

Aufgabenstellung

Es ist die Strömung durch eine Lavaldüse mit Hilfe **eines** der folgenden drei zentralen numerischen Verfahren zu lösen:

- 1: MacCormack
- 2: Lax-Wendroff
- 3: Central Method

Das Ergebnis soll mit der analytischen Lösung aus dem beiliegenden Excel-File verglichen werden.

Folgende Ergebnis-Files werden erstellt:

Mach.out: Mach-Zahl entlang der Düse

Ptot.out: Total-Druck entlang der Düse

Press.out: Statischer Druck entlang der Düse

Cont.out: Dimensionsloser Massenstrom entlang der Düse

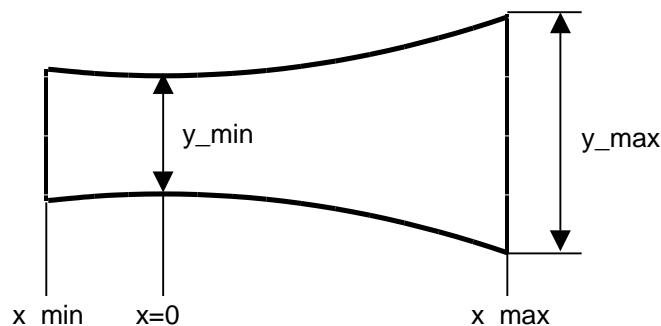
Nozzle.out: die 3 Größen des Zustandsvektors und am Ende die „vergangene“ Zeit

Die Randbedingungen und Steuerparameter sind im File nozzle_3.dat zu finden, der vom Programm eingelesen wird.

Geometriedefinition:

Die Kontur der Lavaldüse (= Querschnittsfläche) konstanter Breite 1 ist durch folgende Beziehung gegeben, sodass der engste Querschnitt y_{\min} sich bei $x=0$ befindet:

$$A(x) = (y_{\min} + (y_{\max} - y_{\min}) \frac{x^2}{x_{\max}^2}) * 1$$



Task

The flow in a Laval nozzle has to be calculated with **one** of the following central methods:

- 1: MacCormack
- 2: Lax-Wendroff
- 3: Central Method

The numerical result shall be compared with the analytical solution of the attached Excel file.

The code will generate following result files:

Mach.out: Mach number along the nozzle axis

Ptot.out: Total pressure along the nozzle axis

Press.out: Static pressure along the nozzle axis

Cont.out: Non-dimensional mass flow along the nozzle axis

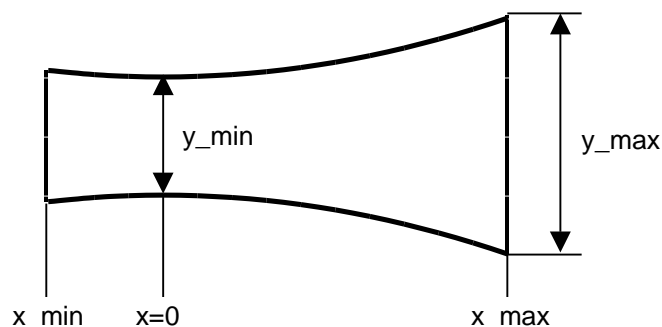
Nozzle.out: contains the three variables of the state vector and at the end to „past“ time span

The boundary conditions and the control parameters are listed in the input file nozzle_3.dat, which is read by the code.

Geometry:

The contour (=area) of the Laval nozzle of constant width 1 is given by following simple relation; the minimal flow cross section y_{\min} is at $x=0$:

$$A(x) = (y_{\min} + (y_{\max} - y_{\min}) \frac{x^2}{x_{\max}^2}) * 1$$



Variablendefinition

area	Fläche
cfl	CFL-Zahl
convergence	Konvergenzlimit
da_dx	1. Ableitung der Fläche nach x
delta_u	ΔU -Vektor
dissip	Dissipations-Vektor
dt	Zeitschrittgröße
dx	Netzweite
end	=1: Konvergenzkriterium erreicht
f	Flussvektor
f_star	Stern-Flussvektor
gamma	Isentropenkoeffizient
cp	spez. Wärmekapazität
eps_s	Parameter für „einfache“ Dissipation
imax	Anzahl der Knotenpunkte
iread	=0: Neustart, =1: Fortsetzung
itr	Index des Iterationsschrittes
k2	2nd Order – Parameter für „komplexe“ Dissipation
k4	4th Order – Parameter für „komplexe“ Dissipation
max_iter	Anzahl der Iterationsschritte
method	Verfahrensauswahl (1=MCC, 2=LW, 3=Central)
nprint	Schreiben des Residuums bei jedem nprint-Schritt
p_exit	statischer Druck beim Austritt
p_tot	Totaldruck beim Eintritt
R	Gaskonstante
resid1	Gesamtresiduum der 1. Komponente beim 1. Zeitschritt
resid2	Gesamtresiduum der 2. Komponente beim 1. Zeitschritt
resid3	Gesamtresiduum der 3. Komponente beim 1. Zeitschritt
rho_tot	Totaldichte beim Eintritt
source	Quellterm
sub_exit	=1: Unterschallaustritt, sonst Überschallaustritt
time	Gesamtzeit
T_tot	Totaltemperatur beim Eintritt
u	Zustandsvektor
u_q	U_quer- Zustandsvektor

u_qq	U_quer_quer-Zustandsvektor
x	x-Koordinate
x_max	Endkoordinate des Netzes
x_min	Anfangskoordinate des Netzes
y_max	y-Koordinate (Querschnitt) bei x_max
y_min	kleinste y-Koordinate (engster Querschnitt) bei x=0

Definition of Variables

area	Area
cfl	CFL number
convergence	Convergence limit
da_dx	1st derivative of flow area along the x-axis
delta_u	ΔU , change in state 'vector
dissip	Dissipation vector
dt	time step size
dx	grid spacing
end	=1: convergence achieved
f	Flux vector
f_star	Star flux vector
gamma	Isentropic coefficient (ratio of specific heats)
cp	specific heat
eps_s	Parameter for „simple“ dissipation
imax	Number of grid points
iread	=0: new start, =1: continue with calculation
itr	Index of iteration step
k2	2nd Order parameter for „complex“ dissipation
k4	4th Order parameter for „complex“ dissipation
max_iter	Maximum number of iteration steps
method	Method parameter (1=MCC, 2=LW, 3=Central)
nprint	Write a residuum at every nprint step
p_exit	Static pressure at the exit
p_tot	Total pressure at the inlet
R	Gas constant
resid1	Total residuum of the 1 st state vector component at 1 st time step
resid2	Total residuum of the 2 nd state vector component at 1 st time step
resid3	Total residuum of the 3 rd state vector component at 1 st time step
rho_tot	Total density at the inlet
source	Source term (vector)
sub_exit	=1: subsonic outflow, else supersonic outflow
time	Total time
T_tot	Total temperature at the inlet
u	State vector
u_q	U_quer state vector (MCC)

u_qq	U_quer_quer state vector (MCC)
x	x coordinate (nozzle axis)
x_max	x coordinate of nozzle end
x_min	x coordinate of nozzle start
y_max	y coordinate (flow area) at x_max
y_min	Smallest y-coordinate (flow area) at x=0

Input file for 1d-nozzle solver

Laval nozzle flow

```

-----
C.. IREAD   ITER      NPRINT    CONV
    0      100000        10    1.e-4
C.. imax    x_min[m]  x_max[m]  y_min[m]  y_max[m]
   101    -0.333333    1.      0.1      0.2
C.. R       kappa
  287.0    1.4
C.. p_tot[bar] t_tot[K]  p_exit[bar]  subsonic exit
    1.0      273.15    0.9          1
C.. Method (MCC=1, LW=2, Central=3)  simple Dissip (yes=1)
    3                                0
C.. CFL      eps_s      k4      k2
   0.35    10000.0     8.0    200.0

```

all3.c

```

/*      program CENTRAL
c*****
c
c              1D CFD code for
cftt
c              students of
c              CFD in turbomachinery
c
c              solution of the 1-D unsteady Euler equations for nozzle flows
c              with a time-iterative central method
c
c              numerical algorithm:
c              - MacCormack algorithm
c              - Lax-Wendroff algorithm
c              - explicit central method with simple and "sophisticated" 4th order
c              artificial dissipation
c
c              Remarks to central method: CFL < 0.1
c              values of eps, k2, k4 Parameter are important
c              good results for eps=50, k4=0.04,k2=1
c              (if k2 is too small, Dissip4 is not switched off)
c
c*****/

/*----- SUBROUTINES -----*/
void init();
void grid();
void input();
void boundary();
void boundary_q();
void calc_uq();
void calc_uqq();
void calc_f();
void dissip_simple();
void dissip_complex();
void calc_f_star_LW();
void calc_f_star_central();
int conv(int itr);
void output();
void timestep();

/*----- DECLARATIONS -----*/
#include <math.h>
#include <stdio.h>
#include <stdlib.h>

#ifndef max
#define max(a,b) (((a) > (b)) ? (a) : (b))
#endif

#ifndef fabs

```



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                                all3.c
#define fabs(a) (((a) < (0.0)) ? -(a)) : (a))
#endif

/* max. dimension of the arrays*/
#define Mat_dim 1001

/*----- INPUT VARIABLES-----*/
int      iread;                      /*0:std, 1:read from input file */
int      max_iter;                   /*max number of iterations*/
int      nprint;                     /*print at xxth iteration*/
double   convergence;                /*convergence limit*/
int      imax;                       /*number of cells*/
double   x_min;                      /*[m]*/
double   x_max;                      /*[m]*/
double   y_min;                      /*[m] for laval nozzle*/
double   y_max;                      /*[m] for laval nozzle*/
double   R;                          /*R*/
double   gamma;                      /*kappa*/
double   p_tot;                      /*total inlet pressure [bar]*/
double   p_exit;                     /*static exit pressure [bar]*/
double   T_tot;                      /*total inlet temperature [K]*/
int      sub_exit;                   /*sub/supersonic conditions*/
int      method;                     /*=1: MCC, =2: LW, =3:central*/
int      simple_dissip;               /*1: simple dissipation, else
sophisticated dissipation*/
double   cfl;                        /*courant number <0 => transient*/
double   eps_s;                      // Parameter of simple dissipation
double   k4;                         // 4th order parameter for
complex dissipation
double   k2;                         // 2nd order parameter for
complex dissipation
/*----- END INPUT VARIABLES -----*/

/*----- STATIC VARIABLES-----*/
/*Files*/
FILE *logfile;
/*control*/
double dt;
double dx ;
double time ;
/*geometry*/
double area[Mat_dim] = {0.0};
double da_dx[Mat_dim] = {0.0};
/*vektor*/
double u[Mat_dim][4] = {0.0};
double u_q[Mat_dim][4] = {0.0};
double u_qq[Mat_dim][4] = {0.0};
double dissip[Mat_dim][4] = {0.0};
double delta_u[Mat_dim][4] = {0.0};
double f[Mat_dim][4] = {0.0};
double f_star[Mat_dim][4] = {0.0};
double source[Mat_dim][4] = {0.0};

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/*boundary*/
double rho_tot;
double h_tot;
/*x_coordinaten*/
double x[Mat_dim] = {0.0};
/*residuum*/
double resid1;
double resid2;
double resid3;
/*----- END STATIC VARIABLES-----*/

```

```

void main()
{
    int itr, end=0,i,k;

    input();

    grid();

    init();

    //-----loop start-----
    for (itr=1; itr<=max_iter; itr++)
    {
        timestep();

        switch (method)
        {
            case 1: //MCC

                calc_uq();

                boundary_q();

                calc_uqq();

                for (i=2; i<=imax-1; i++)
                {
                    for (k=1;k<=3;k++)
                    {
                        delta_u[i][k] = 0.5*(u_q[i][k]
+ u_qq[i][k])-u[i][k];
                        delta_u[i][k];
                        u[i][k] = u[i][k] +
                        delta_u[i][k];
                    }
                }

                break;

            case 2: //LW

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        calc_f();

    calc_f_star_LW();

    for (i=2; i<=imax-1; i++)
    {
        for (k=1;k<=3;k++)
        {
            delta_u[i][k] = ... //
Calculation of delta_u using the conservative star fluxes
            u[i][k] = u[i][k] +
delta_u[i][k];
        }
    }

    break;

    case 3: //central

        calc_f();

        if (simple_dissip == 1)
            dissip_simple();
        else
            dissip_complex();

        calc_f_star_central();

        for (i=2; i<=imax-1; i++)
        {
            for (k=1;k<=3;k++)
            {
                delta_u[i][k] =
-dt*(f_star[i][k] - f_star[i-1][k])/dx + dt*source[i][k];
                u[i][k] = u[i][k] +
delta_u[i][k];
            }
        }

        break;

    default:

        printf("\n No numerical method was selected
(1-3)!!!\n");

        exit(0);

}

boundary();

```

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```

        if((itr%nprint == 0) || (itr == max_iter))                end =
conv(itr);

        if (end == 1)
        {
                printf("\n Convergence limit of %lf achieved!
\n",convergence);
                printf("\n Number of iterations: %d \n",itr);
                break;
        }
        }

        //-----loop
end-----

        output();

        fclose(logfile);

        return;
}

/*-----data input-----*/
void input()
{
        FILE *input;
        char  dummy[81];

        input=fopen("nozzle_3.dat","rt");
        fgets(dummy,80,input);
        fgets(dummy,80,input);
        fgets(dummy,80,input);
        fgets(dummy,80,input);
        fscanf(input,"%d%d%d%lf\n",&iread,&max_iter,&nprint,&convergence);
        fgets(dummy,80,input);
        fscanf(input,"%d%lf%lf%lf%lf\n",&imax,&x_min,&x_max,&y_min,&y_max);
        fgets(dummy,80,input);
        fscanf(input,"%lf%lf\n",&R,&gamma);
        fgets(dummy,80,input);
        fscanf(input,"%lf%lf%lf%d\n",&p_tot,&T_tot,&p_exit,&sub_exit);
        fgets(dummy,80,input);
        fscanf(input,"%d%d\n",&method, &simple_dissip);
        fgets(dummy,80,input);
        fscanf(input,"%lf%lf%lf%lf\n",&cfl,&eps_s, &k4, &k2);

        if (imax-1 > Mat_dim)

```

```

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    {
        printf("*** Specified number of cells is higher than allocated
vector size ! **\n");
    }

    p_tot=p_tot*100000.0;
    p_exit=p_exit*100000.0;
    h_tot = gamma/(gamma-1)*R*T_tot;
}

/*-----grid definition
-----*/
void grid()
{
    int i;
    // Berechnen von dx, x[i], area[i], da_dx[i]
    // Calculation of dx, x[i], area[i], da_dx[i]

}

/*-----initializing-----*/
void init()
{
    FILE *old_data;
    int i;

    // Berechnen von rho_tot, am Eintritt fuer die Randbedingungen
    // Calculaton of rho_tot at the inlet for the boundary condition
algorithm

    if (iread == 0)
    {
        // Initialisieren des Stroemungsfeldes (Zustandsvektor U) mit
den Ruhezustandswerten
        // Initialisation of the flow field (state vector U) with the
stagnation values (=total values)

    }
    else
    {
        old_data = fopen("nozzle.out","r");

        for(i=1; i<=imax; i++)

fscanf(old_data,"%lf%lf%lf\n",&u[i][1],&u[i][2],&u[i][3]);

        fclose(old_data);
    }
}

```

```

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    logfile = fopen("nozzle.log","w");
        fprintf (logfile, "%s\n", " Iter cont_resid imp_resid energy_resid");
}

//-----timestep
calculation-----
void timestep()
{
    int i;
    double eigenmax,vel,p,c,eigen;

    /*
    Bestimmen des maximalen Eigenwertes eigenmax fuer das gesamte Stroemungsfeld
        eigen = max(fabs(vel+c),fabs(vel-c))
    Calculation of the maximum eigenvalue eigenmax for the total flow field
        eigen = max(fabs(vel+c),fabs(vel-c))

    Bestimmen von dt als Funktion von cfl und max. Eigenwert
    Find dt as function of cfl and maximum eigenvalue

    */
        time = time + dt;
}

//-----flux and source
vector-----
void calc_f()
{
    double rho,vel,p, temp;
    int i;

    //Berechnung des des Flussvektors F und des Source-Vektors in allen
    Punkten
    //Calcalaton of flux vector F and source vector S in all grid points

}

//-----simple dissipation
vector-----
void dissip_simple()
{
    int i,k;

    // dissipation vector at i+1/2

    // dissipation vector at i=1 and i=imax-1

}

```

all3.c

```
//-----complex dissipation
vector-----
void dissip_complex()
{
    int i,k;
    double rho,vel,c,p,pm,pp;
    double eigen, eigenp;
    double eps2,eps4;
    double sensor[Mat_dim];

    // dissipation vector at i+1/2

    // dissipation vector for i=1 and i=imax-1

}

//-----f_star
central-----
void calc_f_star_central()
{
    int i,k;

    // calculation of f_star at i+1/2 for central method

}

//-----f_star
Lax-Wendroff-----
void calc_f_star_LW()
{
    int i,k;

    // calculation of f_star at i+1/2 for Lax-Wendroff method

}

//-----MCC U_q
vector-----
void calc_uq()
{
    double rho,vel,p;
    int i;

    /*
    fuer U      Berechnung des Flussvektors F und des Source-Vektors in allen Punkten
                Bestimmung von U_q (forward)
    */
}
```

all3.c

```

    Calculaton of flux vector F and source vector S in all grid points for
U
    Calculate U_q (forward)
    */
}

//-----MCC_U_qq
vector-----
void calc_uqq()
{
    double rho,vel,p;
    int i;

    /*
    Berechnung des des Flussvektors F und des Source-Vektors in allen
Punkten fuer U_q
    Bestimmung von U_qq (backward)

    Calculaton of flux vector F and source vector S in all grid points for
U_q
    Calculate U_qq (backward)
    */
}

//-----U_q boundary
conditions-----
void boundary_q()
{
    double rho,p,vel;

    //    Bestimmen der Randwerte fuer i=1 und i=imax fuer U_q-Vektor
    //    Calculation of boundary values for i=1 and i=imax for U_q vector

    /*inlet i=1*/

    if (rho > rho_tot)    rho = rho_tot;

    /*outlet i=imax*/
}

//-----U boundary
conditions-----
void boundary()
{
    double rho,p,vel,temp;

    //    Bestimmen der Randwerte fuer i=1 und i=imax fuer U-Vektor
    //    Calculation of boundary values for i=1 and i=imax for U vector

```


all3.c

```

/*inlet i=1*/

if (rho > rho_tot)    rho = rho_tot;

/*outlet i=imax*/
}

//-----
int conv(int itr)
{
    int i,k,end;
    double resid[4] = {0.0};

    if (itr == 1) return;

    printf("calc timestep = %d\t", itr);

    for(i=2; i<=imax-1; i++)
    {
        for (k=1;k<=3;k++)
        {
            resid[k] = resid[k] + fabs(delta_u[i][k]);
        }
    }

    if ((itr == nprint) || (itr==2))
    {
        resid1 = resid[1];
        resid2 = resid[2];
        resid3 = resid[3];
    }

    fprintf(logfile,"%d %lf %lf %lf\n",itr, resid[1]/resid1,
resid[2]/resid2, resid[3]/resid3);

    if (resid[3]/resid3 < convergence) end = 1;

    printf("resid = %lf\n", resid[3]/resid3);

    return end;
}

//-----
void output()

```

```

{
    int i;
    double temp,cont0, rho,vel;
    double p[Mat_dim], mach[Mat_dim],p_tot_is[Mat_dim], cont[Mat_dim];
    FILE *result,*machzahl,*pressure,*continuity,*total_pressure;

    result = fopen("nozzle.out","wt");
    machzahl = fopen("mach.out","wt");
    pressure = fopen("press.out","wt");
    continuity = fopen("cont.out","wt");
    total_pressure = fopen("ptot.out","wt");

    for (i=1;i<=imax;i++)
fprintf(result,"%lf\t%lf\t%lf\n",u[i][1],u[i][2],u[i][3]);
    fprintf(result,"\n %lf \n", time);

    for (i=1; i<=imax; i++)
    {
        rho = u[i][1];
        vel = u[i][2]/rho;
        p[i] = (gamma-1)*(u[i][3]-rho*vel*vel/2);
        mach[i] = vel/pow((gamma*p[i]/rho),0.5);
        temp = 1+(gamma-1)/2*mach[i]*mach[i];
        p_tot_is[i] = p[i]*pow(temp,(gamma/(gamma-1)));
        if (i == 1)
        {
            cont0 = rho*vel*area[i];
            if(cont0<=0.) cont0 = 1.e-5;
        }
        cont[i] = rho*vel*area[i]/cont0;
    }

    for (i=1;i<=imax;i++) fprintf(pressure,"%lf\t%lf\n", x[i], p[i]/1.e5);
    for (i=1;i<=imax;i++) fprintf(machzahl,"%lf\t%lf\n", x[i], mach[i]);
    for (i=1;i<=imax;i++) fprintf(continuity,"%lf\t%lf\n", x[i], cont[i]);
    for (i=1;i<=imax;i++) fprintf(total_pressure,"%lf\t%lf\n", x[i],
p_tot_is[i]/p_tot);

    fclose (pressure);
    fclose (machzahl);
    fclose (continuity);
    fclose (total_pressure);
    fclose (result);
}

```