

# High-Fidelity Simulations for Turbulent Flows

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Arts et Métiers  
Sciences et Technologies



## Part V

### Discretization of the Navier-Stokes equations

1 Classification of PDE

2 Methods for Hyperbolic Equations

3 Methods for Parabolic Equations

4 Advection–Diffusion Equation

## 1 Classification of PDE

## 2 Methods for Hyperbolic Equations

## 3 Methods for Parabolic Equations

## 4 Advection–Diffusion Equation

# 1st order PDE - Characteristics (I)

- PDE order determined by **highest derivatives**

- **Linear:** no powers or products of the unknown functions or its partial derivatives are present

$$x \frac{\partial w}{\partial x} + y \frac{\partial w}{\partial y} = w, \quad \frac{\partial w}{\partial x} + \frac{\partial w}{\partial y} + 2xw = 0$$

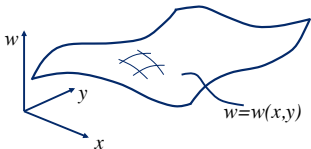
- **Quasi-linear** if it is true for the partial derivatives of the highest order

$$w \frac{\partial^2 w}{\partial x^2} + \left( \frac{\partial w}{\partial y} \right)^2 = w, \quad x^2 \frac{\partial w}{\partial x} + y^2 \frac{\partial w}{\partial y} = w^2$$

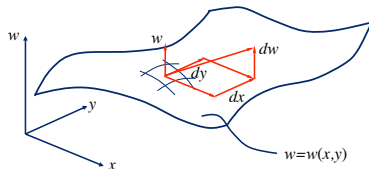
- Consider the 1<sup>st</sup>-order linear PDE

$$a \frac{\partial w}{\partial x} + b \frac{\partial w}{\partial y} = c$$

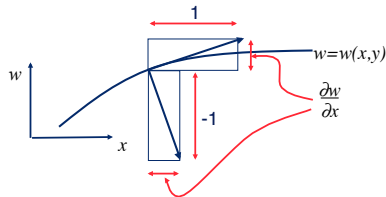
with  $a = a(x, y, w)$ ,  $b = b(x, y, w)$ ,  $c = c(x, y, w)$



- Arbitrary change in  $w$ :  $dw = \frac{\partial w}{\partial x} dx + \frac{\partial w}{\partial y} dy$



- Normal vector to the curve  $w = w(x, y)$



- Same argument in  $y$ -direction, thus

$$\vec{n} = \left( \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}, -1 \right)$$

# 1st order PDE - Characteristics (II)

The original equation and the condition for a small change can be rewritten as

$$a \frac{\partial w}{\partial x} + b \frac{\partial w}{\partial y} = c \implies \left( \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}, -1 \right) \cdot (a, b, c) = 0$$

$$dw = \frac{\partial w}{\partial x} dx + \frac{\partial w}{\partial y} dy \implies \left( \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}, -1 \right) \cdot (dx, dy, dw) = 0$$

- ▶ Both  $(a, b, c)$  and  $(dx, dy, dw)$  are normal to the surface
- ▶ Picking the displacement in the direction of  $(a, b, c)$ :

$$(dx, dy, dw) = ds(a, b, c)$$

And separating the components:

$$\underbrace{\frac{dx}{ds} = a, \quad \frac{dy}{ds} = b, \quad \frac{dw}{ds} = c,}_{\frac{dx}{dy} = \frac{a}{b}}$$

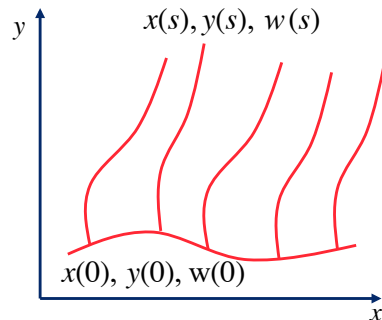
- The 3 equations specify lines in the  $x - y$  plane

## Characteristics

Given the initial conditions:

$$x = x(s, t_0), \quad y = y(s, t_0), \quad w = w(s, t_0)$$

The equations can be integrated in time:

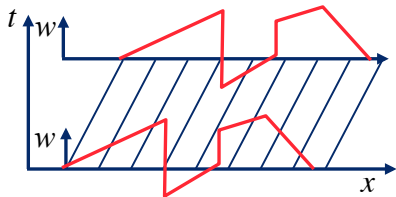
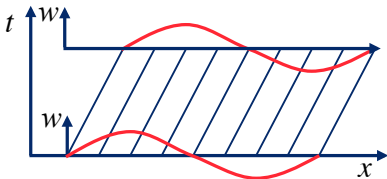


# Linear advection equation

$$\boxed{\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = 0} \implies \text{Characteristics: } \frac{dt}{ds} = 1, \quad \frac{dx}{ds} = a, \quad \frac{dw}{ds} = 0 \quad \text{or} \quad \frac{dx}{dt} = a, \quad dw = 0$$

The solution moves along straight characteristics without changing its value!

Graphically:  $w(x, t) = w_{t=0}(x - at)$



- Solution:  $w(x, t) = f(x - at)$  with  $f(x) = w(x, t = 0)$
- Verified by direct substitution: set  $\eta(x, t) = x - at$ , then:

$$\frac{\partial w}{\partial t} = \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial t} = \frac{\partial f}{\partial \eta} (-a)$$

$$\frac{\partial w}{\partial x} = \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial x} = \frac{\partial f}{\partial \eta} (1)$$

- Replace into the original equation:

$$\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = \cancel{\frac{\partial f}{\partial \eta} (-a)} + a \cancel{\frac{\partial f}{\partial \eta}} = 0$$

- Since the solution propagates along characteristics independently of the solution at the next spatial point, there is no requirement that it is differentiable or even continuous

# Linear advection equation

## ► Linear advection with source term:

$$\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = -w$$

Characteristics :  $\frac{dt}{ds} = 1, \quad \frac{dx}{ds} = a, \quad \frac{dw}{ds} = -w$

or  $\frac{dx}{dt} = a, \quad \frac{dw}{dt} = -w \quad \Rightarrow \quad w = w(0)e^{-t}$

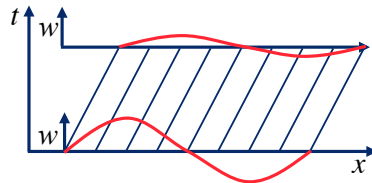
## ► Quasi-linear advection equation:

$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial x} = 0$$

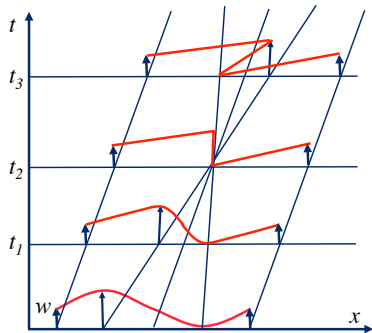
Characteristics :  $\frac{dt}{ds} = 1, \quad \frac{dx}{ds} = w, \quad \frac{dw}{ds} = 0$

or  $\frac{dx}{dt} = w, \quad dw = 0$

- The slope of the characteristics depends on the value of  $w(x, t)$
- Why unphysical solutions? Because mathematical equation neglects some physical process (**dissipation**)
- Additional (**entropy**) condition required to pick out the physically relevant solution, using conservation of  $w$



Moving wave with decaying amplitude



Multi-valued solution..



## 2nd order PDE - Characteristics (I)

$$\boxed{a \frac{\partial^2 w}{\partial x^2} + b \frac{\partial^2 w}{\partial x \partial y} + c \frac{\partial^2 w}{\partial y^2} = d} \quad (*)$$

with

$$a = a(x, y, w, w_x, w_y)$$

$$b = b(x, y, w, w_x, w_y)$$

$$c = c(x, y, w, w_x, w_y)$$

$$d = d(x, y, w, w_x, w_y)$$

► First write the PDE as a system of 1<sup>st</sup>-order eqs:

- Define  $f = \frac{\partial w}{\partial x}$  and  $g = \frac{\partial w}{\partial y}$
- Then (\*) becomes:  $a \frac{\partial f}{\partial x} + b \frac{\partial f}{\partial y} + c \frac{\partial g}{\partial y} = d$
- The 2<sup>nd</sup> eq. is obtained from:

$$\frac{\partial^2 w}{\partial x \partial y} = \frac{\partial^2 w}{\partial y \partial x} \implies \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} = 0$$

► (\*) is then equivalent to

$$\begin{cases} a \frac{\partial f}{\partial x} + b \frac{\partial f}{\partial y} + c \frac{\partial g}{\partial y} = d \\ \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} = 0 \end{cases}$$

- Any high-order PDE can be rewritten as a system of 1<sup>st</sup>-order equations
- In matrix form, one has

$$\begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial g}{\partial x} \end{bmatrix} + \underbrace{\begin{bmatrix} \frac{b}{a} & \frac{c}{a} \\ -1 & 0 \end{bmatrix}}_A \cdot \begin{bmatrix} \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial y} \end{bmatrix} = \begin{bmatrix} \frac{d}{a} \\ 0 \end{bmatrix}$$

$$\text{or } \vec{u}_x + A \vec{u}_y = \vec{s} \quad \text{with} \quad \vec{u} = \begin{bmatrix} f \\ g \end{bmatrix}$$

- Are there lines in the  $x - y$  plane, along which the solution is determined by an ODE?

## 2nd order PDE - Characteristics (II)

The **total derivative** is:

$$\frac{df}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial x} = \frac{\partial f}{\partial x} + \alpha \frac{\partial f}{\partial y} \quad \text{with} \quad \alpha = \frac{\partial y}{\partial x}$$

- ▶ Rate of change of  $f$  with  $x$ , along the line  $y = y(x)$
- ▶ If there are lines (determined by  $\alpha$ ) where the solution is governed by ODE's, then it must be possible to rewrite the eqs. such that the result contains only  $\alpha$  and the total derivatives!

- Add the original equations:

$$\lambda_1 \left( \frac{\partial f}{\partial x} + \frac{b}{a} \frac{\partial f}{\partial y} + \frac{c}{a} \frac{\partial g}{\partial y} \right) + \lambda_2 \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) = \lambda_1 \frac{d}{a}$$

- And compare to

$$\lambda_1 \left( \frac{\partial f}{\partial x} + \alpha \frac{\partial f}{\partial y} \right) + \lambda_2 \left( \frac{\partial g}{\partial x} + \alpha \frac{\partial g}{\partial y} \right) = \lambda_1 \frac{d}{a}$$

for some  $\lambda$ 's and  $\alpha$

- ▶ The two systems are equal if:

$$(\star) \begin{cases} \lambda_1 \frac{b}{a} - \lambda_2 = \lambda_1 \alpha \\ \lambda_1 \frac{c}{a} = \lambda_2 \alpha \end{cases} \Rightarrow \begin{bmatrix} \frac{b}{a} - \alpha & -1 \\ \frac{c}{a} & -\alpha \end{bmatrix} \cdot \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

- ▶ Characteristic lines exist if  $(\star)$  is verified
- ▶ The system can be recast as

$$\underbrace{\begin{bmatrix} \frac{b}{a} & -1 \\ \frac{c}{a} & 0 \end{bmatrix}}_{A^T} \cdot \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} - \begin{bmatrix} -\alpha & 0 \\ 0 & -\alpha \end{bmatrix} \cdot \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow (A^T - \alpha I) \vec{\lambda} = 0$$

- It has a solution  $\iff$  the determinant is zero!

$$-\alpha \left( \frac{b}{a} - \alpha \right) + \frac{c}{a} = 0 \iff \boxed{\alpha = \frac{1}{2a} \left( b \pm \sqrt{b^2 - 4ac} \right)}$$

1.  $b^2 - 4ac > 0$ : **2 real characteristics: hyperbolic**
2.  $b^2 - 4ac = 0$ : **1 real characteristic: parabolic**
3.  $b^2 - 4ac < 0$ : **0 real characteristics: elliptic**

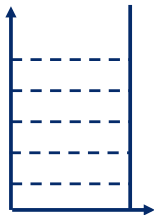
# Examples

Comparing with the standard form 
$$a \frac{\partial^2 w}{\partial x^2} + b \frac{\partial^2 w}{\partial x \partial y} + c \frac{\partial^2 w}{\partial y^2} = d$$

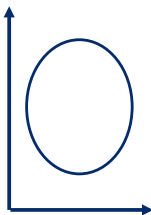
	Equation	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	$b^2 - 4ac$	Type
Wave propagation	$\frac{\partial^2 w}{\partial x^2} - c^2 \frac{\partial^2 w}{\partial y^2} = 0$	1	0	$-c^2$	0	$4c^2 > 0$	Hyperbolic
Diffusion equation	$\frac{\partial w}{\partial x} - \nu \frac{\partial^2 w}{\partial y^2} = 0$	0	0	$-\nu$	0	0	Parabolic
Laplace equation	$\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} = 0$	1	0	1	0	$-4 < 0$	Elliptic



Hyperbolic



Parabolic



Elliptic

- Why the classification is so important?
  - Different initial and boundary conditions
  - Different physics
  - Different numerical methods

# Examples

## Incompressible Navier–Stokes

$$\underbrace{\frac{\partial u}{\partial t}}_{(1)} + \underbrace{u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y}}_{(2)} = - \underbrace{\frac{1}{\rho} \frac{\partial p}{\partial x}}_{(3)} + \nu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

	Steady		Unsteady	
	Type		Type	
<b>Viscous flow</b>	(3)	Elliptic	(1)+(3)	Parabolic
<b>Inviscid flow</b>	(2)	$Ma \ll 1$ : Elliptic $Ma > 1$ : Hyperbolic	(1)+(2)	Hyperbolic
<b>Thin shear layers</b>	(2)+(3)	Parabolic	(1)+(3)	Parabolic

- ▶ NS eqs. contains three equation types having their own characteristic behavior
- ▶ Depending on the configuration, one behavior can be dominant. Examples:
  - **Inviscid flows:**
    - $Ma \ll 1$ : pressure disturbances travel faster than flow speed  $\Rightarrow$  **elliptic** character
    - $Ma > 1$ : pressure disturbances cannot travel upstream  $\Rightarrow$  **hyperbolic** character
  - **Thin shear layers:**  $\frac{\partial(\bullet)}{\partial x} \ll \frac{\partial(\bullet)}{\partial y} \Rightarrow$  only one second order term  $\Rightarrow$  **parabolic** character

# Ill-posed problems

Consider the IVP: 
$$\frac{\partial^2 w}{\partial t^2} = -\frac{\partial^2 w}{\partial x^2}$$

with  $w^0$  and  $\frac{\partial w^0}{\partial t}$  given on the boundaries

- ▶ This is simply **Laplace's equation**, which has a solution if  $w(t)$  or  $\frac{\partial w}{\partial t}$  are given on the boundaries
- ▶ Here, it appears as an IVP (BCs given only at  $t = 0$ )
- ▶ **General solution:**  $w(x, t) = \sum_k \hat{w}_k(t) e^{ikx}$   
 $\hat{w}_k(t)$  depending on ICs
- ▶ Replacing in the equation:  $\frac{d^2 \hat{w}_k}{dt^2} = k^2 \hat{w}_k$   
For which one has  $\hat{w}_k(t) = Ae^{kt} + Be^{-kt}$ 
  - $A, B$  determined by the ICs  $\hat{w}_k^0$  and  $ik\hat{w}_k^0$
  - $\hat{w}_k \rightarrow \infty$  as  $t \rightarrow \infty$ : **Ill-posed problem!**
- ▶ Similar behavior obtained for diffusion equation with  $\nu < 0$ : unbounded growth rate for high-wavenumber modes
- ▶ Ill-posed problems generally appear when ICs or BCs and the equation type **do not match**, or because small but important higher-order effects have been **neglected**
- ▶ They result in **exponential growth** of small perturbations, so that the solution does not depend continuously on the initial data
- ▶ **Examples:** inviscid vortex sheet roll-up, multiphase flow models, viscoelastic constitutive models, ..

## Remainder: the NS equations

$$\frac{\partial w}{\partial t} + \nabla \cdot (\mathbf{F}^e - \mathbf{F}^v) = 0 \quad w = \begin{bmatrix} \rho \\ \rho \vec{u} \\ \rho E \end{bmatrix} \quad F^e = \begin{bmatrix} \rho \vec{u} \\ \rho \vec{u} \vec{u} + p \mathbf{I} \\ \rho \vec{u} H \end{bmatrix} \quad F^v = \begin{bmatrix} 0 \\ \vec{\tau} \\ \vec{\tau} \vec{u} - \vec{q} \end{bmatrix}$$

### ► Boundary conditions

- **Inlet/Outlet:** viscous effects negligible (no BLs): **same BCs** as in inviscid flows hold
- **Walls:** no-slip condition ( $\vec{u} = \vec{u}_{\text{wall}}$ ) + condition on  $T$  (Adiabatic,  $\vec{q} = 0$ , or Isothermal,  $T = T_{\text{wall}}$ )

### ► For aerodynamic problems, $Pr \approx 0.72$ and $Re \gg 1$

- Most of the flow dominated by inviscid effects
- Viscous effects important in regions with strong gradients
- Shock waves too thin to be resolved in common use meshes  $\Rightarrow$  **captured** or seen as **discontinuities**

### ► A good NS solver should be, first of all, a good **Euler solver**

- Already seen in the Basics of Numerical Methods course
- We focus on the discretisation of viscous terms and interactions with convective terms and time derivatives (stability issues)

■ Classification of PDE

■ Methods for Hyperbolic Equations

■ Methods for Parabolic Equations

■ Advection–Diffusion Equation

# Model problem: stability analysis

Consider the wave equation:

$$\boxed{\frac{\partial^2 w}{\partial t^2} - c^2 \frac{\partial^2 w}{\partial x^2} = 0} \quad \text{write as} \quad \begin{cases} \frac{\partial f}{\partial t} - c^2 \frac{\partial g}{\partial x} = 0 \\ \frac{\partial g}{\partial t} - \frac{\partial f}{\partial x} = 0 \end{cases} \quad \text{or} \quad \begin{bmatrix} \frac{\partial f}{\partial t} \\ \frac{\partial g}{\partial t} \end{bmatrix} + \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial g}{\partial x} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Most of the issues involved can be addressed by examining the linear advection equation

$$\boxed{\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = 0}$$

**Example: Upwind method for advection equation** ( $\mathcal{O}(\Delta t, \Delta x)$  accurate)

- ▶ Write the solution as  $\hat{w}_j^n = \hat{w}^n e^{ikx_j}$
- ▶ Replace in the discretized equation

$$\begin{aligned} \frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} &= 0 \\ \frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{w_j^n - w_{j-1}^n}{\Delta x} &= 0 \\ \frac{\hat{w}_j^{n+1} - \hat{w}_j^n}{\Delta t} + a \frac{\hat{w}_j^n - \hat{w}_{j-1}^n}{\Delta x} &= 0 \\ \frac{\hat{w}^{n+1} - \hat{w}^n}{\Delta t} + \frac{a \hat{w}^n}{\Delta x} (1 - e^{-ik\Delta x}) &= 0 \end{aligned}$$

- ▶ Evaluate the **amplification factor**  $G$ :

$$\begin{aligned} \Rightarrow G &= \frac{\hat{w}^{n+1}}{\hat{w}^n} = 1 - \frac{a\Delta t}{\Delta x} (1 - e^{-ik\Delta x}) \\ &= 1 - \dot{a} (1 - e^{-ik\Delta x}) \quad \text{with} \quad \dot{a} = \frac{a\Delta t}{\Delta x} \\ &= 1 - \dot{a} + \dot{a} e^{-ik\Delta x} = 1 - \dot{a} + \dot{a} e^{-i\beta} \end{aligned}$$

- ▶ **Stability**  $\iff$  errors remain **bounded** (i.e.  $|G| < 1$ )
- ▶ Need to find values of  $\dot{a}$  for which  $|G| < 1$ !

Two classical methods: 1) **Analytical**, 2) **Graphical**



# Von Neumann Stability Analysis

$$G = 1 - \dot{a} + \dot{a}e^{-i\beta} = (1 - \dot{a} + \dot{a} \cos \beta) - i(\dot{a} \sin \beta) \quad (*)$$

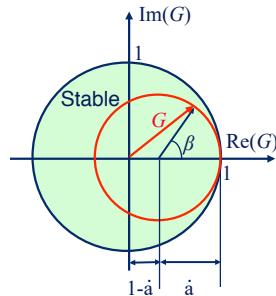
## Analytical method

$$\begin{aligned}
 |G|^2 &= (1 - \dot{a} + \dot{a} \cos \beta)^2 + (\dot{a} \sin \beta)^2 \\
 &= (1 - \dot{a})^2 + 2(1 - \dot{a})\dot{a} \cos \beta + \dot{a}^2 \cos^2 \beta + \dot{a}^2 \sin^2 \beta \\
 &= (1 - \dot{a})^2 + 2(1 - \dot{a})\dot{a} \cos \beta + \dot{a}^2 \\
 &= 1 - 2\dot{a} + 2\dot{a}^2 + 2(1 - \dot{a})\dot{a} \cos \beta \\
 &= 1 + 2\dot{a}(1 - \dot{a})(1 - \cos \beta) \leq 1 \\
 &\iff \dot{a}(1 - \dot{a})(\cos \beta - 1) \leq 0
 \end{aligned}$$

► Since  $\cos \beta - 1 \leq 0 \quad \forall \beta$ , then

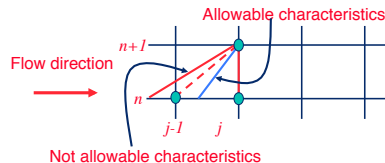
$$\begin{aligned}
 |G|^2 \leq 1 &\iff \dot{a}(1 - \dot{a}) \geq 0 \\
 &\iff \boxed{0 \leq \dot{a} \leq 1}
 \end{aligned}$$

## Graphical method



- **Green region:**  
stability zone ( $|G| < 1$ )
- **Red circle:**  
representation of (\*)
- Circle must be contained in green region, thus:
- $|G|^2 \leq 1 \iff \dot{a} \leq 1$

The signal must travel less than 1  $\Delta x$  in 1  $\Delta t$ !



# Generalized Upwind Scheme

$$w_j^{n+1} = \begin{cases} w_j^n - \frac{a\Delta t}{\Delta x}(w_j^n - w_{j-1}^n) & a > 0 \\ w_j^n - \frac{a\Delta t}{\Delta x}(w_{j+1}^n - w_j^n) & a < 0 \end{cases}$$

**Generalized case:** define

$$a^+ = \frac{1}{2}(a + |a|) \quad a^- = \frac{1}{2}(a - |a|)$$

And combine into a single expression:

$$w_j^{n+1} = w_j^n - \frac{\Delta t}{\Delta x} [a^+(w_j^n - w_{j-1}^n) + a^-(w_{j+1}^n - w_j^n)]$$

Replacing  $a^+$  and  $a^-$  with their definitions:





$$w_j^{n+1} = w_j^n - \frac{a\Delta t}{2\Delta x}(w_{j+1}^n - w_{j-1}^n) + \frac{|a|\Delta t}{2\Delta x}(w_{j+1}^n - 2w_j^n + w_{j-1}^n)$$

► Central difference + numerical viscosity obtained!  $\nu_{\text{num}} = \frac{|a|\Delta x}{2}$







# Summary: First-order schemes

$$\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = 0$$

$$\dot{a} = \frac{a \Delta t}{\Delta x}$$

Name / Stencil	Scheme	Error term	Stability
<b>FTCS</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{w_{j+1}^n - w_{j-1}^n}{2\Delta x} = 0$	$-\Delta t \frac{a^2}{2} w_{xx} - \frac{a \Delta x^2}{6} (1 + 2\dot{a}^2) w_{xxx}$	Unconditionally Unstable
<b>Upwind</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{w_j^n - w_{j-1}^n}{\Delta x} = 0$	$\frac{a \Delta x}{2} (1 - \dot{a}) w_{xx} - \frac{a \Delta x^2}{6} (2\dot{a}^2 - 3\dot{a} + 1) w_{xxx}$	Stable for $\dot{a} \leq 1$
<b>Implicit</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{w_{j+1}^{n+1} - w_{j-1}^{n+1}}{2\Delta x} = 0$	$\frac{a^2 \Delta t}{2} w_{xx} - \left[ \frac{1}{6} a \Delta x^2 + \frac{1}{3} a^3 \Delta t^2 \right] w_{xxx}$	Unconditionally Stable
<b>Lax-Friedrichs</b> 	$\frac{w_j^{n+1} - \frac{1}{2}(w_{j+1}^n + w_{j-1}^n)}{\Delta t} + a \frac{w_{j+1}^n - w_{j-1}^n}{2\Delta x} = 0$	$\frac{a \Delta x}{2} \left[ \frac{1}{\dot{a}} - \dot{a} \right] w_{xx} + \frac{a \Delta x^2}{3} (1 - \dot{a}^2) w_{xxx}$	Stable for $\dot{a} \leq 1$

# Summary: Second-order schemes

Name / Stencil	Scheme	Error term	Stability
<b>Leap Frog</b> 	$\frac{w_j^{n+1} - w_j^{n-1}}{2\Delta t} + a \frac{w_{j+1}^n - w_{j-1}^n}{2\Delta x} = 0$	$\frac{a\Delta x^2}{6}(\dot{a}^2 - 1)w_{xxx}$	Stable for $\dot{a} \leq 1$
<b>Lax-Wendroff I</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{w_{j+1}^n - w_{j-1}^n}{2\Delta x} - a^2 \Delta t^2 \frac{w_{j+1}^n - 2w_j^n + w_{j-1}^n}{2\Delta x^2} = 0$	$-\frac{a\Delta x^2}{6}(1 - \dot{a}^2)w_{xxx} - \frac{a\Delta x^3}{8}\dot{a}(1 - \dot{a}^2)w_{xxxx}$	Stable for $\dot{a} \leq 1$
<b>Lax-Wendroff II</b>  (Lax + Leapfrog)	$\frac{w_{j+1/2}^{n+1/2} - (w_{j+1}^n + w_j^n)/2}{\Delta t/2} + a \frac{w_{j+1}^n - w_j^n}{\Delta x} = 0$ $\frac{w_j^{n+1} - w_j^n}{\Delta t} - a \frac{w_{j+1/2}^{n+1/2} - w_{j-1/2}^{n+1/2}}{\Delta x} = 0$	Same as Lax-Wendroff I	Stable for $\dot{a} \leq 1$
<b>MacCormack</b>  (Predictor/Corrector)	$\frac{w_j^t - w_j^n}{\Delta t} + a \frac{w_{j+1}^n - w_j^n}{\Delta x} = 0$ $\frac{w_j^{n+1} - (w_j^n + w_j^t)/2}{\Delta t} + a \frac{w_j^t - w_{j-1}^t}{\Delta x} = 0$	Same as Lax-Wendroff I	Stable for $\dot{a} \leq 1$
<b>Beam-Warming</b>  (Predictor/Corrector)	$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{3w_j^n - 4w_{j-1}^n + w_{j-2}^n}{2\Delta x} - \frac{a^2 \Delta t}{2\Delta x^2}(w_j^n - 2w_{j-1}^n + w_{j-2}^n) = 0$	$\frac{a\Delta x^2}{6}(1 - \dot{a})(2 - \dot{a})w_{xxx} - \frac{a\Delta x^3}{8}(1 - \dot{a})^2(2 - \dot{a})w_{xxxx}$	Stable for $0 \leq \dot{a} \leq 2$
<b>QUICK</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{(3w_j^n + 6w_{j-1}^n - w_{j-2}^n) - (3w_{j+1}^n + 6w_j^n - w_{j-1}^n)}{8\Delta x} = 0$		Stable for $\dot{a} \leq 1$

# Stability in terms of fluxes: FTCS for Advection

Consider  $\boxed{\frac{\partial w}{\partial t} + \frac{\partial F}{\partial x} = 0}$  with  $F = aw$

- Finite volume approximation:

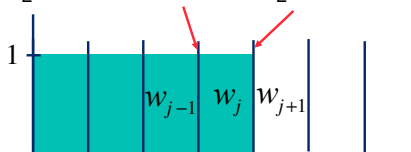
$$\frac{dw_j}{dt} = \frac{F_{j-\frac{1}{2}} - F_{j+\frac{1}{2}}}{\Delta x} \quad F_{j+\frac{1}{2}} = aw_{j+\frac{1}{2}} \approx \frac{a}{2}(w_{j+1} + w_j)$$

- Update:

$$\begin{aligned} w_j^{n+1} &= w_j^n - \frac{\Delta t}{\Delta x} (F_{j+\frac{1}{2}}^n - F_{j-\frac{1}{2}}^n) \\ &= w_j^n - \frac{a\Delta t}{2\Delta x} (w_{j+1} - w_{j-1}) \end{aligned}$$

- Consider the following IC with  $a=1$  and  $\frac{\Delta t}{\Delta x}=0.5$ :

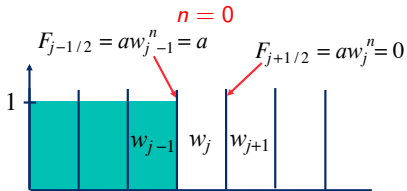
$$F_{j-\frac{1}{2}} = \frac{a}{2}(w_{j-1}^n + w_j^n) = 1 \quad F_{j+\frac{1}{2}} = \frac{a}{2}(w_{j+1}^n + w_j^n) = 0.5$$



$$\begin{aligned} w_j^{n+1} &= w_j^n - \frac{\Delta t}{\Delta x} (F_{j+\frac{1}{2}}^n - F_{j-\frac{1}{2}}^n) \\ &= 1 - 0.5 \cdot (0.5 - 1) = 1.25 \end{aligned}$$

- **Cell  $j$  will overflow immediately!**
- It is easy to see why the centred difference approximation is always unstable

# Stability in terms of Fluxes: Upwind for Advection



- Finite volume approximation:

$$\frac{dw_j}{dt} = \frac{F_{j-\frac{1}{2}} - F_{j+\frac{1}{2}}}{\Delta x} \quad F_{j+\frac{1}{2}} = aw_{j+\frac{1}{2}} \approx aw_j$$

- Update:

$$w_j^{n+1} = w_j^n - \frac{\Delta t}{\Delta x} \left( \overbrace{F_{j+\frac{1}{2}}^n}^{=aw_{j-1}^n} - \overbrace{F_{j-\frac{1}{2}}^n}^{=aw_j^n} \right) = w_j^n - \frac{a\Delta t}{\Delta x} (w_j^n - w_{j-1}^n)$$

- Consider  $a = 1$ ,  $\frac{\Delta t}{\Delta x} = 1.5a = 1.5$ . Start iterations:

- $n = 0$ :  $w_j^0 = 0$   $F_{j+\frac{1}{2}}^0 = 0$   $F_{j-\frac{1}{2}}^0 = 1$

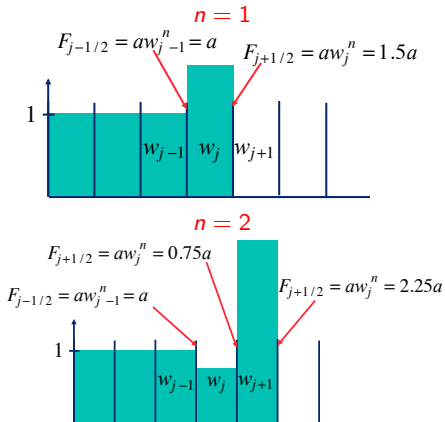
- $n = 1$ :  $w_j^1 = w_j^0 - \frac{\Delta t}{\Delta x} (F_{j+\frac{1}{2}}^0 - F_{j-\frac{1}{2}}^0) = 0 - 1.5 \cdot (0 - 1) = 1.5$

- $n = 2$ :  $w_j^2 = w_j^1 - \frac{\Delta t}{\Delta x} (F_{j+\frac{1}{2}}^1 - F_{j-\frac{1}{2}}^1) = 0 - 1.5 \cdot (1.5 - 1) = 0.75$

$$w_{j+1}^2 = w_{j+1}^1 - \frac{\Delta t}{\Delta x} (F_{j+\frac{3}{2}}^1 - F_{j+\frac{1}{2}}^1) = 0 - 1.5 \cdot (0 - 1.5) = 2.25$$

- $n = 3$ : Even larger positive value, until overflow (NaN)

- If  $\frac{a\Delta t}{\Delta x} > 1$  scheme unstable!

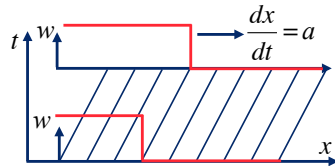


# Discontinuous solutions: shocks

## Linear advection Equation

$$\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = 0 \quad w(x, 0) = \begin{cases} w_L & x < x_0 \\ w_R & x > x_0 \end{cases} \quad (w_L > w_R)$$

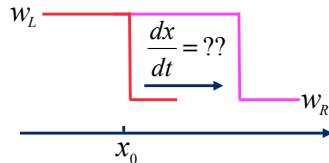
- ▶ Analytic solution obtained by characteristics:  $\frac{dx}{dt} = a \quad \frac{dw}{dt} = 0$
- ▶ Discontinuity of solution is allowed!



## Inviscid Burgers' Equation

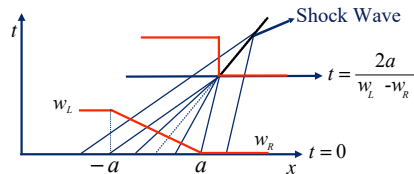
$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial x} = 0 \quad w(x, 0) = \begin{cases} w_L & x < x_0 \\ w_R & x > x_0 \end{cases} \quad (w_L > w_R)$$

- ▶ Characteristics:  $\frac{dx}{dt} = w \quad \frac{dw}{dt} = 0$
- ▶ Slight variation of the initial condition: formation of shock



$$w(x, 0) = \begin{cases} w_L & x < -a \\ \frac{1}{2} \left[ w_L + w_R - (w_L - w_R) \frac{x}{a} \right] & -a < x < a \\ w_R & x > a \end{cases}$$

- How to compute the shock speed?



# Shock speed

Reference frame of the shock:  $x' = x - Ct$

$$\Rightarrow \frac{\partial w}{\partial t} = \frac{\partial w}{\partial t} + \frac{\partial w}{\partial x'} \frac{\partial x'}{\partial t} = \frac{\partial w}{\partial t} + C \frac{\partial w}{\partial x'}$$

Replace into the equation:

$$\frac{\partial w}{\partial t} + \frac{\partial F}{\partial x} = 0$$

$$\frac{\partial w}{\partial t} - C \frac{\partial w}{\partial x'} + \frac{\partial F}{\partial x'} = 0$$

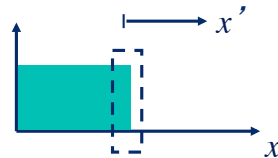
$$\int_{\Delta \rightarrow 0} \left( \frac{\partial w}{\partial t} - C \frac{\partial w}{\partial x'} + \frac{\partial F}{\partial x'} \right) dx = 0$$

$$\cancel{\int_{\Delta \rightarrow 0} \frac{\partial w}{\partial t} dx} - \int_{\Delta \rightarrow 0} C \frac{\partial w}{\partial x'} dx + \int_{\Delta \rightarrow 0} \frac{\partial F}{\partial x'} dx = 0$$

$$-C(w_R - w_L) + (F_R - F_L) = 0$$

## ► Rankine-Hugoniot Relations!

$$C = \frac{F_R - F_L}{w_R - w_L}$$



Example:

$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial x} = 0 \quad F = \frac{w^2}{2}$$

$$C = \frac{F_R - F_L}{w_R - w_L} = \frac{1}{2} \frac{w_R^2 - w_L^2}{w_R - w_L}$$

$$= \frac{1}{2} \frac{(w_R + w_L) \cdot \cancel{(w_R - w_L)}}{\cancel{w_R - w_L}}$$

$$= \frac{1}{2} (w_R + w_L)$$



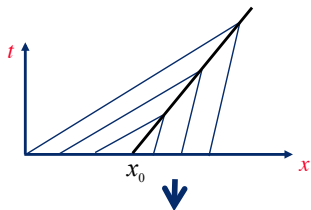
# Entropy conditions (I)

Inviscid Burgers equation:

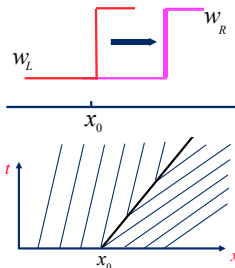
$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial x} = 0$$

Characteristics:  $\frac{dx}{dt} = w, \quad \frac{dw}{dt} = 0$

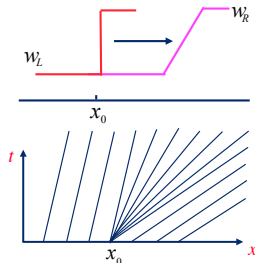
- The transformation  $x \rightarrow -x, t \rightarrow -t$  leaves the equation unchanged but results in unphysical solution!
- Need for entropy condition to select the correct one



**Reverse shock (?)**  
Unstable, entropy-violating solution



**Rarefaction wave**  
Physically correct solution



# Entropy conditions (II)

Weak solution to hyperbolic equations may not be unique

- ▶ How to find the **physical solution** out of many weak solution?
- ▶ The actual physics always includes **dissipation**:  $\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial x} = \nu \frac{\partial^2 w}{\partial x^2}$ 
  - What we are seeking is the solution for viscous Burgers' eq. for  $\nu \rightarrow 0$

## Entropy Condition:

A discontinuity propagating with speed  $C$  satisfies the entropy condition if

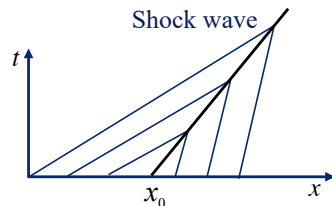
$$(I) \quad F'(w_L) > C > F'(w_R)$$

$$(II) \quad \frac{F(w) - F(w_L)}{w - w_L} \geq C \geq \frac{F(w) - F(w_R)}{w - w_R} \quad \text{for } w_L \geq w \geq w_R$$

Given  $\frac{\partial w}{\partial t} + \frac{\partial F(w)}{\partial x} = 0$ , in characteristic form:

$$\frac{\partial w}{\partial t} + \frac{\partial F}{\partial w} \frac{\partial w}{\partial x} = 0 \quad \text{where} \quad \frac{dt}{ds} = 1, \quad \frac{dx}{ds} = \frac{\partial F}{\partial w} \implies \frac{dx}{dt} = \frac{\partial F}{\partial w} = F'(w)$$

- ▶ The condition states that characteristics must “enter” the discontinuity  $\implies$  its speed  $C$  must satisfy (I)
- ▶ Since  $C = \frac{F_R - F_L}{w_R - w_L}$ , then (II) is satisfied
  - The hypothetical shock speed for values of  $w$  between  $L$  and  $R$  must give shock speeds that are larger on the left and smaller on the right



# Conservative discretization

In FVM, equations in **conservative forms** are needed in order to satisfy conservation properties!

- Consider a 1D equation

$$\frac{\partial w}{\partial t} + \frac{\partial F[w(x, t)]}{\partial x} = 0 \quad x \in [0, L]$$

with  $F$  a general advection or diffusion term

- Integrate over the domain  $L$ :

$$\int_0^L \frac{\partial w}{\partial t} dx + \int_0^L \frac{\partial F}{\partial x} dx = 0$$

$$F(L) - F(0) = 0 \implies \frac{d}{dt} \int_L w dx = 0$$

- If  $F = 0$  at the endpoints,  $w$  is conserved!

- In discretized form:

$$\begin{aligned} \int_0^L \frac{\partial F}{\partial x} dx &= \sum \frac{F_{j+\frac{1}{2}} - F_{j-\frac{1}{2}}}{\Delta x} \Delta x \\ &= [\dots + F_{j-\frac{1}{2}} - F_{j-\frac{3}{2}} + F_{j+\frac{1}{2}} \\ &\quad - F_{j-\frac{1}{2}} + F_{j+\frac{3}{2}} - F_{j+\frac{1}{2}} + \dots] \\ &= F_L - F_0 \end{aligned}$$

**Examples:**  $\frac{\partial (\frac{1}{2} w^2)}{\partial x}$  vs  $w \frac{\partial w}{\partial x}$

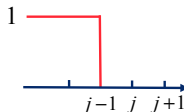
$$\underbrace{\frac{\partial (\frac{1}{2} w^2)}{\partial x}}_{=} \approx \underbrace{\frac{1}{2\Delta x} (w_j^2 - w_{j-1}^2)}_{\neq} \quad \text{Cons.}$$

$$\underbrace{w \frac{\partial w}{\partial x}}_{=} \approx \underbrace{\frac{w_j}{\Delta x} (w_j - w_{j-1})}_{\neq} \quad \text{Non cons.}$$

- Terms cancel out only for conservative form!
  - Cons. schemes guarantee the **correct shock speed**
  - Non-cons. schemes may or may not. Example:

$$\text{(NC)} \quad w_j^{n+1} = w_j^n - \frac{\Delta t}{\Delta x} w_j^n (w_j^n - w_{j-1}^n) = 0$$

$$\text{(C)} \quad w_j^{n+1} = w_j^n - \frac{\Delta t}{2\Delta x} [(w_j^n)^2 - (w_{j-1}^n)^2] = \frac{\Delta t}{2\Delta x}$$



With **(NC)**, shock never moves!

■ Classification of PDE

■ Methods for Hyperbolic Equations

■ **Methods for Parabolic Equations**

■ Advection–Diffusion Equation

# 1D heat equation: explicit method

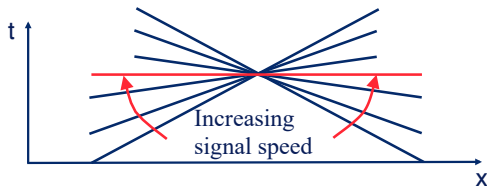
$$\boxed{\frac{\partial w}{\partial t} = \nu \frac{\partial^2 w}{\partial x^2}}, \quad t > 0, a \leq x \leq b$$

Parabolic equation requiring

► **Initial Condition:**  $w(x, 0) = w_0(x)$

► **Boundary Conditions:**

- Dirichlet:  $w(a, t) = \phi_a(t)$
- Neumann:  $\frac{\partial w}{\partial x}(a, t) = \varphi_a(t)$



► Can be viewed as the limit of a hyperbolic equation as signal speed  $\rightarrow \infty$

► **Example of explicit method: FTCS**

$$\frac{w_j^{n+1} - w_j^n}{\Delta t} = \nu \frac{w_{j+1}^n - 2w_j^n + w_{j-1}^n}{\Delta x^2}$$

► **Modified equation:**

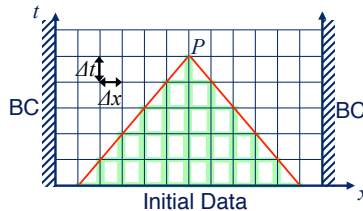
$$\frac{\partial w}{\partial t} - \nu \frac{\partial^2 w}{\partial x^2} = \frac{\nu \Delta x^2}{12} (1 - 6\dot{\nu}) w_{xxxx} + \mathcal{O}(\Delta t^2, \Delta x^2 \Delta t, \Delta x^4) w_{6xx} \quad \text{with} \quad \dot{\nu} = \frac{\nu \Delta t}{\Delta x^2}$$

- Accuracy  $\mathcal{O}(\Delta t, \Delta x^2)$

► **Stability analysis** gives the **Fourier condition:**

$$G = \frac{\hat{w}^{n+1}}{\hat{w}^n} = 1 - 4 \frac{\nu \Delta t}{\Delta x^2} \sin^2 k \frac{\Delta x}{2} = 1 - 4\dot{\nu} \sin^2 \frac{\beta}{2}$$

$$\Rightarrow -1 < 1 - 4\dot{\nu} < 1 \iff 0 \leq \dot{\nu} \leq \frac{1}{2}$$



► Boundary effect not felt at  $P$  for many time steps with FTCS! May result in unphysical behavior

## 1D heat equation: implicit method

- Example of **implicit method**: **Backward Euler**

$$\frac{w_j^{n+1} - w_j^n}{\Delta t} = \nu \frac{w_{j+1}^{n+1} - 2w_j^{n+1} + w_{j-1}^{n+1}}{\Delta x^2}$$

- **Modified equation**:

$$\frac{\partial w}{\partial t} - \nu \frac{\partial^2 w}{\partial x^2} = \frac{\nu \Delta x^2}{12} (1 + 6\dot{\nu}) w_{4x} + \mathcal{O}(\Delta t^2, \Delta x^2 \Delta t, \Delta x^4) w_{6x}$$

- The + sign suggests that implicit methods may be less accurate than corresponding explicit ones
- **Stability analysis**:

$$G = \frac{\widehat{w}^{n+1}}{\widehat{w}^n} = \frac{1}{1 + 2\dot{\nu}(1 - \cos \beta)}$$

- Unconditionally stable!

- Rewritten as a tridiagonal matrix system:

$$w_j^{n+1} - w_j^n = \frac{\nu \Delta t}{\Delta x^2} (w_{j+1}^{n+1} - 2w_j^{n+1} + w_{j-1}^{n+1})$$

$$\dot{\nu} w_{j-1}^{n+1} - (1 + 2\dot{\nu}) w_j^{n+1} + \dot{\nu} w_{j+1}^{n+1} = -w_j^n$$

$$a_k w_{k-1} - d_k w_k + c_k w_{k+1} = b_k$$

- Write in matrix form:

$$d_1 w_1 + c_1 w_2 = b_1$$

$$a_2 w_1 + d_2 w_2 + c_2 w_3 = b_2$$

⋮

$$a_{N-1} w_{N-2} + d_{N-1} w_{N-1} + c_{N-1} w_N = b_{N-1}$$





$$a_N w_{N-1} + d_N w_N = b_N$$

If endpoints are given:  $b_1 = -a_1 w_0$ ,  $b_N = -c_N w_{N+1}$

- Linear system to be solved

# Summary

$$\frac{\partial w}{\partial t} + \nu \frac{\partial^2 w}{\partial x^2} = 0 \quad \dot{\nu} = \frac{\nu \Delta t}{\Delta x^2}$$

Name / Stencil	Scheme	Error term	Stability
<b>FTCS</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} = \nu \frac{w_{j+1}^n - 2w_j^n + w_{j-1}^n}{\Delta x^2}$	$\frac{\nu \Delta x^2}{12} (1 - 6\dot{\nu}) w_{4x}$	Stable for $\dot{\nu} \leq \frac{1}{2}$
<b>BTCS</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} = \nu \frac{w_{j+1}^{n+1} - 2w_j^{n+1} + w_{j-1}^{n+1}}{\Delta x^2}$	$\frac{\nu \Delta x^2}{12} (1 + 6\dot{\nu}) w_{4x}$	Unconditionally Stable
<b>Crank-Nicolson</b> 	$\frac{w_j^{n+1} - w_j^n}{\Delta t} = \frac{\nu}{2\Delta x^2} \left[ (w_{j+1}^{n+1} - 2w_j^{n+1} + w_{j-1}^{n+1}) + (w_{j+1}^n - 2w_j^n + w_{j-1}^n) \right]$	$\frac{\nu \Delta x^2}{12} w_{4x} + \frac{\nu^3 \Delta t^2}{12} w_{6x}$	Unconditionally Stable
<b>DuFort-Frankel</b> 	$\frac{w_j^{n+1} - w_j^{n-1}}{2\Delta t} = \nu \frac{(w_{j+1}^n - w_j^{n+1} - w_j^{n-1} + w_{j-1}^n)}{\Delta x^2}$	$\frac{\nu \Delta x^2}{12} (1 - 12\dot{\nu}^2) w_{4x}$	Unconditionally Stable, Conditionally consistent

$$\frac{w_j^{n+1} - w_j^n}{\Delta t} = \nu \left[ \theta \frac{w_{j+1}^{n+1} - 2w_j^{n+1} + w_{j-1}^{n+1}}{\Delta x^2} + (1 - \theta) \frac{w_{j+1}^n - 2w_j^n + w_{j-1}^n}{\Delta x^2} \right] \quad \theta = \begin{cases} 0 & \text{Explicit (FTCS)} \\ 1 & \text{Implicit (BTCS)} \\ 1/2 & \text{Crank-Nicolson} \end{cases}$$

# Stability in terms of fluxes: FTCS for Diffusion

Consider  $\frac{\partial w}{\partial t} + \frac{\partial F}{\partial x} = 0$  with  $F = -\nu \frac{\partial w}{\partial x}$

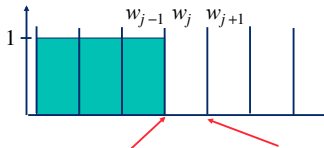
- Finite volume approximation:

$$\frac{dw_j}{dt} = \frac{F_{j-\frac{1}{2}} - F_{j+\frac{1}{2}}}{\Delta x} \quad F_{j+\frac{1}{2}} = -\nu \frac{w_{j+1} - w_j}{\Delta x}$$

- Update:

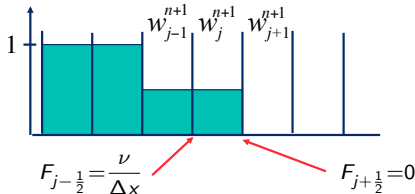
$$w_j^{n+1} = w_j^n + \frac{\nu \Delta t}{\Delta x^2} (w_{j+1}^n - 2w_j^n + w_{j-1}^n)$$

- Consider the following initial conditions:



$$F_{j-\frac{1}{2}} = -\nu \frac{w_j - w_{j-1}}{\Delta x} = \frac{\nu}{\Delta x} \quad F_{j+\frac{1}{2}} = -\nu \frac{w_{j+1} - w_j}{\Delta x} = 0$$

- $\frac{\nu \Delta t}{\Delta x}$  of  $w$  flows into cell  $j$ , but nothing flow out
- Eventually, cell  $j-1$  becomes empty and  $j$  full..



- It seems reasonable to limit  $\Delta t$  such that we stop when both cells are equally full

$$\begin{aligned} w_{j-1}^n + \frac{\nu \Delta t}{\Delta x^2} (w_j^n - 2w_{j-1}^n + w_{j-2}^n) \\ = w_j^n + \frac{\nu \Delta t}{\Delta x^2} (w_{j+1}^n - 2w_j^n + w_{j-1}^n) \end{aligned}$$

Since  $w_{j-2}^n = w_{j-1}^n = 1$  and  $w_j^n = w_{j+1}^n = 0$  we get:

$$1 + \frac{\nu \Delta t}{\Delta x^2} (0 - 2 + 1) = 0 + \frac{\nu \Delta t}{\Delta x^2} (0 - 0 + 1)$$

- Or  $\frac{\nu \Delta t}{\Delta x^2} = 2$  as maximum value for stability!



■ Classification of PDE

■ Methods for Hyperbolic Equations

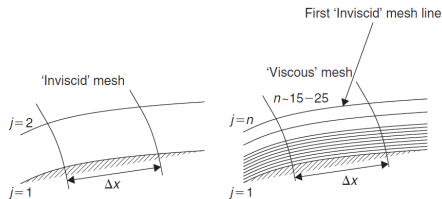
■ Methods for Parabolic Equations

■ Advection–Diffusion Equation

## Grid requirements for BLs

- ▶ BLs have dramatic consequences on grid requirements:

- Thickness of the order of  $1/\sqrt{Re}$
- Need for a minimum of 10-20 points in the BL: **clustering** of the grid points close to the wall



Model problem for BLs:  
**advection-diffusion equation**

$$\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = \nu \frac{\partial^2 w}{\partial x^2}$$

Consider the steady-state **model problem** (2-point BVP)

$$a \frac{\partial w}{\partial x} = \nu \frac{\partial^2 w}{\partial x^2} \quad \text{with} \quad w \in [0, L], \quad w(0) = \alpha, \quad w(L) = \beta$$

- ▶ Define  $Re_u = \frac{a}{\nu} \implies (\star) \frac{\partial^2 w}{\partial x^2} - Re_u \frac{\partial w}{\partial x} = 0$

$$\implies \begin{cases} Re_u \ll 1 & \text{heat equation, easy to solve} \\ Re_u = \mathcal{O}(1) & \text{usual advection-diffusion eq} \\ Re_u \gg 1 & \text{problem!} \end{cases}$$

- ▶ As  $1/Re_u \rightarrow 0$ :

- **Singularly perturbed eq.:** small perturbations change the behaviour
- $(\star)$  reduces to 1<sup>st</sup>-order (**Overimposed problem**)
- $w(x)$  tends to discontinuous function that jumps to  $\beta$
- Region of strong transition called **boundary layer** of thickness  $\mathcal{O}(1/Re)$

- ▶ **Analytical solution:**

$$w(x) = \alpha + (\beta - \alpha) \frac{\exp\left[\frac{ax}{\nu}\right] - 1}{\exp\left[\frac{aL}{\nu}\right] - 1} = \alpha + (\beta - \alpha) \frac{\exp(Re_x) - 1}{\exp(Re_L) - 1}$$

# Preliminary considerations

- Simplest case:  $\alpha = 0$ ,  $\beta = 1$ :

$$w(x) = \frac{\exp(Re_x) - 1}{\exp(Re_L) - 1}$$

- Suppose to represent the **exact** solution on a discrete mesh, defined as  $x_j = j\Delta x$  with  $j \in [1, N]$ :

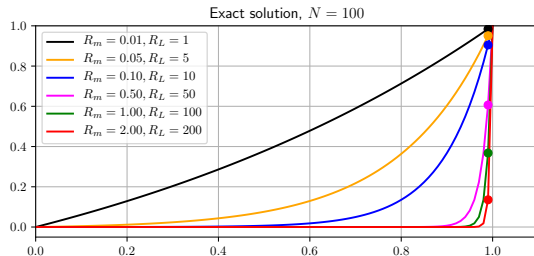
$$Re_x = \frac{ax}{\nu} = \frac{aj\Delta x}{\nu} = jR_m$$

$$Re_L = \frac{aL}{\nu} = \frac{aN\Delta x}{\nu} = NR_m$$

$$\Rightarrow w_j = \frac{e^{jR_m} - 1}{e^{NR_m} - 1}$$

$$w_{N-1} = \frac{e^{(N-1)R_m} - 1}{e^{NR_m} - 1} = \frac{1}{e^{R_m}} \quad \text{for } N \gg 1$$

- $w_{N-1}$  vanishes quickly for  $R_m > 1$ : the boundary layer is no longer resolved
- Similar problems for **interior layers**



- $R_m = \frac{|a|\Delta x}{\nu}$  is the **Mesh Reynolds number**
- Ratio of the time needed to **advect** the solution over one cell to the time needed to **diffuse** it

Now let's try to solve the **discretized equation**

- Transport phenomena intrinsically isotropic  $\Rightarrow$  no physical reason for upwinding viscous terms
- Try using 1<sup>st</sup>-order (upwind) or 2<sup>nd</sup>-order (centred) scheme for convective term

# The Advection-Diffusion equation - Upwind

Recall the operators  $\delta$  and  $\mu$ :

$$\delta(\bullet)_{j+\frac{1}{2}} = (\bullet)_{j+1} - (\bullet)_j$$

$$\mu(\bullet)_{j+\frac{1}{2}} = \frac{1}{2} [(\bullet)_{j+1} + (\bullet)_j]$$

$$\delta\mu(w)_j = \delta \left[ \frac{1}{2} (w_{j+\frac{1}{2}} + w_{j-\frac{1}{2}}) \right]$$

$$= \frac{1}{2} [(w_{j+1} - w_j) + (w_j - w_{j-1})] = \frac{w_{j+1} - w_{j-1}}{2}$$

$$\delta^2(w)_j = \delta \left[ w_{j+\frac{1}{2}} - w_{j-\frac{1}{2}} \right]$$

$$= [w_{j+1} - w_j - (w_j - w_{j-1})] = w_{j+1} - 2w_j + w_{j-1}$$

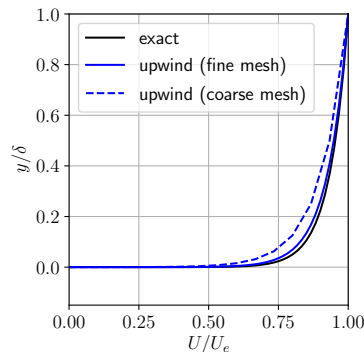
## Generalized Upwind:

(sum of centred term + numerical dissipation):

$$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{\delta\mu w_j^n}{\Delta x} - \frac{1}{2} |a| \Delta x \left[ \frac{\delta^2 w_j^n}{\Delta x^2} \right] = \nu \frac{\delta^2 w_j^n}{\Delta x^2}$$

$$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{\delta\mu w_j^n}{\Delta x} = \nu \left[ 1 + \frac{R_m}{2} \right] \frac{\delta^2 w_j^n}{\Delta x^2}$$

## Velocity profile inside a BL



- ▶ Numerical diffusion **adds** to the physical one
- ▶ Computed velocity profiles correspond to a **lower**  $Re$  than the physical one
- ▶ Possible solutions:
  - Use finer grids (costly)
  - Use a centred (non-dissipative) scheme

# The Advection-Diffusion equation - FTCS (I)

## FTCS:

$$\frac{w_j^{n+1} - w_j^n}{\Delta t} + a \frac{w_{j+1}^n - w_{j-1}^n}{2\Delta x} = \nu \frac{w_{j+1}^n - 2w_j^n + w_{j-1}^n}{\Delta x^2}$$

### ► Modified equation:

$$\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = \left( \nu - \frac{a^2 \Delta t}{2} \right) \frac{\partial^2 w}{\partial x^2} - \frac{a \Delta x^2}{6} \frac{\partial^3 w}{\partial x^3} + \mathcal{O}(\Delta x^3, \Delta t^2)$$

### ► Von Neumann analysis:

$$\frac{\hat{w}_j^{n+1} - \hat{w}_j^n}{\Delta t} + a \frac{\hat{w}_{j+1}^n - \hat{w}_{j-1}^n}{\Delta x} = \nu \frac{\hat{w}_{j+1}^n - 2\hat{w}_j^n + \hat{w}_{j-1}^n}{\Delta x^2}$$

$$\begin{aligned} G &= 1 - \frac{a \Delta t}{2 \Delta x} (e^{i\beta} - e^{-i\beta}) + \frac{\nu \Delta t}{\Delta x^2} (e^{i\beta} - 2 + e^{-i\beta}) \\ &= 1 - 2i\dot{\nu}(1 - \cos \beta) - i\dot{a} \sin \beta \\ &= 1 - 4i\dot{\nu} \sin^2 \frac{\beta}{2} - 2i\dot{a} \sin \frac{\beta}{2} \cos \frac{\beta}{2} \end{aligned}$$

$$1. \hat{w}_{j\pm 1}^n = \hat{w}_j^n e^{\pm i k x_j} e^{\pm i k \Delta x}$$

$$2. e^{\pm i k \Delta x} = e^{\pm i \beta} = \cos \beta \pm i \sin \beta$$

$$\text{Rename } \frac{\beta}{2} = \xi. \text{ For stability, } |G|^2 \leq 1:$$

$$\begin{aligned} 1 - 8i\dot{\nu} \sin^2 \xi + 16i\dot{\nu}^2 \sin^4 \xi + 4\dot{a} \sin^2 \xi \cos^2 \xi &\leq 1 \\ 8i\dot{\nu} \sin^2 \xi (2i\dot{\nu} \sin^2 \xi - 1) + 4\dot{a}^2 \sin^2 \xi \cos^2 \xi &\leq 0 \end{aligned}$$

$$\underbrace{\frac{\dot{\nu}}{\dot{a}^2} \frac{2}{\cos^2 \xi} (2i\dot{\nu} \sin^2 \xi - 1)}_{\text{must be } \leq -1} + 1 \leq 0$$

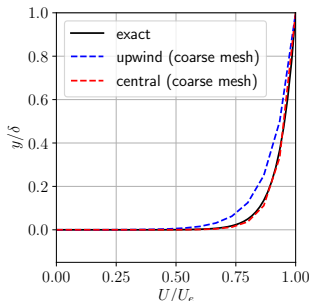
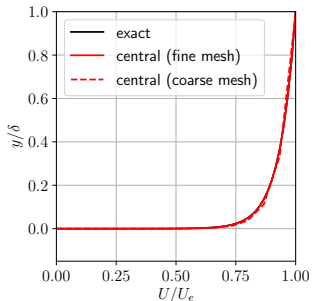
must be  $\leq 0$

$$2i\dot{\nu} \leq 1 \quad \text{and} \quad 2i\dot{\nu} \geq \dot{a}^2$$

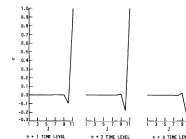
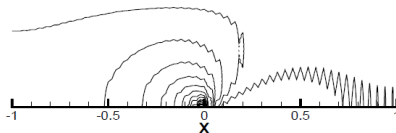
$$\Delta t \leq \frac{\Delta x^2}{2\nu} \quad \text{and} \quad \Delta t \leq \frac{2\nu}{a^2}$$

- It was unconditionally unstable for pure advection
  - Physical diffusion **stabilises** the centred scheme
- Red limit from heat equation
- Blue limit may also be derived from the modified equation (positive dissipation term)
  - Defining  $R_m = \frac{a \Delta x}{\nu}$ , one has:  $R_m \leq \frac{2}{\dot{a}}$

# The Advection-Diffusion equation - FTCS (II)



- It is possible to prove that oscillating solutions are obtained if  $R_m > 2$ !



- Re-write the scheme under the form:

$$\begin{aligned} w_j^{n+1} &= \left( \dot{\nu} - \frac{\dot{a}}{2} \right) w_{j+1}^n + (1 - 2\dot{\nu}) w_j^n + \left( \dot{\nu} + \frac{\dot{a}}{2} \right) w_{j-1}^n \\ &= \frac{\dot{\nu}}{2} (2 - R_m) w_{j+1}^n + (1 - 2\dot{\nu}) w_j^n + \frac{\dot{\nu}}{2} (2 + R_m) w_{j-1}^n \end{aligned}$$

- Suppose  $w^0 = 0$  everywhere (apart for  $w_N^0 = 1$  at  $j = N$  for B.C.)

$$w_{N-1}^1 = \frac{\dot{\nu}}{2} (2 - R_m) w_N^0 + (1 - 2\dot{\nu}) w_{N-1}^0 + \frac{\dot{\nu}}{2} (2 + R_m) w_{N-2}^0$$

- if  $R_m > 2 \implies w_{N-1}^1 < 0 \implies$  **oscillations!**
- This becomes worst at subsequent time levels
- Thus, fine grids again... or **compromise solution**:
  - Add numerical diss. as smaller as possible (given stab. requirements)
  - High-order dissipative schemes well suited (e.g,  $2^{\text{nd}}$ -order upwind)

# The Advection-Diffusion equation - Summary

$$\frac{\partial w}{\partial t} + a \frac{\partial w}{\partial x} = \nu \frac{\partial^2 w}{\partial x^2}$$

**Upwind**





$$w_j = \frac{1 - (1 + R_m)^j}{1 - (1 + R_m)^N}$$

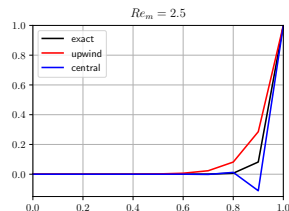
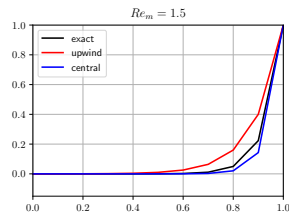
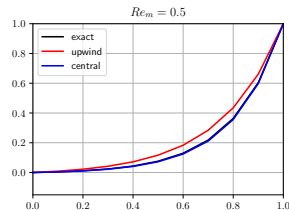
**Centred**

$$w_j = \frac{\left(\frac{2 + R_m}{2 - R_m}\right)^j - 1}{\left(\frac{2 + R_m}{2 - R_m}\right)^N - 1}$$

**Exact**

$$w_j = \frac{e^{jR_m} - 1}{e^{NR_m} - 1}$$

Name / Stencil	Error term	Stability
<b>FTCS</b> 	$\mathcal{O}(\Delta t, \Delta x^2)$	$\dot{\nu} \leq \frac{1}{2} \ \& \ \dot{\nu} \geq \frac{\dot{a}^2}{2}$
<b>Upwind</b> 	$\mathcal{O}(\Delta t, \Delta x)$	$\dot{a} + 2\dot{\nu} \leq 1$
<b>Lax-Wendroff</b> 	$\mathcal{O}(\Delta t^2, \Delta x^2)$	$\dot{a}^2 \leq 2\dot{\nu} \leq 1$
<b>Crank-Nicolson</b> 	$\mathcal{O}(\Delta t^2, \Delta x^2)$	Unconditionally stable



# Complexity for discretization of RANS equations

## ► Time step:

$$\Delta t = \min(\Delta t_c, \Delta t_v) \quad \text{with} \quad \begin{cases} \Delta t_c = \mathcal{O}\left(\frac{\Delta x}{|u| + a}\right) \\ \Delta t_v = \mathcal{O}\left(\frac{\Delta x^2}{\nu}\right) \end{cases} \Rightarrow \frac{\Delta t_v}{\Delta t_c} = \mathcal{O}\left(\frac{(|u| + a)\Delta x}{\nu}\right) = \mathcal{O}\left[R_m \left(1 + \frac{1}{Ma}\right)\right]$$

- For low- $Ma$  flows,  $\Delta t_v \gg \Delta t_c$ ; the opposite for high- $Ma$  flows
- Small grid size near the wall  $\Rightarrow$  explicit schemes **costly** because of viscous terms
- **Implicit schemes** relax the constraint but require efficient solution of linear systems at each iteration

## ► Turbulent transport equations

- **Numerical stiffness** introduced by source terms
- **Strong coupling** of equations by means of source and diffusion terms
- Problems related to the need of preserving **variable positiveness**
- Crucial point to avoid the use of brutal limiters damaging the solution convergence

## ► Discretization of convective terms

- 1<sup>st</sup>-order upwind schemes?
  - ✓ Ensure positivity of variables
  - ✗ Low accuracy!
- TVD schemes?
  - ✓ Ensure positivity of variables
  - ✗ Difficult to develop schemes that are TVD and implicit at the same time  
(Needed for using large CFL on stretched grids)
- Positivity-preserving, not-TVD schemes?
  - ✓ Ensure positivity of variables
  - ✗ Oscillations near discontinuities