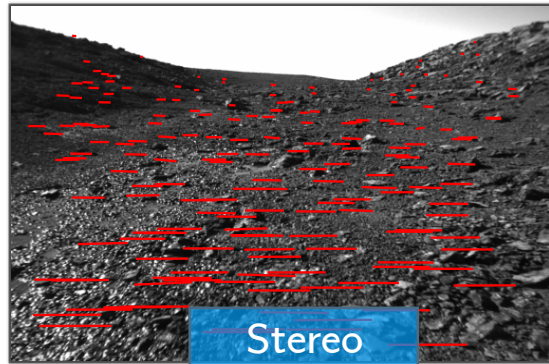
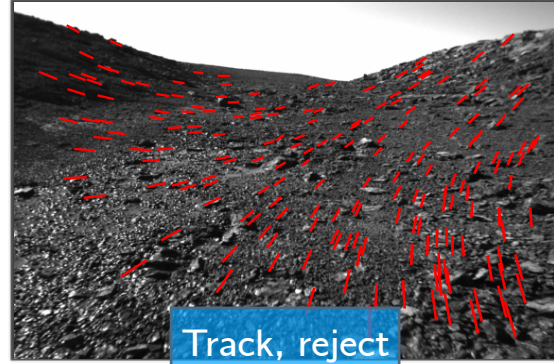


Detect
keypoints



Stereo
match



Track, reject
outliers