ENAE 404 - 0101 Homework 02: 2BP

Due on February 25th, 2025 at 09:30 AM $Dr. \ Barbee, \ 09:30$

Vai Srivastava

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Problem 1:

Given the following position and velocity vectors, calculate the Keplerian orbital elements, assuming Earth is the central body. Do not use a computer code to do this. Vectors are in units of km and $\frac{km}{s}$.

$$\vec{r} = 3634.1\hat{x} + 5926\hat{y} + 1206.6\hat{z}$$

$$\vec{v} = -6.9049\hat{x} + 4.3136\hat{y} + 2.6163\hat{z}$$

Solution

$$\mu_{\oplus} = 398\,600\,\frac{\mathrm{km}^3}{\mathrm{s}^2}$$

$$r = \|\mathbf{r}\| = \sqrt{3634.1^2 + 5926^2 + 1206.6^2} \approx 7055\,\,\mathrm{km}$$

$$v = \|\mathbf{v}\| = \sqrt{(-6.9049)^2 + 4.3136^2 + 2.6163^2} \approx 8.55\,\,\mathrm{km/s}$$

$$\mathbf{h} = \mathbf{r} \times \mathbf{v}$$

$$h = \|\mathbf{h}\| \approx 6.02 \times 10^4\,\,\mathrm{km}^2/\mathrm{s}$$

$$\mathcal{E} = \frac{v^2}{2} - \frac{\mu_{\oplus}}{r} \approx \frac{73.16}{2} - \frac{398600}{7055} \approx 36.58 - 56.50 \approx -19.92\,\,\mathrm{km}^2/\mathrm{s}^2$$

$$a = -\frac{\mu_{\oplus}}{2\mathcal{E}}$$

$$a \approx \frac{398600}{39.84} \approx 1 \times 10^4\,\mathrm{km} \quad \Box$$

$$e = \sqrt{1 + \frac{2\mathcal{E}\,h^2}{\mu_{\oplus}^2}} \approx 0.30 \quad \Box$$

$$\mathbf{n} = \hat{\mathbf{k}} \times \mathbf{h}$$

$$\|\mathbf{n}\| \approx 2.06 \times 10^4\,\frac{\mathrm{km}^2}{\mathrm{s}} \quad \Box$$

$$\Omega = \arccos\left(\frac{n_x}{\|\mathbf{n}\|}\right) \approx \arccos(0.8660) \approx 30^\circ \quad \Box$$

$$\omega = \arccos\left(\frac{\mathbf{n} \cdot \mathbf{e}}{\|\mathbf{n}\|}\right)$$

$$\omega \approx 15^\circ \quad \Box$$

$$\nu = \arccos\left(\frac{\mathbf{e} \cdot \mathbf{r}}{er}\right)$$

$$\nu \approx 30^\circ \quad \Box$$

$$a \approx 1 \times 10^4 \, \mathrm{km}$$

 $e \approx 0.30$
 $i \approx 20^{\circ}$
 $\Omega \approx 30^{\circ}$
 $\omega \approx 15^{\circ}$
 $\nu \approx 15^{\circ}$

Problem 2:

- 1. Write code to convert form Cartesian coordinates to orbital elements.
- 2. Using subplot, plot the osculating orbital elements for the orbit of Didymos from HW00.
- 3. Describe why your plots make sense (in reference to both the time variation of the orbital elements as well as the plot of the orbit in 3D space).

Solution

Part A

```
1 import numpy as np
2 import scipy as sp
3 import matplotlib.pyplot as plt
5 \text{ mu\_sun} = 1.32712440018e11
8 def state_to_keplerian(r_vec, v_vec, mu):
      Convert Cartesian state vectors to orbital elements.
11
      Parameters:
12
        r_vec: Position vector (km)
13
        v_vec: Velocity vector (km/s)
14
               Gravitational parameter (km<sup>3</sup>/s<sup>2</sup>)
15
        mu:
16
      Returns:
17
18
        a
                   : semimajor axis (km)
                   : eccentricity (unitless)
                   : inclination (rad)
        inc
        RAAN
                   : right ascension of the ascending node (rad)
        arg_peri : argument of perigee (rad)
                   : true anomaly (rad)
23
        nu
24
      r = np.array(r_vec)
25
      v = np.array(v_vec)
26
      r_norm = np.linalg.norm(r)
27
      v_norm = np.linalg.norm(v)
28
29
      # Specific angular momentum vector and magnitude
30
      h = np.cross(r, v)
31
      h_norm = np.linalg.norm(h)
32
33
      # Inclination
34
      inc = np.arccos(h[2] / h_norm)
35
      # Node vector (pointing toward ascending node)
      K = np.array([0, 0, 1])
      n = np.cross(K, h)
      n_norm = np.linalg.norm(n)
40
41
      # Eccentricity vector and eccentricity magnitude
42
      e_{vec} = (np.cross(v, h) / mu) - (r / r_norm)
43
      e = np.linalg.norm(e_vec)
44
45
      # Semimajor axis (using vis-viva equation)
46
      a = 1 / (2 / r_norm - v_norm**2 / mu)
47
```

```
48
       # RAAN
49
       if n_norm > 1e-8:
50
51
           RAAN = np.arccos(n[0] / n_norm)
52
           if n[1] < 0:</pre>
               RAAN = 2 * np.pi - RAAN
53
54
      else:
          RAAN = 0
57
       # Argument of perigee
       if n_norm > 1e-8 and e > 1e-8:
58
           arg_peri = np.arccos(np.dot(n, e_vec) / (n_norm * e))
59
60
           if e_vec[2] < 0:</pre>
61
               arg_peri = 2 * np.pi - arg_peri
62
       else:
           arg_peri = 0
63
64
       # True anomaly
65
       if e > 1e-8:
66
           nu = np.arccos(np.dot(e_vec, r) / (e * r_norm))
67
           if np.dot(r, v) < 0:</pre>
68
               nu = 2 * np.pi - nu
69
70
       else:
           # For nearly circular orbits, use angle from node vector
71
           if n_norm > 1e-8:
               nu = np.arccos(np.dot(n, r) / (n_norm * r_norm))
               if r[2] < 0:
                    nu = 2 * np.pi - nu
76
           else:
               nu = 0
78
79
       return a, e, inc, RAAN, arg_peri, nu
80
81
82 def two_body_equations(t, state, mu):
83
       Two-body equations for a central gravitational force.
84
      state: [rx, ry, rz, vx, vy, vz]
85
86
      r = state[0:3]
87
       v = state[3:6]
88
      r_norm = np.linalg.norm(r)
       a = -mu * r / r_norm**3
       return np.concatenate((v, a))
92
93
94 if __name__ == "__main__":
95
       # Initial state for Didymos
       r0 = np.array([-2.39573e8, -2.35661e8, 9.54384e6]) # position in km
96
       v0 = np.array([12.4732, -9.74427, -0.87661]) # velocity in km/s
97
       state0 = np.concatenate((r0, v0))
98
99
       # Propagation time (seconds)
100
       tmaxDidymos = 7.0e7
101
       t_span = (0, tmaxDidymos)
102
       # Use 1000 time points
       t_eval = np.linspace(0, tmaxDidymos, 1000)
104
       # Propagate the orbit using ODE solver
106
       sol = sp.integrate.solve_ivp(
           fun=lambda t, y: two_body_equations(t, y, mu_sun),
           t_span=t_span,
```

```
y0=state0,
           t_eval=t_eval,
           rtol=1e-9,
112
           atol=1e-9,
114
       )
       # Extract the propagated state vectors
       r_sol = sol.y[0:3, :].T # positions (km)
117
       v_sol = sol.y[3:6, :].T # velocities (km/s)
118
119
       # Initialize lists for each orbital element
120
       a_vals = []
121
       e_vals = []
122
123
       inc_vals = [] # in degrees
       RAAN_vals = [] # in degrees
124
       argp_vals = [] # in degrees
125
       nu_vals = [] # in degrees
126
127
       for r, v in zip(r_sol, v_sol):
128
           a_i, e_i, inc_i, RAAN_i, argp_i, nu_i = state_to_keplerian(r, v, mu_sun)
           a_vals.append(a_i)
130
           e_vals.append(e_i)
131
           inc_vals.append(np.degrees(inc_i))
           RAAN_vals.append(np.degrees(RAAN_i))
           argp_vals.append(np.degrees(argp_i))
           nu_vals.append(np.degrees(nu_i))
       # 3D Orbit Plot
       fig1 = plt.figure(figsize=(10, 8))
138
       ax1 = fig1.add_subplot(111, projection="3d")
139
       ax1.plot(r_sol[:, 0], r_sol[:, 1], r_sol[:, 2], "b-", label="Orbit Path")
140
141
       ax1.scatter(
           r_sol[0, 0], r_sol[0, 1], r_sol[0, 2], color="green", s=100, label="Start"
142
143
       ax1.set_xlabel("X (km)")
144
       ax1.set_ylabel("Y (km)")
145
       ax1.set_zlabel("Z (km)")
146
       ax1.set_title("3D Orbit of Didymos")
147
       # Set equal axes
148
       max_range = np.max(np.abs(r_sol))
149
       ax1.set_xlim([-max_range, max_range])
       ax1.set_ylim([-max_range, max_range])
       ax1.set_zlim([-max_range, max_range])
       ax1.legend()
153
154
       # Osculating Orbital Elements Subplots
       fig2, axs = plt.subplots(3, 2, figsize=(14, 12), sharex=True)
156
157
       # Semimajor axis
158
       axs[0, 0].plot(sol.t / 86400, a_vals, "b-")
       axs[0, 0].set_ylabel("a (km)")
160
       axs[0, 0].set_title("Semimajor Axis")
161
       axs[0, 0].set_ylim([-max_range, max_range])
162
       axs[0, 0].grid(True)
163
164
       # Eccentricity
165
       axs[0, 1].plot(sol.t / 86400, e_vals, "r-")
166
       axs[0, 1].set_ylabel("e")
167
       axs[0, 1].set_title("Eccentricity")
168
       axs[0, 1].set_ylim([-max_range, max_range])
       axs[0, 1].grid(True)
```

```
# Inclination
172
       axs[1, 0].plot(sol.t / 86400, inc_vals, "g-")
       axs[1, 0].set_ylabel("i (deg)")
174
       axs[1, 0].set_title("Inclination")
176
       axs[1, 0].set_ylim([-max_range, max_range])
       axs[1, 0].grid(True)
177
178
       # RAAN
179
       axs[1, 1].plot(sol.t / 86400, RAAN_vals, "m-")
180
       axs[1, 1].set_ylabel("RAAN (deg)")
       axs[1, 1].set_title("RAAN")
       axs[1, 1].set_ylim([-max_range, max_range])
183
       axs[1, 1].grid(True)
184
185
       # Argument of Perigee
186
       axs[2, 0].plot(sol.t / 86400, argp_vals, "c-")
187
       axs[2, 0].set_ylabel("omega (deg)")
188
       axs[2, 0].set_title("Argument of Perigee")
189
       axs[2, 0].set_xlabel("Time (days)")
190
       axs[2, 0].set_ylim([-max_range, max_range])
191
       axs[2, 0].grid(True)
192
193
194
       # True Anomaly
       axs[2, 1].plot(sol.t / 86400, nu_vals, "k-")
195
       axs[2, 1].set_ylabel("nu (deg)")
196
       axs[2, 1].set_title("True Anomaly")
       axs[2, 1].set_xlabel("Time (days)")
       axs[2, 1].set_ylim([-max_range, max_range])
       axs[2, 1].grid(True)
200
201
       plt.tight_layout()
202
203
       plt.show()
```

Listing 1: Python code for HW02 P02

Part B

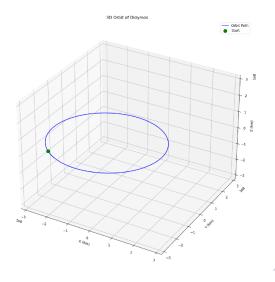


Figure 1: Osculating orbital elements for orbit of Didymos

Part C

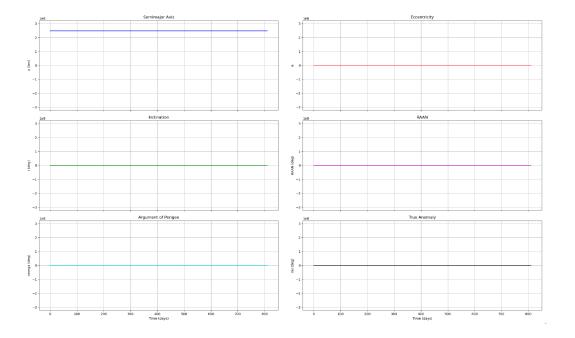


Figure 2: Osculating orbital elements for orbit of Didymos

The 3D plot shows a complete elliptical path. This is consistent with Kepler's first law: objects in a two-body problem follow elliptical orbits around the central body. The starting point is clearly marked, and the overall shape confirms the stability of the orbit under the chosen initial conditions.

In a perfect two-body system, the semimajor axis and eccentricity (which define the size and shape of the ellipse) remain constant. The inclination, RAAN, and argument of perigee, which determine the orbit's orientation, should also remain constant (except for the continuous increase in true anomaly as the body moves along the orbit). The subplots show smooth variations—especially the true anomaly's continuous growth—which confirm that the simulation captures the expected periodic and nearly constant behavior of the other elements. Slight numerical variations can be seen due to the integration method, but overall, the behavior is consistent with the theory.

Problem 3:

Given the following orbit: $a=2\times 10^4$ km, $e=0.4, i=100^\circ, \Omega=30^\circ, \omega=15^\circ, \nu=15^\circ$

- 1. Write code to convert from orbital elements to Cartesian coordinates.
- 2. Propogate the orbit (around Earth) for one period.
- 3. State the period of the orbit.
- 4. Plot the orbit in 3D (use equal-length axes).
- 5. Plot the deviation of the energy as compared to the inital energy $(E_i E_0)$.
- 6. Plot the osculating orbital elements.

Solution

Part A

See code in Listing 2

Part B

See code in Listing 2

Part C

Orbital period: $7.82\,\mathrm{hr}$

Part D

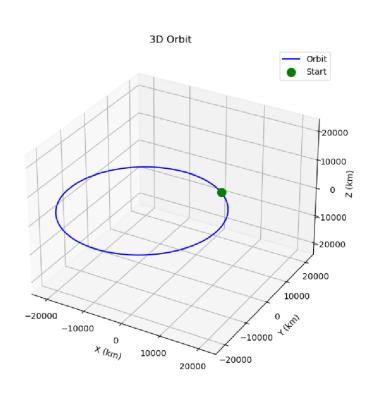


Figure 3: 3D Orbit about Earth

Part E

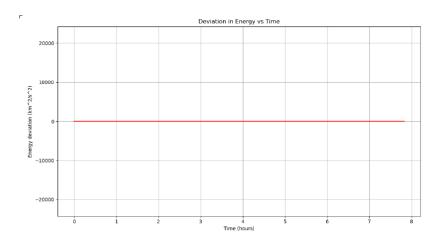


Figure 4: Deviation of Energy w.r.t. Initial Energy $(E_i - E_0)$

Part F

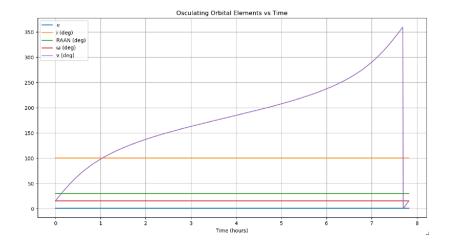


Figure 5: Oscilating Orbital Elements

Code

```
Inputs:
12
                  - semimajor axis (km)
       a
13
                  - eccentricity (unitless)
14
        inc
                  - inclination (rad)
15
16
                 - right ascension of the ascending node (rad)
       arg_perigee - argument of perigee (rad)
17
                 - true anomaly (rad)
18
        mu
                   - gravitational parameter (km^3/s^2)
19
      Returns:
20
21
       r_eci, v_eci: position (km) and velocity (km/s) vectors in the ECI frame.
22
      # Compute the distance (km) from the central body
23
      r = a * (1 - e**2) / (1 + e * np.cos(nu))
24
25
      # Position in the perifocal (PQW) frame
26
      r_{perifocal} = np.array([r * np.cos(nu), r * np.sin(nu), 0.0])
27
28
      # Parameter p
29
      p = a * (1 - e**2)
30
      # Velocity in the perifocal frame
31
      v_perifocal = np.array(
32
           [-np.sqrt(mu / p) * np.sin(nu), np.sqrt(mu / p) * (e + np.cos(nu)), 0.0]
33
34
35
      # Rotation matrix from perifocal to ECI frame
      cos_0 = np.cos(RAAN)
      sin_0 = np.sin(RAAN)
      cos_w = np.cos(arg_perigee)
40
      sin_w = np.sin(arg_perigee)
41
      cos_i = np.cos(inc)
      sin_i = np.sin(inc)
42
43
      # Transformation matrix (from PQW to ECI)
44
      R = np.array(
45
           Ε
46
               Γ
47
                   cos_0 * cos_w - sin_0 * sin_w * cos_i,
48
                   -cos_0 * sin_w - sin_0 * cos_w * cos_i,
49
                   sin_0 * sin_i,
50
               ],
51
52
                   sin_0 * cos_w + cos_0 * sin_w * cos_i,
                   -\sin_0 * \sin_w + \cos_0 * \cos_w * \cos_i,
                   -\cos_0 * \sin_i,
               ],
57
               [sin_w * sin_i, cos_w * sin_i, cos_i],
          ]
58
59
60
      # Convert position and velocity into ECI frame
61
      r_eci = R @ r_perifocal
62
      v_eci = R @ v_perifocal
63
64
      return r_eci, v_eci
65
66
67
68 def two_body_equations(t, state, mu):
69
      Equations of motion for the two-body problem.
70
      state: [rx, ry, rz, vx, vy, vz]
71
72
      0.00
      r = state[0:3]
```

```
v = state[3:6]
74
       r_norm = np.linalg.norm(r)
75
       # Gravitational acceleration
76
77
       a = -mu * r / r_norm**3
78
       return np.concatenate((v, a))
80
81 def state_to_keplerian(r_vec, v_vec, mu):
       Compute orbital elements from state vectors.
       Returns: a, e, inc, RAAN, arg_perigee, nu (all in SI units, angles in rad)
85
       r = np.array(r_vec)
86
87
       v = np.array(v_vec)
88
       r_norm = np.linalg.norm(r)
       v_norm = np.linalg.norm(v)
89
90
       # Specific angular momentum vector and its magnitude
91
       h = np.cross(r, v)
92
       h_norm = np.linalg.norm(h)
93
94
       # Inclination
95
96
       inc = np.arccos(h[2] / h_norm)
97
       # Node vector (pointing towards ascending node)
       K = np.array([0, 0, 1])
       n = np.cross(K, h)
       n_norm = np.linalg.norm(n)
       # Eccentricity vector
       e_{vec} = (np.cross(v, h) / mu) - (r / r_norm)
       e = np.linalg.norm(e_vec)
106
       # Semimajor axis (using vis-viva)
107
       a = 1 / (2 / r_norm - v_norm**2 / mu)
108
       # Right ascension of the ascending node (RAAN)
       if n_norm != 0:
           RAAN = np.arccos(n[0] / n_norm)
112
           if n[1] < 0:</pre>
113
114
                RAAN = 2 * np.pi - RAAN
       else:
           RAAN = 0
117
       # Argument of perigee
118
119
       if n_norm != 0 and e > 1e-8:
           arg_perigee = np.arccos(np.dot(n, e_vec) / (n_norm * e))
120
           if e_vec[2] < 0:</pre>
121
122
                arg_perigee = 2 * np.pi - arg_perigee
123
       else:
           arg_perigee = 0
124
125
       # True anomaly
126
       if e > 1e-8:
127
           nu = np.arccos(np.dot(e_vec, r) / (e * r_norm))
128
           if np.dot(r, v) < 0:</pre>
129
                nu = 2 * np.pi - nu
130
131
           # For circular orbits, true anomaly is undefined; using angle from node vector
132
           if n_norm != 0:
                nu = np.arccos(np.dot(n, r) / (n_norm * r_norm))
                if r[2] < 0:
```

```
nu = 2 * np.pi - nu
136
           else:
               nu = 0
138
139
140
       return a, e, inc, RAAN, arg_perigee, nu
141
142
143 if __name__ == "__main__":
       # Given orbital elements:
       # a in km, e unitless, angles in degrees (convert to radians)
       a = 2e4 \# km
146
       e = 0.4
147
       inc = np.radians(100) # inclination
148
149
       RAAN = np.radians(30) # Right Ascension of Ascending Node
       arg_perigee = np.radians(15) # Argument of perigee
150
       nu = np.radians(15) # True anomaly
152
       # Convert orbital elements to Cartesian state (position and velocity)
       r0, v0 = keplerian_to_cartesian(a, e, inc, RAAN, arg_perigee, nu, mu)
154
       state0 = np.concatenate((r0, v0))
155
156
       # Compute the orbital period using Kepler's third law (T in seconds)
157
158
       T = 2 * np.pi * np.sqrt(a**3 / mu)
       print(f"Orbital period: {T/3600:.2f} hours")
       # Time span for propagation (one period)
       t_span = (0, T)
       # Evaluation times (using 1000 sample points)
       t_eval = np.linspace(0, T, 1000)
164
165
       # Propagate the orbit using ODE solver
166
167
       sol = sp.integrate.solve_ivp(
           fun=lambda t, y: two_body_equations(t, y, mu),
168
           t_span=t_span,
169
           y0=state0,
           t_eval=t_eval,
           rtol=1e-9,
           atol=1e-9,
173
174
       # Extract position and velocity from the solution
176
177
       r_{sol} = sol.y[0:3, :].T # shape (N, 3)
       v_{sol} = sol.y[3:6, :].T # shape (N, 3)
178
179
       # Compute specific mechanical energy at each time step: E = v^2/2 - mu/|r|
180
181
       energy = np.array(
           Ε
182
               0.5 * np.linalg.norm(v) ** 2 - mu / np.linalg.norm(r)
183
               for r, v in zip(r_sol, v_sol)
184
           ٦
185
       )
186
       E0 = energy[0]
187
       energy_deviation = energy - E0
188
189
       # Osculating Orbital Elements vs Time
190
       a_vals = []
191
       e_vals = []
192
       inc_vals = []
193
       RAAN_vals = []
194
       arg_perigee_vals = []
       nu_vals = []
       for r, v in zip(r_sol, v_sol):
```

```
a_i, e_i, inc_i, RAAN_i, argp_i, nu_i = state_to_keplerian(r, v, mu)
198
           a_vals.append(a_i)
199
           e_vals.append(e_i)
200
           inc_vals.append(np.degrees(inc_i)) # converting to degrees for plotting
201
202
           RAAN_vals.append(np.degrees(RAAN_i))
203
           arg_perigee_vals.append(np.degrees(argp_i))
           nu_vals.append(np.degrees(nu_i))
204
       # Plotting
207
       fig = plt.figure(figsize=(14, 10))
208
       # 3D Orbit plot with equal axes
209
       ax1 = fig.add_subplot(221, projection="3d")
210
211
       ax1.plot(r_sol[:, 0], r_sol[:, 1], r_sol[:, 2], "b-", label="Orbit")
212
       ax1.scatter(
           r_sol[0, 0],
213
           r_sol[0, 1],
214
           r_sol[0, 2],
215
           color="green",
216
           marker="o",
217
           s = 100,
218
           label="Start",
219
220
       ax1.set_title("3D Orbit")
221
       ax1.set_xlabel("X (km)")
       ax1.set_ylabel("Y (km)")
       ax1.set_zlabel("Z (km)")
       # Set equal aspect ratio
       max_range = np.max(np.abs(r_sol))
       ax1.set_xlim([-max_range, max_range])
       ax1.set_ylim([-max_range, max_range])
       ax1.set_zlim([-max_range, max_range])
       ax1.legend()
230
231
       # Energy deviation plot
232
       ax2 = fig.add_subplot(222)
233
       ax2.plot(sol.t / 3600, energy_deviation, "r-")
234
       ax2.set_xlabel("Time (hours)")
235
       ax2.set_ylabel("Energy deviation (km^2/s^2)")
236
       ax2.set_title("Deviation in Energy vs Time")
237
238
       ax2.set_ylim([-max_range, max_range])
239
       ax2.grid(True)
       # Osculating orbital elements plot (a, e, i, RAAN, arg_perigee, nu)
       ax3 = fig.add_subplot(212)
       # ax3.plot(sol.t / 3600, a_vals, label='a (km)') # skip plotting a, as it is orders of
       magnitude outside range of others
       ax3.plot(sol.t / 3600, e_vals, label="e")
244
       ax3.plot(sol.t / 3600, inc_vals, label="i (deg)")
245
       ax3.plot(sol.t / 3600, RAAN_vals, label="RAAN (deg)")
246
       ax3.plot(sol.t / 3600, arg_perigee_vals, label="omega (deg)")
247
       ax3.plot(sol.t / 3600, nu_vals, label="nu (deg)")
248
       ax3.set_xlabel("Time (hours)")
249
       ax3.set_title("Osculating Orbital Elements vs Time")
250
       ax3.legend()
251
       ax3.grid(True)
252
253
       plt.tight_layout()
254
       plt.show()
```

Listing 2: Python code for HW02 P03

Problem 4:

Sketch the following orbits in 2D and 3D. Assume that none of the spacecraft impact Earth.

- In the 2D orbit, label:
 - periapsis
 - angular momentum vector
 - ascending node
 - descending node
 - spacecraft location
 - portion of the orbit in the southern hemisphere
- In the 3D orbit, label:
 - angular momentum vector
 - ascending node
 - periapsis

Spacecraft ID	e	i (°)	$\Omega\left(^{\circ}\right)$	ω (°)	ν (°)
A	0.3	60	30	160	30
В	0.3	60	330	90	10
\overline{C}	0.5	120	30	30	180

Solution

Part A

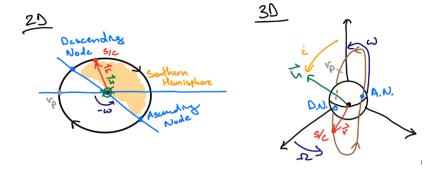


Figure 6: Spacecraft A Orbit in 2D (left) and 3D (right)

Part B

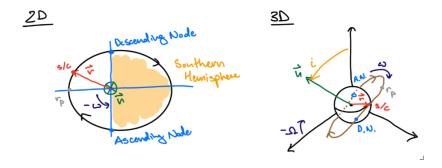


Figure 7: Spacecraft B Orbit in 2D (left) and 3D (right)

Part C

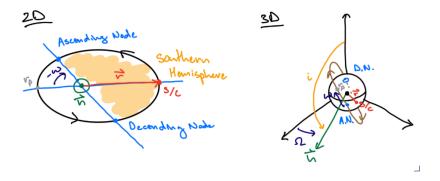


Figure 8: Spacecraft C Orbit in 2D (left) and 3D (right)

Problem 5:

Consider a spacecraft on a hyperbolic trajectory that will fly by Mars. The trajectory's semi-major axis is -11×10^3 km and its eccentricity is 1.8. Calculate:

- 1. Turn angle
- 2. Hyperbolic excess speed
- 3. Miss distance
- 4. Radius of periapsis of the flyby

Solution

Part A

$$a = -11 \times 10^{3} \text{ km}$$

$$e = 1.8$$

$$\frac{1}{e} = \sin \frac{\delta}{2}$$

$$\delta = 2 \sin^{-1} \frac{1}{e} = 67.50^{\circ} \quad \Box$$

Part B

$$\mu = 4.282\,837 \times 10^4 \, \frac{\mathrm{km}^3}{\mathrm{s}^2}$$

$$v_{\infty} = \sqrt{\frac{-\mu}{a}} = 1.973 \, \frac{\mathrm{km}}{\mathrm{s}} \quad \Box$$

Part C

$$p = a\left(1 - e^2\right) = 24\,640\,\mathrm{km}$$

$$h = \sqrt{\mu p} = 32\,485.86\,\frac{\mathrm{km}^2}{\mathrm{s}}$$

$$h = v_\infty \Delta$$

$$\Delta = \frac{h}{v_\infty} = 16\,463\,\mathrm{km} \quad \Box$$

Part D

$$r_p = a(1 - e) = 8800 \,\mathrm{km}$$

Problem 6:

Give the orbital element for an Earth-orbiting spacecraft crossing the \hat{y} axis in a retrograde, equatorial, circular orbit at an altitude of 1 DU. All angles should be given in degrees.

- 1. What is the semi-major axis (in DU)?
- 2. Eccentricity?
- 3. Inclination?
- 4. Logitude of the ascending node?
- 5. Argument of periapsis?
- 6. True anomaly?
- 7. True longitude at epoch?

Solution

Part A

Circular orbit $\therefore a = 2 \,\mathrm{DU} \quad \Box$

Part B

Circular orbit $:: e = 0 \quad \square$

Part C

Retrograde orbit : $i = 180^{\circ}$ \square

Part D

Equatorial orbit $:: \Omega = 0 \quad \Box$

Part E

Circular orbit $:: \omega = 0 \quad \square$

Part F

Crossing the $\hat{\boldsymbol{y}}$ axis $\therefore \nu = 270^{\circ}$

Part G

Crossing the $\hat{\boldsymbol{y}}$ axis $\therefore L = 270^{\circ}$

Problem 7:

Match the following orbits to the descriptions below:

Spacecraft ID	e	i (°)	$\Omega\left(^{\circ}\right)$	ω (°)	ν (°)
A	1	60	180	160	30
В	2	160	260	90	10
C	0.5	20	210	30	180
D	0.2	90	110	210	270

- 1. This is a retrograde orbit
- 2. This spacecraft currently has a positive flight path angle
- 3. This spacecraft is currently in the southern hemisphere
- 4. This spacecraft is currently at apoapsis
- 5. This orbit has a periapsis in the southern hemisphere
- 6. This orbit has a line of nodes that is colinear with \hat{x}

Solution

- 1. B
- 2. A, B
- 3. A, C
- 4. C
- 5. D
- 6. A

Problem 8:

Given an elliptical orbit about the Earth with an eccentricity of 0.3 and a radius of periapsis of 8000 km, calculate the time of flight of the following:

- 1. From $\nu = 20^{\circ} \rightarrow 30^{\circ}$
- 2. From $\nu = 300^{\circ} \rightarrow 20^{\circ}$

Solution

Part A

$$\nu = 30^{\circ}$$

$$\nu_{0} = 20^{\circ}$$

$$k = 0$$

$$\mu = 3.986 \times 10^{5} \frac{\text{km}^{3}}{\text{s}^{2}}$$

$$E = \arccos\left(\frac{e + \cos(\nu)}{1 + e\cos(\nu)}\right) = 0.3883 \text{ rad}$$

$$E_{0} = \arccos\left(\frac{e + \cos(\nu_{0})}{1 + e\cos(\nu_{0})}\right) = 0.2573 \text{ rad}$$

$$r_{p} = a(1 - e) \implies a = \frac{r_{p}}{1 - e} = 11428.57 \text{ km}$$

$$\Delta T = \sqrt{\frac{a^{3}}{\mu}} \left(2k\pi + (E - e\sin(E)) - (E_{0} - e\sin(E_{0}))\right) = 181.35 \text{ s} \quad \Box$$

Part B

$$\nu = 20^{\circ}$$

$$\nu_{0} = 300^{\circ}$$

$$k = 1$$

$$E = \arccos\left(\frac{e + \cos(\nu)}{1 + e\cos(\nu)}\right) = 0.2573 \text{ rad}$$

$$E_{0} = \arccos\left(\frac{e + \cos(\nu_{0})}{1 + e\cos(\nu_{0})}\right) = -0.80147 \text{ rad} \implies E_{0} = 2\pi + (-0.80147) = 5.4817 \text{ rad}$$

$$\Delta T = \sqrt{\frac{a^{3}}{\mu}} \left(2k\pi + (E - e\sin(E)) - (E_{0} - e\sin(E_{0}))\right) = 1484.2 \text{ s} \quad \Box$$