

What about phase?

Recall:

$$\angle G(j\omega) = \angle K_B - N\angle(j\omega) + \sum_{i=1}^m \angle(1 - \frac{j\omega}{z_i}) - \sum_{k=N+1}^n \angle(1 - \frac{j\omega}{p_k})$$

$$\angle K_B = \begin{cases} 0 & K_B > 0 \\ -180 & K_B < 0 \end{cases} \text{ for all } \omega \geq 0$$

$$\angle(j\omega) = 90^\circ \text{ for all } \omega \geq 0$$

So, low frequency phase is constant at

$$-90N \quad \text{if } K_B > 0$$

$$-180 - 90N \quad \text{if } K_B < 0$$

Other poles/zeros will cause "bends" at higher freqs.

Phase response from other poles/zeros

Consider again in generic form $(1+j\omega\tau)$ with

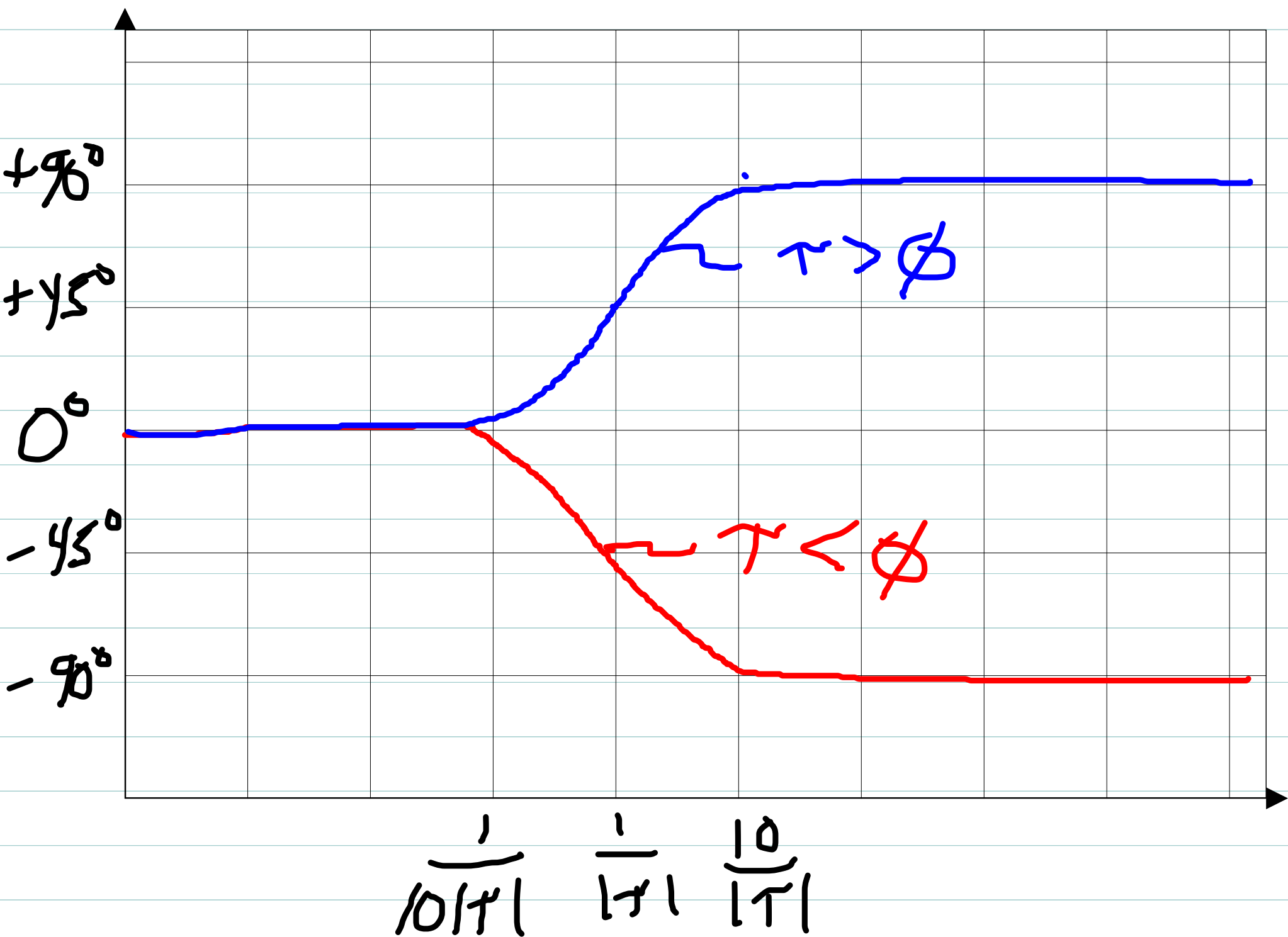
$$\tau = -1/z_i \text{ or } \tau = -1/p_k$$

$$\angle(1+j\omega\tau) = \tan^{-1}\omega\tau$$

$$= \begin{cases} 0 & \text{if } \omega \ll 1/|\tau| \\ +45^\circ & \text{if } \omega = 1/|\tau| \\ +90^\circ & \text{if } \omega \gg 1/|\tau| \end{cases}$$

above is for $\tau > 0$. If instead $\tau < 0$

$$\angle(1+j\omega\tau) = -\tan^{-1}\omega|\tau| = \begin{cases} 0 & \text{if } \omega \ll 1/|\tau| \\ -45^\circ & \text{if } \omega = 1/|\tau| \\ -90^\circ & \text{if } \omega \gg 1/|\tau| \end{cases}$$



Observations

=> Phase change due to a single factor occurs in a 2 decade band of frequencies centered at the magnitude corner frequency $1/\tau$

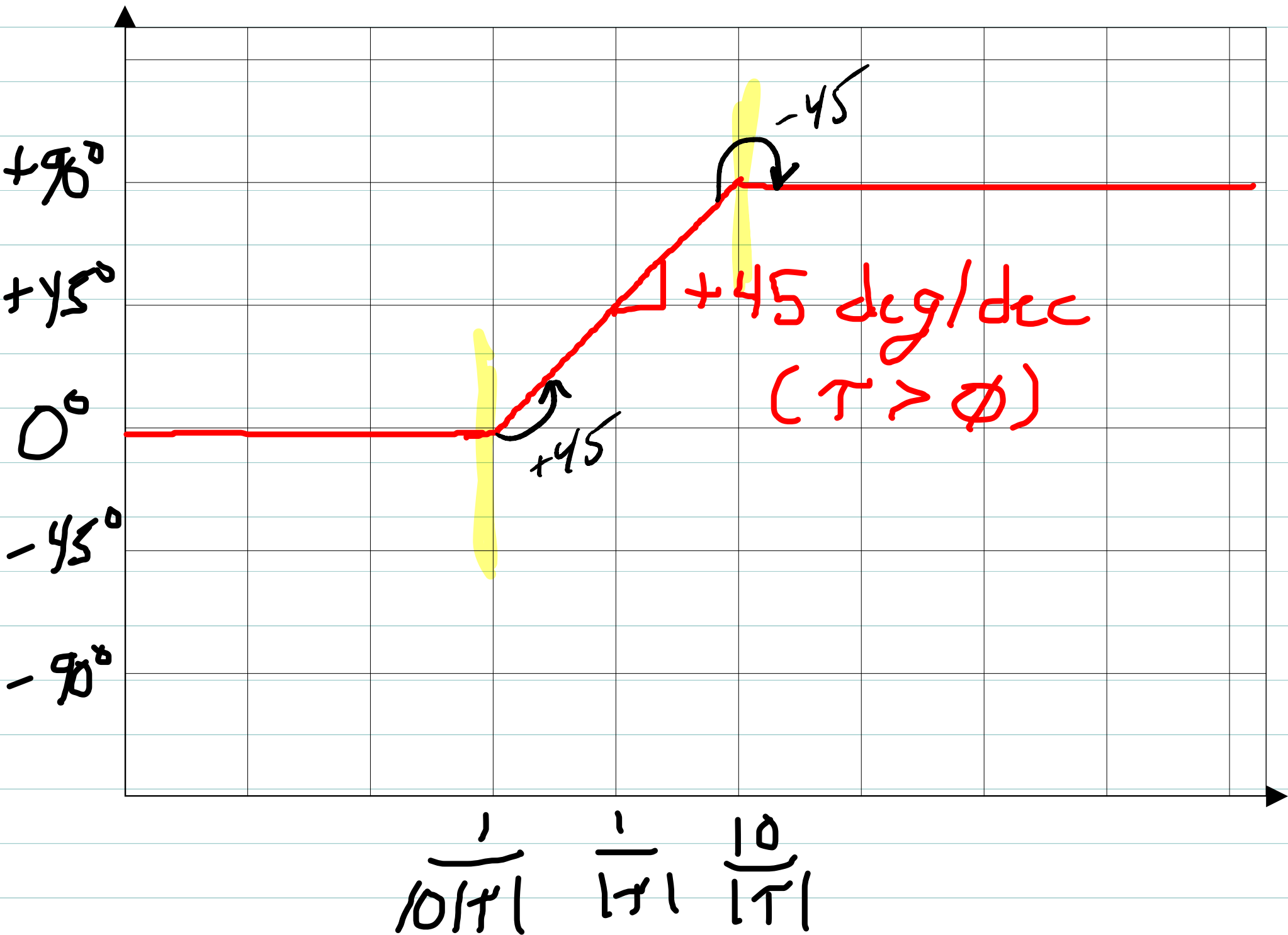
i.e. in band $\frac{1}{10|\tau|} \leq \omega \leq 10/|\tau|$

=> Phase is constant outside this band

low freq phase $\approx 0^\circ$

h.f. phase $\approx \pm 90^\circ$ ($+90^\circ$ if $\tau > 0$, -90° if $\tau < 0$)

=> Phase change is approximate linear across band with slope $\pm 45^\circ/\text{dec}$



Sign of phase change depends on:

=> whether factor is pole or zero

=> whether factor is RHP ($\tau < 0$) or LHP ($\tau > 0$)

Suppose all factors are LHP, $z_i < 0$ $p_k < 0$

then all $\tau = -1/z_i$ or $-1/p_k$ are positive.

This is called the "minimum phase" case

Then:

=> zeros cause $+90^\circ$ phase change over band
 $\frac{10}{10}$ to $10|z_i|$

=> poles cause -90° change over $\frac{10}{10}$ to $10|p_k|$

(Minimum Phase Systems)

Slopes of phase change are $+45^\circ/\text{dec}$ (zeros) or $-45^\circ/\text{dec}$ (poles) in these bands

Note phase changes in minimum phase cases mirror those for magnitude changes:

\Rightarrow zeros cause positive slope changes

\Rightarrow poles cause negative slope changes.

Graphical addition is again straightforward, but requires a little care:

\Rightarrow slopes are nonzero only in a 2 decade band

\Rightarrow bands from different factors may overlap.

Example:

$$G(s) = \frac{10s+1}{s(s+1)(s/10+1)}$$

Low freq. phase -90°

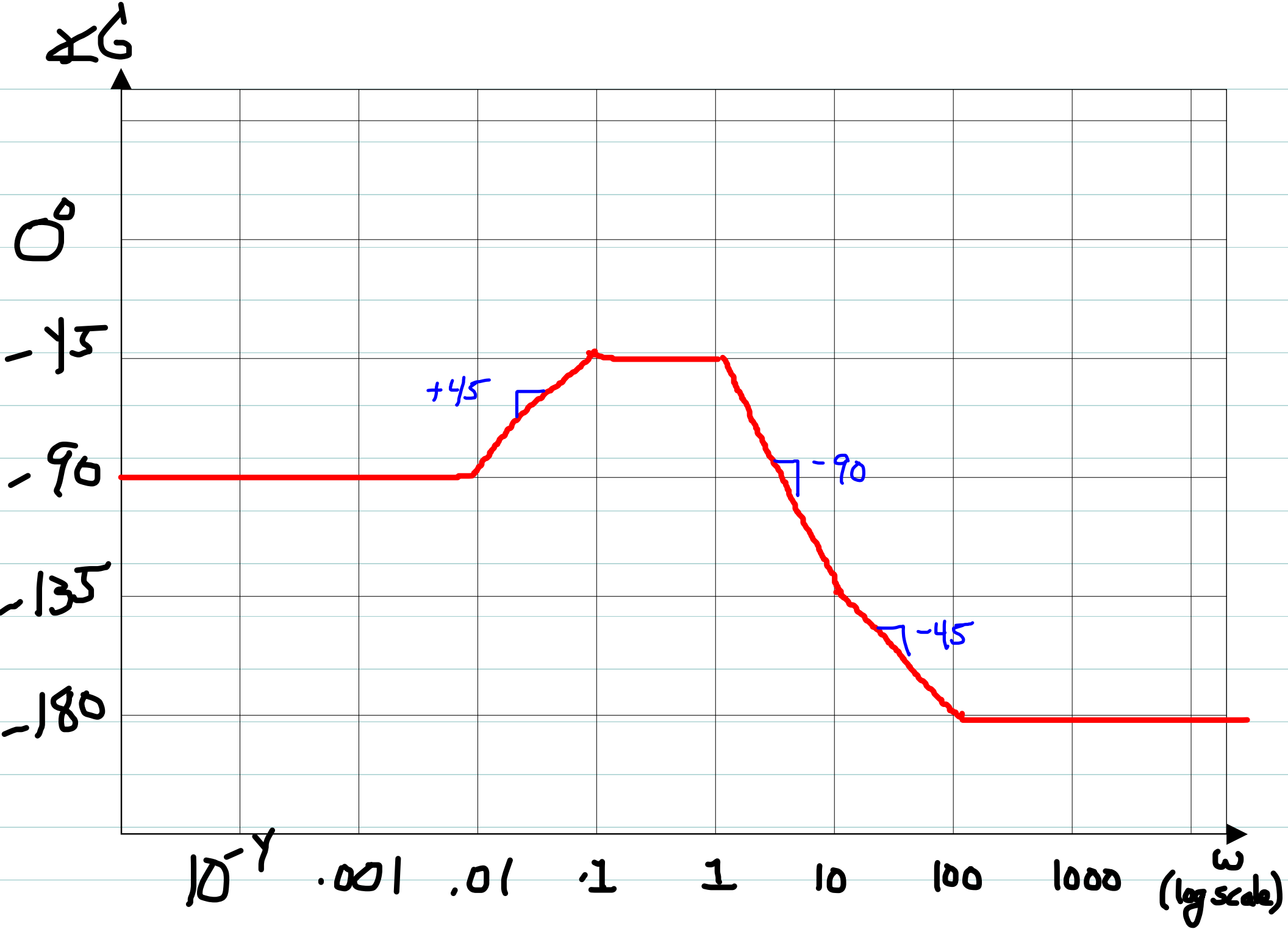
Phase changes:

$+45^\circ/\text{dec}$ in $.01$ to 1
 $-45^\circ/\text{dec}$ in $.1$ to 10
 $-45^\circ/\text{dec}$ in 1 to 100

Net:

$+45^\circ/\text{dec}$ in $.01$ to $.1$
 $0^\circ/\text{dec}$ in $.1$ to 1
 $-90^\circ/\text{dec}$ in 1 to 10
 $-45^\circ/\text{dec}$ in 10 to 100

Constant for $\omega > 100$.



Repeated factors

Repeated factors $(1+j\omega T)^l$ multiply the phase changes by l , just like magnitudes.

Example:

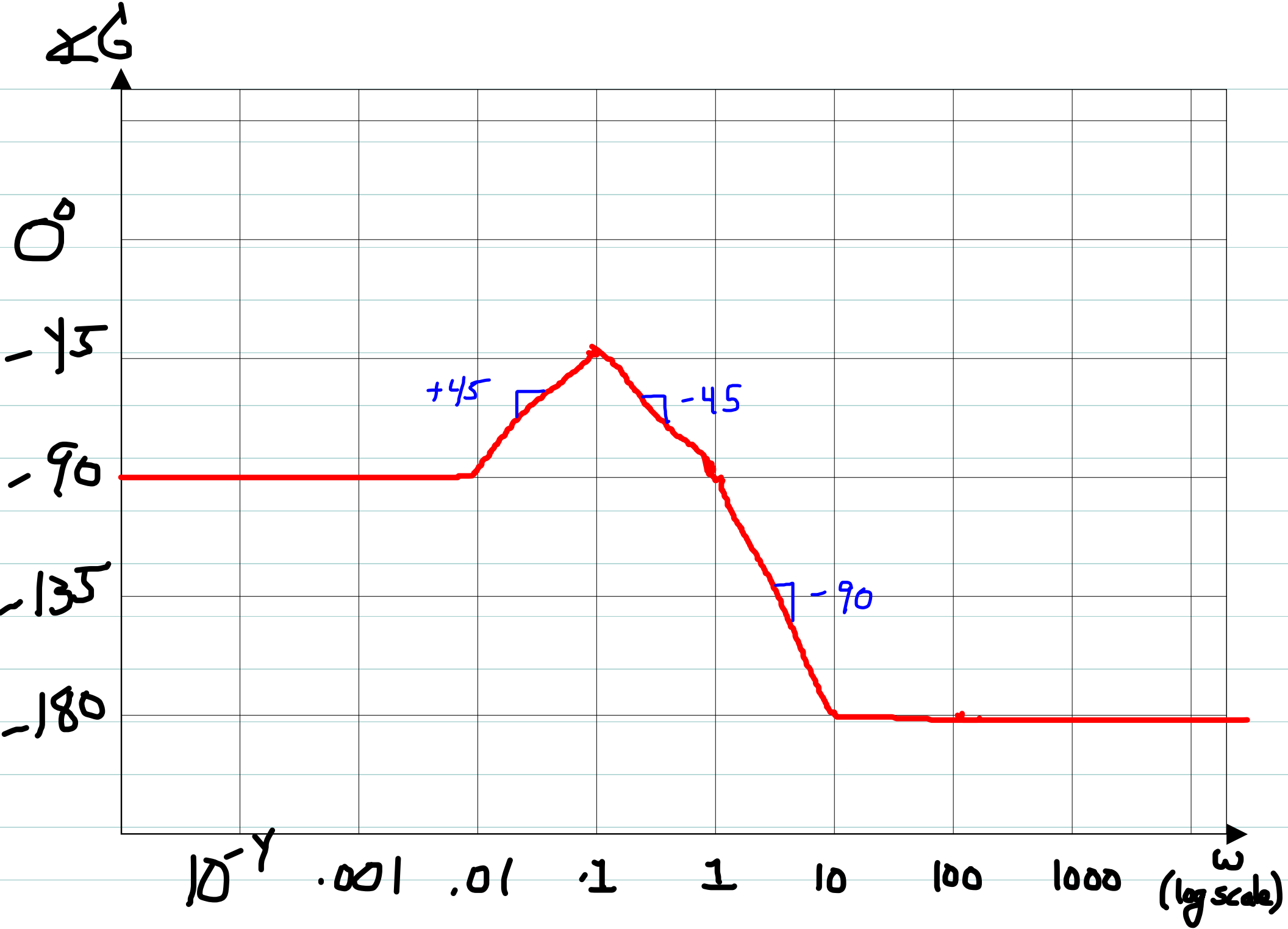
$$G(s) = \frac{10s+1}{s(s+1)^2}$$

Changes:

+45°/dec in .01 to 1
-90°/dec in .1 to 10

Net:

+45°/dec in .01 to .1
-45°/dec in .1 to 1
-90°/dec in 1 to 10



Summary (minimum phase)

\Rightarrow Low freq. phase is $\angle K_B - N 90^\circ$

\Rightarrow high freq. phase is $\angle K_B - 90^\circ (n-m)$

\Rightarrow Note low and high freq. phases are constant (slope is zero).

\Rightarrow Recall typically $n > m$ for a physical system so high freq. phase is typically negative for a minimum phase system.

\Rightarrow zeros cause $+90^\circ$ change at rate of $+45^\circ/\text{dec}$ in 2 decade band centered at $|z_i|$

\Rightarrow poles cause -90° change at rate of $-45^\circ/\text{dec}$ in 2 decade band centered at $|p_k|$.

Can be tricky to accurately sketch phase

- ⇒ Overlapping change regions for multiple factors
- ⇒ No standard formula for phase change of underdamped factors
- ⇒ Helps to ^{1st} make a table of slope changes over frequency ranges as above
- ⇒ Generally, straight-line phase sketch is less accurate than magnitude sketch.
- ⇒ Still sufficiently accurate to give us a good general idea of phase behavior.
- ⇒ We'll use Matlab when greater accuracy is required.

Non-minimum phase systems

If any poles or zeros of $G(s)$ in RHP, the system is "Non-minimum phase"

Corresponds to $\tau < 0$ in phase analysis and
 $\angle(1+j\omega\tau) = -\tan^{-1}\omega/|\tau|$.

\Rightarrow Phase response is negative of that seen above

\Rightarrow In particular, zeros cause -90° phase change in 2 decade band around corner freq.

poles cause $+90^\circ$ change

Opposite of minimum phase behavior, but

Corner freqs unchanged ($|z_i|$ or $|p_k|$)

Example:

$$G(s) = \frac{(10s+1)}{(1-s)}$$

Min phase zero: $+45^\circ/\text{dec}$ change in .01 to 1

Nonmin phase pole: $+45^\circ/\text{dec}$ change in .1 to 10

Net:

- $+45^\circ/\text{dec}$ in .01 to .1
- $+90^\circ/\text{dec}$ in .1 to 1
- $+45^\circ/\text{dec}$ in 1 to 10.

Note: h.f. phase is $+180^\circ$ here. Above rule for h.f. phase in min phase systems does not apply if $G(s)$ has RHP poles or zeros

Underdamped factors

$$(s^2 + 2\xi\omega_n s + \omega_n^2) \Rightarrow \left[\left(\frac{s}{\omega_n}\right)^2 + 2\xi\left(\frac{s}{\omega_n}\right) + 1 \right] \text{ in Bode form.}$$

How do we draw magnitude response when $G(s)$ contains these factors?

\Rightarrow If $\frac{\sqrt{2}}{2} \leq \xi \leq 1$, we can well approximate the response as a repeated pole at $-\omega_n$ (it isn't really, but it's a good approx to sketch this way).

\Rightarrow If $0 \leq \xi < \frac{\sqrt{2}}{2}$ a more substantial correction is needed...

\Rightarrow To illustrate, suppose

$$G(s) = \frac{\omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2} = \frac{1}{\left[\left(s/\omega_n\right)^2 + 2\xi\left(s/\omega_n\right) + 1 \right]}$$

Let's find $|G(j\omega)|$ here

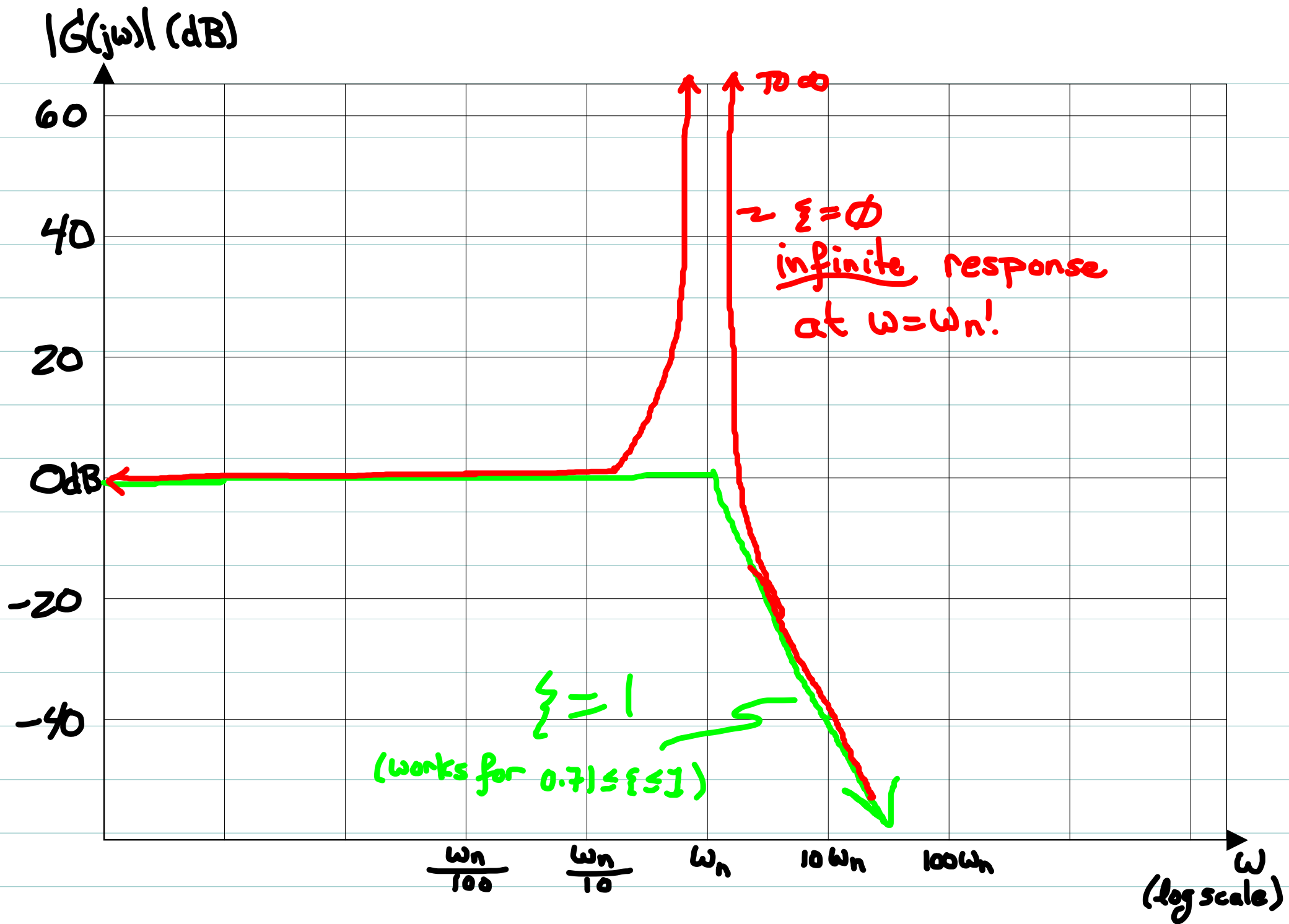
$$|G(j\omega)| = \left| \left(\frac{j\omega}{\omega_n} \right)^2 + 2\xi \left(\frac{j\omega}{\omega_n} \right) + 1 \right|^{-1}$$
$$= \left[\sqrt{\left(1 - \left(\frac{\omega}{\omega_n} \right)^2 \right)^2 + 4\xi^2 \left(\frac{\omega}{\omega_n} \right)^2} \right]^{-1}$$

Which is ugly, so why bother?

Consider if $\xi = 0$, then

$$|G(j\omega)| = \frac{1}{\left| 1 - \left(\frac{\omega}{\omega_n} \right)^2 \right|} \approx \begin{cases} 1 & \text{if } \omega \ll \omega_n \\ \left| \frac{\omega}{\omega_n} \right|^{-2} & \omega \gg \omega_n \end{cases}$$

so that $|G(j\omega)|_{\omega=\omega_n} = \infty$ **!!!** Definitely something goes on!



When $0 < \zeta < \sqrt{2}/2$, a similar "peaking"

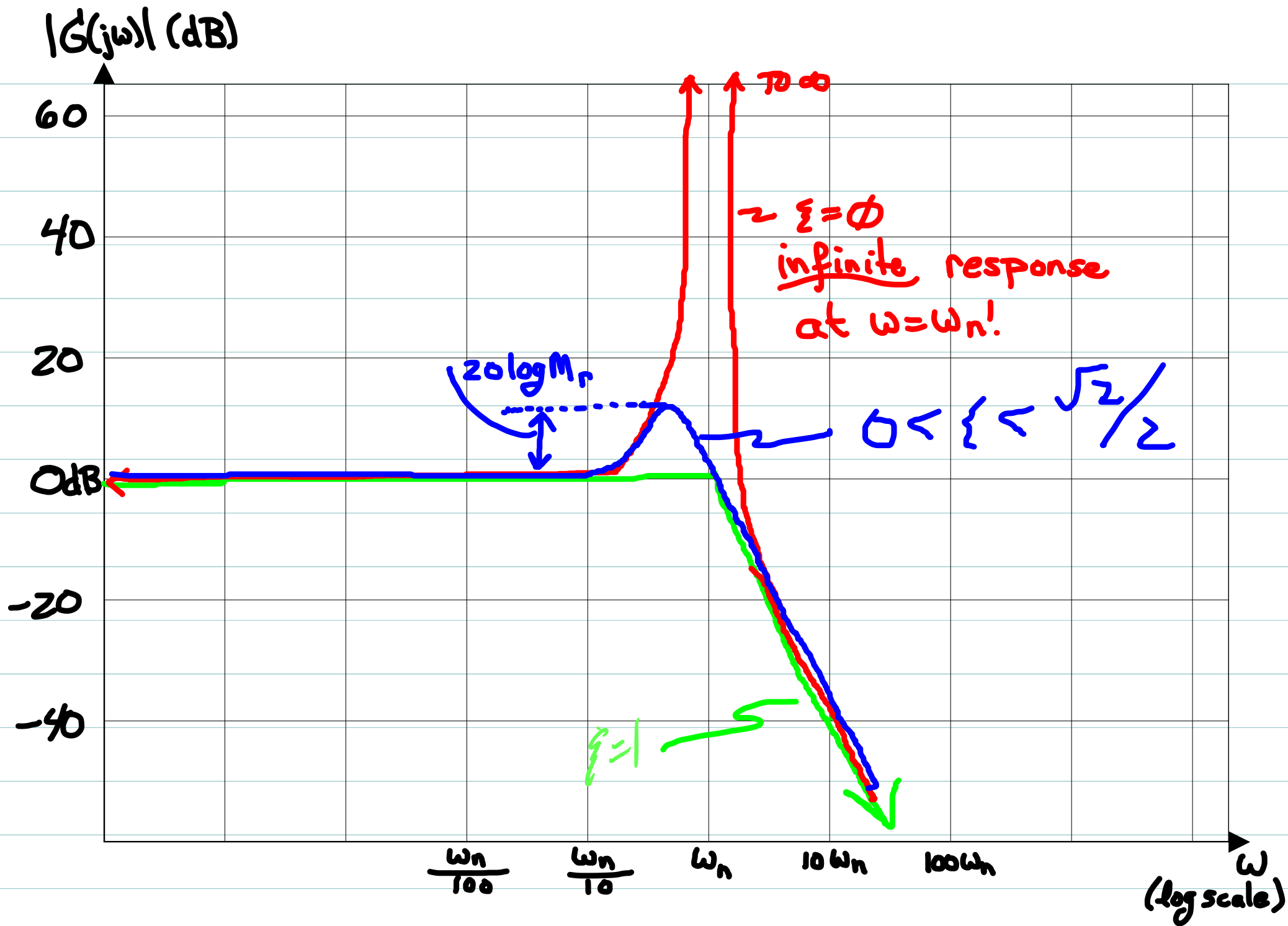
phenomenon occurs, but peak height is finite:

for $G(s) = \left[\left(\frac{s}{\omega_n} \right)^2 + 2\zeta \left(\frac{s}{\omega_n} \right) + 1 \right]^{-1}$

Max $|G(j\omega)|$ occurs at:
 $\omega \geq 0$

$$\omega_r = \omega_n \sqrt{1 - 2\zeta^2}$$

and $|G(j\omega_r)| = \frac{1}{2\zeta\sqrt{1-\zeta^2}} \triangleq M_r$



This is the phenomenon of resonance

An ideal (no zeros) underdamped 2nd order system with $0 \leq \xi < \frac{\sqrt{2}}{2}$ will exhibit output amplitudes significantly greater than the input amplitude when input frequency is close to the natural frequency ω_n .

The largest amplitude ratio will occur at the

resonant frequency

$$\omega_r = \omega_n \sqrt{1 - 2\xi^2} < \omega_n$$

and the maximal amplitude ratio (maximal resonance) is

$$M_r = \frac{1}{2\xi\sqrt{1-\xi^2}}$$

Notes:

- 1.) Height of peak on diagram is M_r in dB, i.e. $20 \log M_r$
- 2.) When 2nd order factor in TF with other factors, the peak is $20 \log M_r$ above whatever magnitude the plot would otherwise have at ω_r . That is, M_r is a relative offset to plot, not absolute.

3.) For small ξ , say $0 < \xi \leq 1/10$

$$\omega_r \approx \omega_n \quad \text{and} \quad M_r \approx 1/(2\xi)$$

So $20 \log M_r \approx -[6 + 20 \log \xi]$ is a good approximation

i.e. at $\xi = 1/10$, $20 \log M_r \approx +14$ dB

Example

$$G(s) = \left[\frac{40s+1}{s \left(\left(\frac{s}{10} \right)^2 + 0.2 \left(\frac{s}{10} \right) + 1 \right)} \right]$$

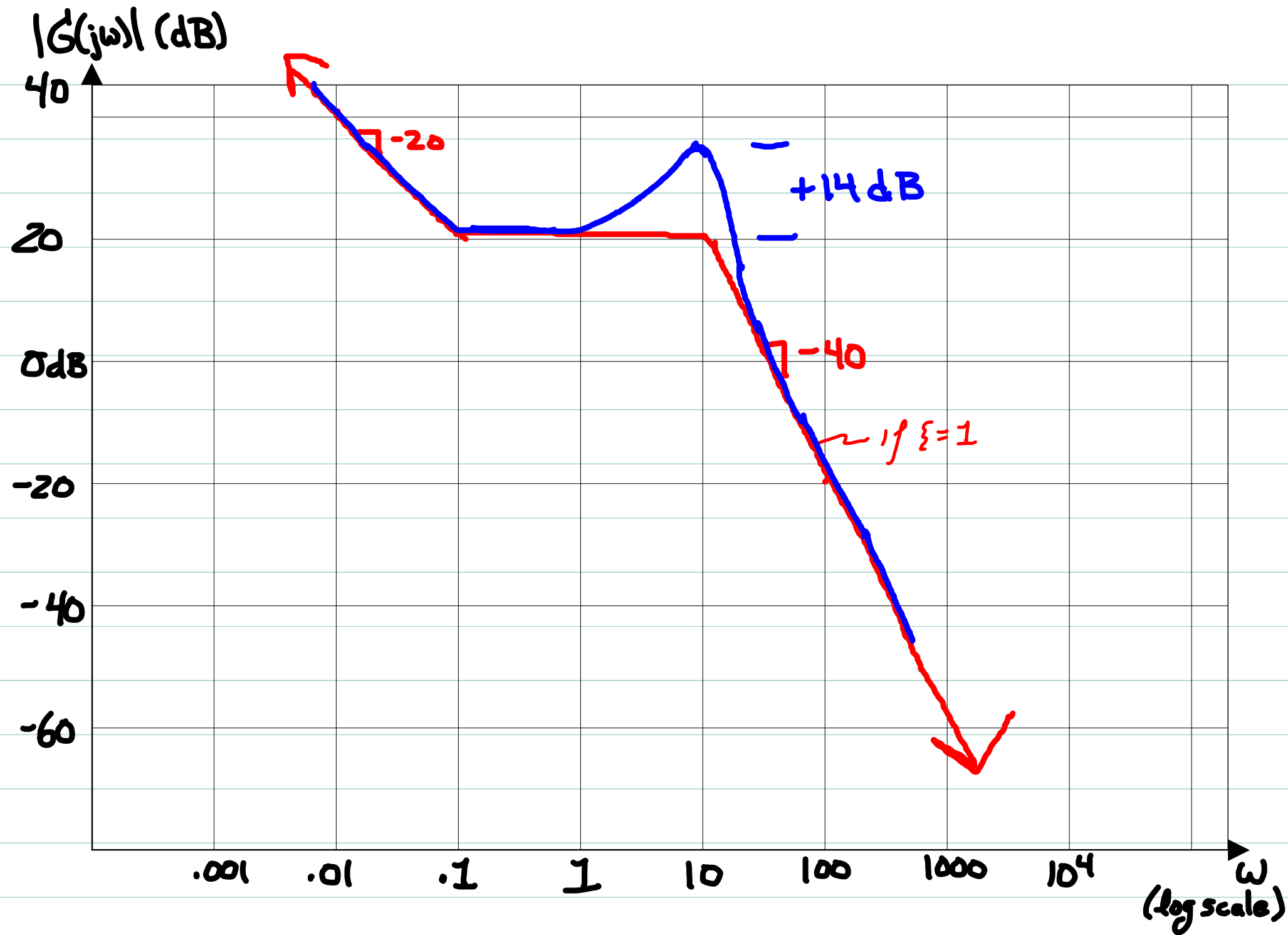
Same as example above, except:

$$K_B = 1 \quad (\text{instead of } 10)$$

$$\xi = 0.1 \quad (\text{instead of } \xi = 1)$$

$$\omega_n = 10$$

\Rightarrow Expect resonant peak of height +14dB
near $\omega = 10$.



2nd order min phase factors - phase

$$\left[\left(\frac{s}{\omega_n} \right)^2 + 2\zeta \left(\frac{s}{\omega_n} \right) s + 1 \right]^{\pm 1}$$

\Rightarrow Like magnitudes, can sketch as repeated real factor ($\zeta=1$) for $\sqrt{2}/2 \leq \zeta \leq 1$

\Rightarrow for $0 \leq \zeta < \frac{\sqrt{2}}{2}$, a more significant correction is needed

\Rightarrow When $\zeta=0$, phase changes discontinuously by $\pm 180^\circ$ at $\omega = \omega_n$

Example:

$$G(s) = \frac{(s/10 + 1)}{[s^2 + 2\zeta s + 1]}$$

If $\zeta = 1$:

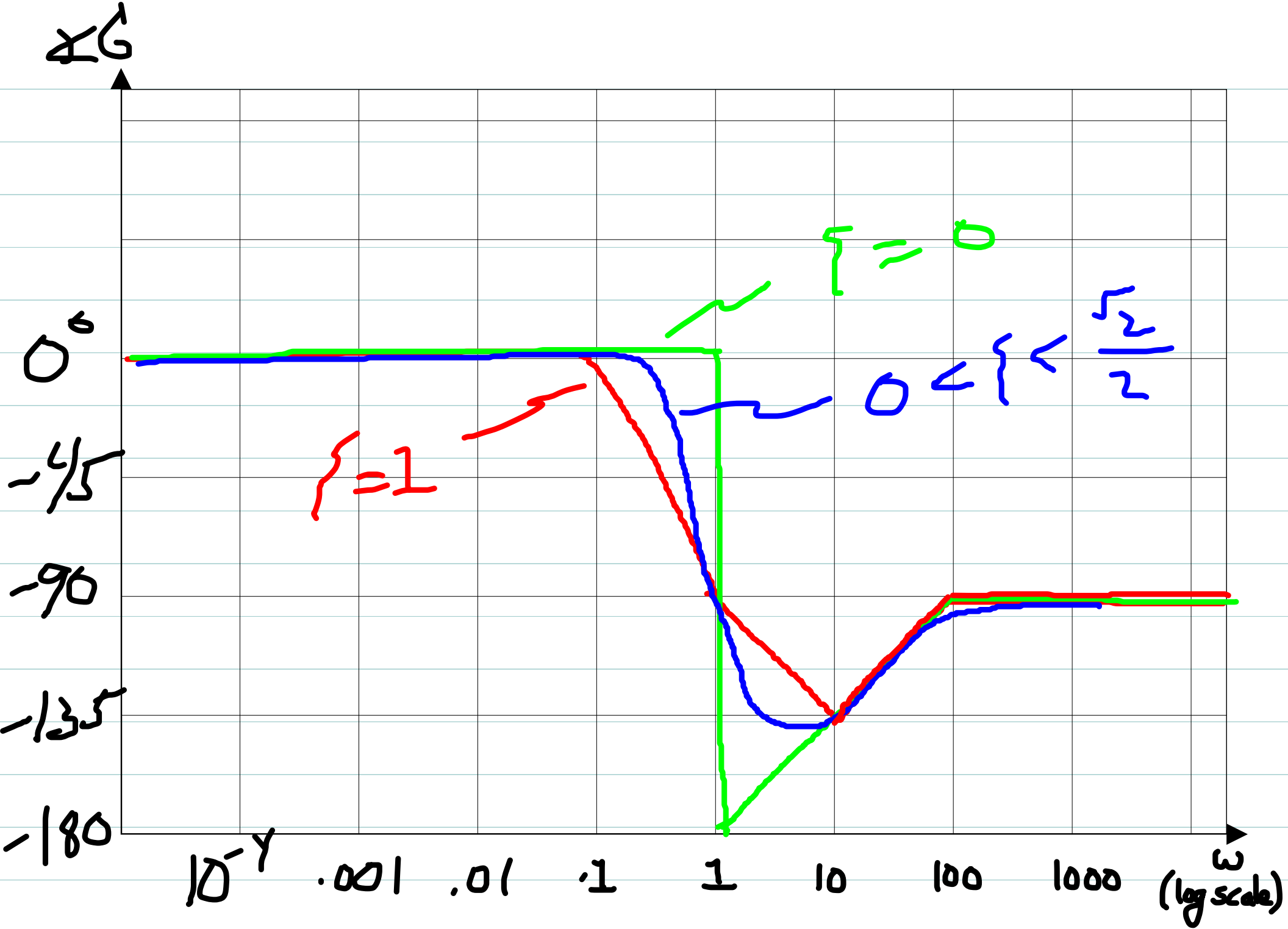
Change of $-90^\circ/\text{dec}$ in $.1$ to 10
Change of $+45^\circ/\text{dec}$ in 1 to 100

Net is $-90^\circ/\text{dec}$ from $.1$ to 1
 $-45^\circ/\text{dec}$ from 1 to 10
 $+45^\circ/\text{dec}$ from 10 to 100

If $\zeta = 0$

Change of $+45^\circ/\text{dec}$ in 1 to 100

-180° drop at $\omega = \omega_n = 1$



Notes: (2nd order phase, small ξ)

- Unlike magnitude, no useful simple formula to quantify "steepness" of phase drop for small ξ .
- Usually sketch something in between the $\xi=1$ and $\xi=0$ limits
- Necessarily qualitative - will use Matlab when precise analysis is needed.
- Note generally that we expect to see steep phase drops near frequencies where magnitude diagram shows resonant peaks!