

problem 2

```
% givens  
s = zpk('s');  
G = 5*(s-1)/(s-6);
```

```
% display  
G
```

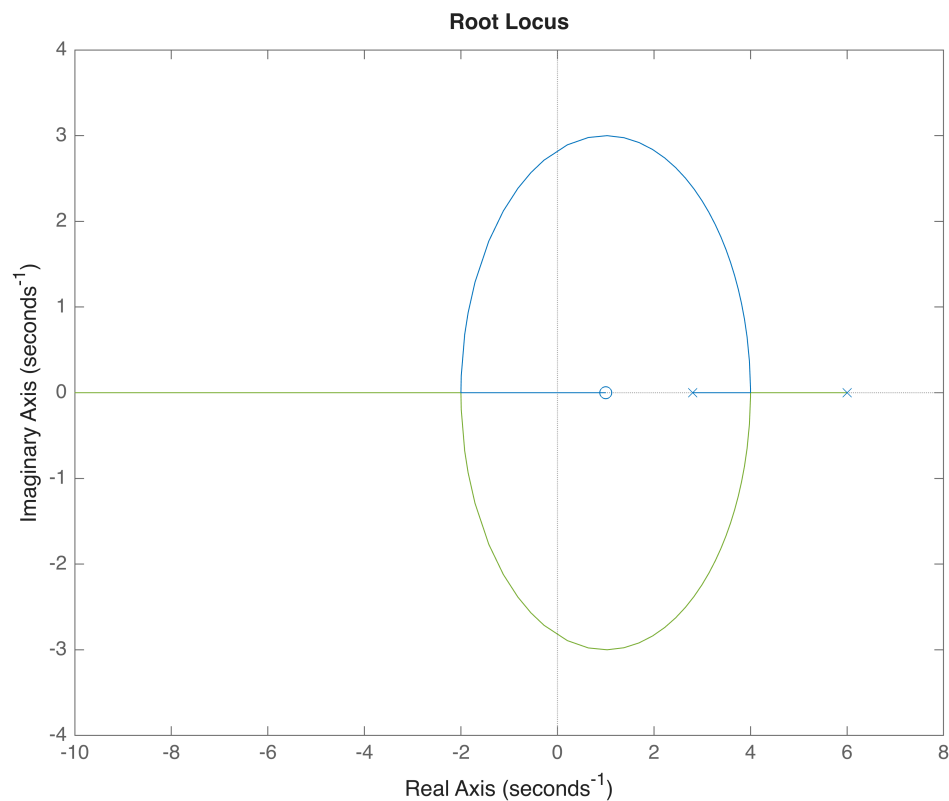
G =

$$\frac{5(s-1)}{(s-6)}$$

Continuous-time zero/pole/gain model.
Model Properties

part b

```
K = 64/25;  
p = 14/5;  
H = K/(s-p);  
L = H*G;  
  
fig = figure;  
rlocusplot(L);  
saveas(fig, './images/s02b.png');
```

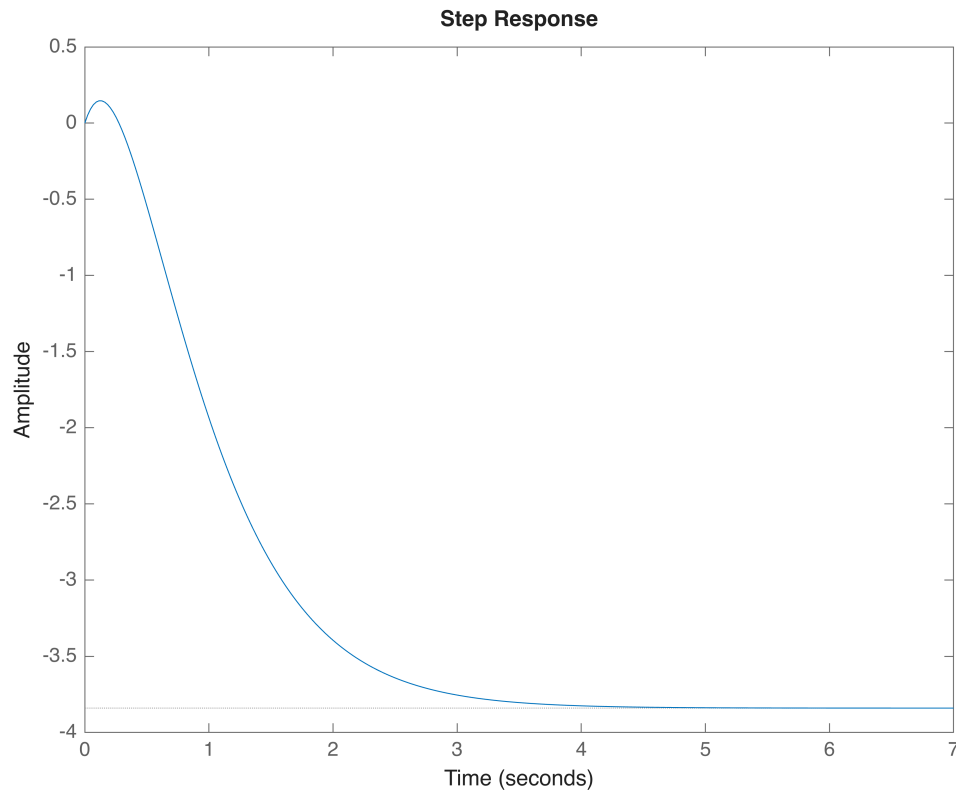


part c

```
syms s_sym

R = feedback(H, G);
R_info = stepinfo(R);

fig = figure;
stepplot(R);
saveas(fig, './images/s02c.png');
```



```
[R_num, R_den] = tfdata(R);
RN = poly2sym(R_num, s_sym);
RD = poly2sym(R_den, s_sym);
R_sym = RN/RD;
U_sym = R_sym/s_sym;
ut_sym = ilaplace(U_sym)
```

ut_sym =

$$\frac{96e^{-2t}}{25} + \frac{256te^{-2t}}{25} - \frac{96}{25}$$

```
% display
R, R_info, ut_sym
```

R =

$$\frac{2.56 (s-6)}{(s+2)^2}$$

Continuous-time zero/pole/gain model.

Model Properties

R_info = struct with fields:

RiseTime: 1.6515
TransientTime: 3.0421
SettlingTime: 3.0640
SettlingMin: -3.8400
SettlingMax: -3.4571
Overshoot: 0
Undershoot: 3.8196
Peak: 3.8400
PeakTime: 7.8058

ut_sym =

$$\frac{96 e^{-2t}}{25} + \frac{256 t e^{-2t}}{25} - \frac{96}{25}$$

part d

```
% assuming sample time Ts = 1 second
```

```
Ts = 1/25;
```

```
% solution
```

```
[Ah, Bh, Ch, Dh] = ssdata(canon(H));
```

```
H_zoh.Ad = expm(Ah*Ts);
```

```
H_zoh.Bd = Ah \ (H_zoh.Ad-eye(size(Ah)))*Bh;
```

```
H_zoh.Cd = Ch;
```

```
H_zoh.Dd = Dh;
```

```
[Ad, Bd, Cd, Dd] = ssdata(c2d(H, Ts, 'tustin'));
```

```
H_tustin = struct('Ad', Ad, 'Bd', Bd, 'Cd', Cd, 'Dd', Dd);
```

```
% display tustin
```

```
H_zoh, H_tustin
```

```
H_zoh = struct with fields:
```

Ad: 1.1185
Bd: 0.0847
Cd: 1.2800
Dd: 0

```
H_tustin = struct with fields:
```

Ad: 1.1186
Bd: 0.3639
Cd: 0.3158
Dd: 0.0542