Deep Driving model

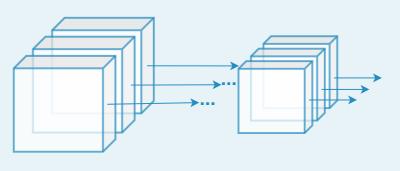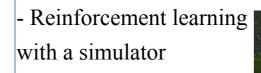**Sensors**
- Camera
- RADAR
- LiDAR
- IMU
- GPS

Inputs
- Local history
- Point clouds
- RGB Video
- Object detections
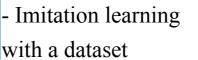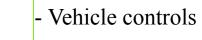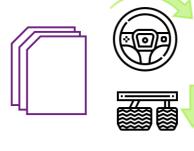- Semantic segmentations
- Depth maps
- Bird-eye-view

Learning
- Imitation learning with a dataset
- Reinforcement learning with a simulator

Outputs
- Vehicle controls
- Future trajectory