

Open Source Formal Verification engines

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Introduction

Model Checking

Model checking

Method for checking whether a finite-state model of a system meets a given specification

- Applied to state machines
 - A hardware model is by itself a state machine
 - State represented by the D flip-flops and memories
 - Inputs are simply the inputs of the module
 - The specification is given by properties and invariants

Model Checking

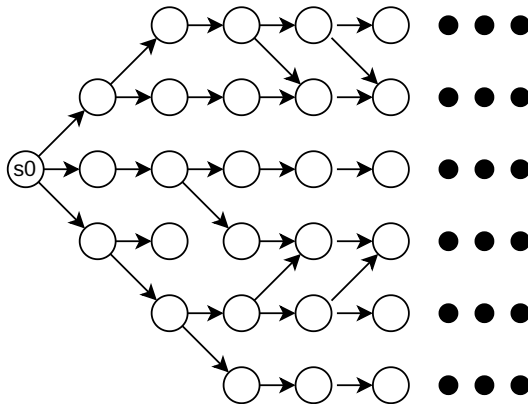
- Concept:

- From a reset condition
- Try to find a state where an assertion fails

- Process:

- 1 Start from an initial state
- 2 Check that assertions hold
- 3 Generate the next states
- 4 Back to 2

- *Success* if no failure is detected
- *Fail* if an assertion fails
- *Unconclusive* if the entire state space cannot be reached



Bounded Model Checking

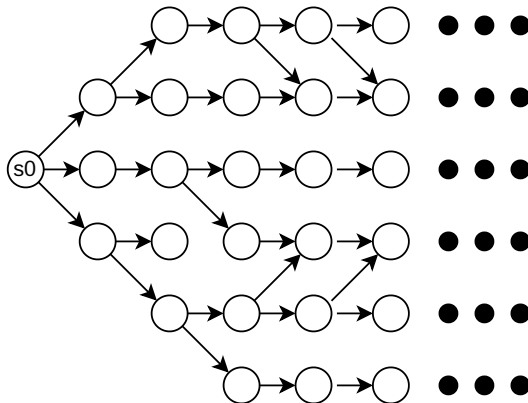
- Concept:

- From a reset condition
- Try to find a state where an assertion fails
- **For at most N steps** (the depth)

- Process:

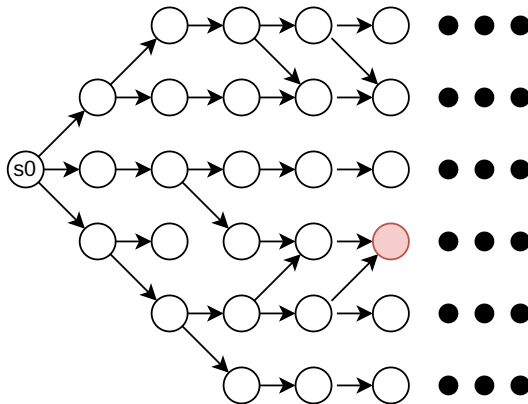
- 1 Start from an initial state
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Bounded Model Checking

- Red state corresponds to a failing assertion
- Found after 5 cycles
- If the depth is at least 5, then the failure will be detected
- If the depth is less than 5, then the checker will not detect it



What depth?

- Crucial question: What depth?
 - Too short \Rightarrow Does not verify anything
 - Too big \Rightarrow Too much processing time
- Depends on the system
- Examples:
 - For a FIFO, it seems fair not to check more writes than 4 times the FIFO size
 - For a counter, if it offers a load operation, 2-3 steps are sufficient
 - For a counter, without a load operation, should be at least the maximum value
 - A good argument for generic parameters

Proof

- BMC is not ideal because of the depth to be chosen
- Can we prove the correctness?
- Option: k-induction

k-induction

- Concept: Check correctness of K steps and then prove that if any K steps are correct, then the $(K + 1)^{\text{th}}$ will be correct

Example: 1-induction

$$P(0) \wedge \forall n(P(n) \Rightarrow P(n + 1)) \Rightarrow \forall nP(n)$$

Example: 2-induction

$$P(0) \wedge P(1) \wedge \forall n((P(n) \wedge P(n + 1)) \Rightarrow P(n + 2)) \Rightarrow \forall nP(n)$$

Interesting: <http://www.ccs.neu.edu/home/wahl/Publications/k-induction.pdf>

k-induction

- Mathematically, k-induction is identical to 1-induction
- Why k ?
- Because it helps the proof, starting with more initial conditions

Verification

- The proof exploits a solver
- The solvers are usually based on SAT or SMT solvers
- SAT (Boolean satisfiability problem)
 - Is there a combination of variables that satisfy a boolean equation in its conjunctive form?
 - $(x1 \wedge x3) \vee (\overline{x2} \wedge x3) \vee (x1 \wedge \overline{x3})$
 - NP-complete problem
- SMT (satisfiability modulo theories)
 - Generalizes SAT to more complex formulas involving:
 - Real numbers, integers
 - Lists, arrays, bit vectors
 - ...

Engines in SBY

Mode	Engine
bmc	smtbc [all solvers] btor btormc btor pono abc bmc3 abc sim3 aiger aigbmc
prove	smtbmc [all solvers] abc pdr aiger suprove
cover	smtbmc [all solvers] btor btormc

smtbmc solvers (1)

- The SMTBMC engine supports the following solvers:
 - **yices** (<https://yices.csl.sri.com/>)
 - Yices 2 is an SMT solver that decides the satisfiability of formulas containing uninterpreted function symbols with equality, real and integer arithmetic, bitvectors, scalar types, and tuples.
 - **boolector** (<https://boolector.github.io/>)
 - A Satisfiability Modulo Theories (SMT) solver for the theories of fixed-size bit-vectors, arrays and uninterpreted functions.
 - **bitwuzla** (<https://bitwuzla.github.io/>)
 - Bitwuzla is a Satisfiability Modulo Theories (SMT) solver for the theories of fixed-size bit-vectors, floating-point arithmetic, arrays and uninterpreted functions and their combinations.
 - **z3** (<https://github.com/Z3Prover/z3>)
 - Z3 is a theorem prover from Microsoft Research.

smtbmc solvers (2)

- The SMTBMC engine supports the following solvers:
 - **mathsat** (<https://mathsat.fbk.eu/>)
 - MathSAT 5 is an efficient Satisfiability modulo theories (SMT) solver supporting a wide range of theories (including e.g. equality and uninterpreted functions, linear arithmetic, bit-vectors, and arrays) and functionalities.
 - **cvc4** (<https://cvc4.github.io/>)
 - CVC4 is an efficient open-source automatic theorem prover for satisfiability modulo theories (SMT) problems. It can be used to prove the validity (or, dually, the satisfiability) of first-order formulas in a large number of built-in logical theories and their combination.
 - **cvc5** (<https://cvc5.github.io/>)
 - cvc5 is an efficient open-source automatic theorem prover for Satisfiability Modulo Theories (SMT) problems. It can be used to prove the satisfiability (or, dually, the validity) of first-order formulas with respect to (combinations of) a variety of useful background theories.

btor

- The btor engine works with btor2 files. It supports the following solvers:
 - **btormc**: <https://github.com/Boolector/boolector>
 - **pono**: <https://github.com/stanford-centaur/pono>

aiger

- The aiger engine (<https://github.com/arminbiere/aiger>) offers two solvers:
 - aigbmc
 - suprove (quite good for proofs)

- The abc engine (<https://github.com/berkeley-abc/abc>) offers three solvers:
 - pdr (most used)
 - bmc3
 - sim3

Prove vs BMC

- A proof can be faster than bounded model checking
- For BMC you need to setup the depth
 - Choice to be made
 - As small as possible, but not smaller
 - *"Aussi petite que possible, mais aussi grande que nécessaire"*

Conclusion

A proof is better than bounded model checking

⇒

Use a proof is possible, else go for model checking

- Do not hesitate to compare various engines to find the most efficient one
 - Can be done by hand
 - or with the `-autotune` option of `sby`
 - Reduces the computing time for regression tests