

The background of the slide features a large, light blue watermark of the KTH logo. It consists of a crown at the top, a circular wreath of oak leaves in the middle, and the text 'KTH VETENSKAP OCH KONST' at the bottom.

# Numerical solutions of differential equations

Patrick Henning

[pathe@kth.se](mailto:pathe@kth.se)

Division of Numerical Analysis, KTH, Stockholm

Course **SF2521**, 7.5 ECTS, VT18



## Lecture 3

# The Heat Equation - Part 2



# Repetition: Stability of linear ODE solvers

## Repetition: Stability of linear ODE solvers

**Example.** Linear test equation: for  $\lambda \in \mathbb{C}$ , find  $u(t)$  with

$$\frac{d}{dt}u(t) = \lambda u(t) \quad \text{and} \quad u(0) = u_0.$$

Solution:

$$u(t) = u_0 e^{\lambda t}.$$

If  $\lambda$  is real and  $\lambda < 0$  we have

$$u(t) = u_0 e^{\lambda t} \rightarrow 0 \quad \text{for } t \rightarrow \infty.$$

This behavior should be reproduced for discretizations.

## Repetition: Stability of linear ODE solvers

**Example.** Linear test equation: for  $\lambda < 0$ , find  $u(t)$  with

$$\frac{d}{dt}u(t) = \lambda u(t) \quad \text{and} \quad u(0) = u_0 \Rightarrow u(t) = u_0 e^{\lambda t}.$$

**Explicit Euler** discretization with step size  $\Delta t > 0$ :

$$u_{n+1} = u_n + \Delta t \lambda u_n \quad (u_{n+1} = u_n + \Delta t f(t_n, u_n))$$

Hence:

$$u_n = \underbrace{(1 + \Delta t \lambda)}_{=: \Phi(\Delta t \lambda)} u_{n-1} = (1 + \Delta t \lambda)^n u_0$$

**Case 1:**  $|\lambda \Delta t| < 2 \Rightarrow -1 < (1 + \Delta t \lambda) < 1$ . Physically correct behavior

$$u_n = (1 + \Delta t \lambda)^n u_0 \xrightarrow{n \rightarrow \infty} 0$$

**Case 2:**  $|\lambda \Delta t| \geq 2 \Rightarrow 1 + \Delta t \lambda \leq -1$ . Unphysical behavior

$u_n = (1 + \Delta t \lambda)^n u_0$  is strongly oscillating (with blow-up).

In **Case 2** the method is not numerically stable!

## Repetition: Stability of linear ODE solvers

**Example.** Linear test equation: for  $\lambda \in \mathbb{C}$ , find  $u(t)$  with

$$\frac{d}{dt}u(t) = \lambda u(t) \quad \text{and} \quad u(0) = u_0 \quad \Rightarrow \quad u(t) = u_0 e^{\lambda t}.$$

General numerical one step scheme with step size  $\Delta t$ :

$$u_n = \Phi(\Delta t \lambda) u_{n-1} \quad \Rightarrow \quad u_n = \Phi(\Delta t \lambda)^n u_0.$$

The scheme defined through  $\Phi$  and  $\Delta t$  is stable, if

$$\Delta t \lambda \in \{z \in \mathbb{C} \mid |\Phi(z)| < 1\} = \underline{\text{Stability region}}.$$

## Repetition: Stability of linear ODE solvers

General case in  $\mathbb{R}^N$ : Let (as in our case)

- ▶  $\mathbf{A} \in \mathbb{R}^{N \times N}$ : real, symmetric and invertible matrix;
- ▶ hence,  $\mathbf{A}$  is diagonalizable, i.e.

$$\mathbf{A} = \mathbf{R}\mathbf{\Lambda}\mathbf{R}^{-1},$$

where  $\mathbf{\Lambda}$  is diagonal matrix of eigenvalues  $\lambda_1, \dots, \lambda_N$  of  $\mathbf{A}$ , i.e.

$$\mathbf{\Lambda} := \text{diag}(\lambda_1, \dots, \lambda_N).$$

Find  $\mathbf{u}(t) \in \mathbb{R}^N$  with

$$\frac{d}{dt}\mathbf{u}(t) = \mathbf{A}\mathbf{u}(t) \quad \text{and} \quad \mathbf{u}(0) = \mathbf{u}_0 \quad \Rightarrow \quad \mathbf{u}(t) = e^{\mathbf{A}t} \mathbf{u}_0.$$

General numerical one step scheme with step size  $\Delta t$ :

$$\mathbf{u}_n = \Phi(\Delta t \mathbf{A}) \mathbf{u}_{n-1} \quad \Rightarrow \quad \mathbf{u}_n = \Phi(\Delta t \mathbf{A})^n \mathbf{u}_0.$$

## Repetition: Stability of linear ODE solvers

Find  $u(t) \in \mathbb{R}^N$  with

$$\frac{d}{dt}u(t) = \mathbf{A} u(t) \quad \text{and} \quad u(0) = u_0 \quad \Rightarrow \quad u(t) = e^{\mathbf{A}t} u_0.$$

General numerical one step scheme with step size  $\Delta t$ :

$$u_n = \Phi(\Delta t \mathbf{A}) u_{n-1} \quad \Rightarrow \quad u_n = \Phi(\Delta t \mathbf{A})^n u_0.$$

To define stability, we reduce the problem to the case  $N = 1$ :  
using  $\mathbf{A} = \mathbf{R} \mathbf{\Lambda} \mathbf{R}^{-1}$  we define  $z := \mathbf{R}^{-1} u$  and obtain that  $z$  solves

$$\frac{d}{dt}z(t) = \mathbf{\Lambda} z(t) \quad \text{and} \quad z(0) = \mathbf{R}^{-1} u_0 \quad \Rightarrow \quad u(t) = \mathbf{R} e^{\mathbf{\Lambda}t} \mathbf{R}^{-1} u_0.$$

We recover  $N$  scalar ODEs with  $1 \leq k \leq N$

$$\frac{d}{dt}z_k(t) = \lambda_k z_k(t) \quad \Rightarrow \quad \text{define stability as before for each } \lambda_k.$$



## Repetition: Stability of linear ODE solvers

**Example:** Find  $u(t) \in \mathbb{R}^N$  with

$$\frac{d}{dt}u(t) = \mathbf{A} u(t) \quad \text{and} \quad u(0) = u_0 \quad \Rightarrow \quad u(t) = e^{\mathbf{A}t} u_0.$$

**Explicit Euler** discretization with step size  $\Delta t$ :

$$\begin{aligned} u_{n+1} &= u_n + \Delta t \mathbf{A} u_n = (\mathbf{I} + \Delta t \mathbf{A}) u_n \\ &= \mathbf{R}(\mathbf{I} + \Delta t \mathbf{A}) \mathbf{R}^{-1} u_n = \mathbf{R}(\mathbf{I} + \Delta t \mathbf{A})^{n+1} \mathbf{R}^{-1} u_0. \end{aligned}$$

Since  $\mathbf{I} + \Delta t \mathbf{A}$  is a diagonal matrix with entries  $1 + \Delta t \lambda_k$ , the **Explicit Euler** discretization is stable if

$$|1 + \Delta t \lambda_k| < 1 \quad \text{for all } 1 \leq k \leq N.$$