

# New developments in modeling at GFDL

## Second ISENES Workshop on HPC for Climate Models

### Toulouse FRANCE

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NOAA/GFDL and Princeton University

31 January 2013

# Outline

- 1 GFDL Strategic Plan: 2012-2016
- 2 Scientific drivers: complexity, resolution, uncertainty
  - Atmospheric physics and chemistry
  - Marine and terrestrial biogeochemistry
  - Climate modeling at high resolution
  - Decadal predictability and prediction studies
- 3 Software drivers: concurrency and heterogeneous computing
  - The hardware jungle and the software zoo
  - Framework infrastructure and superstructure
  - Component concurrency
- 4 The Finite-Volume Cubed-Sphere Dynamical Core
  - Mosaic representation
  - Variable-resolution gridding within the cubed-sphere
  - Concurrent nesting
  - Global cloud-resolving model
- 5 Summary

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# GFDL Strategic Plan: 2012-2016

- Basic climate **processes** and their **representations** in models.
- **Comprehensive modeling** of climate system variability and change.
- Understanding, detection and attribution, and prediction of **extreme events**.
- Understanding, **detection** and **attribution**, and **predictability** of modes of climate variability.
- Cryospheric amplification of climate change and **sea-level rise**.
- Understanding the Earth system including **biosphere** and human activities.
- Climate science, **impacts and services**.

Google “GFDL Strategic Science Plan”.

# Current suite of GFDL models

- CM3: comprehensive tropospheric and stratospheric chemistry, aerosol-cloud feedbacks.
- ESM2M and ESM2G: free-running carbon cycle.
- DECP: decadal prediction models at various resolutions with advanced initialization (ECDA).
- C180, C360: atmospheric models with AM3 physics optimized for tropical storm “permitting” simulations (HiRAM).
- Cloud-resolving models (C2560) with bulk microphysics.
- Under development for CM4: unified ocean core MOM6, simplified aerosol chemistry.
- **Performance guidelines** for CMIP-class models: **4** models running at **100** years/month using **half** the available machine.
- Spinup and millennial control runs are **capability** runs. Note ESMs require very long spinup. . .

All models built on **common framework** and run within a single **distributed workflow**.

# FMS: Summary

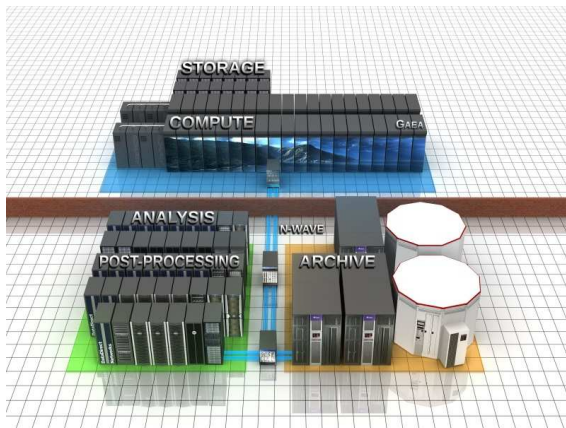
- Scalable high-performance framework on up to  $\mathcal{O}(10^5)$  processors.
- Good, stable, dedicated team in Modeling Services.
- Broad acceptance and widespread contributions to a working system: many useful contributions from external users.
- Impressive list of features: mosaics, parallel ensemble capability, experiment database. Equally impressive list of components and options.
- Component list:
  - atmosphere dycore: FV-CS, FV-LL, BGRID, SPECTRAL, ZETAC.
  - atmospheric physics and chemistry: AM2, AM2.1 (HiRAM), AM2.1 (Lin), AM3, simple, dry. **Simple-Chem**
  - ocean: **MOM6**, GOLD, MOM5, MOM4p1, MOM4p0, mixed-layer.
  - land: LAD/LM2, SHE/LM3v, LAD2/LM3, river.
  - ocean BGC: TOPAZ, COBALT, BLING.
  - ice: SIS, **CICE**.

# Gaea



The NOAA Climate Modeling and Research System *Gaea*. Extended in 2013 to include GPU capabilities.

# Gaea and GFDL



FRE and other elements in the GFDL modeling environment manage the complex scheduling of jobs across a distributed computing resource.



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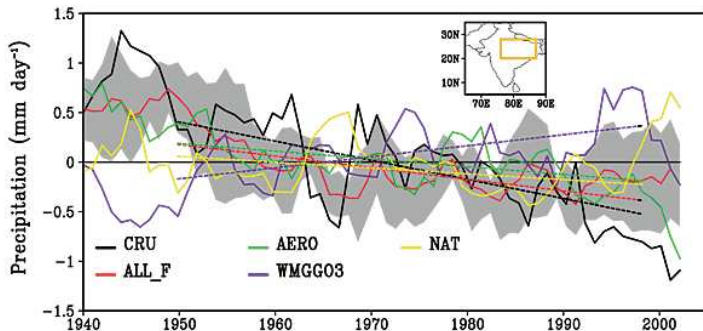
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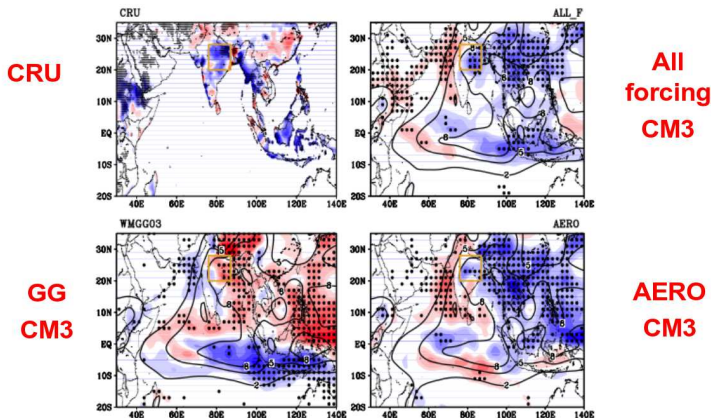
## 5 Summary

# Aerosol indirect effects weaken South Asian monsoon



Cloud-aerosol feedbacks induce a weakening of the Indian monsoon (Figure courtesy Bollasina et al., **Science** 2011).

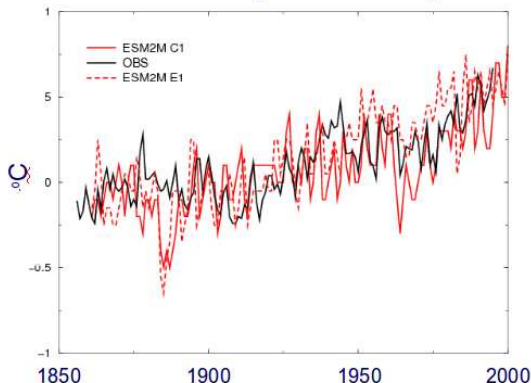
# Aerosol indirect effects weaken South Asian monsoon: summer monsoon spatial pattern



Cloud-aerosol feedbacks induce a weakening of the Indian monsoon (Figure courtesy Bollasina et al., **Science** 2011).

# ESM2M: free-running carbon cycle

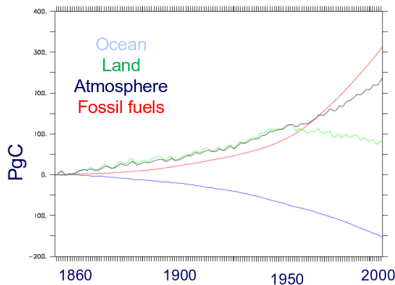
## Surface Air Temperature Response



Free-running carbon cycle in ESM2M. Emissions-driven runs comparable to concentration driven runs (and to observations.) Figure courtesy Ron Stouffer, NOAA/GFDL; **pre-publication**.

# Carbon sources and sinks

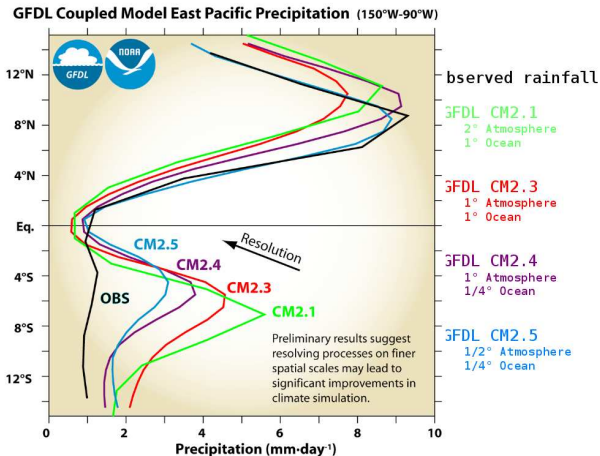
Cumulative Carbon Release into Atmosphere



- Land carbon fluxes dominant before 1960; then trend changes sign.
- Fossil fuels dominant contemporary source.
- Ocean uptake scales with  $p\text{CO}_2$ .

Figure courtesy Ron Stouffer, NOAA/GFDL; pre-publication.

# Resolution as a cure for key model biases



The “double-ITCZ problem” appears to be improved by adding resolution (Figure courtesy Gabe Vecchi, NOAA/GFDL).

# Annual mean SST bias in CM2.5 control

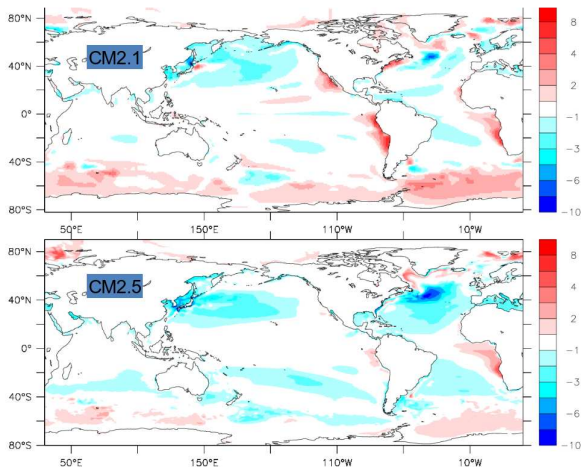
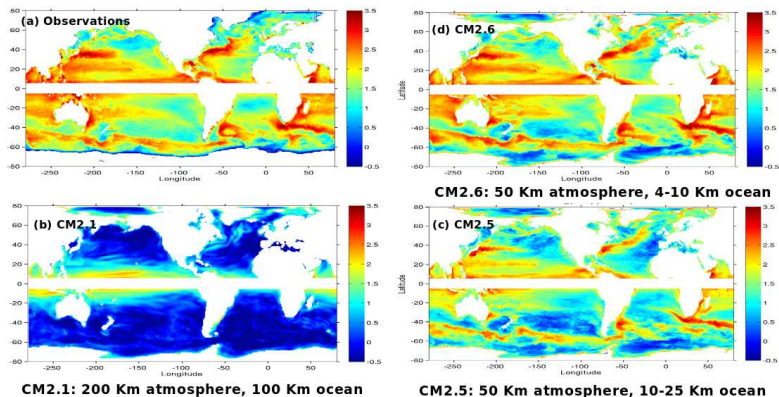


Figure courtesy Delworth et al (2012).

# Ocean Eddy Kinetic Energy in CM2.5 and CM2.6



EKE patterns show marked improvement in the progression toward “eddy-permitting” and “eddy-resolving” ocean models. (Delworth et al 2012).



# Subsurface temperature drift corrected by eddy dynamics

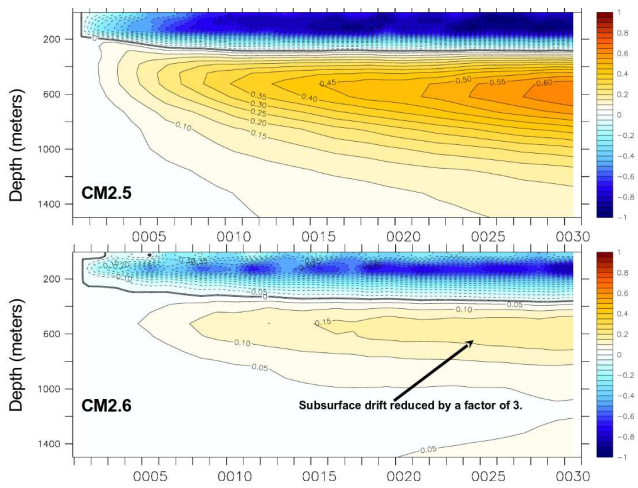
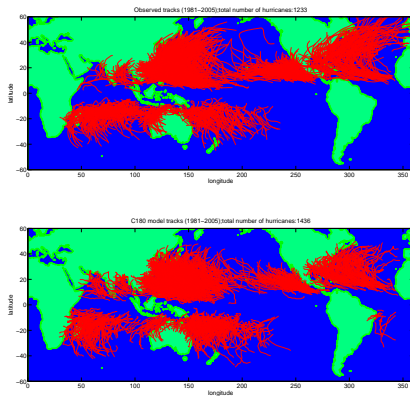


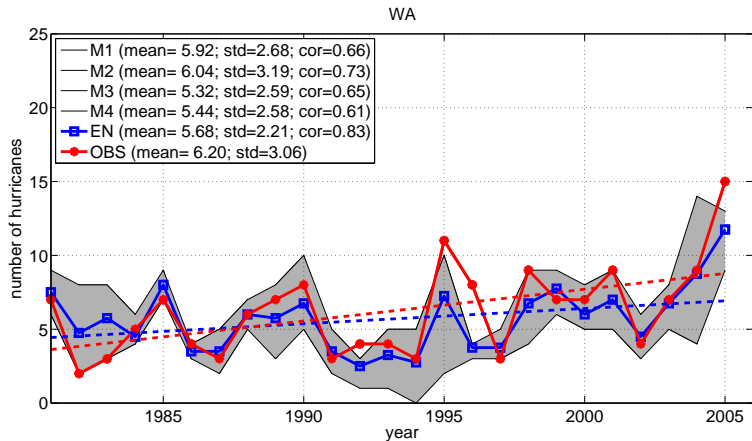
Figure courtesy Delworth et al (2012).

# Hurricane statistics from global high-resolution atmosphere models



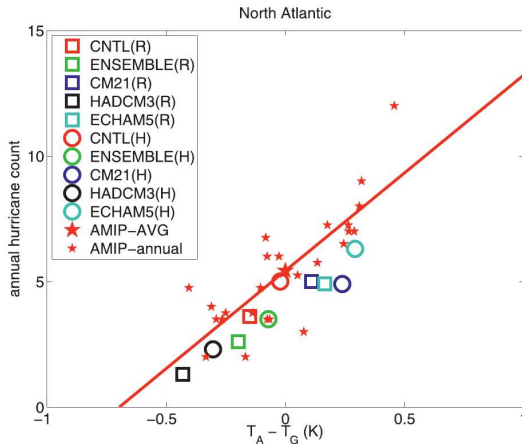
Observed and modeled hurricane tracks from 1981-2005 in a global 50 km (C180) atmospheric model forced by observed SSTs. (Figure courtesy Ming Zhao and Isaac Held, NOAA/GFDL).

# Interannual variability of hurricane frequency



Interannual variability of W. Atlantic hurricane number from 1981-2005 in the C180 runs. (Figure courtesy Ming Zhao and Isaac Held, NOAA/GFDL).

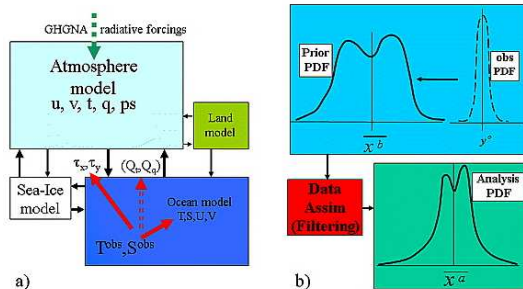
# A simple predictor of hurricane counts?



Difference between Atlantic surface temperature  $T_A$  and mid-tropospheric global temperature  $T_G$  determines hurricane generation rate. From Zhao et al (2009).

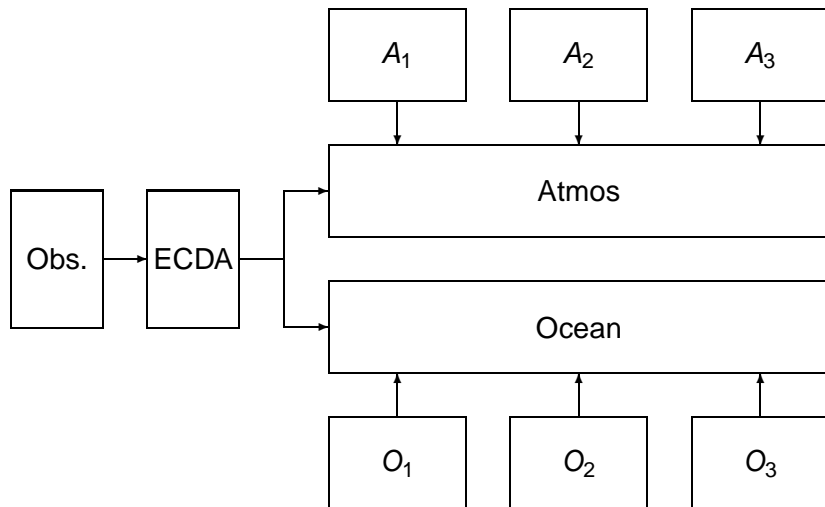
# Data assimilation

Zhang - 2008JC005261



Data assimilation uses ensembles to find likely model trajectory taking into account model error and observational error. (Figure courtesy Zhang et al 2008).

# Ensemble Coupled Data Assimilation (ECDA)



# Model drift in decadal prediction

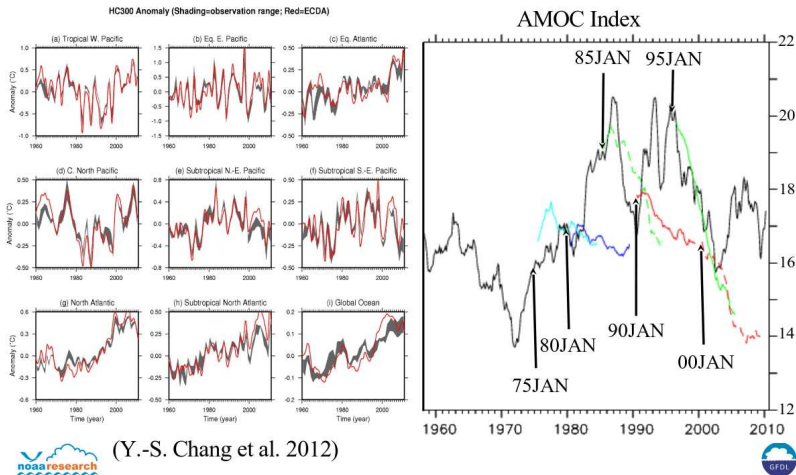
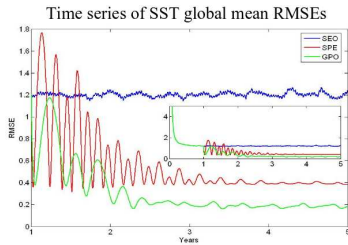


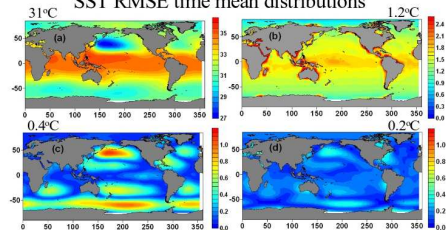
Figure courtesy Shaoqing Zhang and You-Soon Chang, NOAA/GFDL.

# Adapting ECDA for parameter estimation



- Intermediate coupled model with 10 free parameters, all biased.
- SEO: State Estimation Only.
- SPE: Single Parameter Estimation, single-valued.
- GPO: Single Parameter Estimation, geographically dependent parameter optimization.
- Does not deconvolve structural uncertainty from parameter uncertainty.
- Can also be used for multi-parameter optimization (see Wu et al 2012a, 2012b).

SST RMSE time mean distributions





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# The hardware jungle

Upcoming hardware roadmap looks daunting! GPUs, MICs, DSPs, and many other TLAs...

- Intel/AMD x86 **host** coupled to NVIDIA GPU **device**: host launches many (32, 64, ...) parallel threads on device.
- AMD Opteron/Firestream + AMD GPU: similar in structure to above, 64-bit FP registers.
- Firestream + AMD **APU**: integrated on-chip co-processor. Physical memory shared between host and device.
- Intel core + integrated Intel GPU (Ivy Bridge): Intel version of above.
- Intel core + Intel MIC: still a host/device model but threads can be programmed in OpenMP.

# The hardware jungle

More far-fetched stuff . . .

- NVIDIA Denver: ARM processor (low-power) + NVIDIA GPU: shared-memory.
- Texas Instruments! ARM + DSPs
- Convey: x86 + FPGAs. shared virtual memory, permits RMA.
- Tiler, FeiTeng: stream accelerators.
- BG/Q: CPU only, with OpenMP and vector instructions.  
Reportedly 8x faster than P. Memory/core is relatively small.

Some material above adapted from Wolfe (2012), in HPCWire.

# The software zoo

It is unlikely that we will program codes with  $10^6 - 10^9$  MPI ranks: it will be MPI+X. Solve for X . . .

- CUDA and CUDA-Fortran: proprietary for NVIDIA GPUs. Invasive and pervasive.
- OpenCL: proposed standard for MICs that can also be implemented for GPUs.
- ACC from Portland Group: accelerator directives that will be treated as comments on non-compliant hardware. Now being proposed as a new standard OpenACC.
- PGAS languages: Co-Array Fortran, UPC, a host of proprietary languages.

# The software zoo

GFDL is taking a conservative approach:

- it looks like it will be a mix of MPI, threads, and vectors.
- Developing a three-level abstraction for parallelism: **components**, **domains**, **blocks**. Kernels work on blocks and must have vectorizing inner loops.
- **Recommendation: sit tight, make sure MPI+OpenMP works well, offload I/O.**
- Other concerns:
  - Irreproducible computation
  - Tools for analyzing performance.
  - Debugging at scale.

# Can frameworks hold the details of parallelism?

Existing and emerging modeling frameworks already implement distributed data objects.

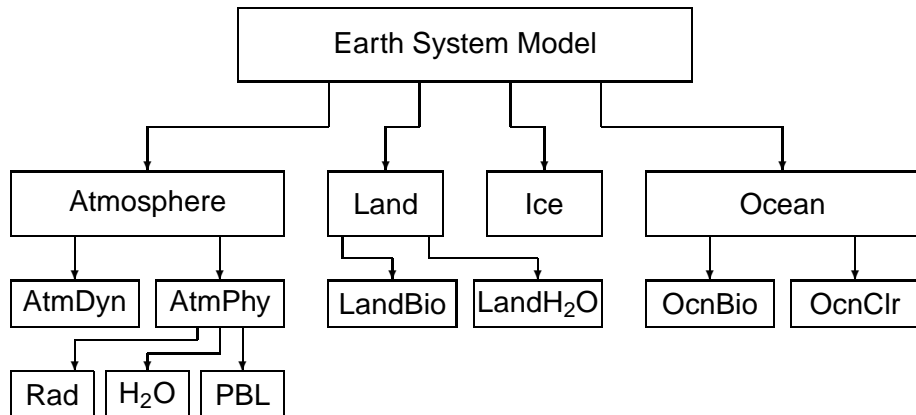
**Distributed array** An `ESMF_Field` holds its distributed contents in an `ESMF_Array`, which already contains metadata describing distribution information (`DataMap`, `Layout`, `VM`). The actual (“naked”) local array can be attached and detached with no data copies.

```
type(ESMF_Field) :: field
real :: a(:, :, :)
a(:, :, :) => ESMF_FieldGetDataPointer(field)
call ESMF_FieldHalo(field)
... = a(i+1, j+1, k) + ...
```

(1)

Some current programming models (e.g CUDA for GPUs) are not amenable to a driver-kernel programming model.

# ESM Architecture



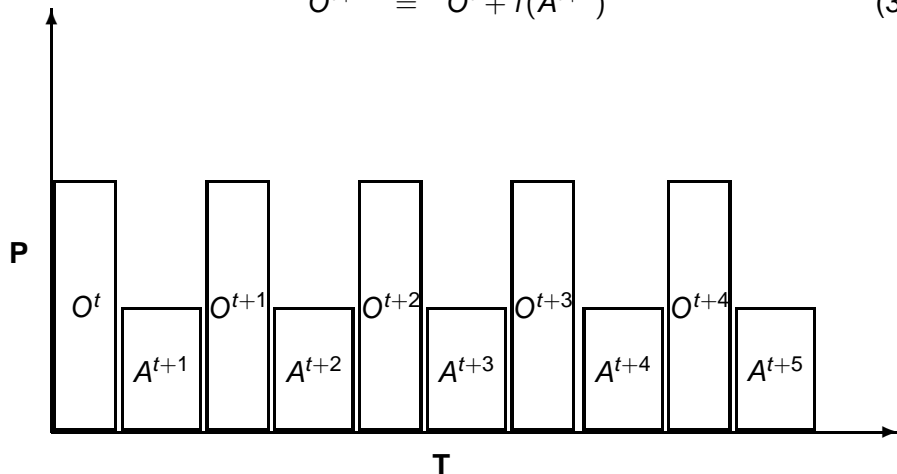
Extending component parallelism to  $\mathcal{O}(10)$  requires a different physical architecture!

# Serial coupling

Uses a forward-backward timestep for coupling.

$$A^{t+1} = A^t + f(O^t) \quad (2)$$

$$O^{t+1} = O^t + f(A^{t+1}) \quad (3)$$



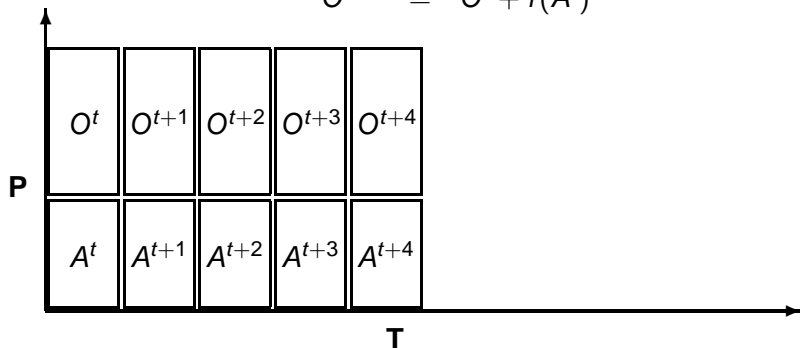


# Concurrent coupling

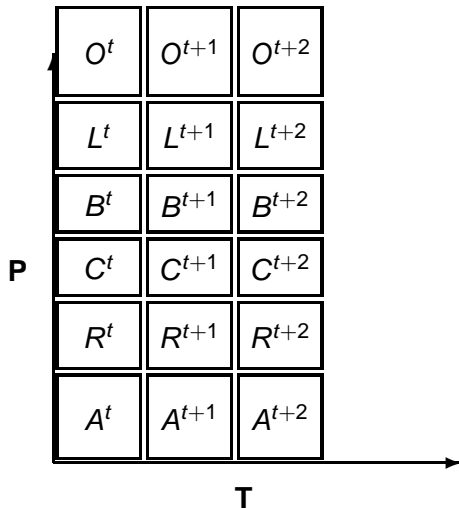
This uses a forward-only timestep for coupling. While formally this is unconditionally unstable, the system is strongly damped\*. Answers vary with respect to serial coupling, as the ocean is now forced by atmospheric state from  $\Delta t$  ago.

$$A^{t+1} = A^t + f(O^t) \quad (4)$$

$$O^{t+1} = O^t + f(A^t) \quad (5)$$

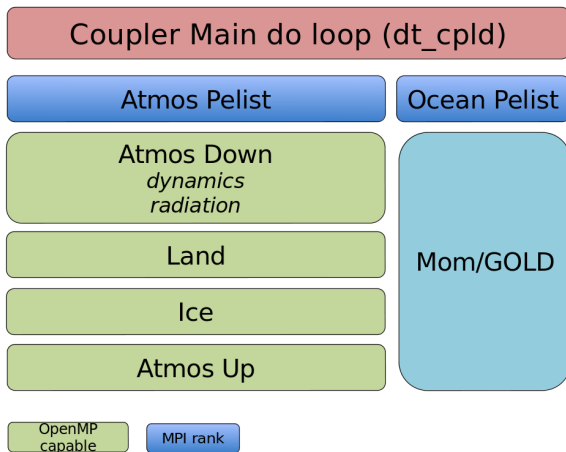


# Massively concurrent coupling



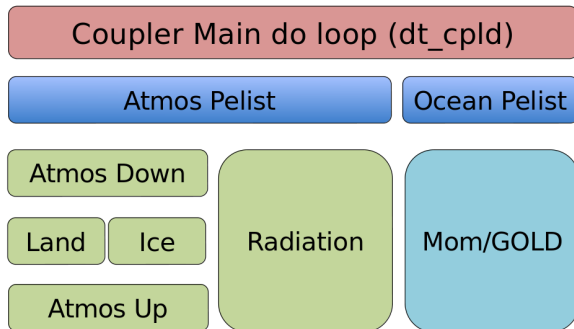
Components such as radiation, PBL, ocean barotropic solver, each could run with its own grid, timestep, decomposition, even hardware. Coupler mediates state exchange.

# Traditional coupling sequence



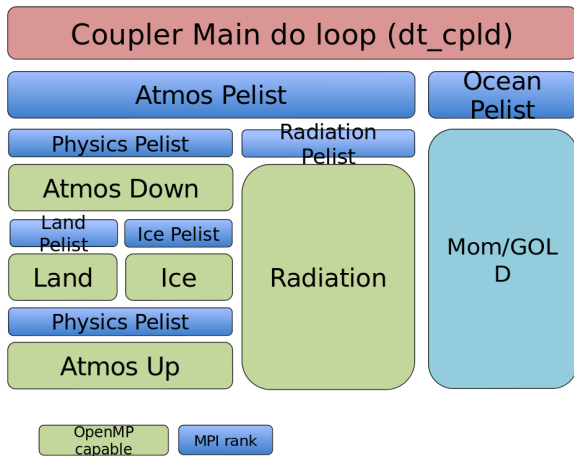
Radiation timestep much longer than physics timestep.  
(Figure courtesy Rusty Benson, NOAA/GFDL).

# Proposed coupling sequence



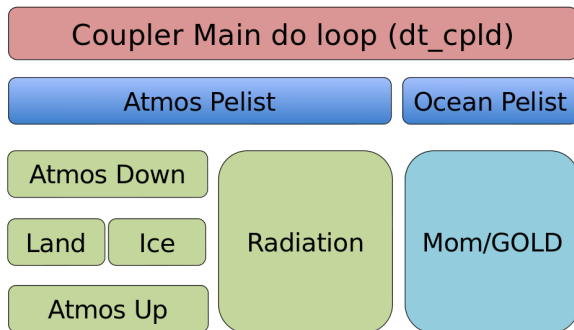
Radiation executes on physics timestep from **lagged** state.  
(Figure courtesy Rusty Benson, NOAA/GFDL).

# Proposed coupling sequence using pelists



Requires MPI communication between physics and radiation.  
(Figure courtesy Rusty Benson, NOAA/GFDL).

# Proposed coupling sequence: hybrid approach

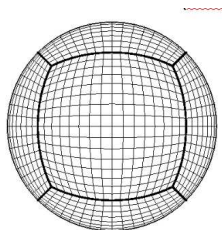


Physics and radiation share memory.  
(Figure courtesy Rusty Benson, NOAA/GFDL).

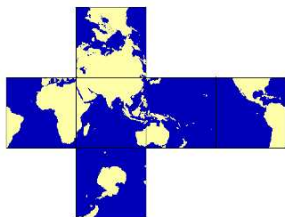
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# Gnomonic Projection



- True equal distance at the 12 edges of the cube
- All coordinate lines are great circles
- Coordinates are continuous at the edges; but derivatives are discontinuous

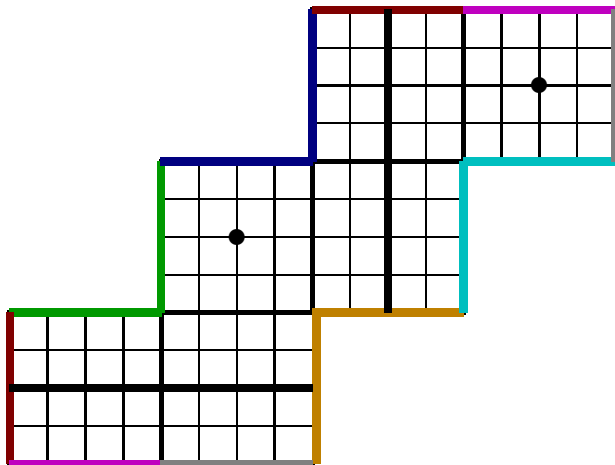


Putman and Lin, *J. Comp. Phys.* 2007.

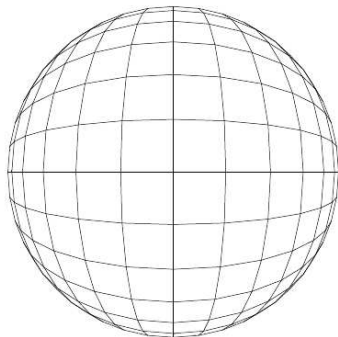
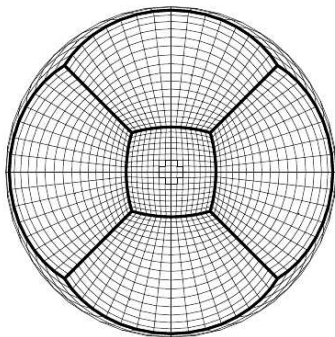


# FMS index space representation of the cubed sphere

- Orientation changes (e.g.  $u \rightarrow -v, v \rightarrow u$ )
- This is a C4 grid (C48  $\sim$  200 km resolution; C2880  $\sim$  3 km resolution)
- Typical pace of a coupled model: 10 y/d at C48; 3 y/d at C180.

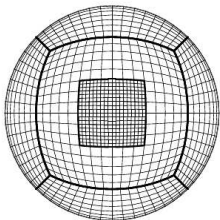


# Stretched grids

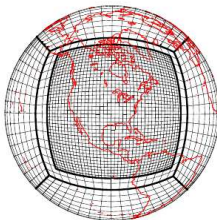


- Opposing face gets very coarse
- Discontinuities in slope
- Scale-aware parameterizations required

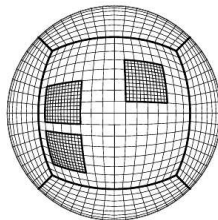
# Nested grids



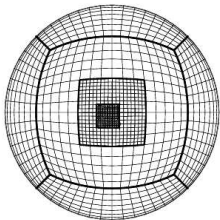
3:1 nested grid



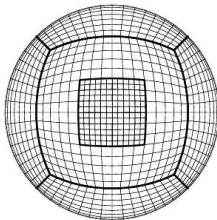
Large nest for RCMs



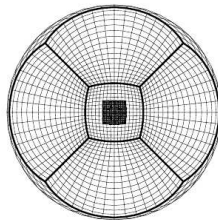
Multiple nests



Telescoping nests



2:1 nested grid



Nest in stretched grid

# Lee vortices off Hawaii under two-way nesting

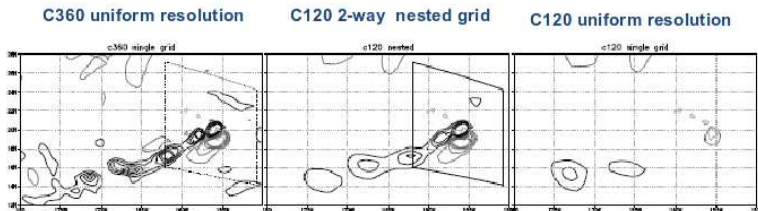
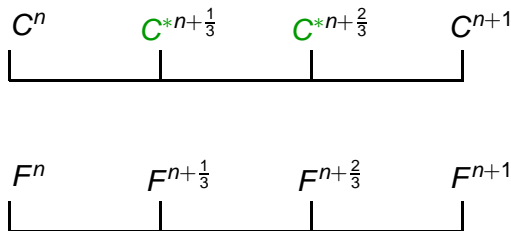


Figure courtesy Harris and Lin 2011, submitted to *Mon. Wea. Rev.*

# Concurrent two-way nesting

Typical nesting protocols force serialization between fine and coarse grid timestepping, since the  $C^*$  are estimated by interpolating between  $C^n$  and  $C^{n+1}$ .



We enable concurrency by instead estimating the  $C^*$  by **extrapolation** from  $C^{n-1}$  and  $C^n$ , with an overhead of less than 10%. (See Harris and Lin 2012 for details.)

# C2560: 3.5 km resolution global cloud-resolving model

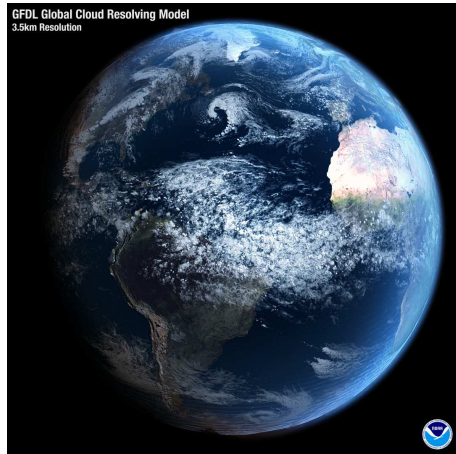
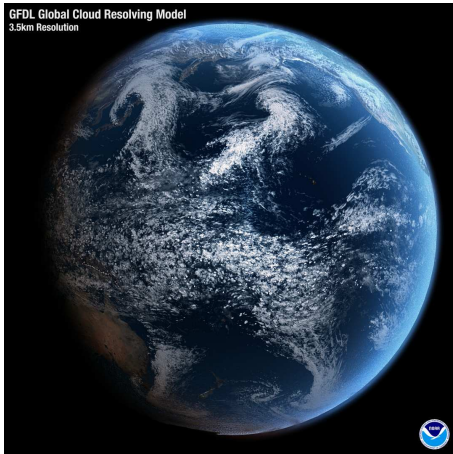


Figure courtesy S-J Lin and Chris Kerr, NOAA/GFDL.

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- GFDL Strategic Plan: process studies; development of comprehensive models; climate extremes; experimental prediction; downstream science.
- Experimental seasonal to decadal prediction, including high-resolution fully coupled ensemble Kalman filter for data assimilation
- Continued development of extremely high-resolution atmosphere models using state of the art dynamical core
- Unification of ocean model development through MOM5 and MOM6 (incorporates capabilities from GOLD model into MOM, incorporates results of Climate Process Teams)
- Development of next generation climate model(s) CM4: convergence of multiple model branches into a few “trunk” models, through a Model Development Team led by Isaac Held.
- Increased integration of NOAA modeling across climate research and extended-range forecasting.



# Challenges for the next generation of models

- Can we have high-level programming models or frameworks to take advantages of new approaches to parallelism? What are the right abstractions?
- Can component-level parallelism via framework **superstructure** be pushed to  $\mathcal{O}(10)$ ?
- Can we approach models as experimental **biological** systems? (single organism or “**cell line**” not exactly reproducible; only the ensemble is.)
- How do we analyze and understand performance on a “sea of functional units” (Kathy Yelick’s phrase)?