Lecture 8

Convergence Theory for Linear Methods - Part 2

SF2521

Checking stability von Neumann Analysis

Goal: derive sufficient condition for stability.

- ► We use von Neumann analysis;
- based on Fourier analysis;
- stability is shown similarly as to how well-posedness is shown for the continuous problem and hence
- von Neumann analysis requires a constant coefficient a.
- More precisely, scheme should have same form at all grid points, i.e. general form reduces to

$$Q_j^{n+1} = \sum_{\ell=-m}^{M} b_{\ell}(\Delta t, \Delta x) \ Q_{j+\ell}^{n}, \tag{S}$$

where b_{ℓ} does not depend on j.

► Moreover: either no boundaries or periodic boundary conditions.

Example for admissible scheme and problem:

Consider the constant coefficient advection problem

$$\partial_t \mathbf{u} + \mathbf{a} \, \partial_x \mathbf{u} = \mathbf{o}.$$

For the upwind scheme applied to it we have

$$Q_j^{n+1} = Q_j^n - \frac{\Delta t}{\Delta x} \mathbf{a} (Q_j^n - Q_{j-1}^n),$$

and hence m = 1, M = 0 and

$$oldsymbol{b}_{ extsf{0}} = \mathbf{1} - \mathbf{a} \lambda_{ extsf{CFL}}, \quad oldsymbol{b}_{- extsf{1}} = \mathbf{a} \lambda_{ extsf{CFL}}, \quad \lambda_{ extsf{CFL}} = rac{\Delta t}{\Delta x}.$$

Remark before we start:

- von Neumann analysis works for any equation, not just hyperbolic problems.
- ▶ However, natural relation between Δt and Δx may then differ.
- ▶ E.g. $\Delta t/\Delta x^2 = \mathcal{O}(1)$ for explicit methods for parabolic problems (compare Lecture 3!)

Checking stability

von Neumann Analysis - Periodic boundary conditions

We consider

$$\partial_t \mathbf{u} + \mathbf{a} \, \partial_x \mathbf{u} = \mathbf{0}.$$

and assume periodic boundary conditions, i.e. $u(t, 0) = u(t, 2\pi)$.

The space discretization is

$$x_j = j\Delta x, \qquad \Delta x = \frac{2\pi}{N},$$

and the approximation Q_i^n satisfies discrete periodicity

$$Q_i^n = Q_{i+N}^n, \quad \forall j, \quad \forall n \geq 0.$$

Hence, we only compute the Q_i^n values for j = 0, ..., N-1, but then define Q_i^n for all j by periodicity.

Also assume that N is even.

Let $\hat{\mathbf{Q}}^n \in \mathbb{R}^N$ be the discrete Fourier transform of $\mathbf{Q}^n \in \mathbb{R}^N$, so that

$$Q_j^n = \sum_{k=-N/2}^{N/2-1} \hat{Q}_k^n e^{\mathrm{i}kx_j}.$$

The Fourier coefficients can be obtained by the transform

$$\hat{Q}_{k}^{n} = \frac{1}{N} \sum_{i=0}^{N-1} Q_{j}^{n} e^{-ikx_{j}}.$$

Using the scheme Φ as in (S) we can derive an expression for \hat{Q}_k^{n+1} in terms of \hat{Q}_k^n as follows.

We use
$$Q_i^n = \sum_{k=-N/2}^{N/2-1} \hat{Q}_k^n e^{ikx_j}$$
 and $\hat{Q}_k^n = \frac{1}{N} \sum_{j=0}^{N-1} Q_j^n e^{-ikx_j}$ to obtain

$$\hat{Q}_{k}^{n+1} = \frac{1}{N} \sum_{j=0}^{N-1} Q_{j}^{n+1} e^{-ikx_{j}} \stackrel{\text{scheme}}{=} \frac{1}{N} \sum_{\ell=-m}^{M} \sum_{j=0}^{N-1} b_{\ell} Q_{j+\ell}^{n} e^{-ikx_{j}}$$

$$\stackrel{\text{periodicity}}{=} \frac{1}{N} \sum_{\ell=-m}^{M} \sum_{j=0}^{N-1} b_{\ell} Q_{j}^{n} e^{-ikx_{j-\ell}}$$

$$\stackrel{\{x_{j-\ell}=x_j-\ell\Delta x\}}{=} \frac{1}{N} \sum_{\ell=-m}^{M} \sum_{j=0}^{N-1} b_{\ell} e^{\mathrm{i}k\ell\Delta x} Q_j^n e^{-\mathrm{i}kx_j}$$

$$=\hat{Q}_k^n\sum_{\ell=-m}^Mb_\ell\,e^{\mathrm{i}k\ell\Delta x}.$$

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We obtained

$$\hat{Q}_k^{n+1} = \hat{Q}_k^n \sum_{\ell=-m}^{M} b_{\ell} e^{\mathrm{i}k\ell\Delta x}.$$

Hence, we can write

$$\hat{Q}_k^{n+1} = g_k(\Delta t, \Delta x) \, \hat{Q}_k^n, \qquad g_k(\Delta t, \Delta x) := \sum_{\ell=-m}^m b_\ell(\Delta t, \Delta x) \, e^{\mathrm{i}k\ell\Delta x}.$$

The factor q_k is called

amplification factor.

It shows how the different frequencies in the solution are amplified in each time step.

von Neumann analysis < □ > < □

Amplification factor - Example

For the upwind scheme we have

$$Q_j^{n+1} = Q_j^n - \frac{\Delta t}{\Delta x} \mathbf{a} (Q_j^n - Q_{j-1}^n),$$

and hence m = 1, M = 0 and

$$b_{ extsf{0}} = extsf{1} - extsf{a} \lambda_{ extsf{CFL}}, \quad b_{- extsf{1}} = extsf{a} \lambda_{ extsf{CFL}}, \quad \lambda_{ extsf{CFL}} = rac{\Delta t}{\Delta x}.$$

We conclude that the amplification factor for upwind is

$$g_k(\Delta t, \Delta x) = b_0 + b_{-1} e^{-i\ell\Delta x} = 1 - a \frac{\Delta t}{\Delta x} + a \frac{\Delta t}{\Delta x} e^{-ik\Delta x}.$$

We have $\hat{Q}_k^{n+1} = g_k(\Delta t, \Delta x) \hat{Q}_k^n$. For simplicity, we write $g_k = g_k(\Delta t, \Delta x)$.

We now use Parseval's theorem, which says that

$$||\mathbf{Q}^n||_{2,\Delta x}^2 = \sum_{j=0}^{N-1} |Q_j^n|^2 \Delta x = \sum_{k=-N/2}^{N/2-1} |\hat{Q}_k^n|^2.$$

We get

$$||\Phi(\mathbf{Q}^n)||_{2,\Delta \mathbf{X}}^2 = ||\mathbf{Q}^{n+1}||_{2,\Delta \mathbf{X}}^2 = \sum_{k=-N/2}^{N/2-1} |\hat{Q}_k^{n+1}|^2 = \sum_{k=-N/2}^{N/2-1} |g_k \hat{Q}_k^n|^2$$

$$\leq \max_{-\frac{N}{2} \leq k \leq \frac{N}{2}-1} |g_k|^2 \sum_{k=-N/2}^{N/2-1} |\hat{Q}_k^n|^2 = \max_{-\frac{N}{2} \leq k \leq \frac{N}{2}-1} |g_k|^2 ||\mathbf{Q}^n||_{2,\Delta \mathbf{X}}^2.$$

Hence,

$$||\Phi(\mathbf{Q}^n)||_{2,\Delta x} \leq \max_{-\frac{N}{2} \leq k \leq \frac{N}{2}-1} |g_k|||\mathbf{Q}^n||_{2,\Delta x},$$

and we see that a sufficient condition for stability is

$$\max_{-\frac{N}{2} \le k \le \frac{N}{2} - 1} |g_k| \le 1 + \alpha \Delta t.$$

Remark:

► In most cases when the exact solution does not grow exponentially we can actually show the stronger version

$$\max_{-\frac{N}{2} \leq k \leq \frac{N}{2} - 1} |g_k| \leq 1.$$

Condition for amplification factor:

$$\max_{-\frac{N}{2} \le k \le \frac{N}{2} - 1} |g_k(\Delta t, \Delta x)| \le 1 + \alpha \Delta t.$$

Example $(\partial_t u + a \partial_x u = o - Advection equation)$

Assume that it holds the CFL condition

$$|\mathbf{a}| \frac{\Delta t}{\Delta x} \leq 1.$$

For the upwind scheme and a > o we have

$$|g_k(\Delta t, \Delta x)| \leq \left|1 - \mathbf{a} \frac{\Delta t}{\Delta x}\right| + \left|\mathbf{a} \frac{\Delta t}{\Delta x}\right| = 1 - \mathbf{a} \frac{\Delta t}{\Delta x} + \mathbf{a} \frac{\Delta t}{\Delta x} = 1.$$

CFL condition is hence both necessary and sufficient for upwind scheme.

Example $(\partial_t u - \triangle u = o - Heat equation)$

Consider forward Euler and central differences for the heat equation:

$$Q_j^{n+1} = Q_j^n + \mu(Q_{j+1}^n - 2Q_j^n + Q_{j-1}^n), \qquad \mu = \frac{\Delta t}{\Delta x^2}.$$

Here m = M = 1 and $b_{-1} = \mu$, $b_0 = 1 - 2\mu$, $b_1 = \mu$. Then

$$g_k(\Delta t, \Delta x) = \mu e^{-ik\Delta x} + 1 - 2\mu + \mu e^{ik\Delta x}$$
$$= 1 + 2\mu \left(\cos(k\Delta x) - 1\right) = 1 - 4\mu \sin^2\left(\frac{k\Delta x}{2}\right).$$

Since

$$\max_{|k| \le \frac{N}{2}} \sin^2 \left(\frac{k \Delta x}{2} \right) = \max_{|k| \le \frac{N}{2}} \sin^2 \left(\frac{k \pi}{N} \right) = \sin^2 \left(\frac{\pi}{2} \right) = 1,$$

 g_k takes values in the interval $[1 - 4\mu, 1]$ and the method is stable if $\mu \le 1/2$.

Example $(\partial_t u + \partial_x u = o - Advection equation)$

Consider forward Euler and central differences for the advection equation:

$$Q_j^{n+1} = Q_j^n + rac{1}{2}\lambda_{\mathsf{CFL}}(Q_{j+1}^n - Q_{j-1}^n), \qquad \lambda_{\mathsf{CFL}} = rac{\Delta t}{\Delta x}.$$

Again, here m=M=1, but $b_{-1}=-\frac{\lambda_{CFL}}{2}$, $b_0=1$, $b_1=\frac{\lambda_{CFL}}{2}$. Then

$$g_k(\Delta t, \Delta x) = -rac{\lambda_{ ext{CFL}}}{2}e^{-\mathrm{i}k\Delta x} + 1 + rac{\lambda_{ ext{CFL}}}{2}e^{\mathrm{i}k\Delta x} = 1 + \lambda_{ ext{CFL}}\mathrm{i}\sin(k\Delta x).$$

Hence,

$$\max_{k} |g_k(\Delta t, \Delta x)| = \max_{k} \sqrt{1 + \lambda_{\mathsf{CFL}}^2 \sin(k\Delta x)^2} > 1,$$

and the method is unstable for all fixed λ_{CFL} .

Example $(\partial_t u + \partial_x u = o - Advection equation)$

Consider forward Euler and central differences for the advection equation:

$$Q_j^{n+1} = Q_j^n + rac{1}{2}\lambda_{\mathsf{CFL}}(Q_{j+1}^n - Q_{j-1}^n), \qquad \lambda_{\mathsf{CFL}} = rac{\Delta t}{\Delta x}.$$

The method is unstable for all fixed λ_{CFL} .

However, if using the "parabolic" CFL condition

$$\lambda_{\mathsf{CFL}} \sim rac{\Delta t}{\Delta x^2} \qquad \Rightarrow \qquad \lambda_{\mathsf{CFL}} \sim \Delta x \sim \sqrt{\Delta t}.$$

then

$$|g_k(\Delta t, \Delta x)| = \sqrt{1 + \lambda_{\mathsf{CFL}}^2 \sin(k\Delta x)^2} \sim \sqrt{1 + \Delta t \sin(k\Delta x)^2} \leq 1 + \alpha \Delta t,$$

for some α and small enough Δt . Choice makes the unstable method stable.



Recap von Neumann analysis Weak solutions Viscosity limits

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Checking stability von Neumann Analysis - No boundaries

- Case of no boundaries is similar to periodic case.
- ► <u>Difference</u>: instead of discrete Fourier transform we use Fourier series.
- \blacktriangleright More precisely, we use \mathbf{Q}^n a <u>coefficients in a Fourier series</u>.
- The infinite sequence Q^n defines a 2π -periodic function $\hat{Q}^n \in L^2(0, 2\pi)$ via

$$\hat{\mathbf{Q}}^n(x) = \sum_{j=-\infty}^{\infty} Q_j^n e^{ijx}, \qquad Q_j^n = \frac{1}{2\pi} \int_0^{2\pi} \hat{\mathbf{Q}}^n(\xi) e^{-ij\xi} d\xi.$$

(simple calculation)

We have

$$\hat{\mathbf{Q}}^{n}(x) = \sum_{i=-\infty}^{\infty} Q_{j}^{n} e^{ijx}, \qquad Q_{j}^{n} = \frac{1}{2\pi} \int_{0}^{2\pi} \hat{\mathbf{Q}}^{n}(\xi) e^{-ij\xi} d\xi.$$

As before we derive an expression for $\hat{\mathbf{Q}}^{n+1}(x)$ in terms of $\hat{\mathbf{Q}}^n(x)$:

$$\hat{\mathbf{Q}}^{n+1}(x) = \sum_{j=-\infty}^{\infty} Q_j^{n+1} e^{ijx} = \sum_{\ell=-m}^{M} \sum_{j=-\infty}^{\infty} b_{\ell} Q_{j+\ell}^{n} e^{ijx}$$

$$= \sum_{\ell=-m}^{M} \sum_{j=-\infty}^{\infty} b_{\ell} Q_j^{n} e^{i(j-\ell)x} = \sum_{\ell=-m}^{M} \sum_{j=-\infty}^{\infty} b_{\ell} e^{-i\ell x} Q_j^{n} e^{ijx}$$

$$= \hat{\mathbf{Q}}^{n}(x) \sum_{\ell=-m}^{M} b_{\ell} e^{-i\ell x}.$$

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We thus have

$$\hat{\mathbf{Q}}^{n+1}(x) = \hat{g}(x, \Delta t, \Delta x) \,\hat{\mathbf{Q}}^{n}(x), \qquad \hat{g}(x, \Delta t, \Delta x) = \sum_{\ell=-m}^{M} b_{\ell}(\Delta t, \Delta x) \,e^{-i\ell x}.$$

For this setting Parseval's theorem says

$$\frac{1}{2\pi} \int_0^{2\pi} |\hat{\mathbf{Q}}^n(x)|^2 dx = \sum_{i=-\infty}^{\infty} |Q_j^n|^2 = \frac{1}{\Delta x} \|\mathbf{Q}^n\|_{2,\Delta x}^2.$$

Therefore,

$$\|\mathbf{\Phi}(\mathbf{Q}^n)\|_{2,\Delta \mathbf{x}}^2 = \|\mathbf{Q}^{n+1}\|_{2,\Delta \mathbf{x}}^2 = \frac{\Delta \mathbf{x}}{2\pi} \int_0^{2\pi} |\hat{\mathbf{Q}}^{n+1}(x)|^2 dx = \frac{\Delta \mathbf{x}}{2\pi} \int_0^{2\pi} |\hat{\mathbf{g}}(x)\hat{\mathbf{Q}}^n(x)|^2 dx$$

$$\leq \sup_{\mathbf{x} \in [0,2\pi]} |\hat{\mathbf{g}}(x)|^2 \frac{\Delta \mathbf{x}}{2\pi} \int_0^{2\pi} |\hat{\mathbf{Q}}^n(x)|^2 dx = \sup_{\mathbf{x} \in [0,2\pi]} |\hat{\mathbf{g}}(x)|^2 \|\mathbf{Q}^n\|_{2,\Delta \mathbf{x}}^2.$$

Hence

$$\|\mathbf{\Phi}(\mathbf{Q}^n)\|_{2,\Delta x} \leq \sup_{x \in [0,2\pi]} |\hat{g}(x)| \|\mathbf{Q}^n\|_{2,\Delta x},$$

and we see that a sufficient condition for stability is

$$\sup_{x\in[0,2\pi]}|\hat{g}(x)|\leq 1+\alpha\Delta t.$$

We note here the relationship

$$\hat{g}(-k\Delta x, \Delta t, \Delta x) = \sum_{\ell=-m}^{M} b_{\ell}(\Delta t, \Delta x) e^{i\ell k\Delta x} = g_{k}(\Delta t, \Delta x).$$

Since \hat{g} is 2π -periodic in x this shows that as $\Delta x \to 0$ the two stability conditions (for q_k and \hat{q}) are equivalent.

von Neumann analysis

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Remark

- For problems with variable coefficients, von Neumann analysis for scheme can only be applied for a *fixed* value of the coefficient.
- Stability for each such frozen coefficient problem is a necessary condition for stability of the whole scheme.
- ► This is often also sufficient.
- **Example:** von Neumann analysis shows that for the upwind scheme we should have $\frac{\Delta L}{\Delta x} \le 1$.

In the variable coefficient case we would then require $\mathbf{a}(x)\Delta t/\Delta x \leq \mathbf{1}$.

