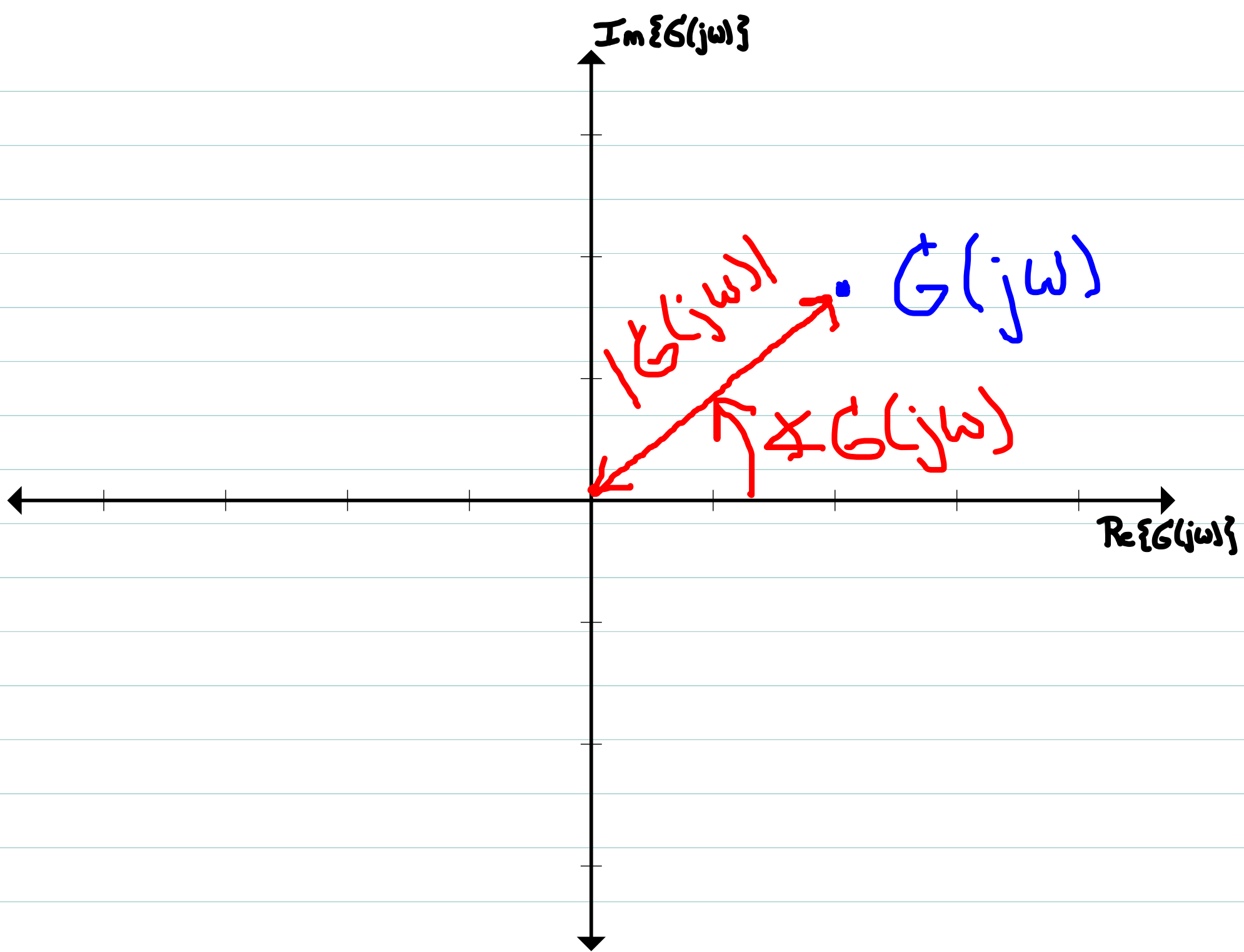


Polar Plots

- => A different way of showing the properties of $G(j\omega)$
- => Bode plots $|G(j\omega)|$ and $\angle G(j\omega)$ vs. ω , using logarithmic scales for $0 \leq \omega < \infty$
- => Polar shows $G(j\omega)$ as points on complex plane as ω VARIES from 0 to ∞ using actual (non-logarithmic) scales
- => Learn to sketch polar from Bode
- => We are aiming for something qualitatively correct, but will deliberately distort scales to make certain critical features readily apparent.



\Rightarrow For each $\omega \in [0, \infty)$, $G(j\omega)$ is a different point on Complex plane

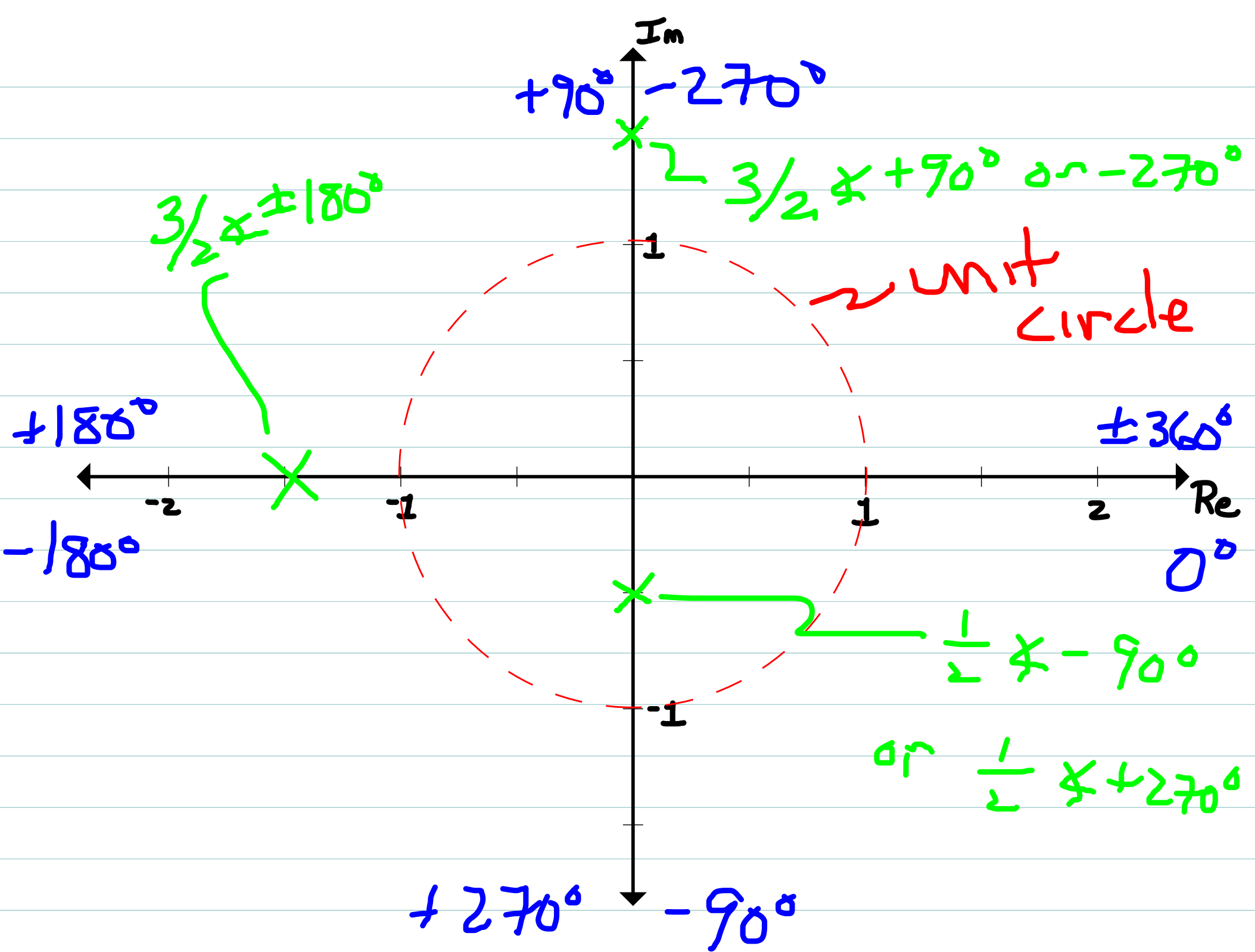
\Rightarrow As ω varies from 0 to ∞ , these points will trace out a curve on complex plane.

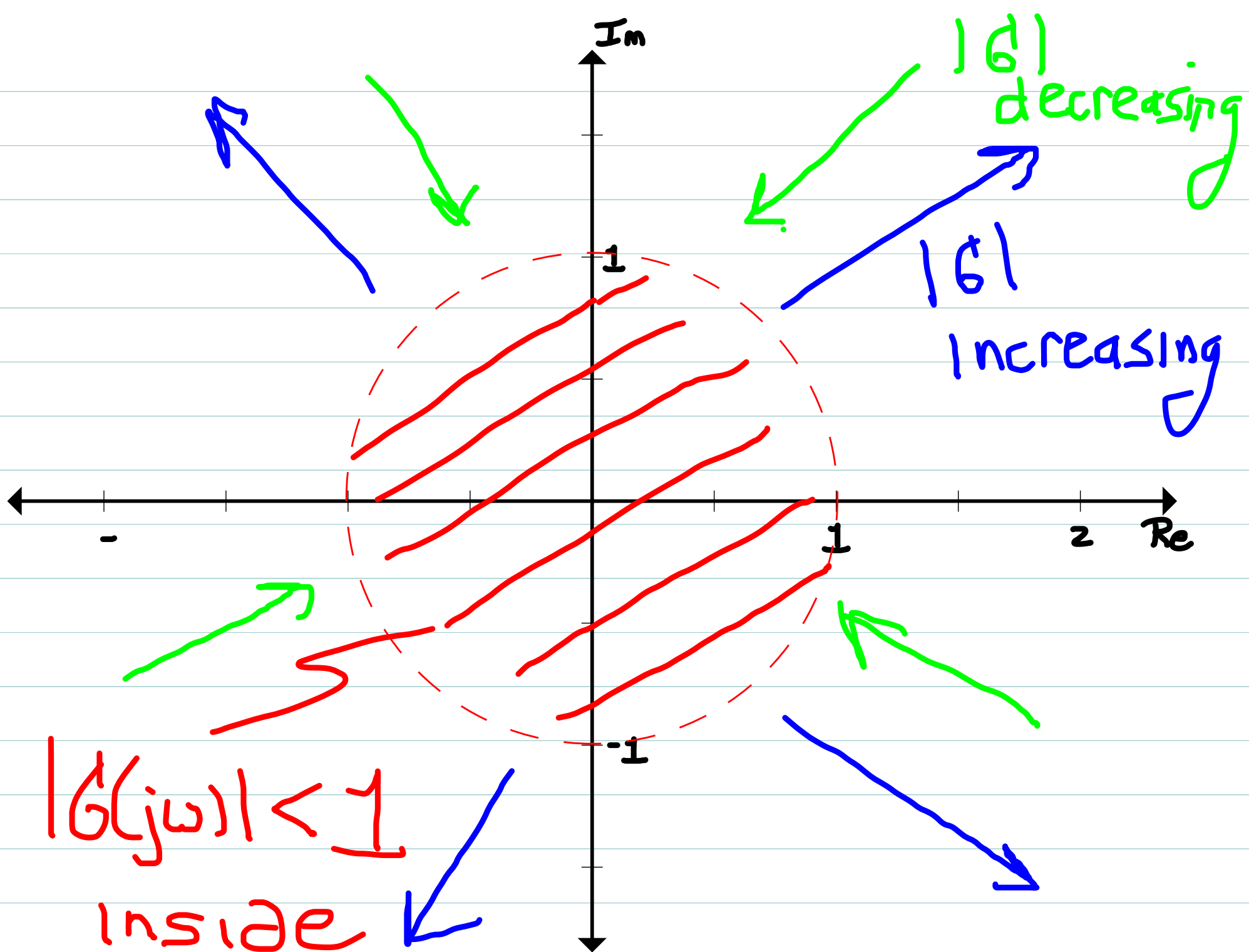
\Rightarrow Bode diagrams show us the polar coordinates of the points $G(j\omega)$ for each ω

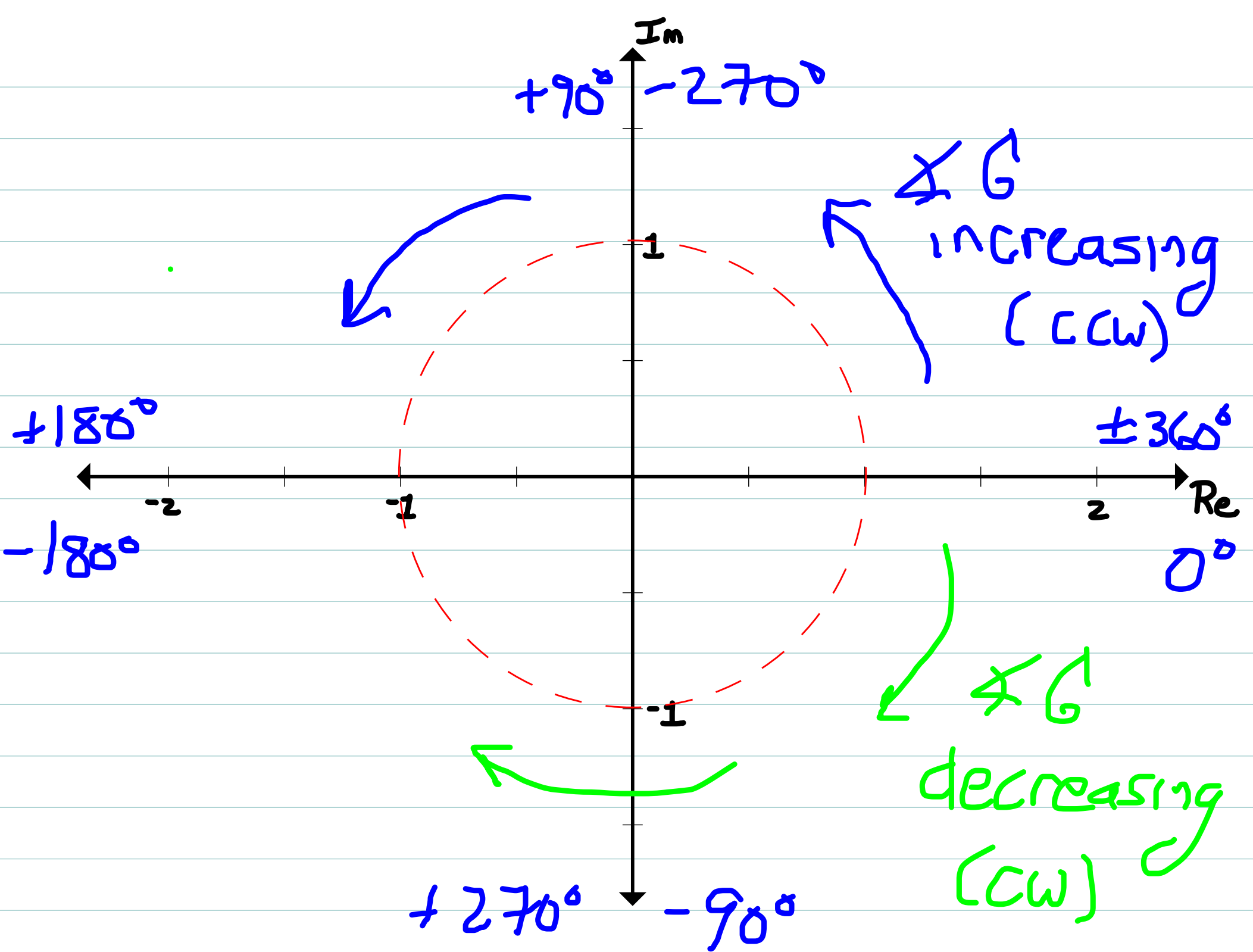
\Rightarrow To map from Bode to polar

1.) Remember to convert magnitudes from dB back to actual.

2.) Remember angle convention for complex numbers.







A simple Example

$$G(s) = \frac{K_B}{(1+\tau s)} \quad \begin{array}{l} \tau > 0 \text{ (min phase)} \\ K_B > 1 \end{array}$$

Always start by thinking about low/high freq.
limiting behavior:

for $\omega \ll \frac{1}{\tau}$: Mag slope =

Phase =

for $\omega \gg \frac{1}{\tau}$: Mag slope =

Phase =

A simple Example

$$G(s) = \frac{K_B}{(1+\tau s)} \quad \begin{array}{l} \tau > 0 \text{ (min phase)} \\ K_B > 1 \end{array}$$

Always start by thinking about low/high freq.
limiting behavior:

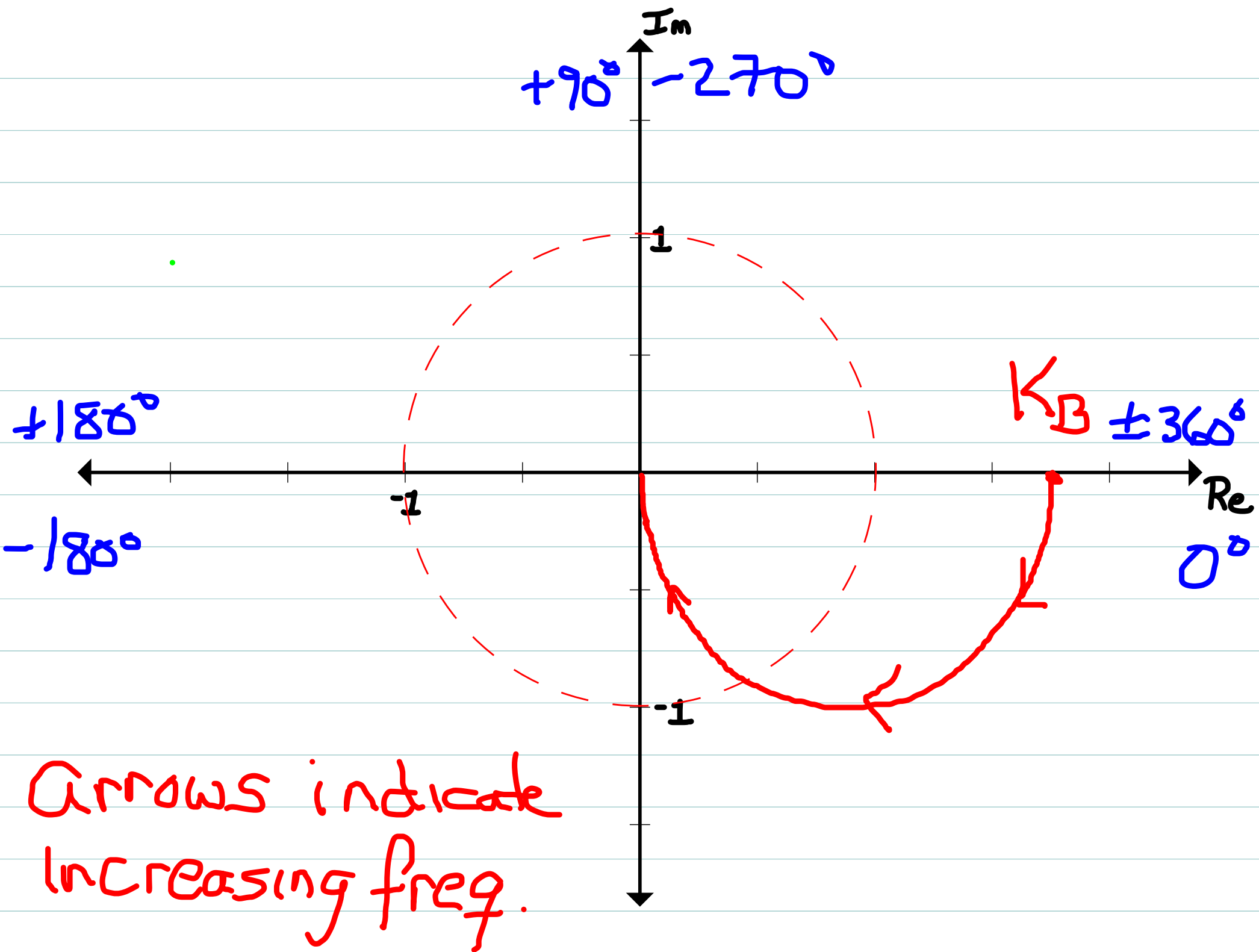
for $\omega \ll \frac{1}{\tau}$: Mag slope = 0 dB/dec (constant)

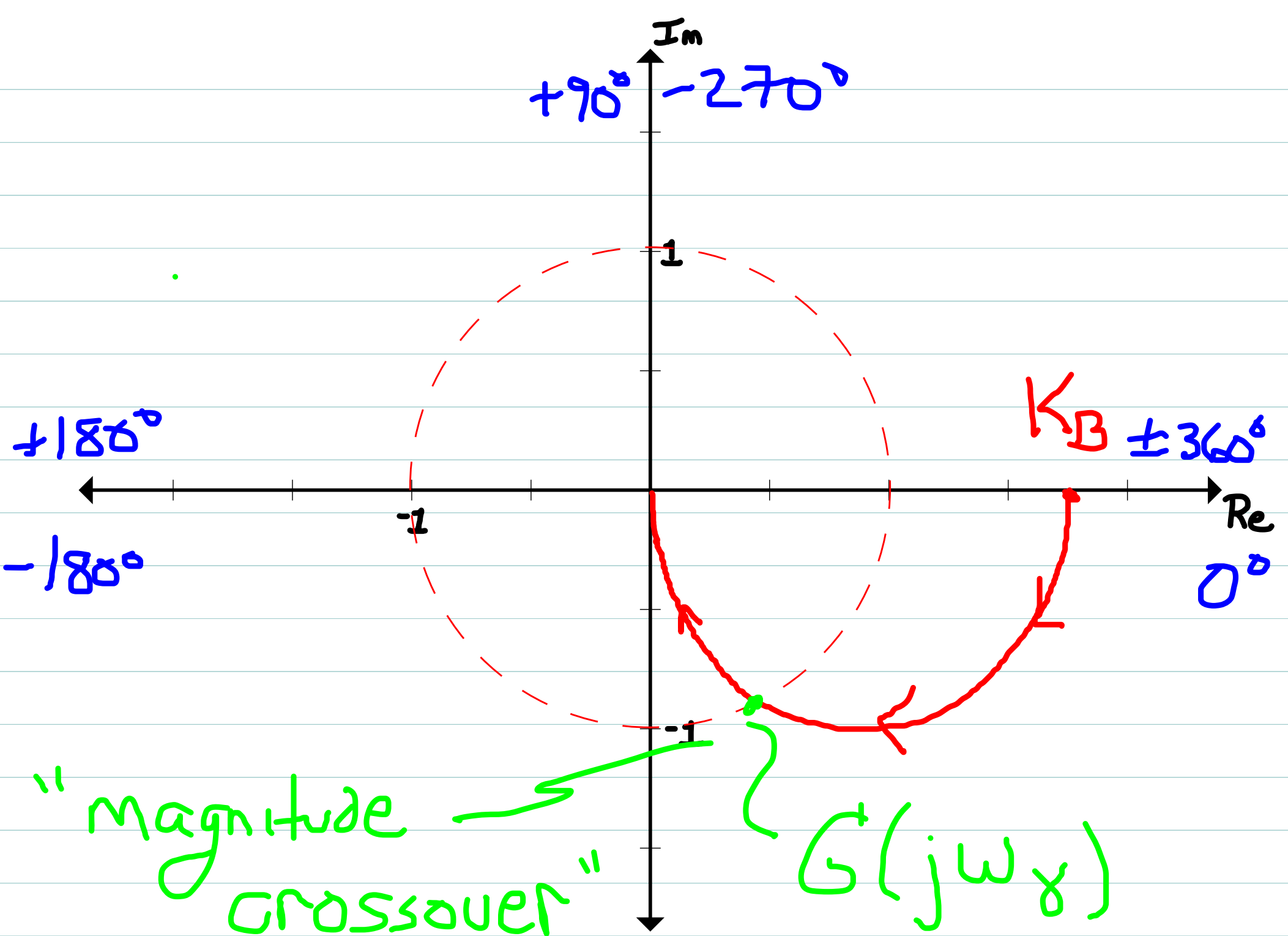
Phase = 0° (constant)

for $\omega \gg \frac{1}{\tau}$: Mag slope = -20 dB/dec

Phase = -90°

Low freq. magnitude is $|K_B| > 1$, high freq. magnitude is 0: $\lim_{\omega \rightarrow \infty} |G(j\omega)| = 0$





Magnitude Crossover

"Magnitude crossover" occurs where polar plot "punctures" the unit circle

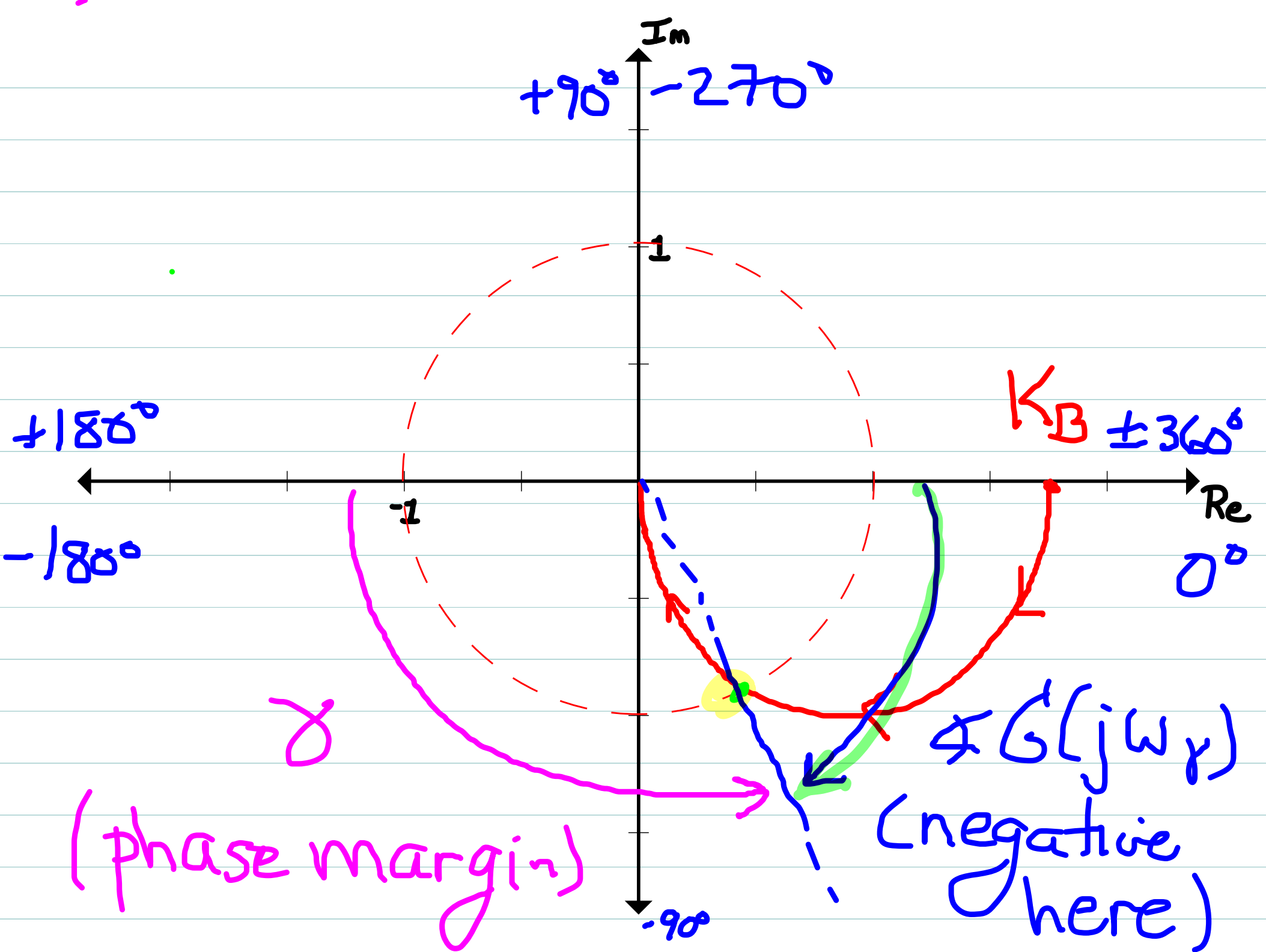
$$|G(j\omega)| = 1 \text{ at this point.}$$

The frequency at which this occurs is the "magnitude crossover freq", termed ω_x

Easily seen on Bode: ω_x is the frequency where $|G(j\omega)| = 0 \text{ dB}$

Note: depending on the system there may be one, many, or no magnitude crossover freq.

Important quantity: $\angle G(j\omega_x)$: phase at magnitude crossover



Phase Margin

The phase margin is the angle around the unit circle from -1 to magnitude crossover point, measured positive counter-clockwise from -1 (or, equiv, CW from mag xover to -1)

The phase margin angle, γ , is expressed in deg (although later it will be convenient to express in rad).

Assuming we write $\angle G(j\omega_x)$ in range $[0^\circ, -360^\circ]$ an expression for γ is:

$$\gamma \in [-180^\circ, 180^\circ]$$

$$\gamma = 180^\circ + \angle G(j\omega_x)$$

$$\left\{ \begin{array}{l} \Rightarrow \gamma > 0 \\ \text{if } \angle G(j\omega_x) > -180^\circ \end{array} \right.$$

Note: Matlab will usually try to wrap phase plot $\angle G(j\omega)$ so that $\angle G(j\omega_x)$ is in this range. Sometimes it doesn't. You can always manually add or subtract a multiple of 360° to get $\angle G(j\omega_x)$ in this range.

$$\gamma \in [-180^\circ, 180^\circ]$$

$$+90^\circ \quad -270^\circ$$

$$\gamma < 0$$

(if mag xover on upper half of unit circle)

$$+180^\circ$$

$$-180^\circ$$

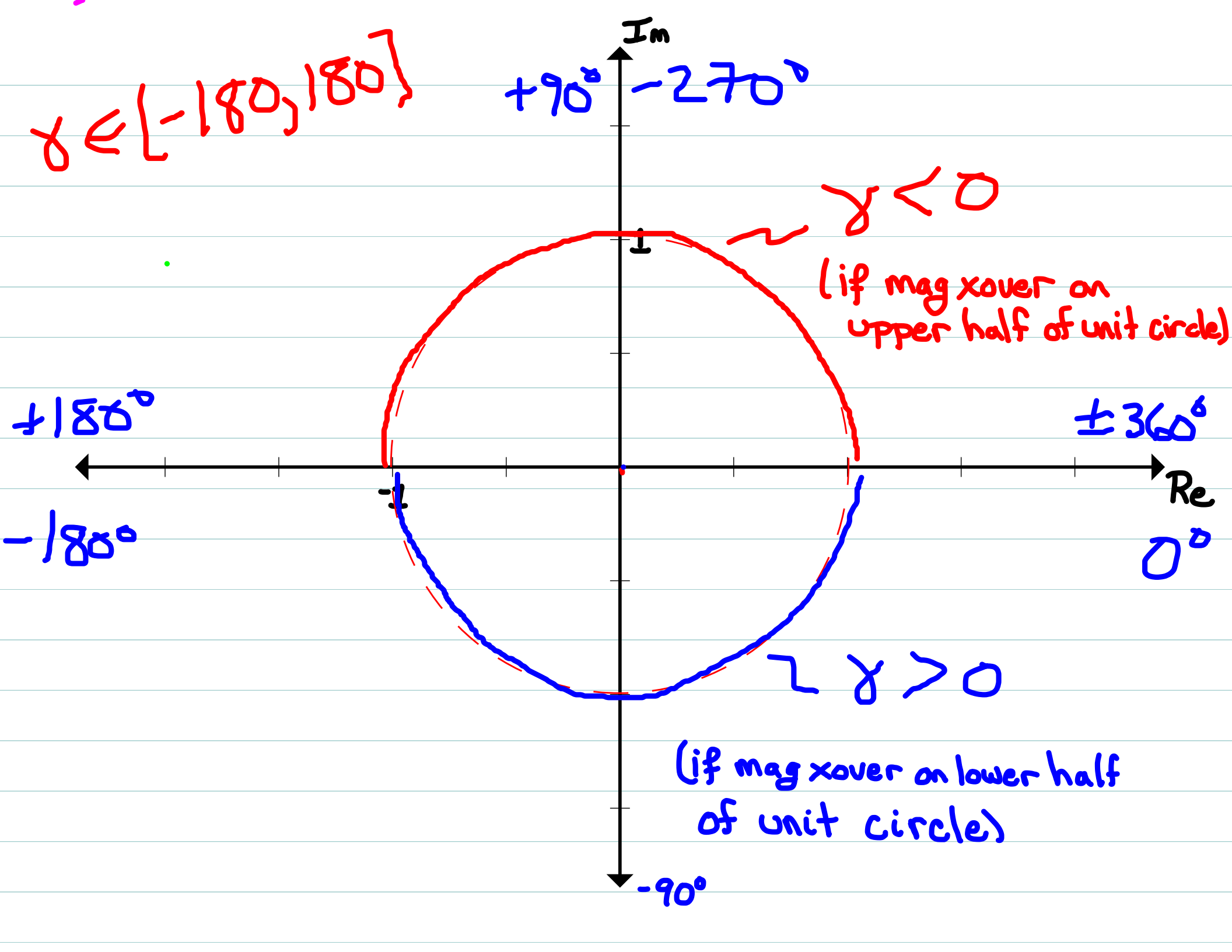
$$\pm 360^\circ$$

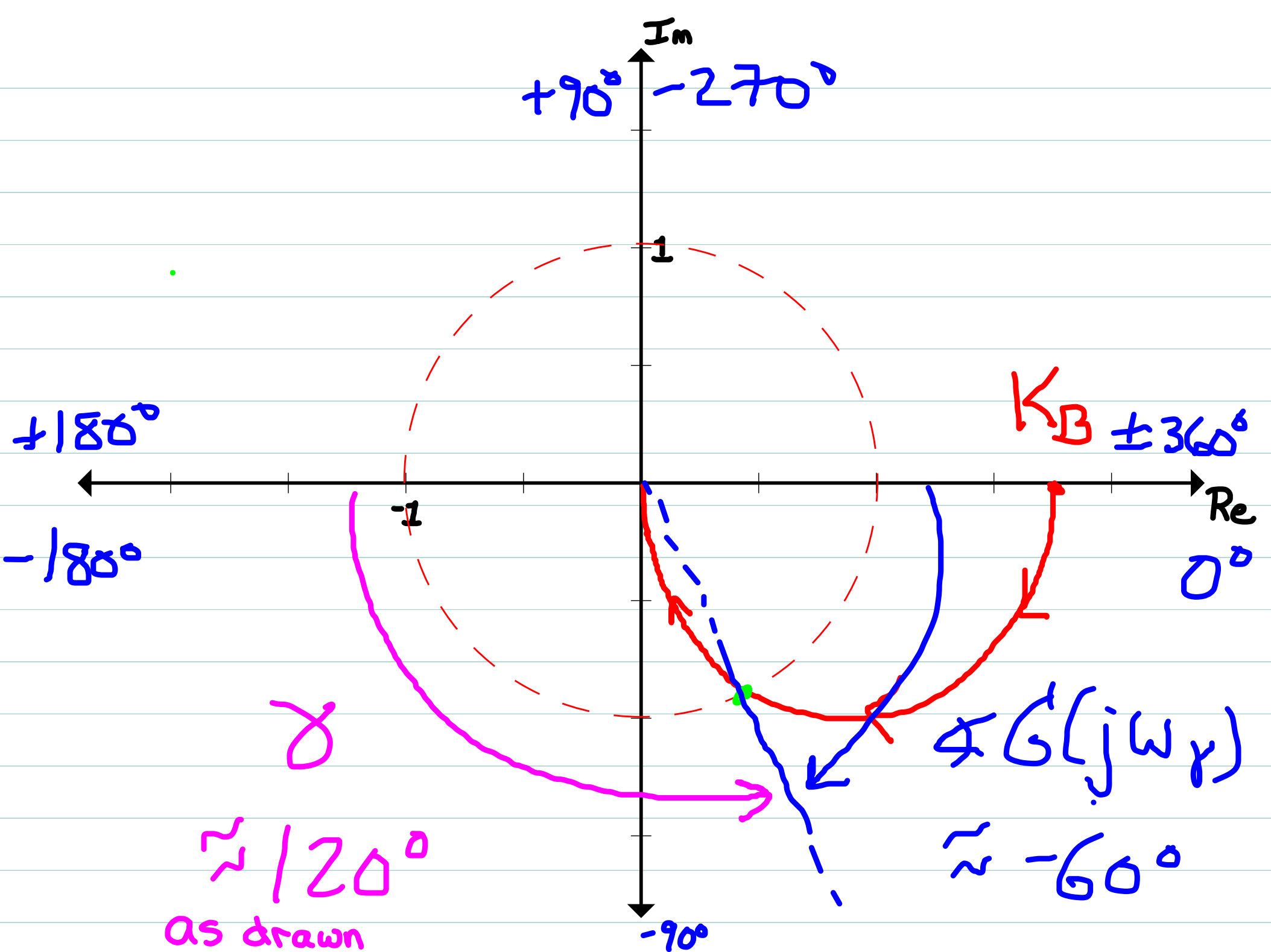
$$0^\circ$$

$$\gamma > 0$$

(if mag xover on lower half of unit circle)

$$-90^\circ$$





Another Example

$$G(s) = \frac{K_B}{(1+\tau s)^3}$$

$$K_B > 1$$
$$\tau > 0$$

Low freq mag: Constant at K_B

Low freq phase: Constant at 0°

High freq. mag slope:

High freq. phase:

Another Example

$$G(s) = \frac{K_B}{(1+\tau s)^3}$$

$$K_B > 1$$
$$\tau > 0$$

Low freq mag: Constant at K_B

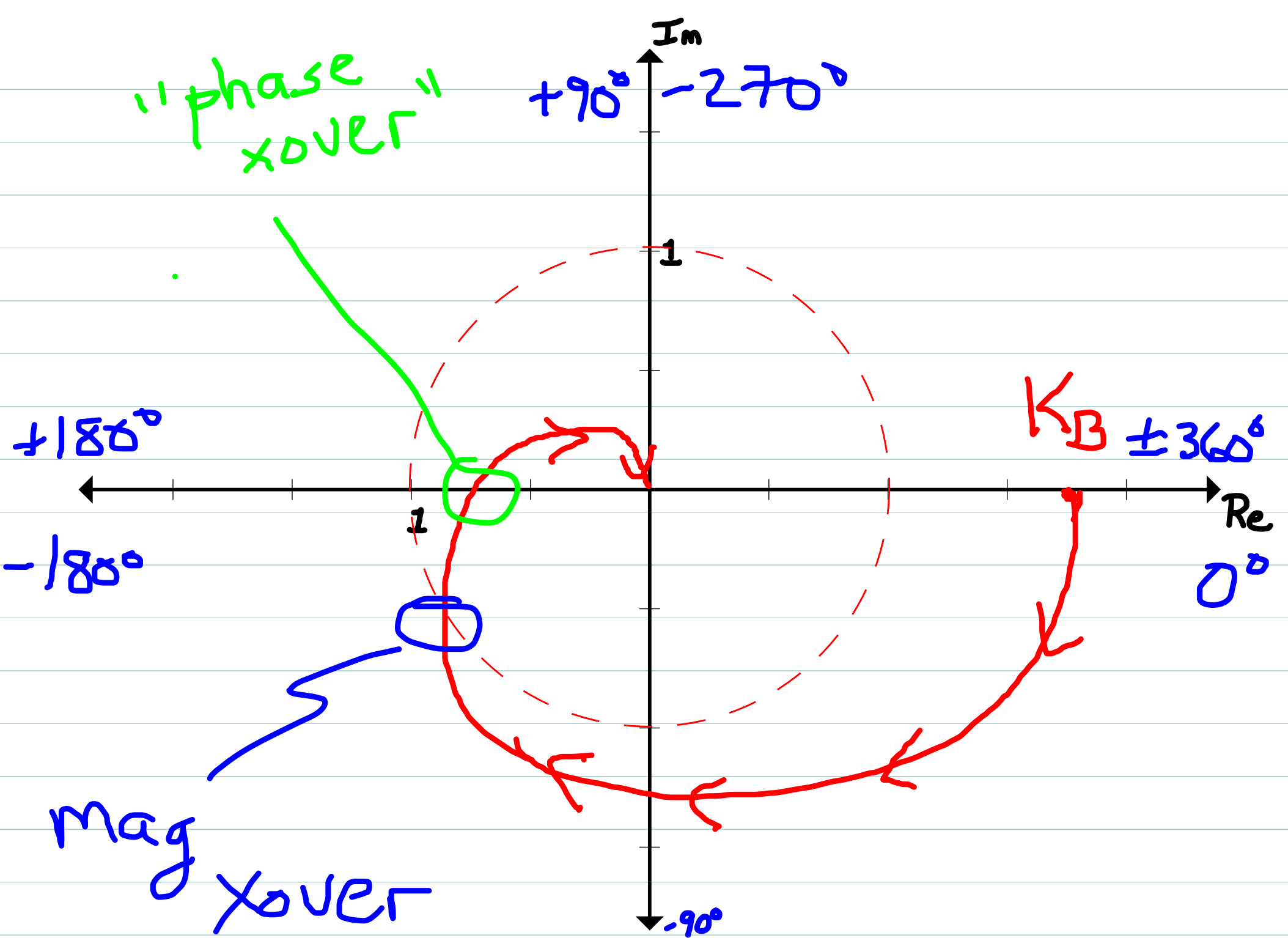
Low freq phase: Constant at 0°

High freq. mag slope: -60 dB/dec

High freq. phase: -270°

Recall: negative high freq. slope means

$$|G(j\omega)| \rightarrow 0 \text{ as } \omega \rightarrow \infty$$



Phase Crossover

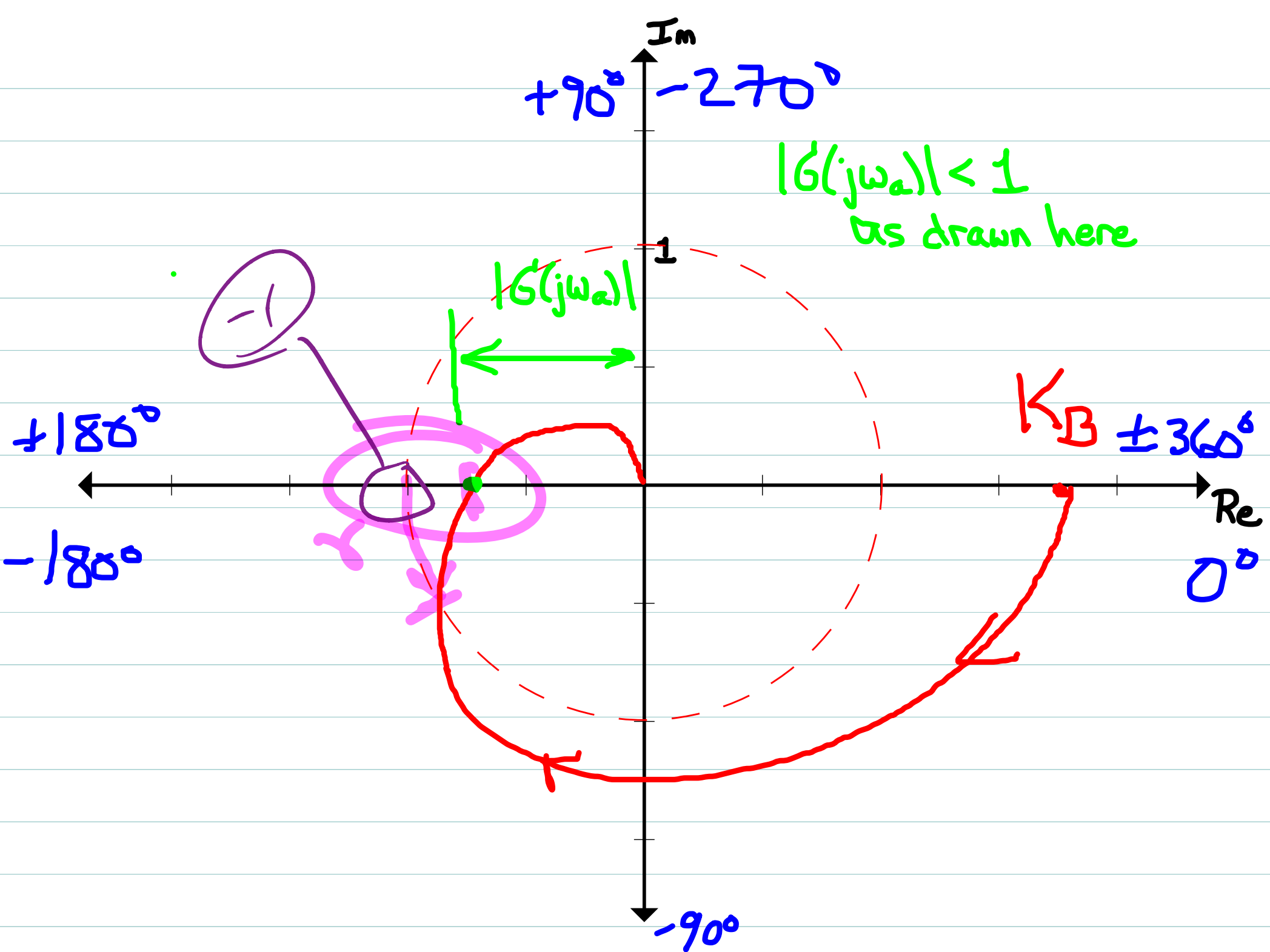
The "phase crossover" of a polar plot is the point where the plot crosses through the negative real axis.

This corresponds to the point where $\angle G(j\omega) = -180^\circ$

Again, easily seen from Bode phase diagrams: call ω_a "phase crossover freq." the value of ω for which $\angle G(j\omega) = -180^\circ$.

Note: May be one, none, or many ω_a depending on system.

Important quantity: $|G(j\omega_a)|$ magnitude at phase crossover frequency



Gain Margin

The gain margin, a , is defined as:

$$a = \frac{1}{|G(j\omega_a)|}$$

Gain margin is commonly expressed in dB:

$$a_{dB} = 20 \log a$$

$$= -|G(j\omega_a)|_{dB}$$

So gain margin in dB is negative of Bode magnitude at phase crossover freq.

Meaning of Gain and phase margins

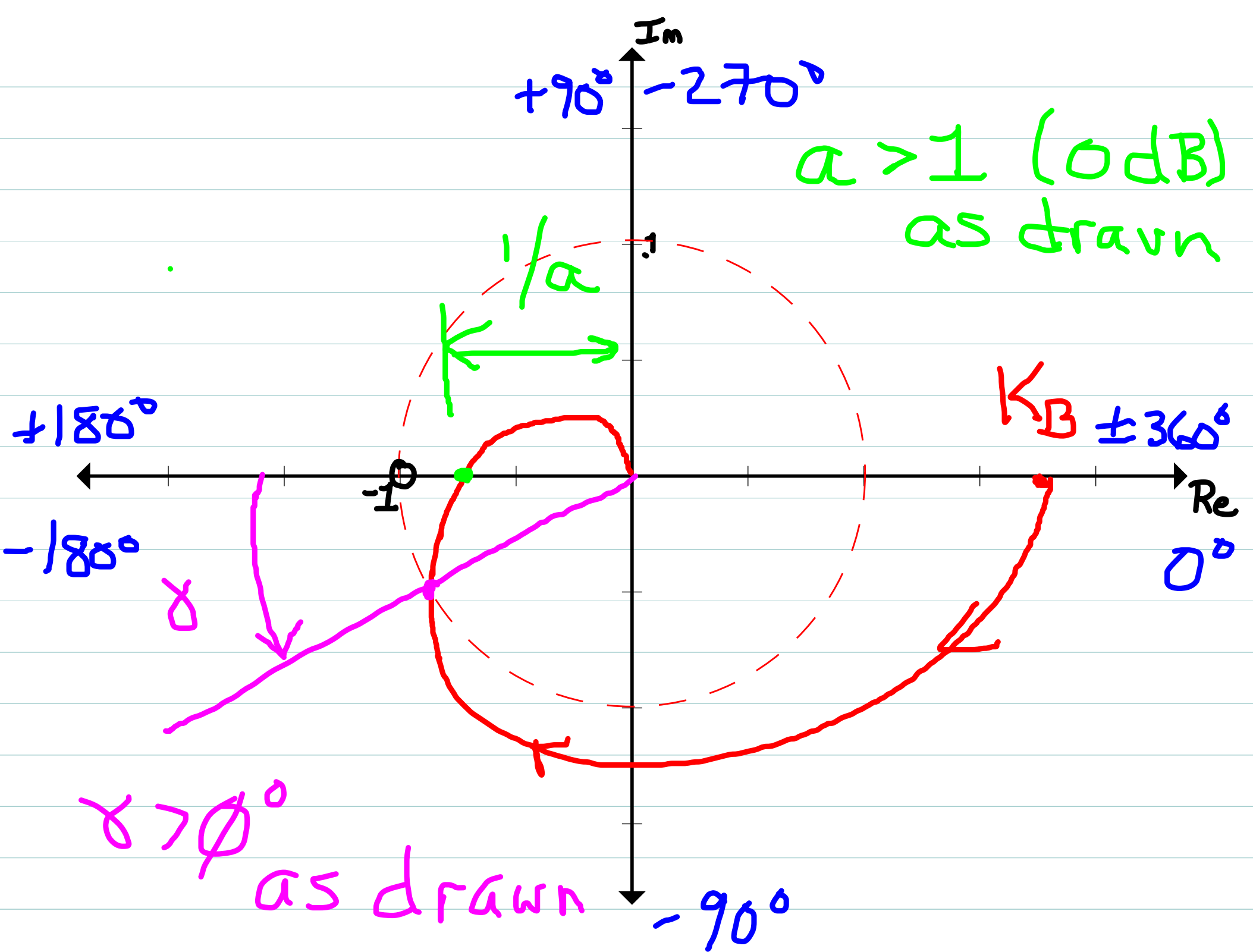
α, γ measure how close polar plot comes to point $-1 + 0j$ ("-1 point") in complex plane. Recall $-1 + 0j = 1 \angle -180^\circ$

Two "pseudo-orthogonal" directions

→ α measures distance to -1 along real axis as a ratio $1/|G(j\omega)|$

⇒ γ measures distance to -1 as an angle around unit circle.

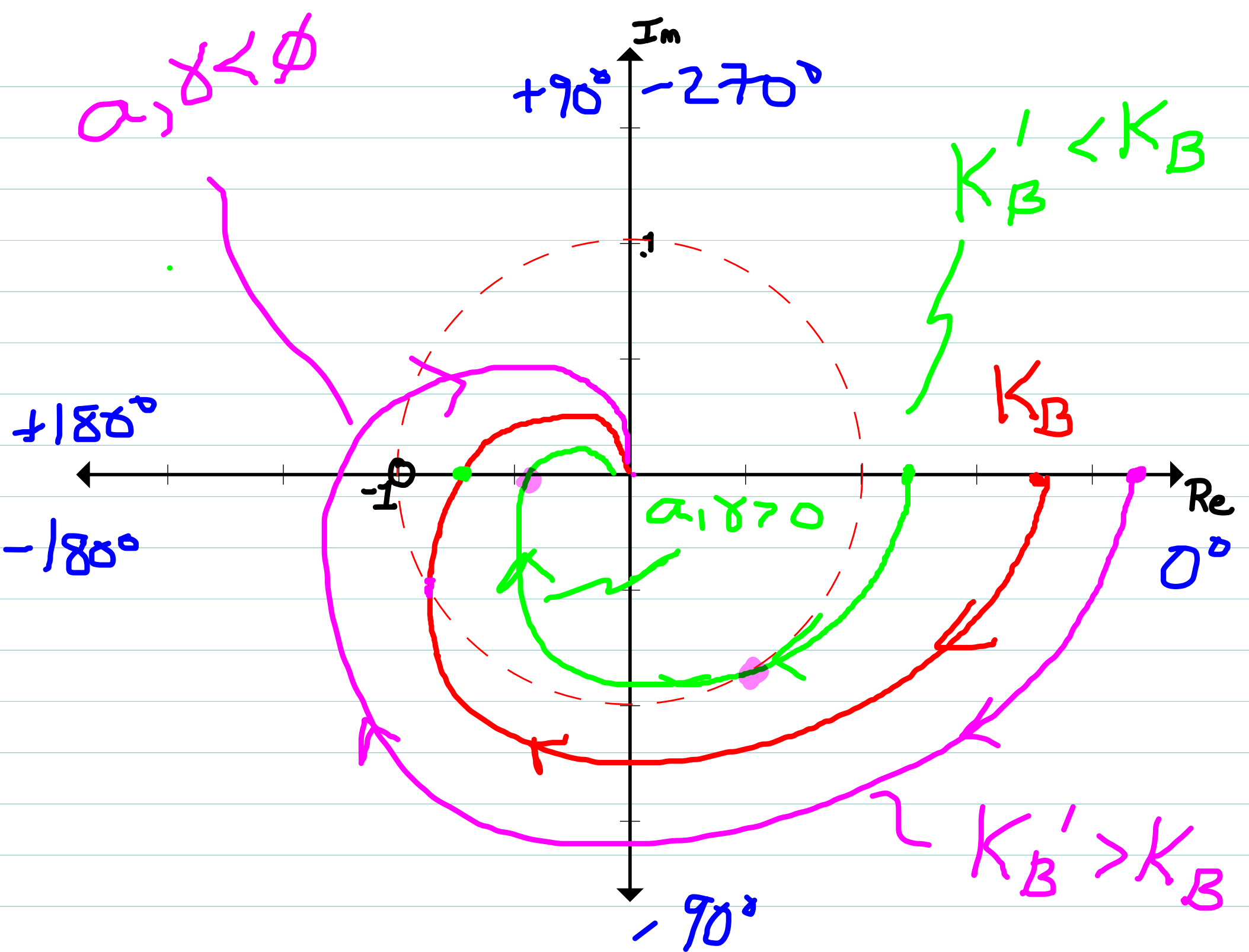
Note: $\alpha > 1$ ($\alpha > 0 \text{ dB}$) means phase crossover occurs inside unit circle. $\alpha < 1$ ($\alpha < 0 \text{ dB}$) means phase crossover is outside unit circle



Effect of Gain Changes

Increasing or decreasing K_B uniformly expands or contracts polar plot about the origin

\Rightarrow Will generally change crossovers and margins



Effect of Zeros

Since they affect magnitude and phase, zeros will change shape of polar plot.

Example:

$$G(s) = K_B \frac{(\tau_1 s + 1)}{(\tau_2 s + 1)^3} \quad \begin{array}{l} K_B > 1 \\ \tau_1, \tau_2 > 0 \end{array}$$

high freq phase: -180° here (why??)

But this limit may be asymptotically approached from above or below as $\omega \rightarrow \infty$

This difference can have a profound impact on shape of plot. Need to check Bode for accuracy, but can often "reason it out" for simple cases.

