# **R** documentation

of '/Users/vaibhavthakkar/Desktop/CS335/randomized\_lp\_solver.rd' March 18, 2020

randomized\_lp\_solver Solving a LP problem using Randomized algorithms.

#### **Description**

Currently, only 2 algorithms are implemented - Randomized Cutting plane and Simulated Annealing.

#### Usage

```
randomized_lp_solver(P, obj, bounds = NULL, algo = 0L, verbose = FALSE)
```

# Arguments

bounds

optional. A list that contains the bound of the variables (the default is complete Real space), as follows:

- indices A vector containing the variable indices (0 indexed) for which the bounds have to be set.
- lowerA vector containing the value of lower bounds for all the variables specified in indices.
- upperA vector containing the value of upper bounds for all the variables specified in indices.

algo

Optional. An unsigned integer that declares which algorithm, as follows:

- 0 Use the Randomized Cutting Plane algorithm (RCP).
- 1 Use the Simulated Annealing algorithm (SIM\_ANN).

verbose

Optional. A boolean parameter for printing out the LP program formed.

P. A convex H Polytope, it is the feasible region of the LP problem  $(Ax \le b)$ .

obj. A vector for the coefficients of the objective function  $(minc^T x)$ .

### Value

A list containing the value of the objective function and value of all variables.

#### References

Dabbene, Fabrizio, Pavel S. Shcherbakov, and Boris T. Polyak., "A randomized cutting plane method with probabilistic geometric convergence," SIAM Journal on Optimization 20.6, (2010): 3185-3207...

Adam Tauman Kalai, Santosh Vempala, "Simulated Annealing for Convex Optimization," Mathematics of Operations Research Vol. 31, No. 2, 2006.

## **Examples**

```
# computing Chebychev ball for a H-polytope (3d cube)
P <- gen_cube(3, 'H')
row_norm <- sqrt(rowSums((P$A)^2))
P$A <- cbind(P$A, row_norm)
var_bounds <- list("indices"=c(3), "lower"=c(0), "upper"=c(1000))
randomized_lp_solver(P, obj=c(0,0,0,-1), bounds=var_bounds, algo=1, verbose=TRUE)</pre>
```

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