

ON LEARNING PROBABILISTIC MODELS FOR STATE ESTIMATION

by

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A thesis submitted in conformity with the requirements
for the degree of Doctor of Philosophy
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April 11, 2018

Abstract

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2018

This is my abstract.

April 11, 2018

To all those who encouraged my intellectual wanderlust.

April 11, 2018

Acknowledgements

I would like to acknowledge my parents, my partner-in-crime, and my partner-in-academia.

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April 11, 2018

Chapter 1

Introduction

Reliable state estimation is at the heart of mobile robotics.

Bibliography