

Lecture 9: Coordinate Frames & Holmann transfers



Coordinate Systems:

Earth-Centered Inertial: (ECI)

\hat{x} : vernal equinox

\hat{y} : completes the RH'd system

\hat{z} : perpendicular to equatorial plane

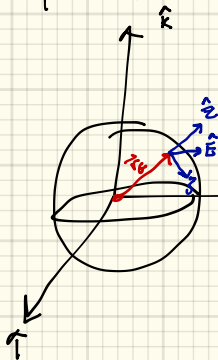
Perifocal Frame: PQW

Earth-Centered Earth-Fixed: (ECEF)

Same as ECI, but the frame rotates with the Earth.

in this case, \hat{x} always points towards the Greenwich meridian.

Topocentric Horizon: SEZ



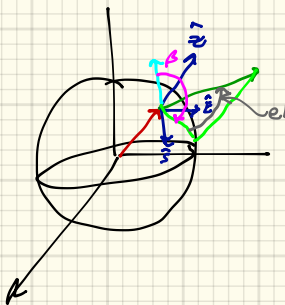
\vec{r}_G : position of the ground station

SEZ origin is at \vec{r}_G

\hat{s} points South

\hat{e} points East

$\hat{z} \parallel \vec{r}_G$



β = azimuth = measured clockwise from North to the projection in the SE plane.

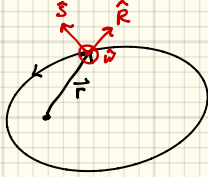
e_1 : elevation: measured from the SE projection to the vector

Heliocentric Ecliptic: origin = sun

\hat{x} : vernal equinox

x, y plane is the ecliptic

Satellite: RSW



\hat{R} is along the position vector

\hat{w} is along \hat{v}

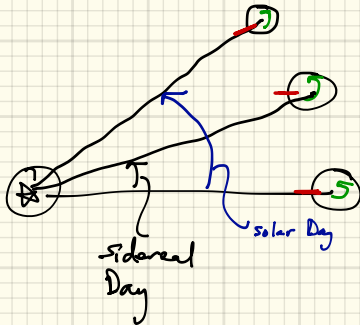
\hat{S} completes the RTH'd system

Time:

Solar Day: Amount of time between 2 sunrises

slightly more time than it's required for Earth to rotate 360° .

Sidereal Day: time required for Earth to rotate 360° about its axis.



Julian Date: Interval of time (measured in Days) from Jan 1 9713 B.C. at Noon

- often used when calculating the position of planetary bodies
- day starts at noon
- Need a lot of sigfigs, b/c values are in the millions

Maneuvers:

Δv is the magnitude of the velocity change from orbit A to orbit B.

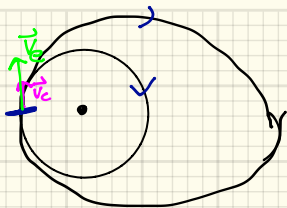
We solve for both Δv magnitude & also the direction of the burn.

Assume instantaneous maneuvers.

Larger $\Delta v \Rightarrow$ more fuel.

To transfer between 2 orbits using a single, instantaneous maneuver, the 2 orbits must intersect.

At the intersection point, change the velocity vector from its initial value to the value on orbit B at that point.



Velocity of ^{this} ellipse at perapsis is greater than the velocity of the circle. (From E eqn $a_{\text{ellipse}} > a_{\text{circle}}$)

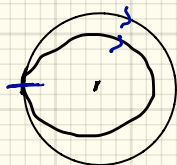
Velocity of the ellipse at perapsis and the circle are in the same direction b/c $\gamma = 0$ for both orbits at that point.

Initially on the Circular orbit.

Execute a maneuver to get on the elliptical orbit, need to increase velocity

$$\Delta V = V_e - V_c$$

This type of maneuver where the velocity vector direction does not change is called a "tangential" maneuver.



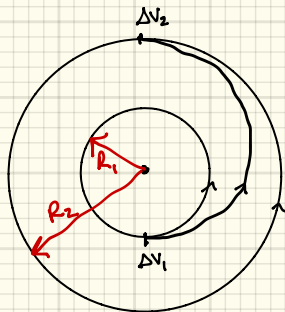
Transfer from Circle to ellipse.

S/C needs to slow down

Velocity vectors are in the same direction = tangential maneuver

$$\Delta V = V_c - V_e$$

Hohmann Transfer: Cheapest Maneuver between 2 circular orbits:



Half an ellipse connects R_1 & R_2

ΔV_1 & ΔV_2 are both tangential maneuvers

$$\Delta V_1 = V_{bp} - V_{c1}$$

V_{bp} = velocity of the transfer orbit at perapsis

$$V_{c1} = \sqrt{\frac{\mu}{R_1}}$$

$$\mathcal{E} = \frac{V_{bp}^2}{2} - \frac{\mu}{R_1} = -\frac{\mu}{R_1 + R_2} \Rightarrow V_{bp} = \sqrt{\frac{2\mu}{R_1} - \frac{2\mu}{R_1 + R_2}}$$

$$\Delta V_1 = \sqrt{\frac{2\mu}{R_1} - \frac{2\mu}{R_1 + R_2}} - \sqrt{\frac{\mu}{R_1}} \rightarrow \text{increase S/C velocity by this amount}$$

$$\Delta V_2 = V_{ca} - V_{c2}$$

$$V_{c2} = \sqrt{\frac{\mu}{R_2}}$$

V_{ca} = velocity of transfer orbit at apoapsis

$$\mathcal{E} = \frac{V_{ca}^2}{2} - \frac{\mu}{R_2} = -\frac{\mu}{R_1 + R_2} \Rightarrow V_{ca} = \sqrt{\frac{2\mu}{R_2} - \frac{2\mu}{R_1 + R_2}}$$

$$\Delta V_2 = \sqrt{\frac{\mu}{R_2}} - \sqrt{\frac{2\mu}{R_2} - \frac{2\mu}{R_1 + R_2}}$$

$$\Delta V_{\text{tot}} = \Delta V_1 + \Delta V_2$$