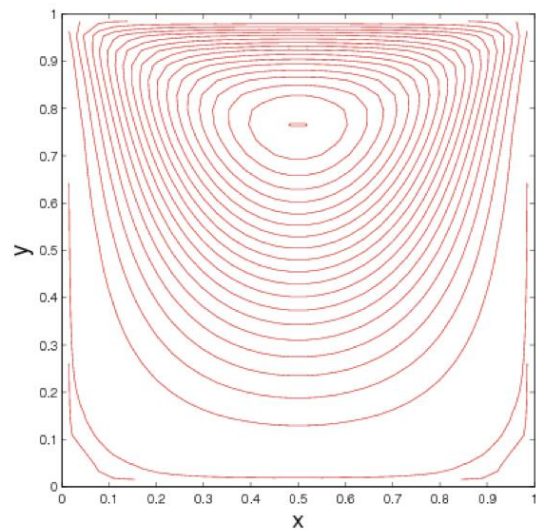
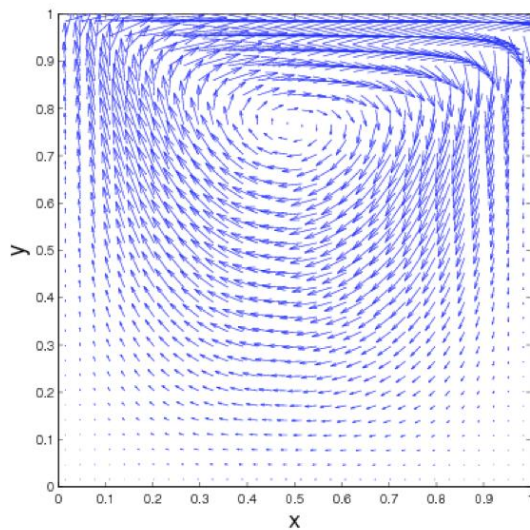


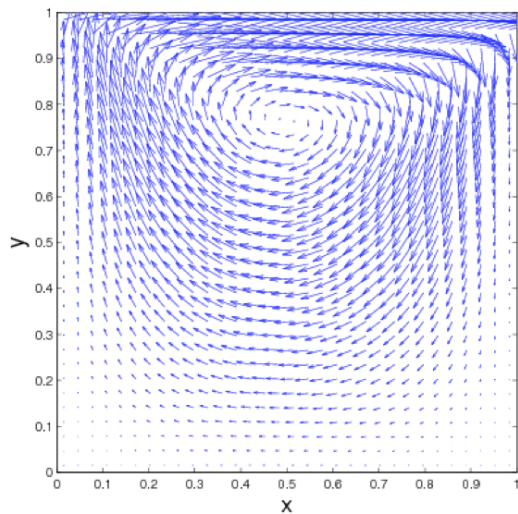
TP#5 : MU4MEM02
Fractional Step/Pressure Projection Method
Stoke's Equation

The objective is to complete a python code for the resolution of the Stoke's equation inside a cavity.

The flow and streamlines are plotted below:



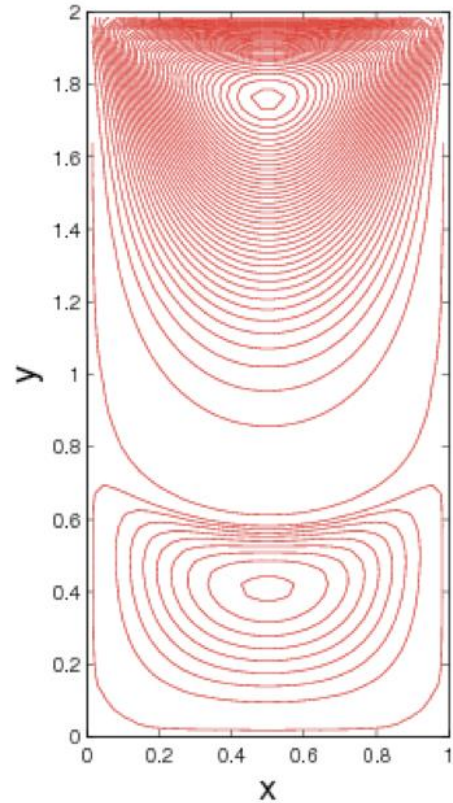
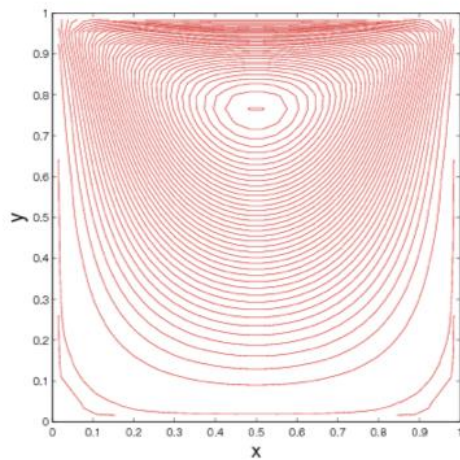
The following characteristics can be identified:



- Symmetric streamlines
- Rapid decay of velocity field
- Strong gradients in upper corners

The effect of the box size:

Appearance of secondary vortices



The equations governing the flow are:

$$\begin{cases} \partial_t u = -\nabla p + \Delta u \\ \nabla \cdot u = 0 \\ u(0 \leq x \leq 1, 0 \leq y \leq 1, t = 0) = 0 \\ u = g \quad \text{sur} \quad \partial\Omega \quad \text{pour} \quad t > 0 \end{cases}$$

Where,

$$g = \begin{cases} 0 & \text{pour} \quad (0 \leq x \leq 1, y = 0), (x = 0, 0 \leq y < 1), (x = 1, 0 \leq y < 1) \\ e_x & \text{pour} \quad (0 \leq x \leq 1, y = 1) \end{cases}$$

And (e_x, e_y) are the orthogonal basis of the plane.

For spatial discretization of the diffusion terms, we will use a central difference scheme in both directions. The Laplacian is also discretized following the same discretization as in TP4. For the temporal integration scheme, we will employ a backward Euler scheme. To solve the system of equations a fractional step method, as described in the class, is employed. So, to solve the for u^{n+1} , starting from u^n we follow:

$$\begin{cases} \frac{u^* - u^n}{\Delta t} = \Delta u^* & (1) \\ u^* = g + \Delta t \nabla p^{n+1} \quad \text{sur } \partial\Omega & (2) \\ \Delta p^{n+1} = \frac{\nabla \cdot u^*}{\Delta t} & (3) \\ \partial_n p^{n+1} = 0 & (4) \\ \frac{u^{n+1} - u^*}{\Delta t} = -\nabla p^{n+1} & (5) \end{cases}$$

Q1: Complete the notebook with the necessary steps.

Q2: What is a cell-centered scheme? Comment on how the restriction and prolongation algorithms differ from those of TP#4.

Q3: How do we account for Neuman and Dirichlet boundary conditions?

Q4: Considering `bc_diri_U` and `bc_diri_V` in the code, explain the method for implementing the boundary condition on a « cell-centered » grid. Code `bc_diri_U2` and `bc_diri_V2` such that:

$$g = \begin{cases} 0 & \text{pour } (0 \leq x \leq 1, y = 0), (x = 0, 0 \leq y < 1) \\ e_y & \text{pour } (x = 1, 0 \leq y < 1) \\ e_x & \text{pour } (0 \leq x \leq 1, y = 1) \end{cases}$$