

Assigment 1 Report

Exercise 1

Ring

I have implemented an MPI program in C with $2P$ messages passing among P processes on a ring topology with periodic boundaries.

The program implements a stream of messages of $4B$ each, both clockwise and anticlockwise: each process in fact send/receive messages of **type int** (the *rank*) with a tag proportional to the rank ($tag = rank * 10$).

When running on P process, the program prints out in folder `./out` a file `'npP.txt'` with the following output ordered by rank (here $P = 5$):

```
I am process 0 and I have received 5 messages. My final messages have tag 0 and value msg-left -10, msg-right 10
I am process 1 and I have received 5 messages. My final messages have tag 10 and value msg-left -10, msg-right 10
I am process 2 and I have received 5 messages. My final messages have tag 20 and value msg-left -10, msg-right 10
I am process 3 and I have received 5 messages. My final messages have tag 30 and value msg-left -10, msg-right 10
I am process 4 and I have received 5 messages. My final messages have tag 40 and value msg-left -10, msg-right 10
```

I have used the following routines for message passing among processes:

- **MPI_Isend: non-blocking send** routine
- **MPI_Irecv: non-blocking receive** routine
- **MPI_Wait:** waits for a non-blocking operation to complete

Using latest version of OpenMPI available on ORFEO (openmpi-4.1.1+gnu-9.3.0), I have run the program up to $P = 24$ processes on a **thin node with InfiniBand network and native protocol**.

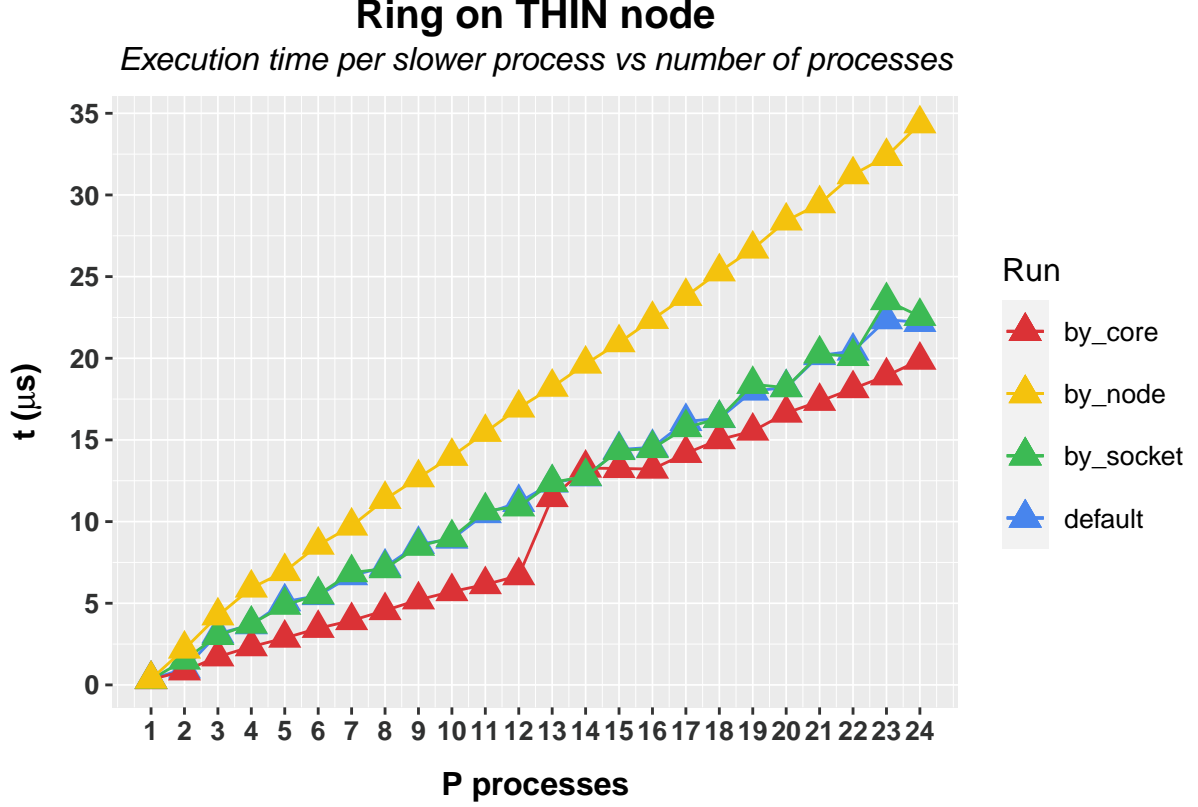
I have taken notes of the runtime (from the first send/receive to the last) when varying the number of processes P by means of the routine `MPI_Wtime()` which returns an elapsed time on the calling process in seconds.

At each run with P processes, for each process I have taken the mean of the **runtime in microseconds** out of **10000** iterations and print it out (along with some statistics) by ranking order on the file `'npP.csv'` in folder `./out`, as follows:

Table 1: Results with $P = 5$

rk	P	t_mean	t_xmsg	var	s2	N	dev	s
0	5	7.073931	1.414786	1425.467	1425.496	10000	37.75536	37.75574
1	5	7.072714	1.414543	1423.095	1423.123	10000	37.72393	37.72430
2	5	7.073540	1.414708	1428.383	1428.412	10000	37.79395	37.79433
3	5	7.072797	1.414559	1419.479	1419.507	10000	37.67598	37.67635
4	5	7.074060	1.414812	1430.666	1430.694	10000	37.82414	37.82452

Then, by taking for each run with different P only the **maximum value of t_mean** between all processes as measure of the performance, I was able to produce the following plot, running the program with different mappings:



Because of the routines that I have used in the program, I expect my data to be in compliance with a P double PingPing model.

By means of **IMB-MPI1 PingPing benchmark** it's possible to measure startup Δt and throughput $\frac{X}{\Delta t}$ of single messages of size X that are obstructed by oncoming messages. To achieve this, two processes communicate with each other using `MPI_Isend`/`MPI_Recv`/`MPI_Wait` calls, just like in my program, as follows:

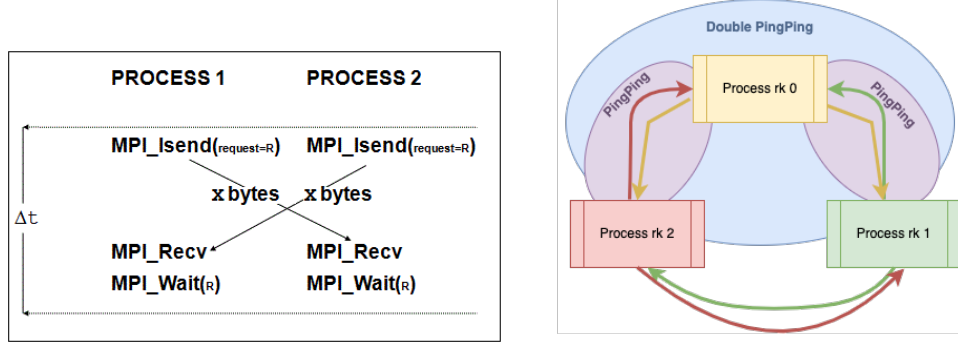


Figure 1: Fig.1 PingPing Pattern from Intel® MPI Benchmarks User Guide and Ring with $P=3$.

With IMB-MPI1 PingPing benchmark I was able to estimate the latency λ_{net} and bandwidth b_{net} on Infiniband network with different processes mappings: across nodes, sockets and cores. Since my t_{mean} is a measure of time in μs of a pair of opposite messages passing through all P process till returning back to the original one, $t_{xmsg} = \frac{t_{mean}}{P}$ is the variable accounting for half of the Δt time measured from the PingPing benchmark results.

Thus, by taking the inverse of the previous relation $t_{mean} = t_{xmsg}P$, our theoretical model will be $t_{theo} =$

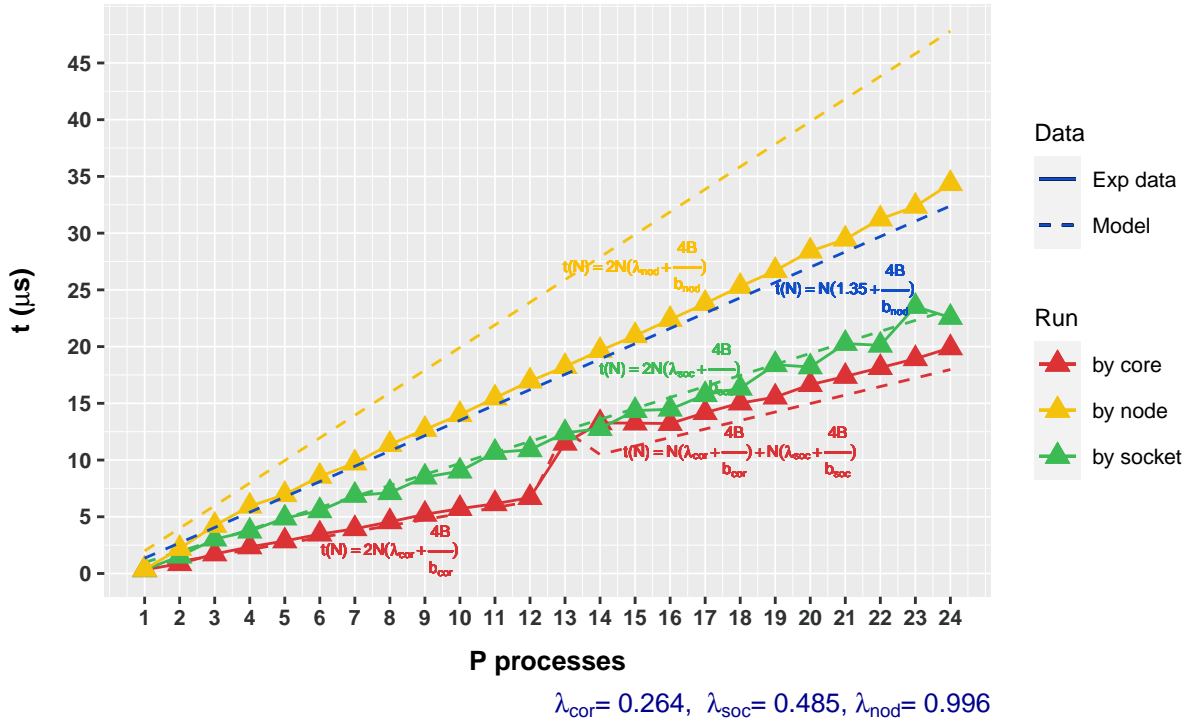
$2\Delta t_{ping}P$, where $\Delta t_{ping} = \lambda_{ping} + \frac{4B}{b_{ping}}$ with λ_{ping} and b_{ping} estimated by least square method on the PingPing benchmark results.

Hence, the following communication model has been used for plotting my data with the PingPing model:

- $t(P) = 2P(\lambda_{core} + \frac{4B}{b_{core}})$ for **core mapping when $P \leq 12$** .
- $t(P) = 2P(\lambda_{socket} + \frac{4B}{b_{socket}})$ for **core mapping when $P = 13$** , assuming that the process chosen as representative of my running is the one with the maximum value of t_{mean} , hence the one which is in the other socket farther from the others 12 cores.
- $t(P) = P(\lambda_{core} + \frac{4B}{b_{core}}) + P(\lambda_{socket} + \frac{4B}{b_{socket}})$ for **core mapping when $P > 13$** , assuming again that the slower process is the one communicating with the previous core which is in the other socket, and the next core which is inside its socket.
- $t(P) = 2P(\lambda_{socket} + \frac{4B}{b_{socket}})$ for **socket mapping**.
- $t(P) = 2P(\lambda_{core} + \frac{4B}{b_{core}})$ for **node mapping**.

Ring comparison with PingPing model of 4B message

Execution time vs number of processes



Oss. The estimated bandwidths of the network for the different mappings are:

- $b_{core} = 6372.991$ MB/s
- $b_{socket} = 5530.801$ MB/s
- $b_{node} = 11945.604$ MB/s

As expected, the measured bandwidth for the 100 Gbit InfiniBand network (process message passing among nodes) reaches up to approximately 12000 MB/s (= 12 GB/s = 12 * 8 Gbit/s = 96 Gbit/s) which is 96% of the theoretical peak performance. Anyway this term in the model can easily be omitted since it's in the order of 10^{-10} .

The estimated latency between two nodes λ_{node} with the PingPing benchmark is somewhat less than the one declared by Mellanox switch constructor ($1.35 \mu s$) used in InfiniBand network: this fact seems to hold when few processes are communicating.

I was indeed expecting that the theoretical performance (evaluated by PingPing benchmark among just

2 process) would have been better than the real scenario when all cores/sockets in nodes are being used simultaneously, and in fact as can be seen from the previous plot, **my model seems to work good for core and socket mapping**, but quite bad for node mapping.

Data from node mapping seem to follow another model that is half the expected one: $t(P) = P(\lambda_{mlx5} + \frac{4B}{b_{node}})$, where $\lambda_{mlx5} = 1.35$ is the latency of the Mellanox switch indeed. This may suggest that the *switch is able to send simultaneously 2 messages of 4B in each direction of the network, halving the time for message passing* between processes placed in different nodes.

Exercise 2

Measure MPI point to point performance

The **Intel MPI IMB-MPI1 benchmark PingPong** has been used to estimate latency λ_{net} and bandwidth b_{net} of all available combinations of topologies and networks on ORFEO computational nodes, using both *IntelMPI* and *openmpi* latest versions libraries availables.

Let's start by looking at ORFEO computational nodes and resources:

```
[valinsogna@login 2021Assignment01]$ pbsnodes -ajS
```

vnode	state	njobs	run	susp	mem f/t	ncpus f/t	nmics f/t	ngpus f/t	jobs
ct1pf-fnode001	job-busy	1	1	0	560gb/1tb	0/36	0/0	0/0	56793
ct1pf-fnode002	free	1	1	0	1tb/1tb	12/36	0/0	0/0	55267
ct1pt-tnode001	job-busy	1	1	0	54gb/754gb	0/24	0/0	0/0	56845
ct1pt-tnode002	job-busy	1	1	0	54gb/754gb	0/24	0/0	0/0	56846
ct1pt-tnode004	job-busy	1	1	0	54gb/754gb	0/24	0/0	0/0	56847
ct1pt-tnode005	job-busy	1	1	0	54gb/754gb	0/24	0/0	0/0	56794
ct1pt-tnode006	free	0	0	0	754gb/754gb	24/24	0/0	0/0	--
ct1pt-tnode007	job-busy	1	1	0	54gb/754gb	0/24	0/0	0/0	56795
ct1pt-tnode008	job-busy	1	1	0	54gb/754gb	0/24	0/0	0/0	56848
ct1pt-tnode009	job-busy	1	1	0	754gb/754gb	0/24	0/0	0/0	57073
ct1pt-tnode010	job-busy	1	1	0	754gb/754gb	0/24	0/0	0/0	57073
ct1pt-tnode003	offline	0	0	0	754gb/754gb	24/24	0/0	0/0	--
ct1pg-gnode001	free	1	1	0	252gb/252gb	44/48	0/0	0/0	57057
ct1pg-gnode002	free	1	1	0	252gb/252gb	24/48	0/0	0/0	56354
ct1pg-gnode003	free	1	1	0	252gb/252gb	24/48	0/0	0/0	56862
ct1pg-gnode004	free	0	0	0	252gb/252gb	48/48	0/0	0/0	--

On ORFEO there are:

- 2 fat nodes: with 2 CPUs (2 NUMA domains) of 18 cores each, with more than 1 TB of RAM.
- 4 gpu nodes: with hyper-threading enabled, with 2 CPUs (2 NUMA domains) of 12 physical cores each with more than 252 GB of RAM.
- 10 thin nodes: with 2 CPUs (2 NUMA domains) of 12 cores each, with more than 754 GB of RAM.
- login node: with 2 CPUs (2 NUMA domains) of 10 cores each.

The MPI point to point performance has been measured only on thin and gpu nodes.

Topology of tested nodes

Now we can look at the node topologies for the thin and gpu ones. This can be either done by typing on the selected node `module load likwid` and then `likwid-topology` or using `module load hwloc` and `lstopo`. The figure below represents the `lstopo` output on a thin node, which is more or less the same for the gpu node.

The main differences between a gpu and a thin node are the hyper-threading enabled on the previous, the different RAM size and the different CPUs models:

- Intel(R) Xeon(R) Gold 6226 CPU @ **2.70GHz** for gpu node
- Intel(R) Xeon(R) Gold 6126 CPU @ **2.60GHz** for thin node

As can be seen by typing `lscpu`:

```
[valinsogna@ct1pt-tnode008 ~]$ lscpu
Architecture:          x86_64
CPU op-mode(s):        32-bit, 64-bit
Byte Order:            Little Endian
```

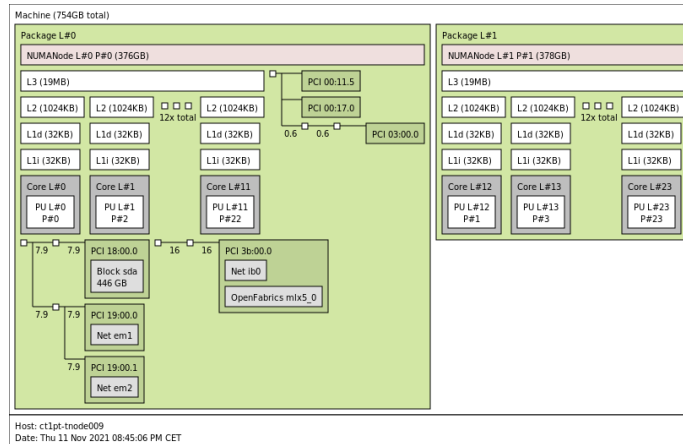


Figure 2: Fig.2 Topology on thin node

```
CPU(s): 24
On-line CPU(s) list: 0-23
Thread(s) per core: 1
Core(s) per socket: 12
Socket(s): 2
NUMA node(s): 2
Vendor ID: GenuineIntel
CPU family: 6
Model: 85
Model name: Intel(R) Xeon(R) Gold 6126 CPU @ 2.60GHz
Stepping: 4
CPU MHz: 3299.999
CPU max MHz: 3700.0000
CPU min MHz: 1000.0000
BogoMIPS: 5200.00
L1d cache: 32K
L1i cache: 32K
L2 cache: 1024K
L3 cache: 19712K
NUMA node0 CPU(s): 0,2,4,6,8,10,12,14,16,18,20,22
NUMA node1 CPU(s): 1,3,5,7,9,11,13,15,17,19,21,23
```

```
[valinsogna@ct1pg-gnode001 ~]$ lscpu
Architecture: x86_64
CPU op-mode(s): 32-bit, 64-bit
Byte Order: Little Endian
CPU(s): 48
On-line CPU(s) list: 0-47
Thread(s) per core: 2
Core(s) per socket: 12
Socket(s): 2
NUMA node(s): 2
Vendor ID: GenuineIntel
CPU family: 6
Model: 85
Model name: Intel(R) Xeon(R) Gold 6226 CPU @ 2.70GHz
Stepping: 7
CPU MHz: 3499.999
CPU max MHz: 3700.0000
CPU min MHz: 1200.0000
BogoMIPS: 5400.00
Virtualization: VT-x
L1d cache: 32K
L1i cache: 32K
L2 cache: 1024K
L3 cache: 19712K
NUMA node0 CPU(s): 0,2,4,6,8,10,12,14,16,18,20,22,24,26,28,30,32,34,36,38,40,42,44,46
NUMA node1 CPU(s): 1,3,5,7,9,11,13,15,17,19,21,23,25,27,29,31,33,35,37,39,41,43,45,47
```

Networks and protocols used

- High Speed Network **100 Gbit InfiniBand**: with $peak\ perf_{theo}$ of 100 Gbit/s = 12.5 GB/s = **12500 MB/s**; eq. (1)
- In band management network **25 Gbit Ethernet**: with $peak\ perf_{theo}$ of 25 Gbit/s = 3.125 GB/s = **3125 MB/s**; eq. (2)

The main differences among these two are the usage of Sockets Interface and TCP/IP protocol for the Ethernet network, and the usage of much more rapid OpenFabrics Verbs (no Kernel stack) with the native IB protocol for InfiniBand network. Moreover, IB protocol has RDMA (Remote Direct Memory Access) that makes InfiniBand faster: it is an operation which access the memory directly without involving the CPU. We thus, expect InfiniBand network with native IB protocol to be much faster (low λ_{net} , high b_{net}) then the Ethernet network. Moreover, I am going to test also InfiniBand network performance when applying plain IP protocol: **IPoIB (IP-over-InfiniBand) is the protocol that defines how to send IP packets over IB**, passing through the Kernel space.

As can be seen from Fig.2, the network cards are placed in each node only inside one of the two NUMA domains, and there are several PCI (Peripheral Component Interconnect) devices that can be seen by typing `ifconfig`:

```
[valinsogna@ctipt-tnode007 ~]$ ifconfig
bond0: flags=5187<UP,BROADCAST,RUNNING,MASTER,MULTICAST> mtu 1500
    inet6 fe80::3680:dff:fe4e:5568 prefixlen 64 scopeid 0x20<link>
    ether 34:80:0d:4e:55:68 txqueuelen 1000 (Ethernet)

br0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 10.128.2.127 netmask 255.255.255.0 broadcast 10.128.2.255
    inet6 fe80::3680:dff:fe4e:5568 prefixlen 64 scopeid 0x20<link>
    ether 34:80:0d:4e:55:68 txqueuelen 1000 (Ethernet)

em1, em2 two physical cards that we have on the node
em1: flags=6211<UP,BROADCAST,RUNNING,SLAVE,MULTICAST> mtu 1500
    ether 34:80:0d:4e:55:68 txqueuelen 1000 (Ethernet)

em2: flags=6211<UP,BROADCAST,RUNNING,SLAVE,MULTICAST> mtu 1500
    ether 34:80:0d:4e:55:68 txqueuelen 1000 (Ethernet)

ib0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 2044
    inet 10.128.6.127 netmask 255.255.255.0 broadcast 10.128.6.255
    inet6 fe80::ba59:9f03:d4:27d6 prefixlen 64 scopeid 0x20<link>
Infiniband hardware address can be incorrect! Please read BUGS section in ifconfig(8).
    infiniband 00:00:09:07:FE:80:00:00:00:00:00:00:00:00:00:00:00:00 txqueuelen 256 (InfiniBand)

lo: flags=73<UP,LOOPBACK,RUNNING> mtu 65536
    inet 127.0.0.1 netmask 255.0.0.0
    inet6 ::1 prefixlen 128 scopeid 0x10<host>
    loop txqueuelen 1000 (Local Loopback)
```

As from above, **em1, em2** are two physical distinguished Ethernet cards that refers to one interface **br0**, whilst **ib0** is **InfiniBand**. More details are shown below with `lstopo`:

```
[valinsogna@ctipt-tnode007 ~]$ lstopo
Machine (754GB total)
  Package L#0
    NUMANode L#0 (P#0 376GB)
      L3 L#0 (19MB)
        L2 L#0 (1024KB) + L1d L#0 (32KB) + L1i L#0 (32KB) + Core L#0 + PU L#0 (P#0)
        L2 L#1 (1024KB) + L1d L#1 (32KB) + L1i L#1 (32KB) + Core L#1 + PU L#1 (P#2)
        ...
      HostBridge
        PCI 00:11.5 (SATA)
        PCI 00:17.0 (SATA)
        PCIBridge
          PCIBridge
            PCI 03:00.0 (VGA)
      HostBridge
        PCIBridge
          PCI 18:00.0 (RAID)
            Block(Disk) "sda"
        PCIBridge
          PCI 19:00.0 (Ethernet)
            Net "em1"
          PCI 19:00.1 (Ethernet)
            Net "em2"
```

```

HostBridge
PCIBridge
  PCI 3b:00.0 (InfiniBand)
    Net "ib0"
    OpenFabrics "mlx5_0"

```

With openMPI implementation and UCX, it's possible to directly select the devices (using UCX_NET_DEVICES specification in the run command), that lead to a specific protocol as consequence. **The devices tested with openMPI across nodes are:**

- **ib0:** IPoIB protocol.
- **br0:** TCP communication, Ethernet.
- **mlx5_0:1:** native IB protocol.

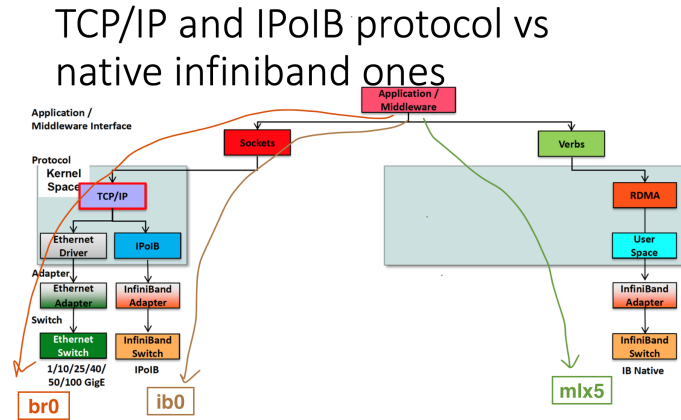


Figure 3: TCP/IP, IPoIB and native IB protocols

IMB-MPI1 Benchmark PingPong

Intel MPI benchmark IMB-MPI1 PingPong measure message passing between two processes and works as follow:

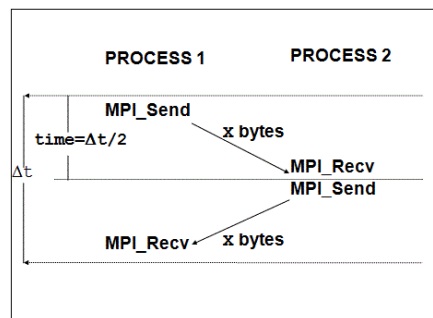


Figure 4: PingPong Pattern from Intel® MPI Benchmarks User Guide

It reports the time $\Delta t/2$ (in μs), throughput $\frac{2X}{\Delta t}$ (in MB/s), number of repetitions and the message size X (in B) in the standard output:

```

#-----
# Benchmarking PingPong
# #processes = 2
#-----
#bytes #repetitions    t[usec]    Mbytes/sec
0,      1000,         0.20,         0.00
1,      1000,         0.21,         4.90

```

2,	1000,	0.20,	10.07
4,	1000,	0.22,	20.26
8,	1000,	0.24,	40.59

Measurements

The bandwidth and the latency estimation for gpu and thin nodes is done across cores, sockets and nodes, with different protocols, PCI devices and libraries.

The nodes involved are:

- ct1pt-tnode007, thin node for results across cores, sockets and nodes.
- ct1pt-tnode008, thin node for results across nodes.
- ct1pg-gnode001, gpu node for results across cores, sockets and nodes.
- ct1pg-gnode003, gpu node for results across nodes.

Each specific run is repeated 10 times with `-msglog 28` and each time for the thin ones the entire node was reserved in order to reduce noise in measurements, **instead for the gpu nodes it wasn't possible due to some queue traffic**. Thus, from the measurements, it was taken the mean time $\Delta t/2$ and the mean throughput $2X/\Delta t$ between the 10 results for each message size X , along with some statistics (ex. maximum error on time and on throughput $e = \frac{t_{max}-t_{min}}{2}$).

The PingPong benchmark is compiled on either the thin or gpu node using two different libraries:

- **OpenMPI**: version **openmpi-4.0.3** for the running across nodes with `UCX_NET_DEVICES` specification and latest **openmpi-4.1.1** for the others.
- **Intel MPI**: version `intel` available on ORFEO.

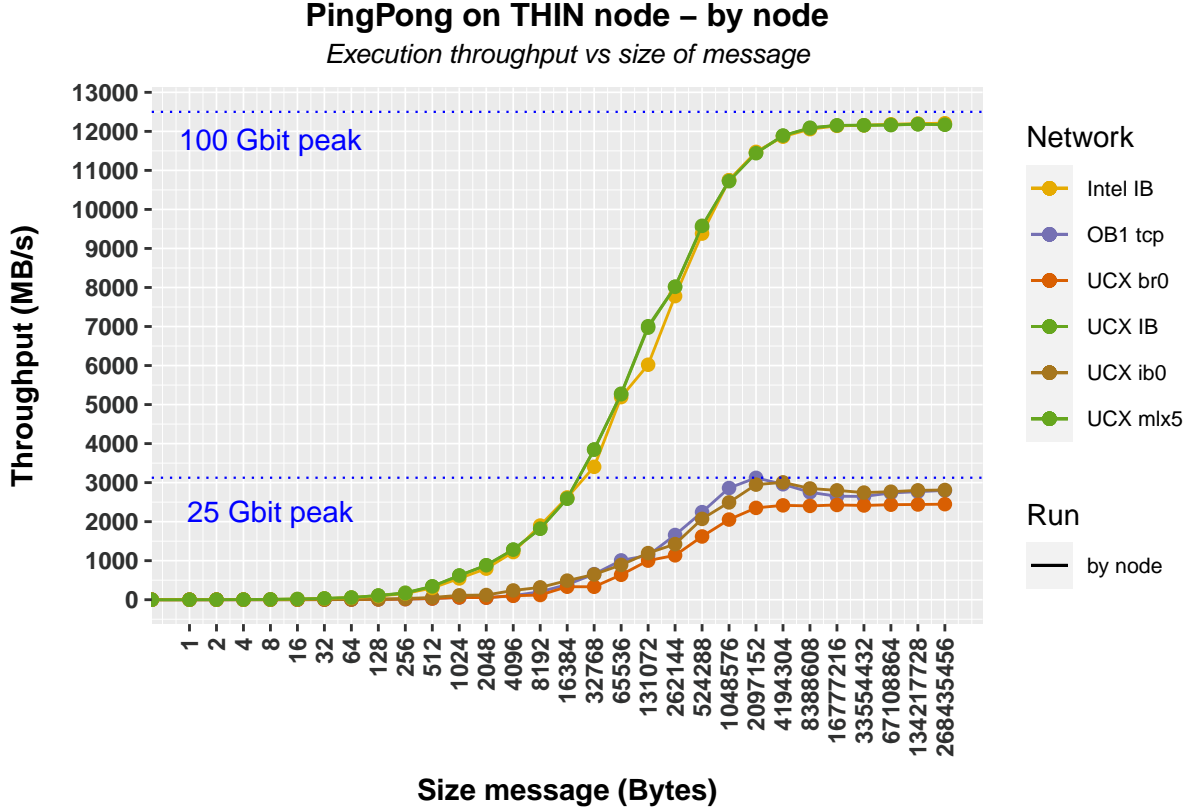
With **OpenMPI** implementation it is possible to specify the MPI frameworks and plugins (like pml and btl) that can be used while running. Across nodes, cores and sockets the following has been tested:

- *PML* : **ob1** and **ucx**.
- *BTL* : **tcp**, **self** and **vader**.

The following graphs show the results both for thin and gpu nodes from plotting the benchmark throuput $2X/\Delta t$ against the message size X with different mappings of the processes: across two different nodes for the first plot and across two sockets or in the same socket for the latter.

Along with the results of 'across nodes' mapping, there has been drawn the lines for the 100 Gbit InfiniBand and 25 Gbit Ethernet, in order to compare the theoretical peak performances with the tested ones.

Moreover, in the plot 'by socket/core' mapping, cache size lines have been drawn too in order to discuss about a general behavior.



From this first plot it is evident that **with Intel MPI, UCX OpenMPI InfiniBand** (the default command) **and UCX native IB with mlx5_0:1 device** (which is the same as the previous), **the asymptotic bandwidth is very high compared to the others protocols/devices and similar to the one expected from the theoretical peak**: more or less my data perform like 97% of the theoretical limit (see eq (2)).

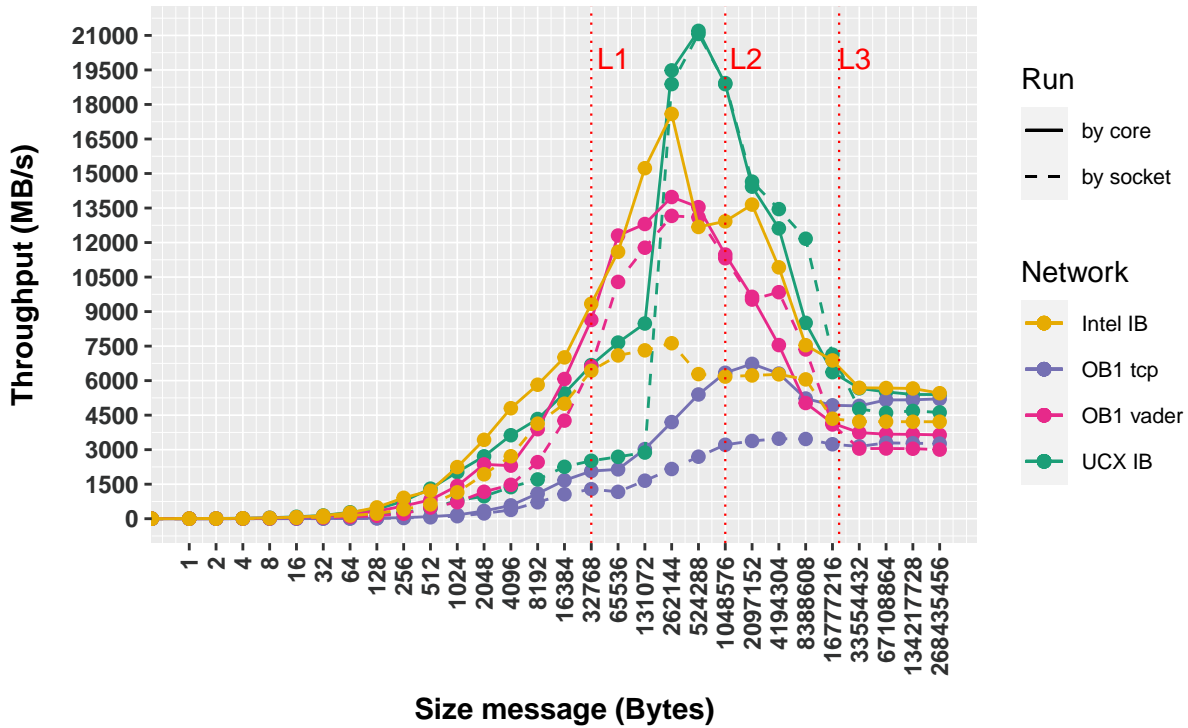
UCX with br0 and OB1 with tcp show a real maximum performance of **about 86%-89% respectively of theoretical bandwidth**: it is a good result if we take into account that tcp protocol is heavier with respect to the native IB one (encoding, no RDMA available). Their latencies are comparable (see table in ‘Results’ section), but OB1 has a higher bandwidth.

IPoIB (aka UCX ib0) happen to have a good latency (see table in ‘Results’ section) but the bandwidth is not so high and in fact it is comparable to the one of the 25 Gbit Ethernet network.

Now let’s look at the performance with the across core and socket configuration.

PingPong on THIN node – by core/socket

Execution throughput vs size of message



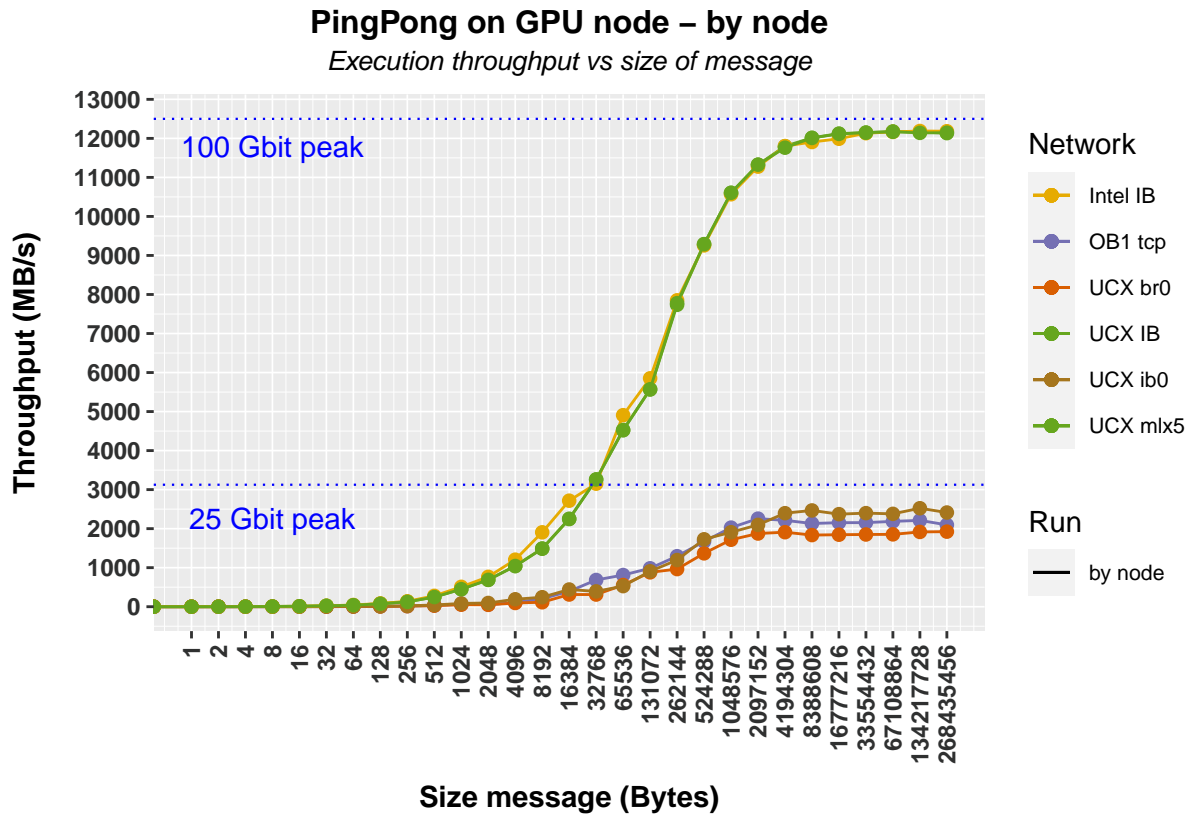
From first glance it is clear that these performance are smaller in bandwidth, but better in latency (see table in 'Report section') when compared to across nodes configuration. Moreover, **mapping the processes in the same socket show often a better performance than mapping them in separate sockets**.

The drop in bandwidth before the asymptotic plateau of throughput is common in both the 2 configurations (by sockets, by nodes) and it shows very different performances among different implementations. **This pattern happens between 32KB and 16 MB included: after that size, measurements become stable.**

By plotting the cache lines it is clear that this behavior **must be related to the cache**: in fact, when the size of the PingPong message becomes too large to fit in **L1**, there's an L1 miss and data are retrieved from cache **L2**. This happens too for L2 as the size grows so there is a visible drop in the throughput. L1 effects is not clearly visible from the bandwidth (probably due the latency), instead for L2 misses after 1 MB, all implementations start losing bandwidth. In the plateau area, instead, the message size is larger than all caches and a stable bandwidth is reached.

Now let's compare protocols. Firstly, **UCX IB shows poor performance before 131 MB** respect to the other protocols and after that size there is an huge increase. **Also Intel InfiniBand, this time shows poor performance respect UCX implementation**, and it might be related to the fact that it undergoes large cache misses. **OB1** implementation seems to be better by usage of *vader* btl rather than *tcp*, as expected since *vader* is suitable for shared memory transfer.

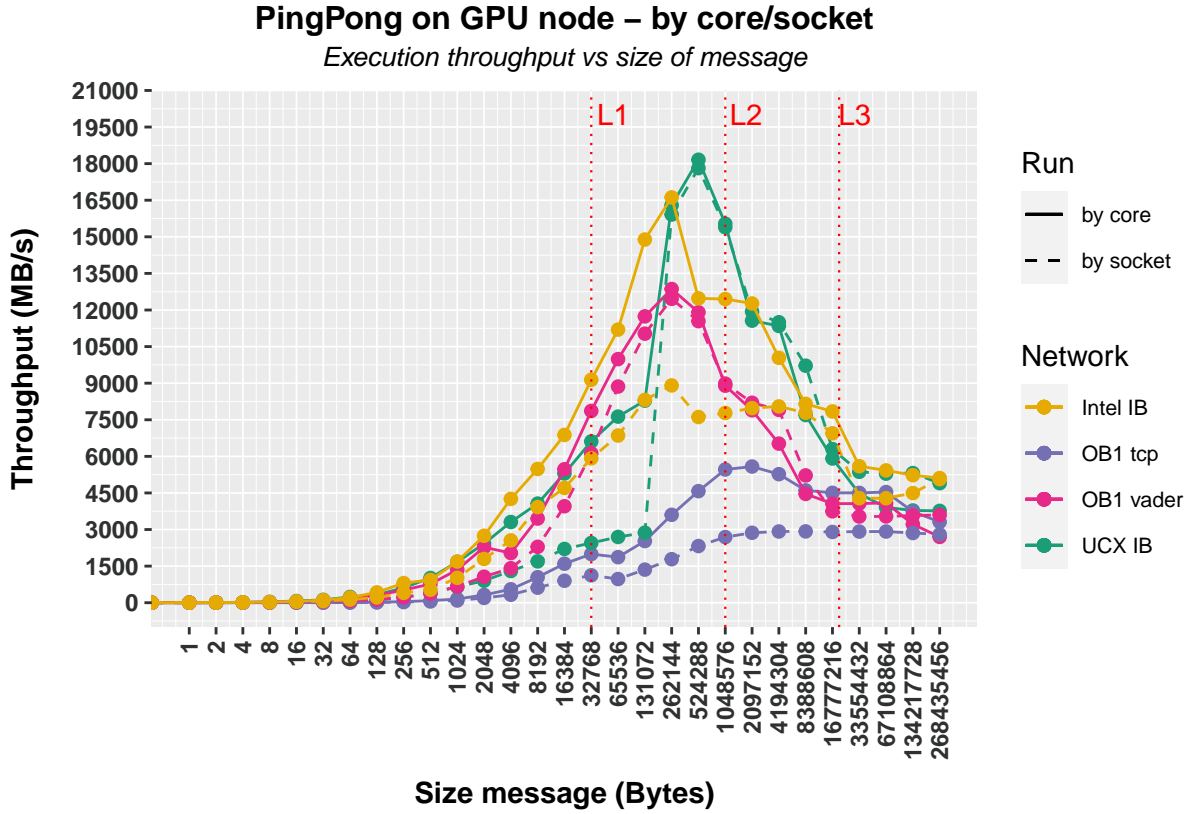
Now let's have a look at the GPU results in terms of throughput.



As can be inferred from the previous plot, Gpu nodes behave like thin node, no major difference pops out, but **GPU node is a bit slower (about 15%)** than thin node, *as already discovered in the exercise 1*.

This can be caused either by the fact that not being able to reverse a whole node (if not 2 in the across node configuration) or, more likely, by the different CPU frequencies and node configurations: remember that even if gpu CPU has a theoretical higher maximum frequency (2.70GHz) with respect to the one of the thin node (2.60GHz), these frequencies are much smaller when running simultaneously on several cores.

Cache size are the same as thin node, then cache effects are similar, as it is shown here:



Results

Here are shown the estimation via least square methods of the latency λ_{net} and bandwidth b_{net} of the networks used. To see the fit model estimation look in the folder *section2/mydata/csv-files/*.

THIN NODE			GPU NODE		
	Latency (us)	Bandwith (MB/s)		Latency (us)	Bandwith (MB/s)
By core			By core		
UCX IB	0,196710	5384,612	UCX IB	0,239114	3760,817
Intel IB	0,234158	5485,757	Intel IB	0,289496	5129,400
OB1 vader	0,276249	3639,492	OB1 vader	0,330979	2801,128
OB1 tcp	5,472147	5196,069	OB1 tcp	5,944020	3400,770
By socket			By socket		
UCX IB	0,414452	4612,174	UCX IB	0,479683	4949,990
Intel IB	0,432647	4208,231	Intel IB	0,474816	4890,206
OB1 vader	0,602071	3000,796	OB1 vader	0,623670	3578,910
OB1 tcp	7,877553	3265,919	OB1 tcp	9,515453	2808,541
By node			By node		
UCX IB	0,981388	12180,267	UCX IB	1,357744	12145,917
Intel IB	1,124170	12210,497	Intel IB	1,287712	12188,889
UCX ib0	10,277036	2764,394	UCX ib0	12,945012	2432,176
OB1 tcp	16,036402	2784,559	OB1 tcp	15,480444	2118,792
UCX br0	15,943306	2433,027	UCX br0	17,777864	1920,804

Figure 5: Latency and bandwith fit estimation

Exercise 3

Jacobi solver

It's a prototype for as stencil-based iterative method used in numerical analysis to solve partial differential equations.

In its most straightforward form, it can be used for solving the diffusion equation for a scalar function $\Phi(r, t)$:

$$\frac{\delta\Phi}{\delta t} = \Delta\Phi$$

on a rectangular lattice subject to Dirichlet boundary conditions. The differential operators are discretized using finite differences:

$$\frac{\delta\Phi(x_i, y_i)}{\delta t} = \frac{\Phi(x_i + 1, y_i) + \Phi(x_i - 1, y_i) - 2\Phi(x_i, y_i)}{\delta x^2} + \frac{\Phi(x_i + 1, y_i + 1) + \Phi(x_i, y_i - 1) - 2\Phi(x_i, y_i)}{\delta y^2}$$

In each time step, a correction $\delta\Phi$ to $\Delta\Phi$ at coordinate (x_i, y_i) is calculated using the “old” values from the four next neighbor points. Of course, the updated Φ values must be written to a second array. After all points have been updated (a “sweep”), the algorithm is repeated till some basic convergence bounded by a threshold ϵ .

The following is a 2D Implementation of the Jacobi algorithm on an $N \times N$ lattice, with a convergence criterion added, taken by G.Hager and G.Wellein “Introduction to high performance computing for scientists and engineers”:

```
double precision, dimension(0:N+1,0:N+1,0:1) :: phi
double precision :: maxdelta,eps
integer :: t0,t1
eps = 1.d-14 ! convergence threshold
t0=0;t1=1
maxdelta = 2.d0*eps
do while(maxdelta.gt.eps)
maxdelta = 0.d0
do k = 1,N
do i = 1,N
phi(i,k,t1) = ( phi(i+1,k,t0) + phi(i-1,k,t0)
+ phi(i,k+1,t0) + phi(i,k-1,t0) ) * 0.25
maxdelta = max(maxdelta,abs(phi(i,k,t1)-phi(i,k,t0)))
enddo
enddo
! swap arrays
i = t0 ; t0=t1 ; t1=i
enddo
```

In a parallel computation, the core of the code implementation is similar but:

- convergence criterion needs to be computed globally (collective reduce operations)
- boundary layers must retrieve info from adjacent subdomains (halo layers exchange) in order to update their values.

For this exercise, we used as **Jacobi solver 3D program given by the professor Cozzini written in FORTRAN**.

Performance model

In order to predict 3D Jacobi model performance P the following model has been used:

$$P(L, N) = \frac{L^3 N}{T_s(L) + T_c(L, N)} \left[\frac{MLUP}{s} \right] \quad (*)$$

where:

- L is the subdomain size, assuming it's a cube..
- $N = N_x N_y N_z$ is the number of the processes involved.
- $L^3 N$ is the problem size. The amount of work, therefore, increase linearly as a function of N ; hence a weak scalability will be considered.
- $MLUP/s$ is the unit for measuring this performance (Mega Lattice Updates Per sec).
- T_s is the time for an entire sweep, thus it can be estimated using the program as serial.
- T_c represent the communication time for total halo exchanges.

The latter is modeled by simply estimating the latency λ , bandwidth b of the network and messages size c .

In a 3D problem, the number of points used to estimate a point of the subdomain is not 4 (5 stencil case) but 6 instead (7 stencil case). When processes communicates whit each other they simultaneously sends each of the 6 point-to-point communication at the same time, so we need to consider full duplex data transfer for bandwidth.

Moreover we assume that the time for copying the halo to/from an intermediate buffer and the communication of a process with itself come at no costs. T_c then can be model as:

$$T_c(L, N) = \frac{c(L)}{b} + k\lambda[s] \quad (**)$$

where:

- $c(L)$ is the amount of data volume transferred over a node's network link.
- b is the bidirectional bandwith of the network link
- λ is the latency
- k is the largest number of coordinate directions in which $N_i > 1$.

Then c is, :

$$c(L) = L^2 k \cdot 2 \cdot 8[B] \quad (***)$$

where:

- k represents the number of directions in which the halo exchange occurs.
- L^2 is the halo surface to transmit.
- 2 is for taking into account the bidirectional halo exchange.
- 8 is for double conversion, assuming that the grid points in the subdomain are double floating points.

Domain decomposition

Since we use a **3D Jacobi FORTRAN program (column-major order)**, there are domains decomposition that are more suitable than others when dealing with contiguous location in memory for halo exchange.

In order to find the best decomposition possible, several tests has been done in order to find the most performing permutation of (N_x, N_y, N_z) .

With $N = 6$ take $(6, 1, 1)$ $(1, 6, 1)$ $(1, 1, 6)$ decompositions when $L = 1200$ on a thin node: experimentally, the first configuration behave better than the other in terms of MLUP/s (oss. use large values of L to see this effect). Example:

Mapping	Nx	Ny	Nx	MLUP/s
core	6	1	1	668
	1	6	1	665
	1	1	6	665
socket	6	1	1	674
	1	6	1	671
	1	1	6	670

Instead when comparing always with $N = 6$, $(6, 1, 1)$ and $(3, 2, 1)$ the first has more buffering cost involved but the latter has more halo exchanges, thus both the two configurations will be taken into account.

Results

As a first step I have tried to compile and run the code on single processor of a thin and gpu node to estimate the serial time on one single core T_s .

I have used OpenMPI implementation on ORFEO both on thin and gpu nodes using native IB protocol.

The size of the subdomain $L = 700$ was fixed and used both for gpu and thin measurements since, due to RAM size on the gpu node (see `pbsnodes -ajS` in Exercise 2), it corresponds to the maximum amount of memory available for comparison between the two different nodes.

The Jacobi program was runned on:

- 4/8/12 processes within the same thin node pinning the MPI processes within the same socket.
- 4/8/12 processes within the same thin node pinning the MPI processes across two sockets.
- 12/24/48 processes using two thin nodes.
- 12/24/48 processes using one gpu node mapping by core (hyperthreading is enabled).
- 12/24/48 processes using one gpu node mapping by socket (hyperthreading is enabled).

The *jacobi3D* program prints out the performance in *MLUP/s* as last column for each run: I have taken the mean of the 10 results. Along with the performance measurements, I took the elapsed time by means of `/usr/bin/time -f "user : %U system: %S elapsed: %e CPU: %P CMD: %C \n"` run command.

The following is an example of running with $L = 700$ and $N = (4, 1, 1)$:

```
# Threadlevel provided: 3 out of 0 1 2 3
  spat_dim , proc_dim, PBC ?
    1 -Dim Input      2800      4 T
    2 -Dim Input       700      1 T
    3 -Dim Input       700      1 T
# 0 Process grid 4 1 1
    0      3      2
    2      3      2
    3      3      2
    1      3      2
# 0 Allocated 2 arrays with a total of 5535.17 Mbytes
# StartResidual 0.00000000000
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06243716300 3.06242734200 2.98796024800 2.99414415400
Residual 12273333.3238 MLUPs 448.009192344
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06078858000 3.06078676400 2.98838307400 2.99486265400
Residual 2041666.66667 MLUPs 448.250496282
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06090752400 3.06090532700 2.98793178100 2.99505510000
Residual 434799.382550 MLUPs 448.233077688
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06095547000 3.06095308700 2.98808474500 2.99490125800
Residual 129179.526716 MLUPs 448.226056683
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06516349800 3.06516215100 2.99001243700 2.99797766000
Residual 52905.8427676 MLUPs 447.610706866
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06256750200 3.06256510400 2.98815335100 2.99561585600
Residual 27258.4295825 MLUPs 447.990125639
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06197104500 3.06196926100 2.98880531000 2.99486067300
Residual 16225.1238619 MLUPs 448.077391927
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06272575000 3.06272477100 2.98845891200 2.99545644500
Residual 10594.4563848 MLUPs 447.966978434
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06178146800 3.06177916200 2.98808213100 2.99487845400
Residual 7372.72712122 MLUPs 448.105135634
4 Maxtime , Mintime + JacobiMi , JacobiMa 3.06086679800 3.06086465500 2.98821124300 2.99498761300
Residual 5375.90215905 MLUPs 448.239041600
```

Even if this model seems accurate, some comments are required: mapping by socket lead a slightly better performance respect core mapping and this is not what expected by theoretical model. If socket map on one hand lead to poor communication performance on other hand exploit better the memory allocation. When one socket is filled with 12 processes the entire grid is stored on socket competence LRDIMM, but spreading processes across 2 socket lead to better exploit of bandwidth using different memory controller and then all memory channel available. This solver at each iteration elaborates an huge amount of memory, given $L = 1200$ and 12 worker at least 300 GB of ram are elaborated (half memory LRDIMM are saturated, then all single socket channel are used). Also with map-by node option experimentally we obtain better results when several processes are involved. The following results report different domain decomposition and binding

with $L = 1200$, $N = 12$ on thin node. Is reported the maximum value over all runs.