

Interaction Between Classes And Algorithm Overview

1. **Class MultiStrokeRec.cpp:** Main Class in order to Run the Project
2. **DirAccess.cpp:** class to load the and simulate a video stream in the application



3. **ImageProcessing.cpp:** The core of the project

```
//Calculates optimized threshold using histogram equalization by iterations
void ImageProc::HistEqu(cv::Mat* ImgSrc, int32_t* Thres, uint16_t bins)
{
    this->Hist(ImgSrc, &Equhist, bins)           //Calculate histogram
    this->CumHist(&Equhist, &EquCumHist)         //Calculate cumulative histogram
    ...
}
```

```
void ImageProc::Thres(cv::Mat& ImgSrc, cv::Mat& ImgDest, int32_t* Thres)
{
    //Segment the hand based on a threshold
```



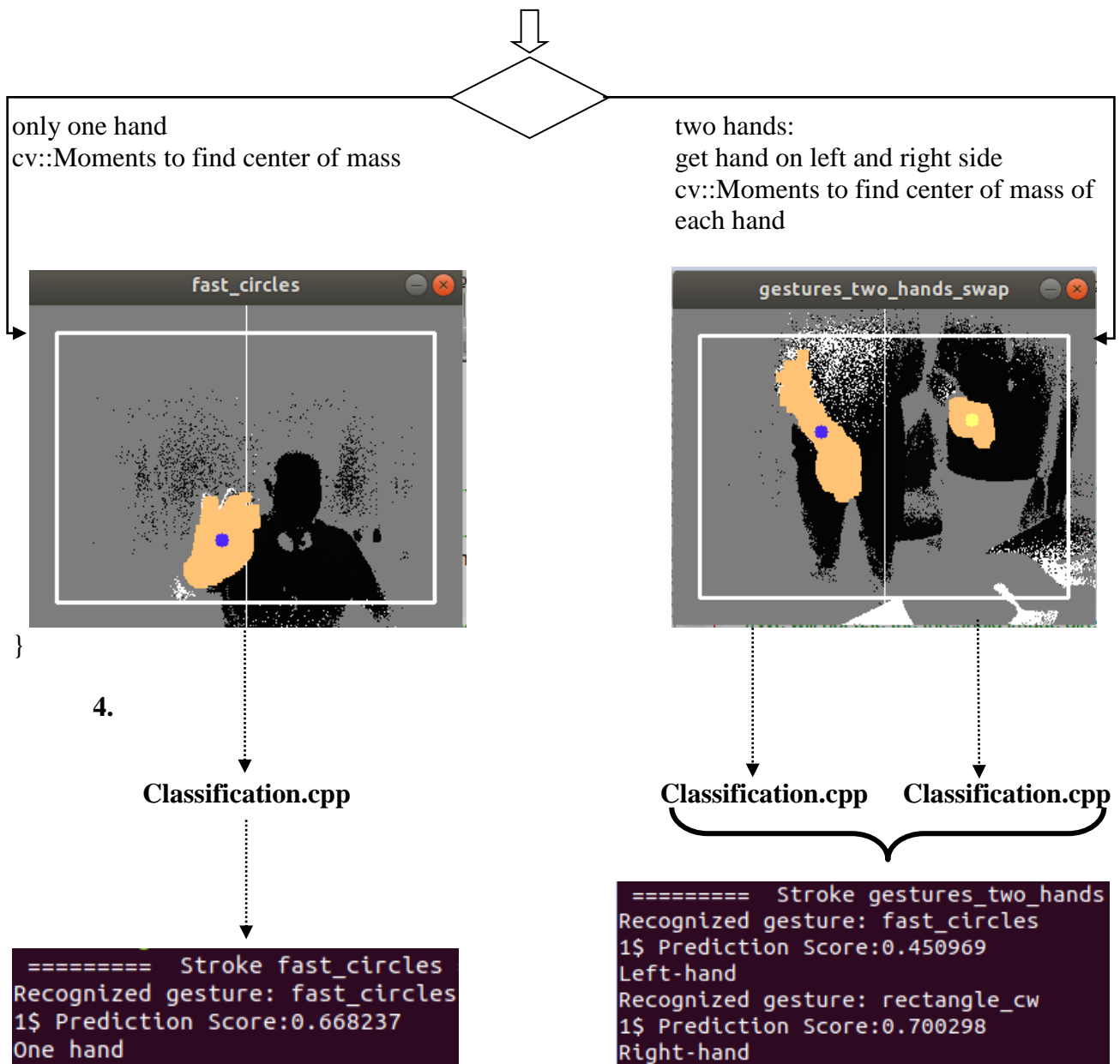
```
}
```

//Calculates the center of the mass utilizing OpenCV available resources

void ImageProc::BlobAnalysis(cv::Mat& ImgSrc, cv::Mat& ImgDest)

{

- a) Calculate the ROI
- b) Divide the screen in two vertical parts
- c) cv::inRange detects object based on range of pixel values that fall under the threshold
- d) cv::erode and cv::dilate to clean image and remove false positives. It also makes the threshold object more visible
- e) cv::findContours to join continuous points with same intensity
- f) get the biggest contour and the second biggest (if exists)
- g) Verify how many hands were found:



Classification.cpp uses the sequence of positions to classify the stroke with \$1 Unistroke Recognizer.

Implementation Guide

Dependencies

OpenCV https://docs.opencv.org/3.3.1/d7/d9f/tutorial_linux_install.html

Go to the project dir

open CMakeLists.txt and adjust the path to your OpenCV dir

in command line `cd <root project dir>`

Build

`cmake CMakeLists.txt`

`make`

Run

`./bin/MultistrokeRec`