

Kepler's Prod



Kepler's Prediction Problem:

3 major concepts related to TOF:

1. How long does it take to get between 2 locations on an orbit?

\Rightarrow TOF eqn

Known: OE, \vec{r}_0 , \vec{r}_1 Unknown: TOF

2. Given an orbit & an initial state, where will the s/c be at some later time?

\Rightarrow Kepler's Pred Prob

Known: OE, \vec{r}_0 , TOF Unknown: \vec{r}_1

3. Given 2 positions & a TOF, what is the orbit?

\Rightarrow Lambert's Prob (also relevant to maneuver design)

Known: \vec{r}_0 , \vec{r}_1 , TOF Unknown: OE's

Kepler's Prediction Problem:

Known: OE, \vec{r}_0 , TOF \rightarrow Find \vec{r}_1

Unfortunately, there is no analytical solution to this problem. Must Iterate.

Given $v_0 \rightarrow E_0$ (Eccentric Anomaly)

M = Mean anomaly (rad) = angular location of the s/c if it's angular velocity were constant

$$= n(t - T)$$

$$n = \text{mean motion} = \sqrt{\frac{\mu}{a^3}}$$

$t - T$ = time since last periastris passage.

$$M = E - e \sin E$$

Known: OE's $\Rightarrow n$

TOF is known

Thus: ΔM is known: $M_1 = M_0 + n(\text{TOF})$

If M_1 is known, solve for E_1 (E_1 = location of the s/c \vec{r}_1)

But: $M = E - e \sin E \leftarrow$ cannot be solved analytically for E . Must solve iteratively

Will not go thru the full derivation.

Algorithm for Solving Kepler's Prediction Prob:

1. Guess x_n (a function of s/c position)
2. Calculate $t_n = f(x_n)$
3. If $(t_i - t_n) > \text{tolerance}$
Calculate x_{n+1}
4. Repeat steps 2 & 3 until $(t_i - t_n) \leq \text{tolerance}$
5. Calculate \vec{r}_i & \vec{v}_i using Lagrange Coefficients (which are a f(x_n))

$$\text{Define } \tilde{x} = \sqrt{\mu}/r$$

Pseudo-Code:

Input: $\vec{r}_0, \vec{v}_0, \Delta t$

$$\mathcal{E} = \frac{v_0^2}{2} - \frac{\mu}{r_0} \rightarrow \text{tells us the type of Conic}$$

$$\text{Solve for } a: \mathcal{E} = -\frac{\mu}{2a}$$

If Circle or Ellipse:

$$x_n = \frac{\sqrt{\mu}}{a} \Delta t$$

If parabola:

$$h = \vec{r}_0 \times \vec{v}_0$$

$$p = h^2/\mu$$

$$\cos(2s) = 3\sqrt{\frac{a}{p^3}} \Delta t$$

$$\tan^3(w) = \tan(s)$$

$$x_n = \sqrt{p} 2 \cot(2w)$$

s & w here are just intermediate variables (not OE's)

If hyperbola:

$$x_n = \text{sign}(\Delta t) \sqrt{-a} \ln \left[\frac{-2\mu \Delta t/a}{(\vec{r}_0 \cdot \vec{v}_0) + \text{sign}(\Delta t) \sqrt{-\mu a} (1 - r_0/a)} \right]$$

$$\psi = x^2/a$$

Calculate C & S :

if $\Psi > 1E-6$

$$C = \frac{1 - \cos(\sqrt{\Psi})}{\Psi}$$

$$S = \frac{\sqrt{\Psi} - \sin(\sqrt{\Psi})}{\sqrt{\Psi^3}}$$

elseif $\Psi < -1E-6$

$$C = \frac{1 - \cosh(\sqrt{-\Psi})}{\Psi}$$

$$S = \frac{\sinh(\sqrt{-\Psi}) - \sqrt{-\Psi}}{\sqrt{(-\Psi)^3}}$$

else $C = 1/2$

$S = 1/6$

while $|t - \Delta t| > 10 \text{ sec}$ (You can play with this tolerance)

(Need to update χ)

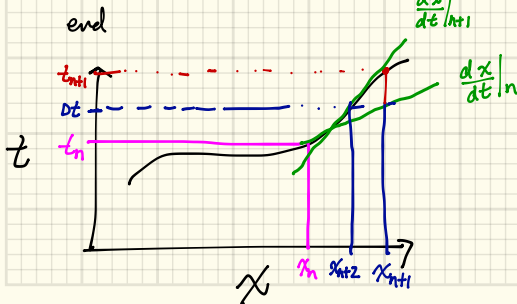
$$r = \chi^2 C + \frac{\vec{r}_0 \cdot \vec{v}_0}{\sqrt{\mu}} \chi (1 - \Psi S) + r_0 (1 - \Psi C)$$

$$\frac{d\chi}{dt} = \sqrt{\mu}/r$$

$$t = \frac{1}{\sqrt{\mu}} \left[\chi^3 S + \frac{\vec{r}_0 \cdot \vec{v}_0}{\sqrt{\mu}} \chi^2 C + r_0 \chi (1 - \Psi S) \right]$$

$$\chi_{n+1} = \chi_n + (\Delta t - t) \frac{d\chi}{dt} \quad (\text{updates } \chi)$$

$$\chi_{n+1} = \chi_n + \frac{d\chi}{dt} \Big|_n (\Delta t - t_n)$$



Newton-Raphson Method to update χ_n .

Lagrange Coefficients:

$$f = 1 - \frac{\chi^2}{r_0} C$$

$$g = t - \frac{\chi^2}{\sqrt{\mu}} S$$

$$\dot{f} = \frac{\sqrt{\mu}}{r_0 r} \chi (\psi S - 1)$$

$$\dot{g} = 1 - \frac{\chi^2}{r} C$$

Output: $\vec{r} = f \vec{r}_0 + g \vec{v}_0$

$$\vec{v} = \dot{f} \vec{r}_0 + \dot{g} \vec{v}_0$$