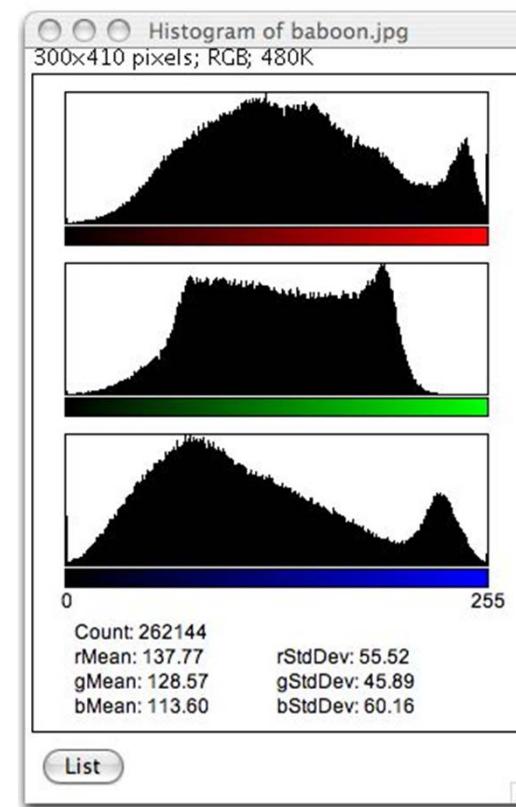
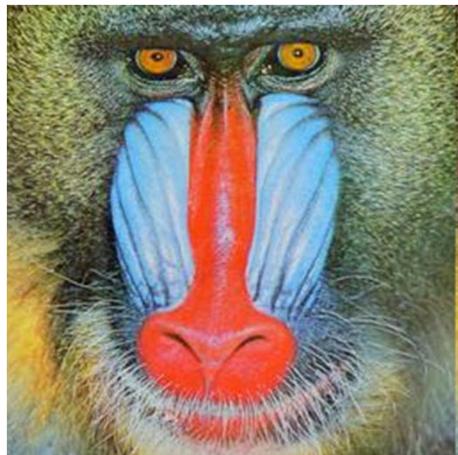
Classification



Extracted from J.Vitrià

Applications

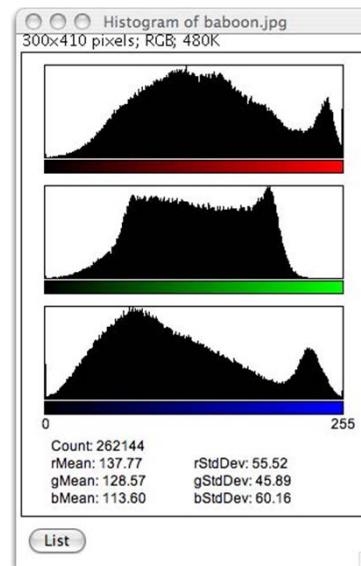
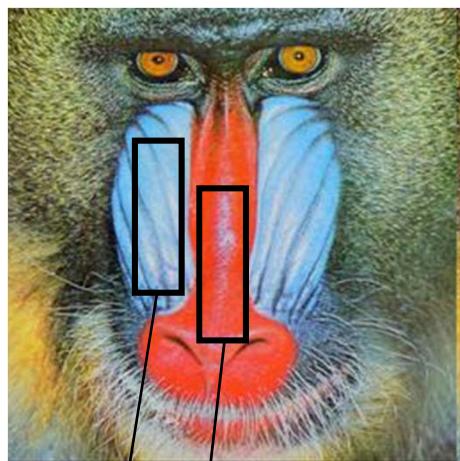
Color histograms for image characterization



Summary. Colour

- There is not an optimum colour space, depends on the application and the type of images used
- We need to know the properties of each colour space
- The selection of a colour space will have an influence on the final results of the application
- Further information on colour:
 - Colour.org color.org
 - <http://www.couleur.org/index.php>

Color characterization



Feature vector 1=[mean R, mean G, mean B, mean H, mean S, mean V, ...]

Feature vector 2=[mean R, mean G, mean B, mean H, mean S, mean V, ...]