

MIA – Medical Image Analysis

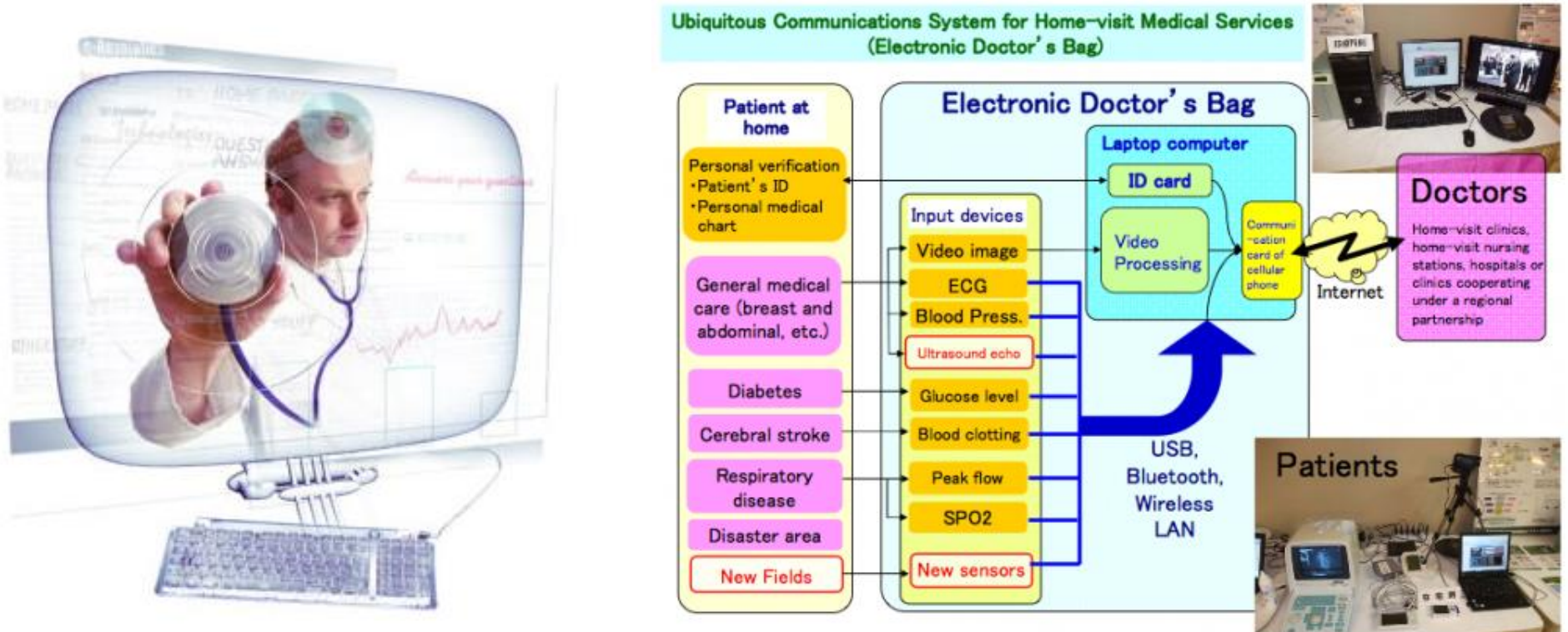
CAD - CARS

CAD: Computer-Aided Diagnosis

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□ Aim:

- ▣ Update the old dream of merging medicine and computer science into an “electronic doctor”.



CAD: Computer-Aided Diagnosis

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- ▣ Stop trying to make computers act like diagnosticians.
- ▣ Develop techniques that can **help radiologists** accurately interpret images and identify potential findings to avoid incorrect interpretation or overlooking of lesions due to subjective judgment.

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- ▣ Update the old dream of merging medicine and computer science into an “electronic doctor”.
- ▣ Stop trying to make computers act like diagnosticians.
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- ▣ **Assist** doctors in the interpretation of medical images.

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□ Historical overview:

- 1959: Early symbolic logic and probability theory to provide diagnoses similar to those speculated by physicians' complex reasoning (Ledley and Lusted).
- 1960s: Early attempts at computerized analysis of medical images.
- 1980s: Serious and systematic investigation on CAD leads to a fundamental change in the concept for utilization of the computer output, from automated computer diagnosis to computer-aided diagnosis.
- 1990s: First scientific evidences for the benefits of CAD in the detection of lesions.

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□ Historical overview:

■ 1990s: First scientific evidences for the benefits of CAD in the detection of lesions:

- Clustered microcalcifications and masses in mammograms
- Lung nodules and interstitial opacities in chest radiographs
- Lung nodules in CT
- Intracranial aneurysms in MRI

■ Current: Practical CAD in screening examinations for the detection of cancer in the breast, lung, and colon.

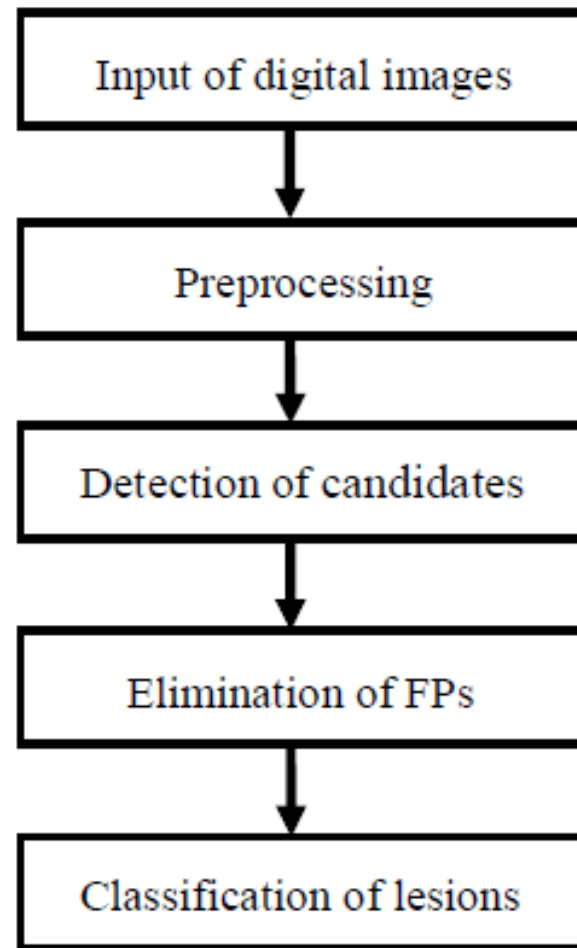
Analysis of performance level in terms of sensitivity at a given false positive ratio per image.

■ Computer-Aided Detection (CAdE) and Diagnosis (CAdx).

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□ Typical flowchart of CAD



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- Components of a CAD systems: restrictions
 - ▣ Not all data from imaging modalities can be obtained in digital formats.
 - ▣ With the use of computed radiography (CR) and flat panel detector (FPD), digitizing images are not longer required.
 - ▣ Important factor for the hardware: **diagnostic time during inspection.**
 - ▣ Computer workstation with powerful calculating capacity.
 - ▣ Some time-consuming calculations could be realized by using hardware instead of software.

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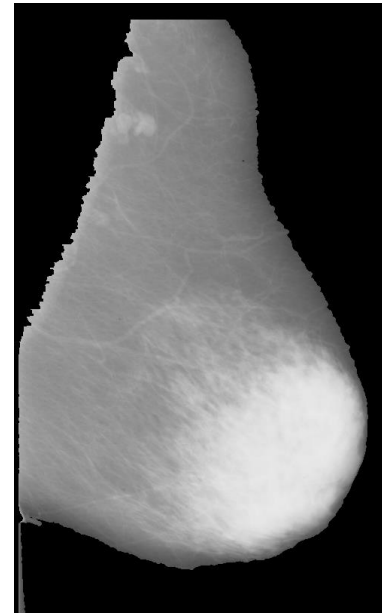
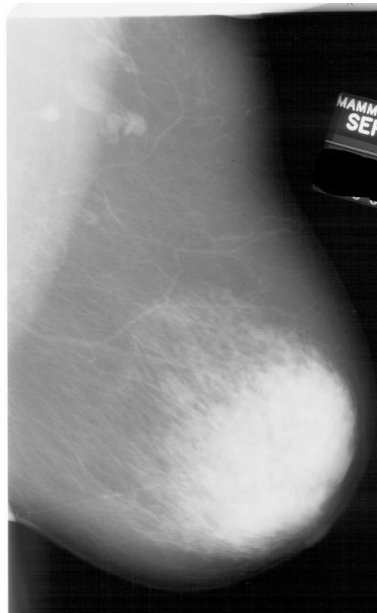
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- Components of a CAD systems:
 - ▣ Image acquisition and **data preprocessing** for noise reduction and removal of artifacts.
 - ▣ Image **extraction** and representation.
 - ▣ Detection of the region of interest (ROI) by **image analysis** on the basis of segmentation and matching.
 - ▣ Evaluation and classification using an appropriate **decision-making** scheme.

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- Image acquisition and data preprocessing:
 - ▣ Image noise reduction.
 - ▣ Removing (reduction) of artifacts: labels, ...
 - ▣ Harmonization of image quality for clearing the image's different basic conditions (exposure parameters).

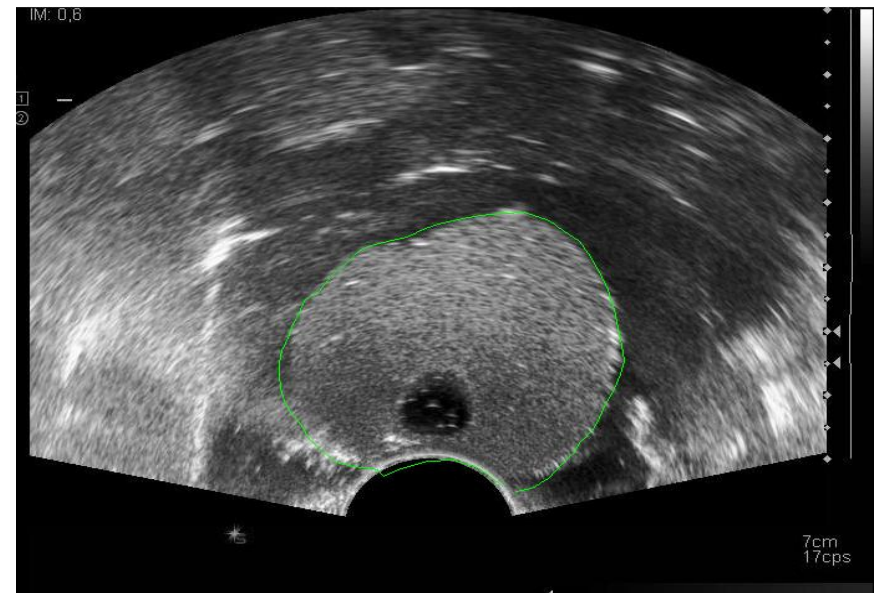
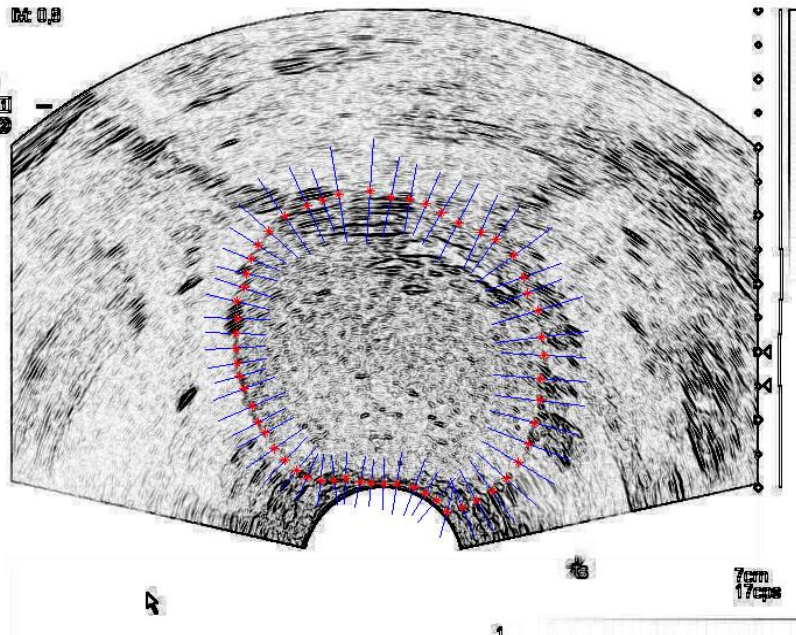


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□ Segmentation:

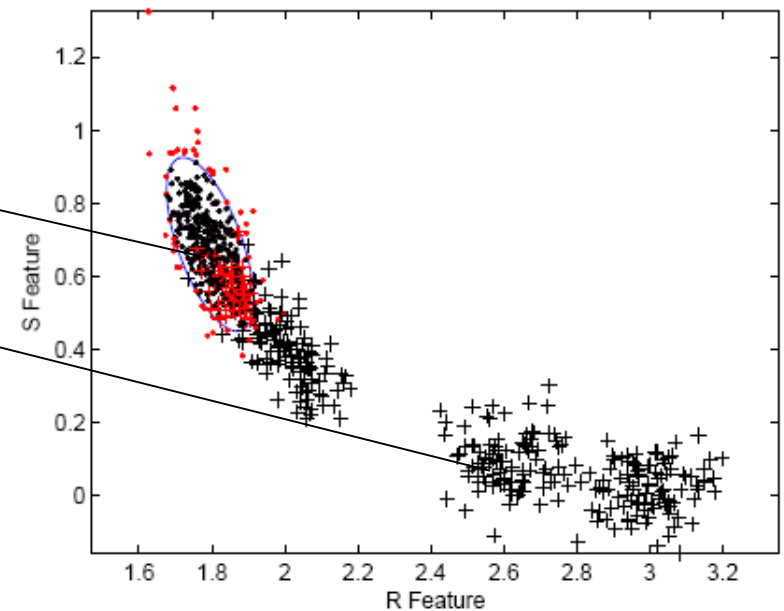
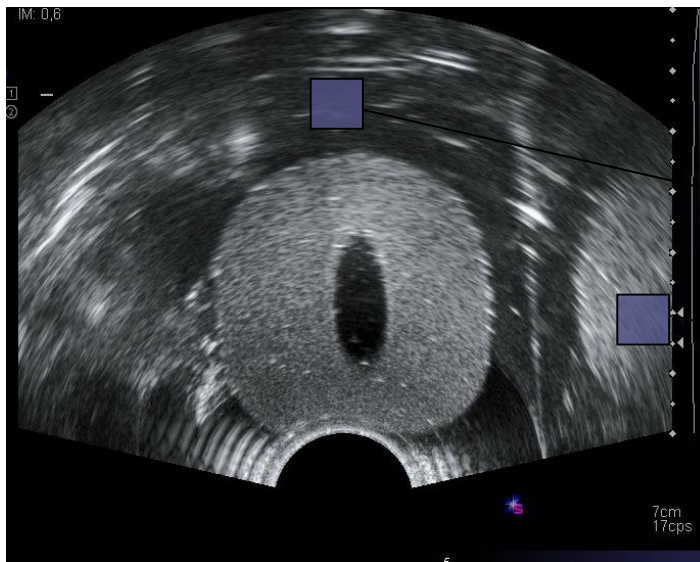
- ▣ Differentiation of structures in the image: heart, lung, prostate, breast, nipple, ...
- ▣ Matching with anatomic databank.



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- Analysis of the region of interest (ROI):
 - ▣ Shape, size and location.
 - ▣ Greylevel values.
 - ▣ Texture analysis.
 - ▣ Reference to close-by structures / ROIs



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□ Evaluation / Classification:

- Every ROI is individually evaluated in order to score for the probability of a TP, according to different procedures:
 - NN rule
 - Minimum distance classifier
 - Bayesian classifier
 - Multilayer perception
 - Support-Vector Machine (SVM)
 - ...

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- Evaluation / Classification:
 - ▣ Sensitivity and specificity
 - ▣ Number of True Positives (TP) and False Positives (FP)
 - ▣ True-negative fraction (TNF) and False-negative fraction (FNF)
 - ▣ FP/image
 - ▣ ROC (Receiver Operating Characteristic)
 - ▣ FROC (Free-Response Receiver Operating Characteristic)
 - ▣ A_z /AUC (Area under the curve)
 - ▣ Recall rate

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- Commercial CAD products:
 - ImageCheckerTM (mammography, produced by R2 Technology, USA).
 - SecondLookTM (mammography, produced by iCAD Technology, USA).
 - CADStreamTM (breast MRI, produced by Confirma, USA).
 - RapidScreenTM (lung cancer, produced by Riverain Medical, USA).
 - MeVis VisiaTM CT Lung System (lung cancer, produced by Mevis Medical Solutions AG, Germany).

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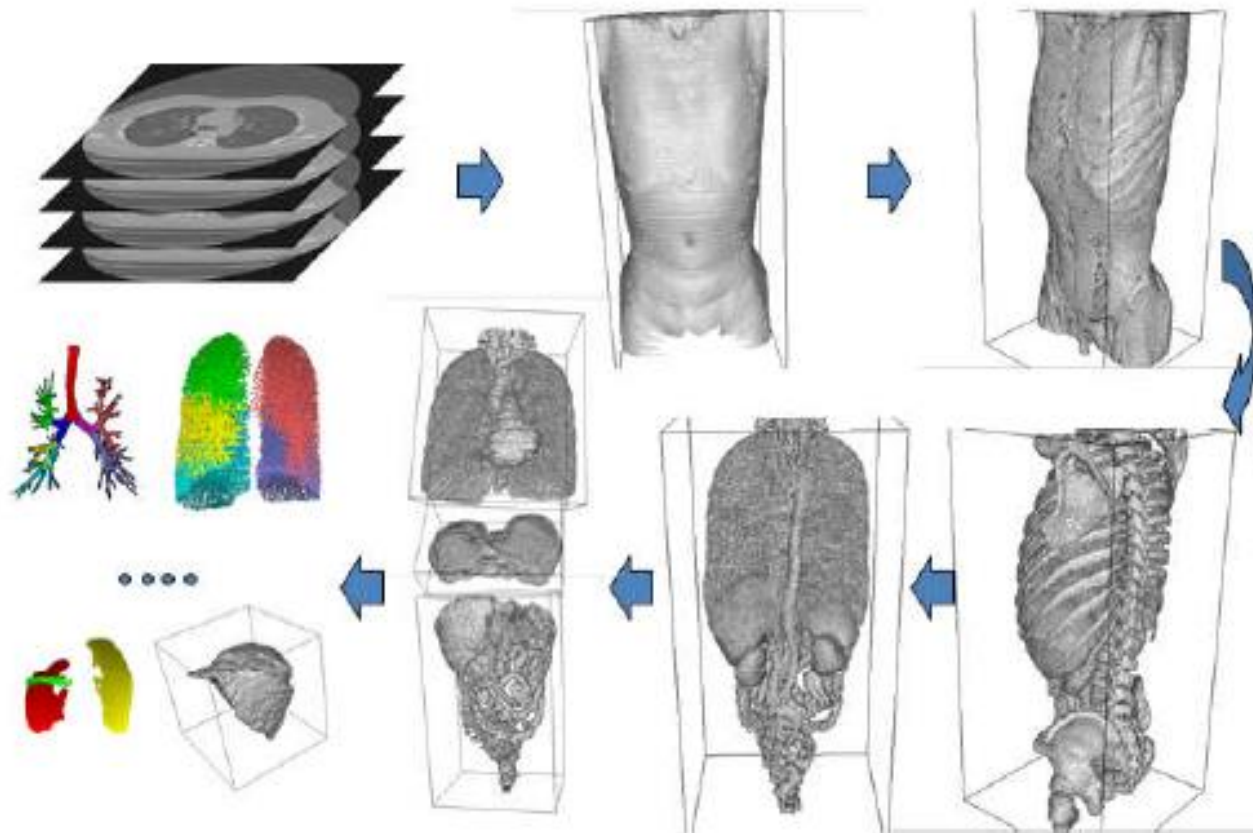
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- Experimental CAD products:
 - ▣ Intelligent Assistance in diagnosis of Multi-dimensional Medical Images project (Gifu University, Japan).
 - ▣ CAD for dental panoramic radiography (City Area Program in Japan).
 - ▣ Automatic Breast Ultrasound – ABUS (Radboud University Nijmegen, The Netherlands).
 - ▣ Multi-view and temporal mammographic system (Universitat de Girona, Catalonia).
 - ▣ Interactive CAD.

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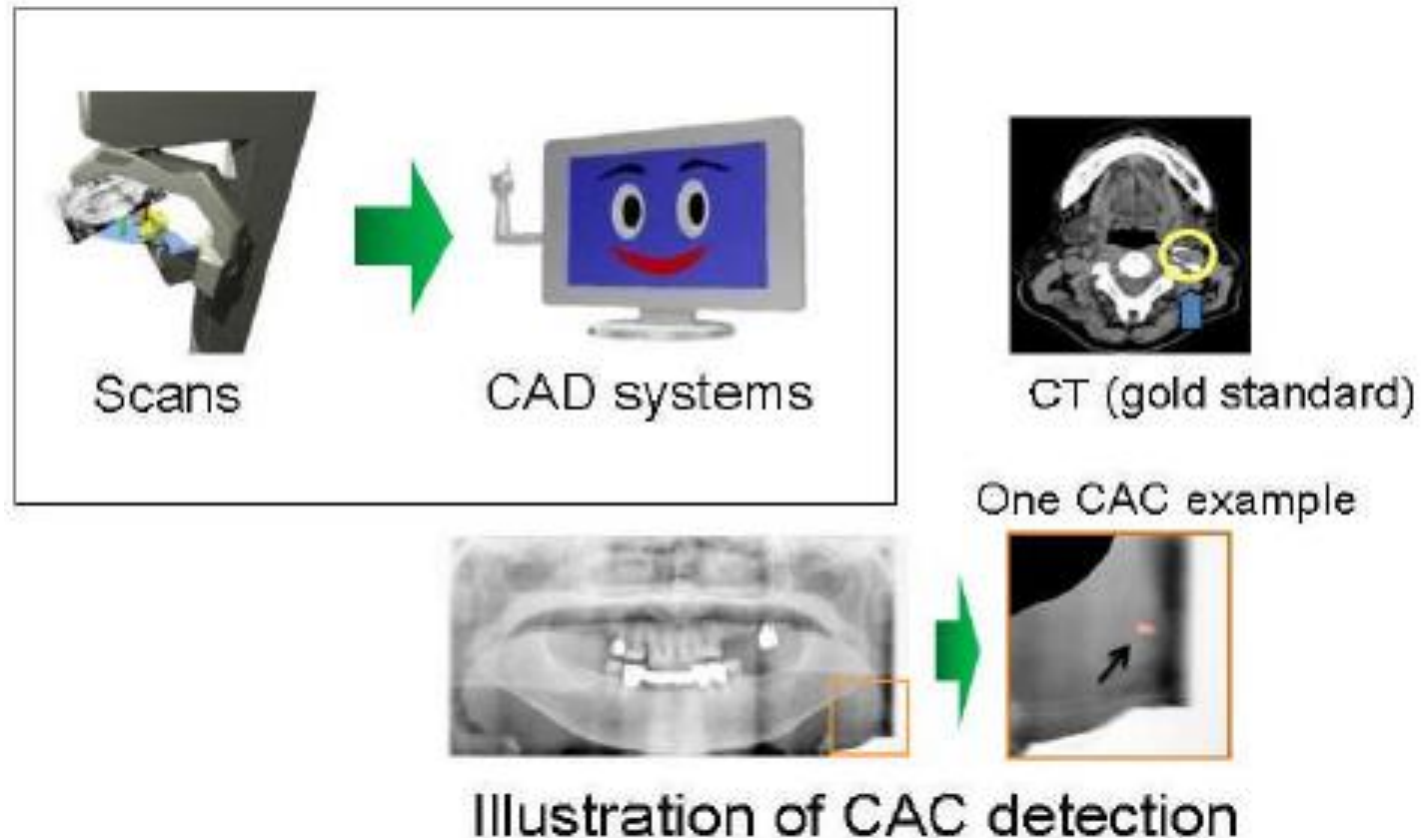
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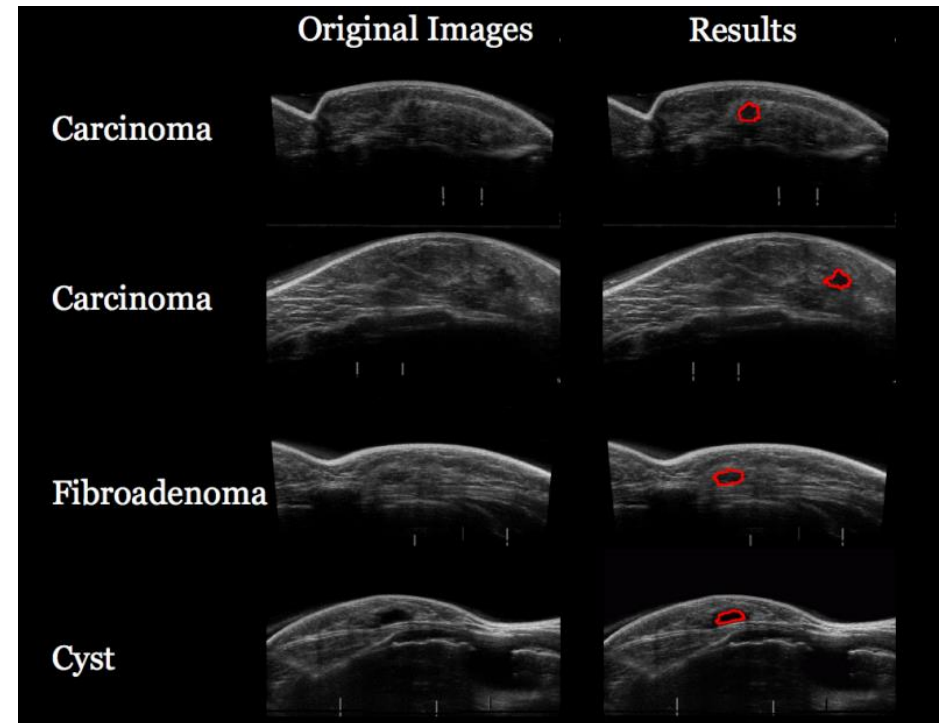
- Experimental CAD products:
 - ▣ CAD for dental panoramic radiography (City Area Program in Japan).



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- Experimental CAD products:
 - Automatic Breast Ultrasound – ABUS (Radboud University Nijmegen, The Netherlands).
 - Whole breast (109 Vol, 80% sens @ 3.8 FP/vol).



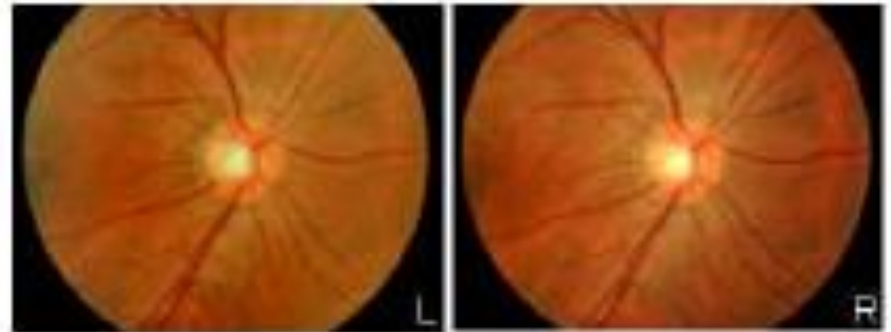
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- Experimental CAD products:
 - ▣ Retinal fundus images (Kowa Company, Japan).



Stereo Fundus Camera

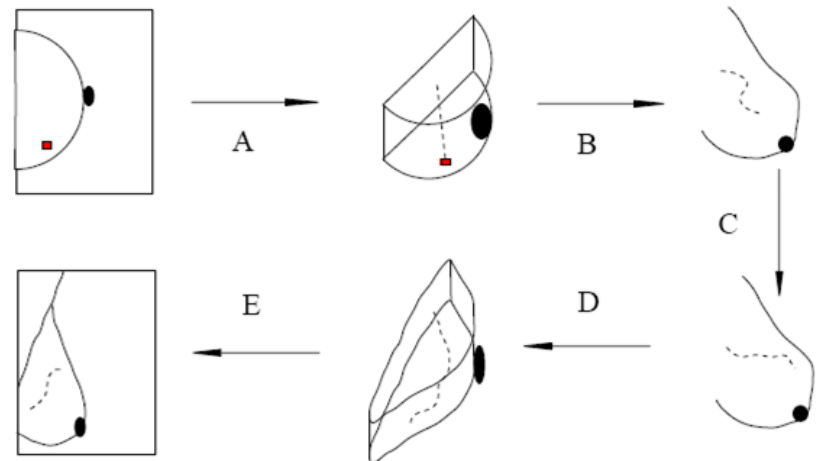
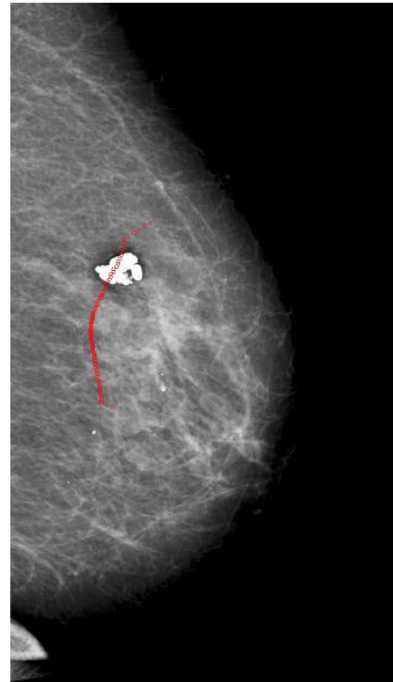


Stereo Fundus Image Pair

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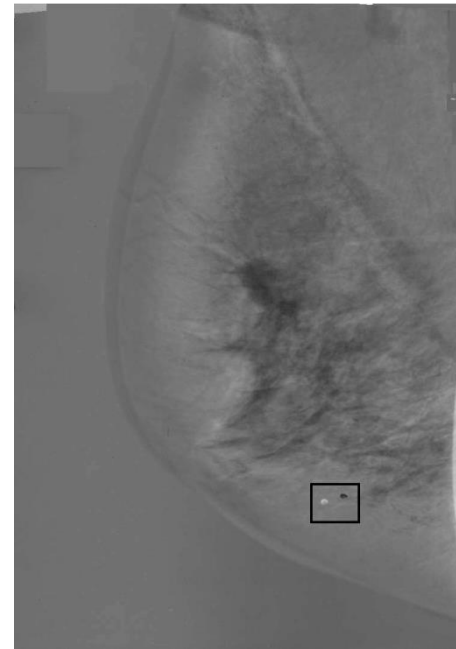
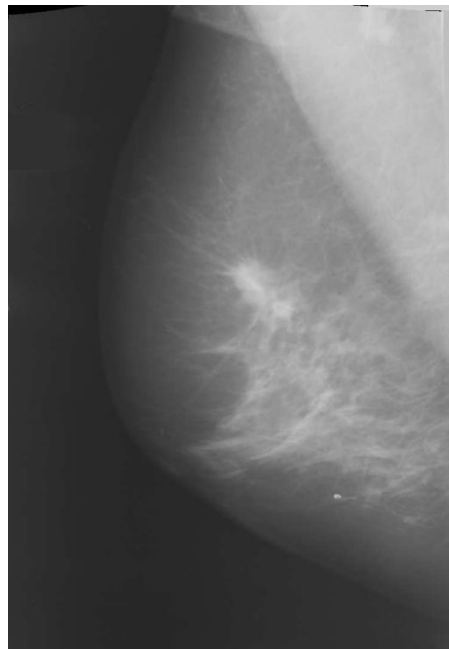
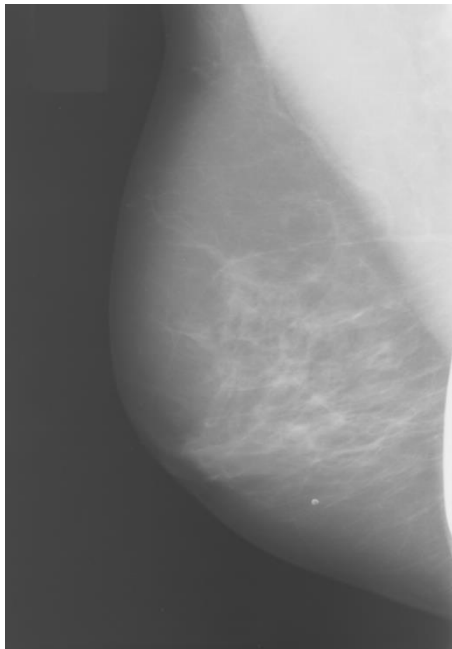
- Experimental CAD products:
 - ▣ Multi-view and temporal mammographic system (Universitat de Girona, Catalonia).
 - ▣ CC-MLO correspondence.



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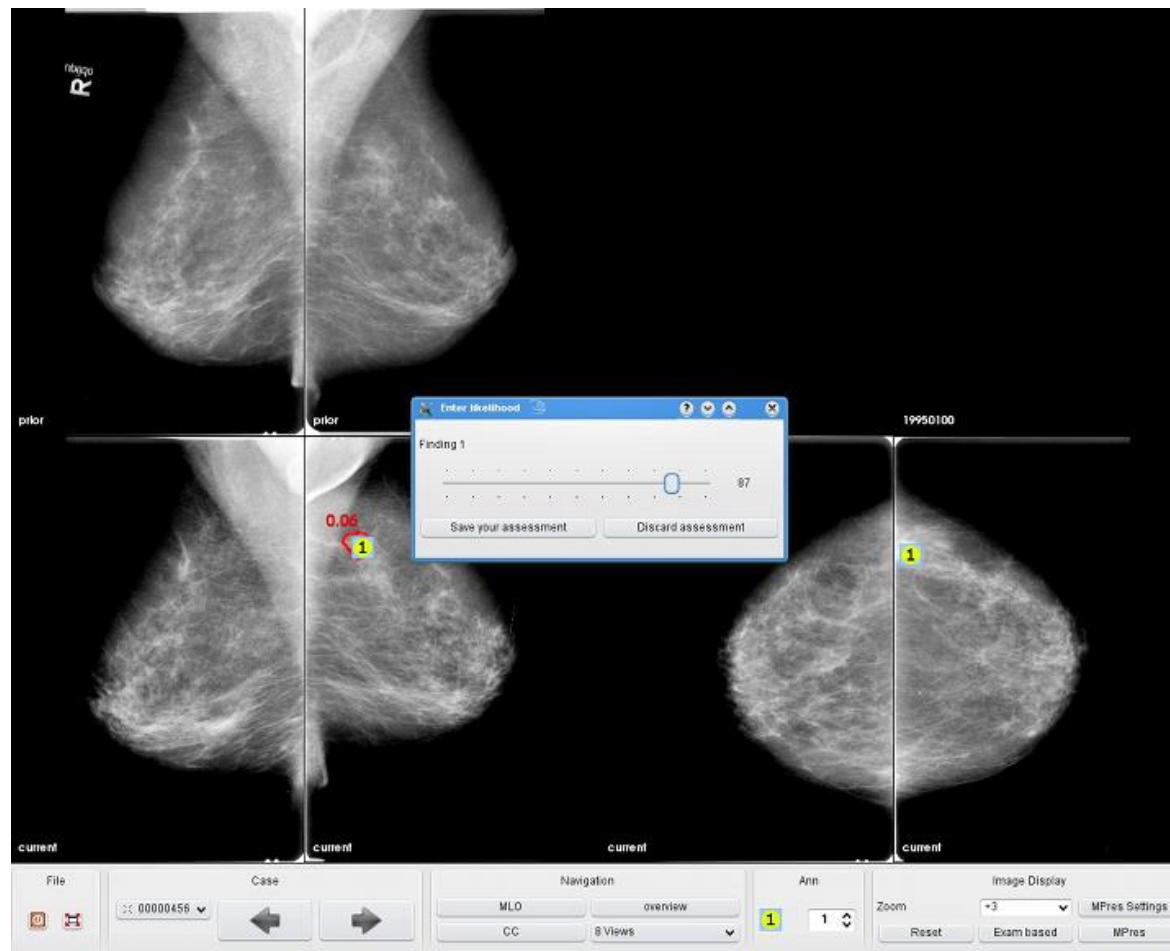
- Experimental CAD products:
 - ▣ Multi-view and temporal mammographic system (Universitat de Girona, Catalonia).
 - ▣ Image Registration.



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- Experimental CAD products:
 - ▣ Interactive CAD



References

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- “Computer-Aided Diagnosis in Medical Imaging: Historical Review, Current Status and Future Potential”. Kunio Doi. Computerized Medical Imaging and Graphics 31 (2007), 198-211.
- “An Introduction and Survey of Computer-Aided Detection/Diagnosis (CAD)”. Hiroshi Fujita et al. 2010 International Conference on Future Computer, Control and Communication, 200-205.
- “Computer-Aided Diagnosis: How to Move from the Laboratory to the Clinic”. Bram van Ginneken et al. Radiology: vol 261, number 3, December 2011, 719-732.
- “Clinically Missed Cancer: How Effectively Can Radiologists Use Computer-Aided Detection?” Robert M. Nishikawa et al. AJR: 198, March 2012, 708-716.

CARS: Computer-Assisted Radiology and Surgery

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- Robotics in Medicine
- Rehabilitation and Assistant Robots
- Robotics in Surgery

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□ Robotics in Medicine

▣ Motivation:

- Need of improvement of surgical and diagnostic procedures.
- Need of increasing the capabilities of disabled people.
- Need of improving rehabilitation techniques.

▣ Systems / Technologies:

- Robots
- Perception systems
- Interaction devices and interfaces

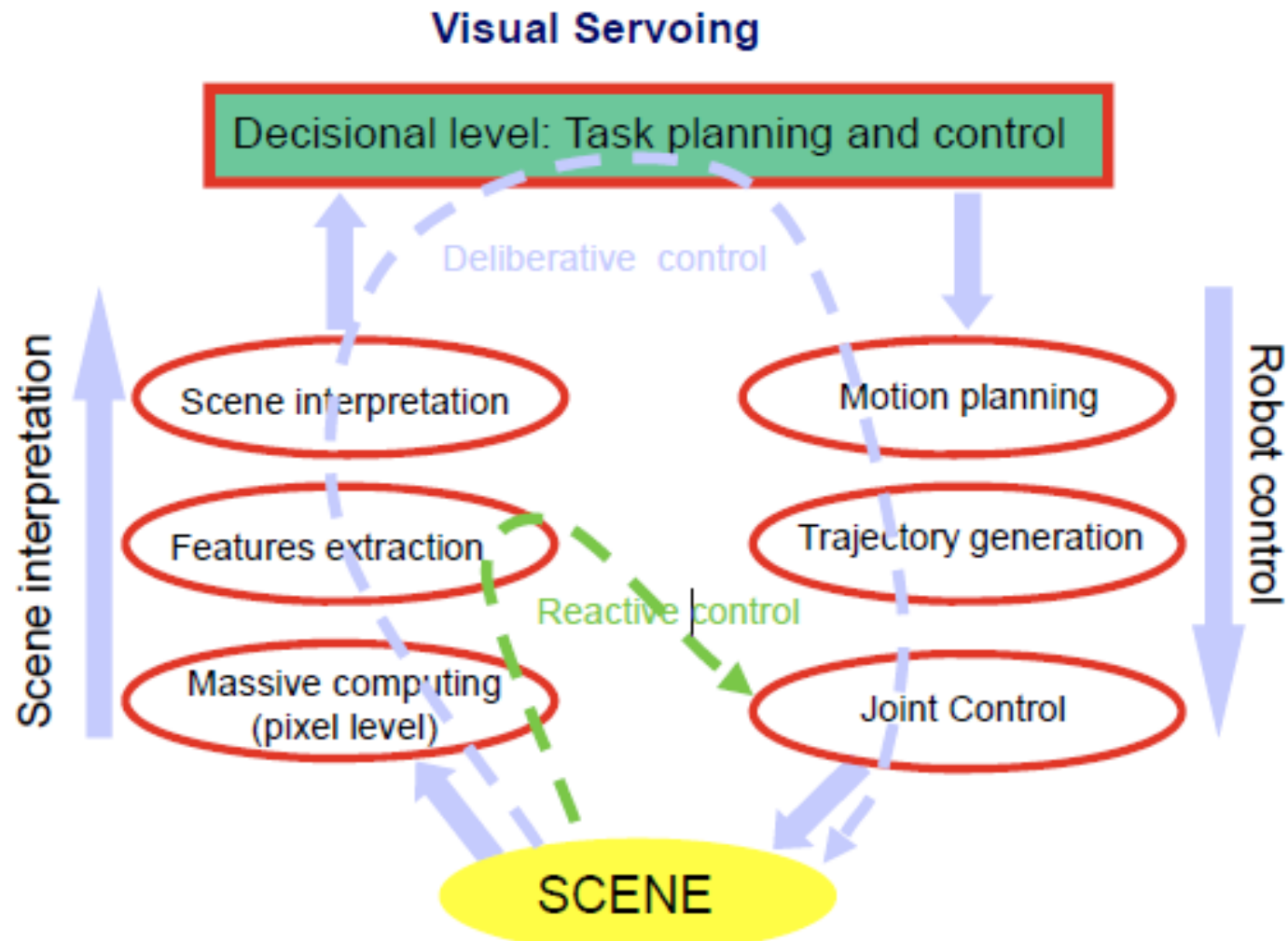
▣ Human-Robot Cooperation levels

- Manual operation
- Teleoperation
- Synergistic-Shared control
- Autonomous

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□ Robotics in Medicine



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□ Rehabilitation and Assistant Robots

- ▣ Robotics and disability
- ▣ Rehabilitation robotics
- ▣ Prosthetic and orthotic devices
- ▣ Assistant robots
- ▣ Human machine interface

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□ Rehabilitation and Assistant Robots



Hand exerciser (Salford University, 2004)
4 fingers, 7 DoF. Finger flexion monitoring



Cyberhand



Stand-alone assistant robot:
ProVAR Professional Vocational
Assistant Robot, Stanford
University, 1998). Industrial robot
arm PUMA 260 used. PC interface

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- Robotics in Surgery:
 - ▣ CAS: Computer Aided Surgery
 - ▣ MIS: Minimally Invasive Surgery
 - ▣ IOR: Intelligent Operating Room

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□ Robotics in Surgery:

- ▣ Hard tissues: non deformable and static.
- ▣ Hard tissues: non deformable but not fixed frames.
- ▣ Soft tissues: Deformable part and not fixed references



Stereotaxis



Variable reference frames

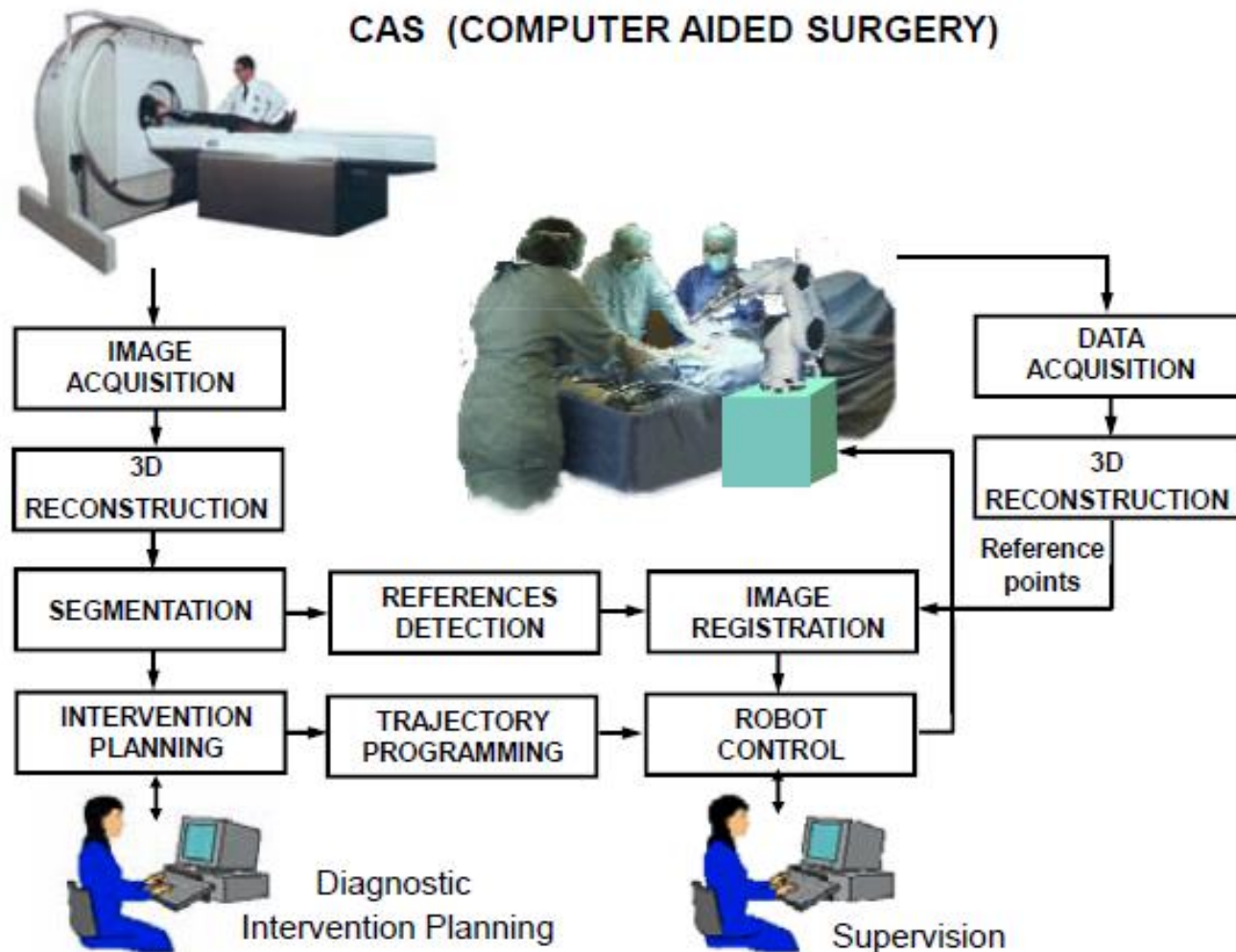


Variable RF &
deformable

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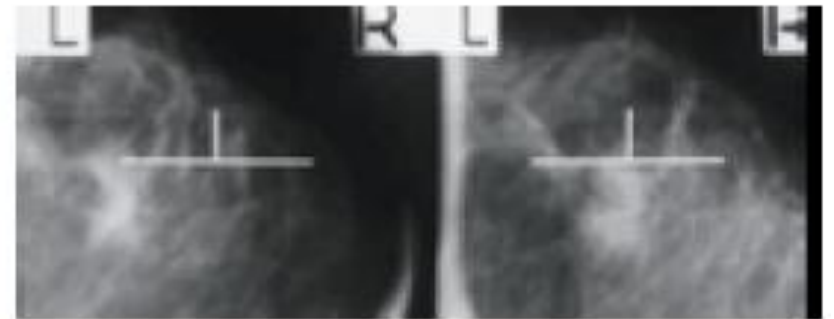
□ Robotics in Surgery:



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- Robotics in Surgery:
 - ▣ Image guided surgery: mammographic biopsy



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□ Robotics in Surgery:

- ▣ Motion compensation in minimally invasive heart surgery

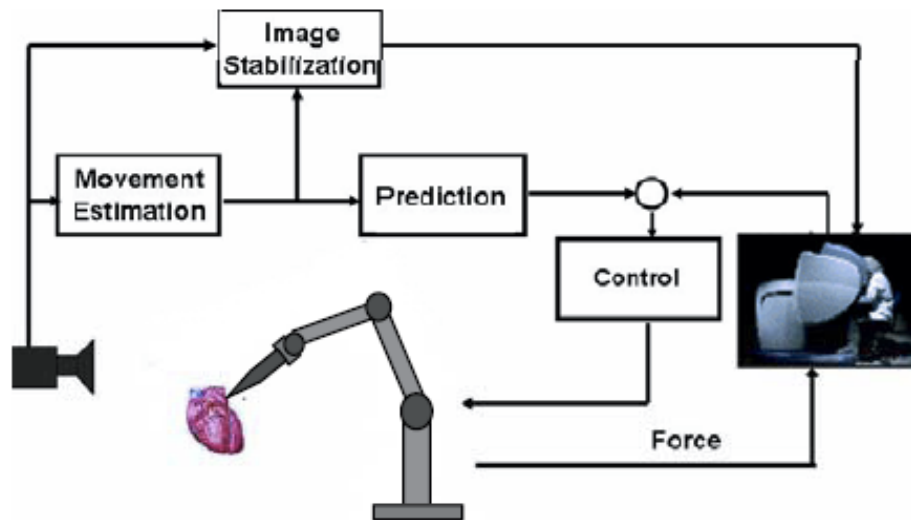


Image Processing



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□ Robotics in Surgery:

- ▣ Da Vinci: teleoperated robot 3 arms, 3D imaging, laparoscopic surgery, prostate surgery



Robot



Set-up



H-M interface



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- Robotics in Surgery: Da Vinci surgical robot

<http://www.youtube.com/watch?v=RJcRABevyCk>



References

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Questions?