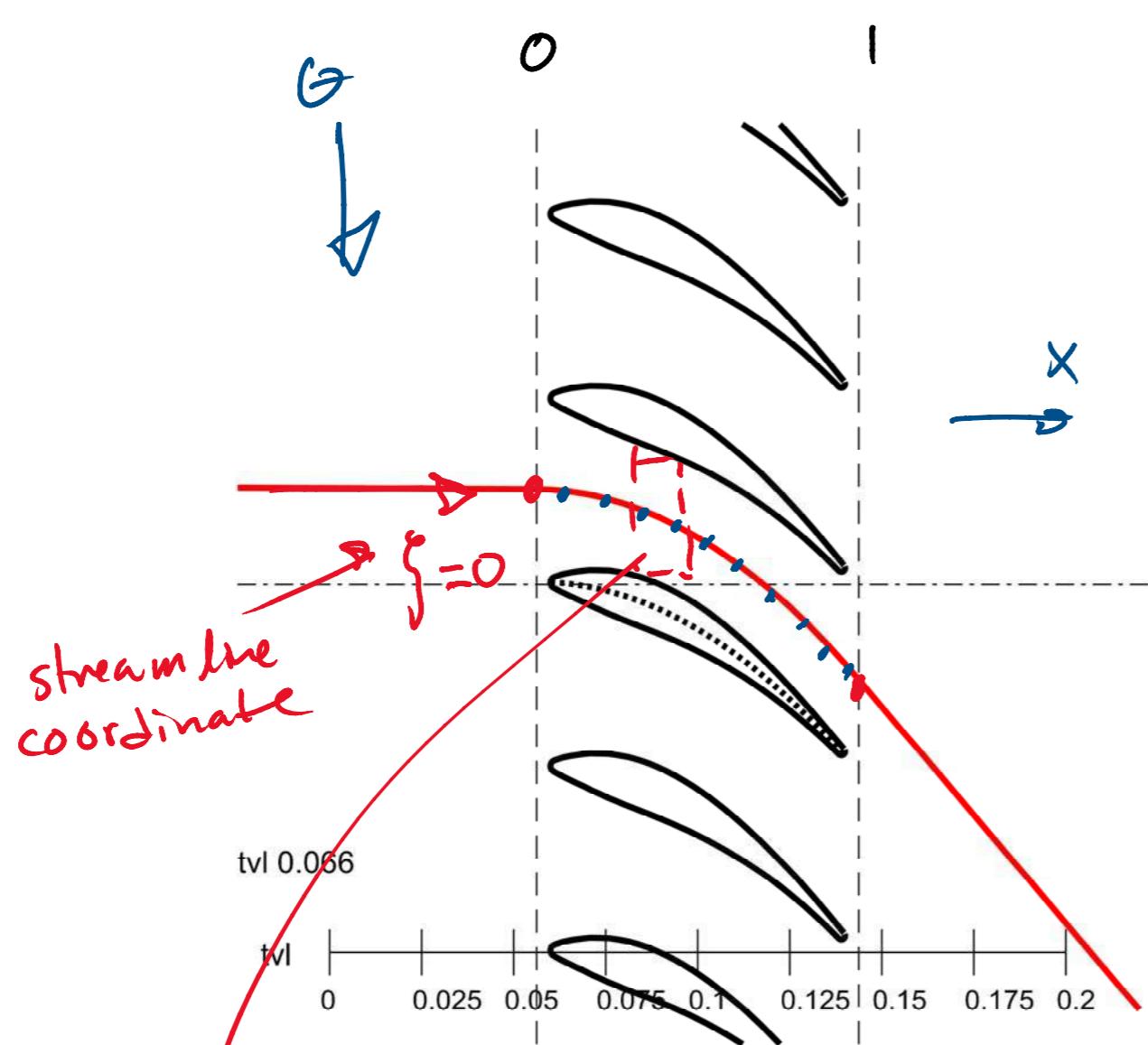


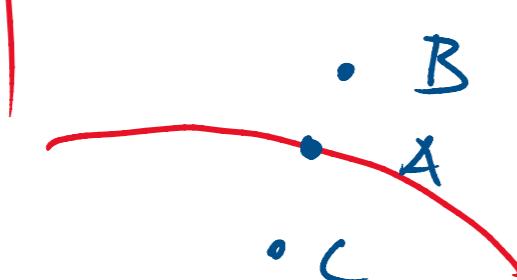
2D aerodynamics



1D aero

flow quantities
change in the
direction of the
flow

$$\begin{array}{ll} c_0, c_1 & c(\xi) \\ \alpha_0, \alpha_1 & \alpha(\xi) \\ p_0, p_1 & p(\xi) \\ T_0, T_1 & T(\xi) \end{array}$$



$$P_A = 170 \text{ kPa}$$

$[P_A \neq P_B \neq P_C] \Rightarrow$ local variations inside
the flow field.

→ There are gradients of flow quantities
inside a flow field

2D → gradients in the blade-to-blade direction ($x-\theta$)

3D → gradients normal to the blade-to-blade surface
→ radial direction ($r-x$)

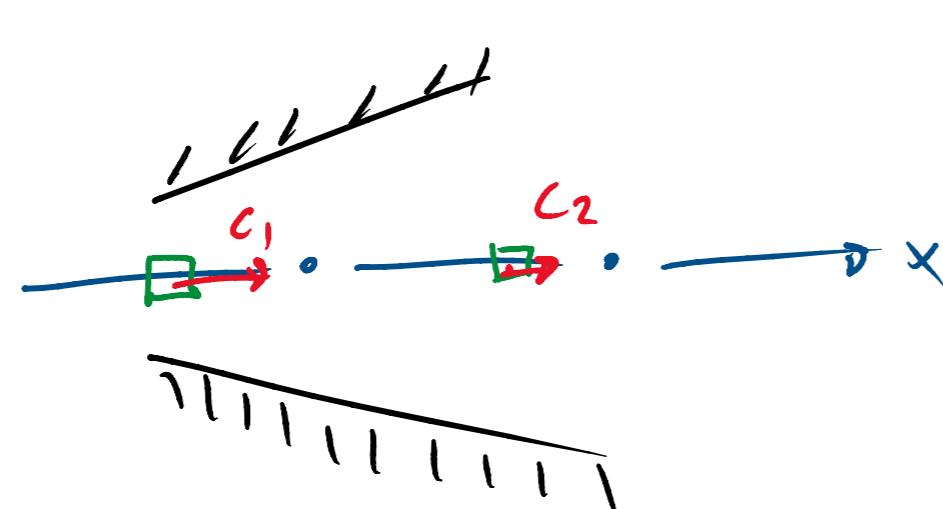
Reasons for having gradients

Global features (flight path of a particle)



the flight path is straight, and
as a consequence, the fluid quantities
change only in the direction of motion

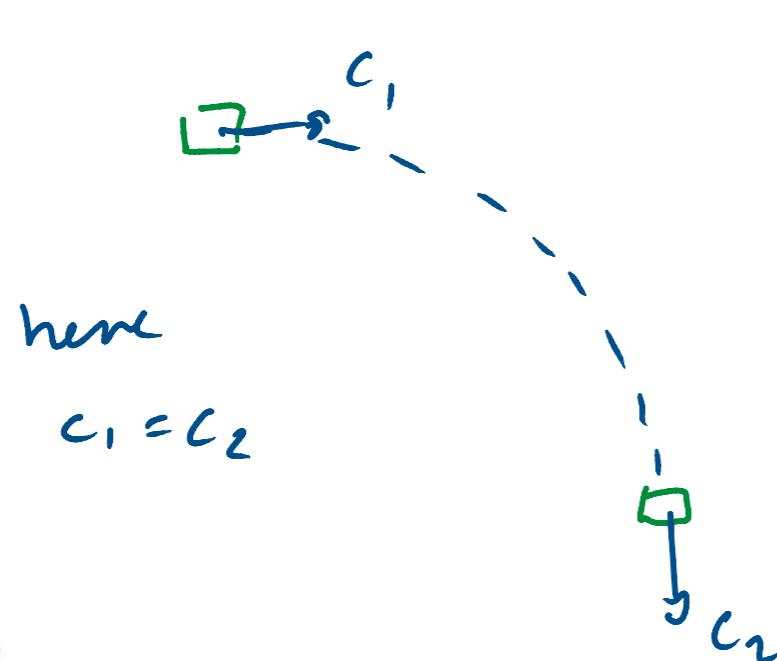
e.g. diffusing flow



increase in pressure

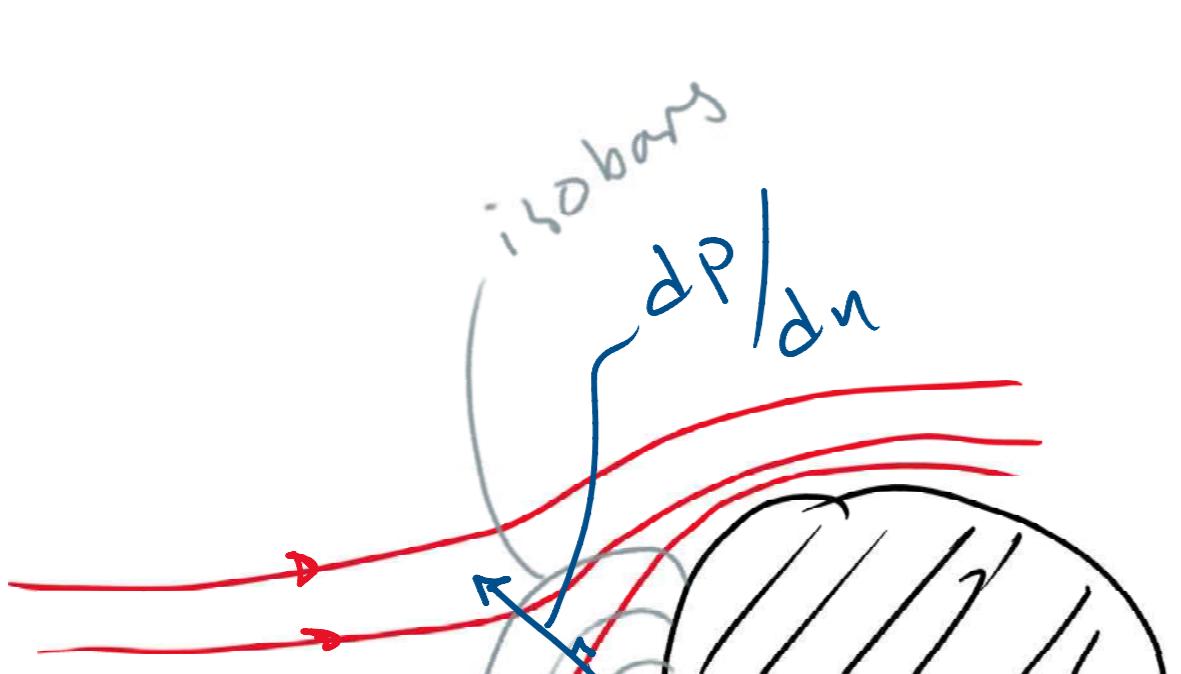
$$\rightarrow P_2 > P_1$$

$$\rightarrow \frac{dp}{dx} > 0 \quad \text{pressure gradient}$$

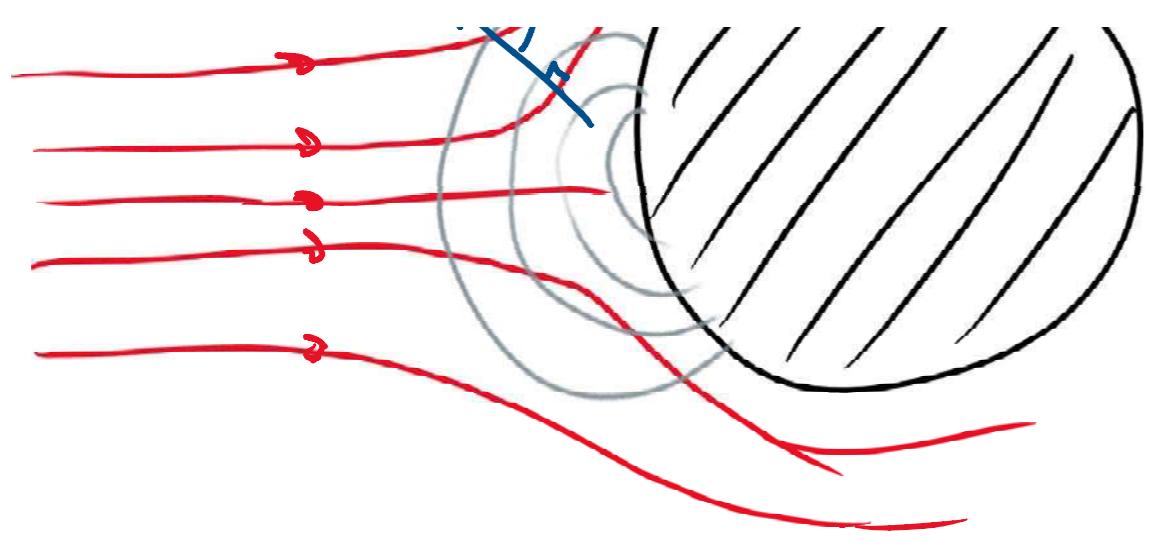


$$(P \cdot A = \text{force})$$

$$c_1 = c_2$$

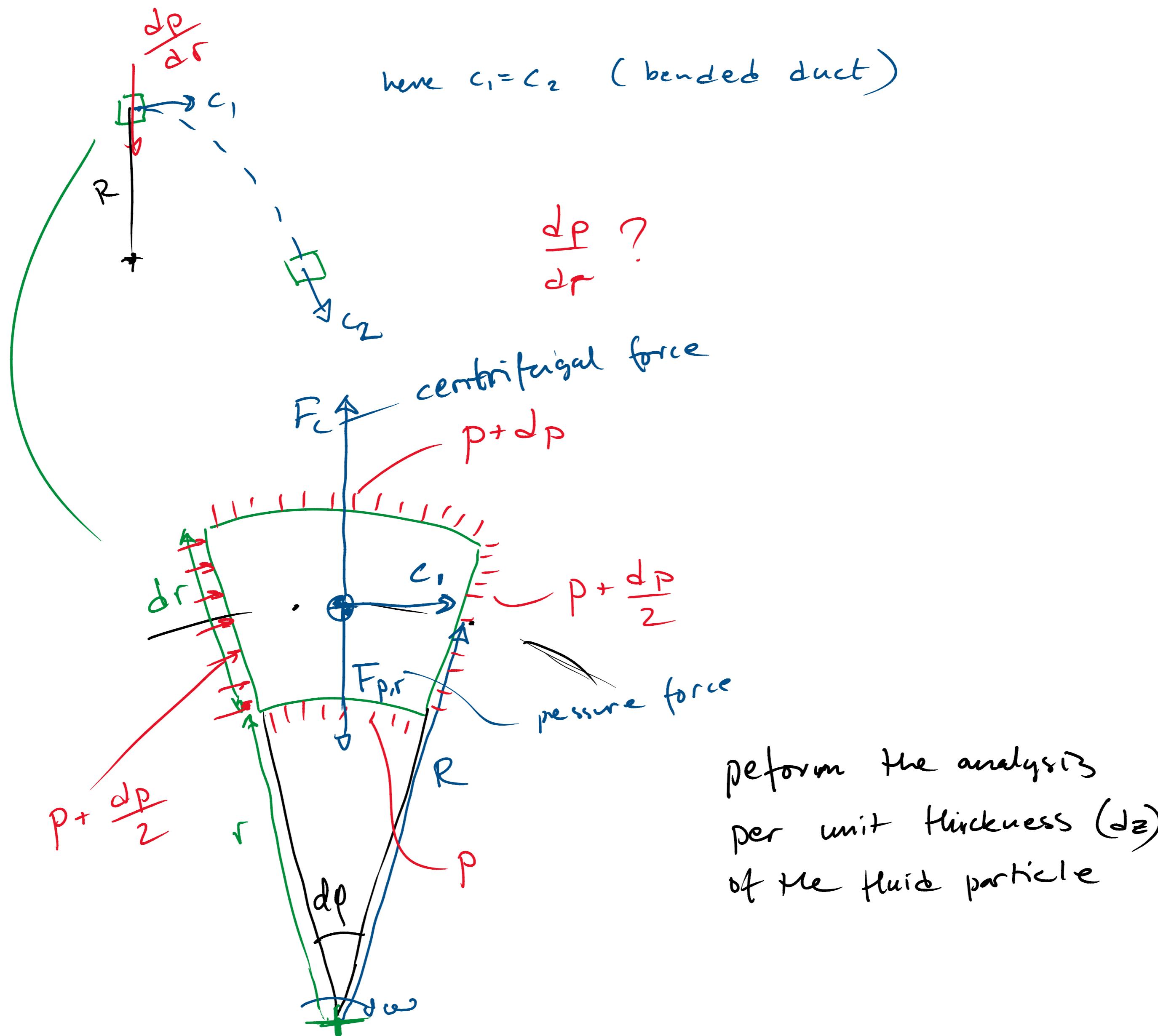


pressure is the
only way how
information can



information can
be communicated
in a flow field

derive an expression how big the pressure gradient
must be to deviate the flow.



Force balance $F_c = F_{p,r}$

i) centrifugal force

$$F_c = dm \cdot R \cdot \omega^2$$

$\omega = \frac{c_1}{R}$

$$F_c = dm \cdot R \cdot \left(\frac{c_1}{R}\right)^2 = dm \cdot \frac{c_1^2}{R}$$

$$dm = dr \cdot r d\varphi \cdot dz \cdot g$$

volume considering per unit thickness

$$\Rightarrow F_c = g \cdot dr \cdot r d\varphi \cdot \frac{c_1^2}{R}$$

ii) pressure forces acting on the particle, $F_{p,r}$
gen: pressure force = pressure \times area

$$F_{p,r} = (p + dp)(r + dr) \cdot d\varphi - p \cdot r \cdot d\varphi - 2 \left(p + \frac{dp}{2}\right) \cdot dr \cdot \sin\left(\frac{d\varphi}{2}\right)$$

top surface lower surface sides

due to inclined surfaces

small $d\varphi$!
 $\rightarrow \sin \frac{d\varphi}{2} \approx \frac{d\varphi}{2}$

≈ 0 (simplification)

$$F_{p,r} = p \cdot r \cdot d\varphi + dp \cdot r \cdot d\varphi + p \cdot dr \cdot d\varphi + dp \cdot r \cdot d\varphi - \dots$$

top

$$\dots = p \cdot r \cdot d\varphi - p \cdot dr \cdot d\varphi - \frac{dp}{2} \cdot dr \cdot d\varphi = \underline{dp \cdot r \cdot d\varphi}$$

Force balance $F_c = F_{p,r}$

$$g \cdot dr \cdot r \cdot d\varphi \cdot \frac{c_i^2}{R} = dp \cdot r \cdot d\varphi$$

$$\Rightarrow \boxed{\frac{dp}{dr} = g \cdot \frac{c_i^2}{R}}$$

observation:

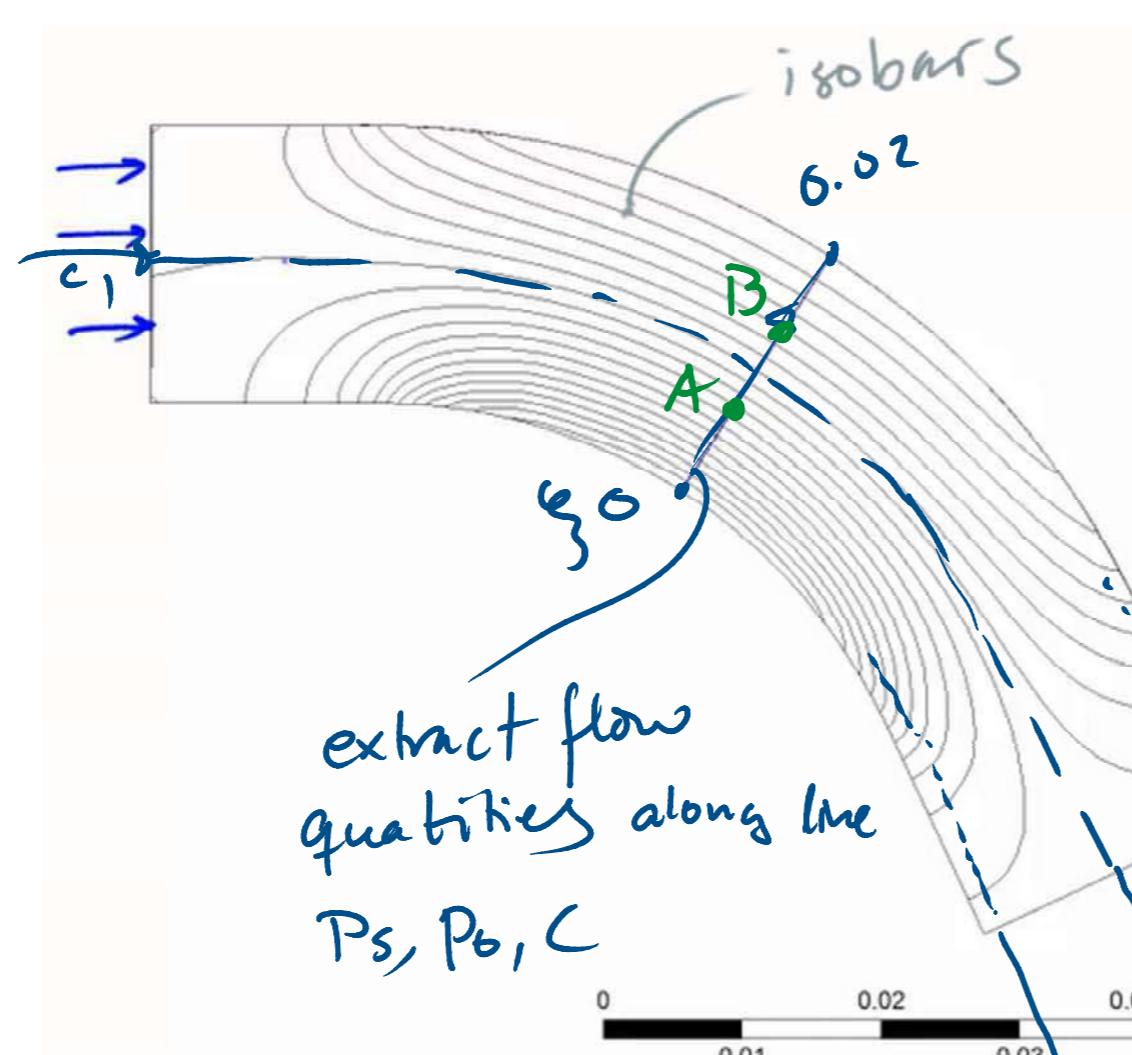
$$R \rightarrow \infty \rightarrow \frac{dp}{dr} \rightarrow 0$$

$$g \uparrow \rightarrow \frac{dp}{dr} \uparrow$$

$$c_i^2 \uparrow \rightarrow \frac{dp}{dr} \uparrow$$

$$R \downarrow \rightarrow \frac{dp}{dr} \uparrow$$

bended channel (const. cross section)



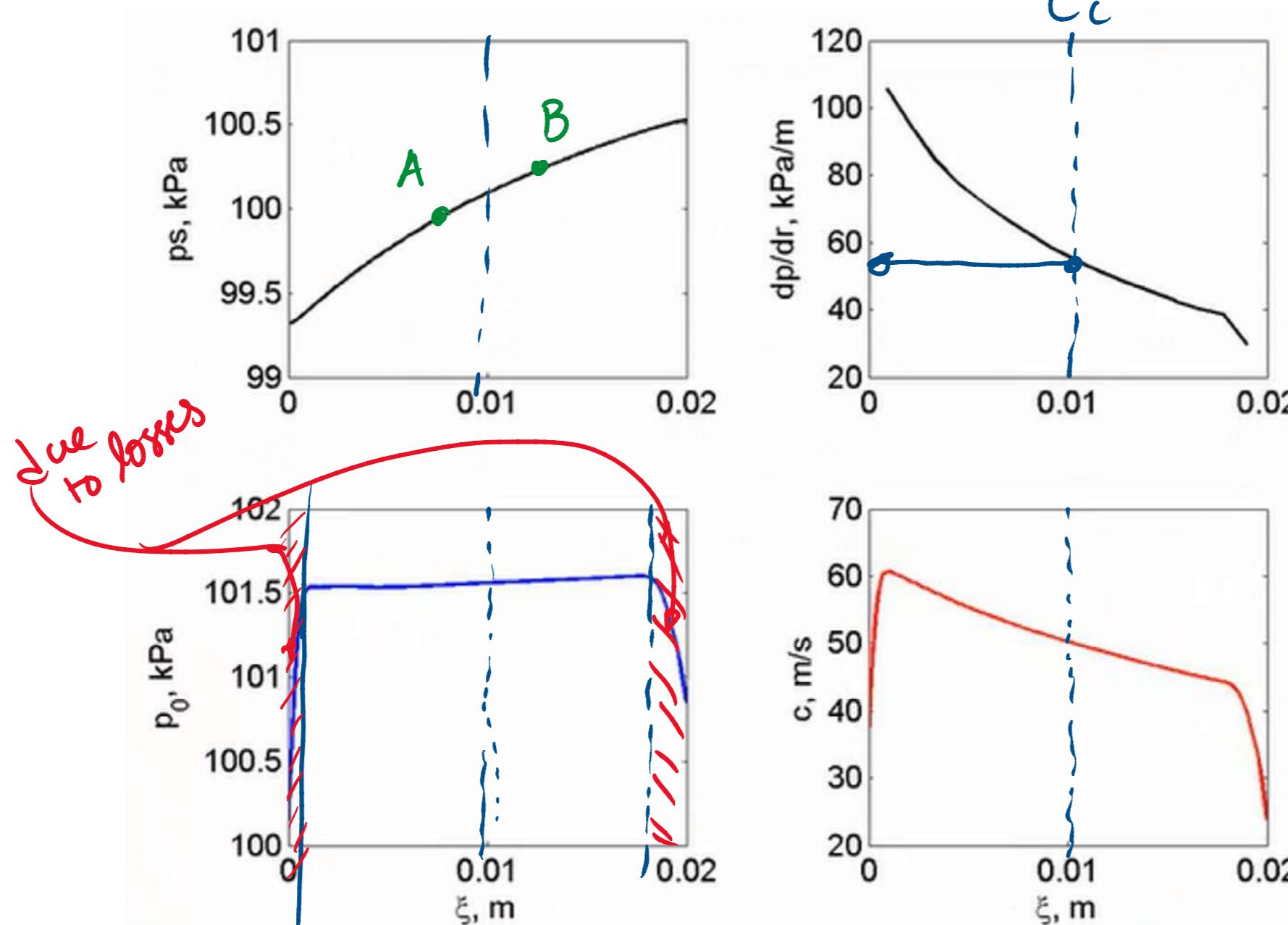
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$$c = \varphi, c_1 = c_2 = c_x$$

$$P_1 = P_2 = P_A$$

(assume no losses)
 $P_0 = \varphi$
at center line

$$P_B > P_A > P_C$$



$$\frac{dp}{dr} = g \cdot \frac{c^2}{R}$$

$$\left\{ \begin{array}{l} g = 1.15 \text{ kg/m}^3 \\ R = 50 \text{ mm} \\ c = 50 \text{ m/s} \end{array} \right.$$

$$\Rightarrow \frac{dp}{dr} = 1.15 \cdot \frac{50^2}{0.05} \approx 58 \text{ kPa/m}$$

Put the global 2D together

