# Graph Algorithms: Home Assignment

#### Valeran MAYTIE

# Exact exponential algorithms for Graph Coloring Problem

- 1. The first non-trivial algorithm for 3-Colour.
  - (a) Intuitively the root has 3 options then the children are constrained by their parents, so they only have 2 as we have a root and n-1 children then, there are  $3 \times 2^{n-1}$  coloring options.

We can proof this property by induction on n.

- n = 0, the case where the tree contains no vertex is not interesting
- n=1, if we have one vertex, so we have  $3=3\times 2^{1-1}$  3-coloring options
- n+1, by hypothesis induction, we know that a tree with n-vertices has  $3 \times 2^{n-1}$  3-coloring options.

If we had a vertex on a leaf of the tree, then it has two possible color options, so there is  $3 \times 2^{n-1} \times 2 = 3 \times 2^n$  3-coloring options.

(b) The 3-coloring algorithm Which uses the *spanning\_tree* which returns the spanning tree: S. We define *top* and *child*, the function who return the top of the tree and the child of a vertex. The function return a map with vertex key and color ( $C = \{c_1, c_{2,3}\}$ ).

## Algorithm 1 $\mathcal{O}^*(3^n)$ algorithm for 3-coloring with spanning tree

```
1: function REC COLORING(G : graph, S: spanning tree, v:vertex, \phi: color)
       for n \in CHILD(S, v) do
2:
           colors = possible colors(G, n)
3:
           for c \in \text{colors do}
4:
               \phi[n] \leftarrow c
5:
               if REC COLORING(G, S, n, \phi) then
6:
                  break
7:
           return false
8:
9:
       return true
10:
11: function 3-COLORING(G : graph)
       S = SPANNING TREE(G)
       top = TOP(S)
13:
       \phi = \{ \text{top} \to c_1 \}
14:
       return REC COLORING(G, S, top(S), \phi)
15:
```

2. (a) To reduce to 2-Sat, we want to find clauses containing exactly 2 literals that allow us to find the colors of the nodes outside the dominating set (X : the dominating set and C : the set of colors). We define the variable:

$$\mathcal{V} = \bigcup_{v \in V(G) \backslash X} \{ v_c | \forall c \in C \}$$

All vertices have 3 variables representing if variable i is true then the node can have the color i. We define a function Cl which return a set of clauses for a vertex v (represent the possible colors for v):

$$Cl(v) = \begin{cases} \{(v_1 \lor v_1), (\neg v_1 \lor \neg v_1)\} & |\phi(X \cap N_G(v))| = 3\\ \{(v_y \lor v_y) | \{y\} = \phi(X \cap N_G(v)) \backslash C\} & |\phi(X \cap N_G(v))| = 2\\ \{(v_i \lor v_j) | \{i, j\} = \phi(X \cap N_G(v)) \backslash C\} & |\phi(X \cap N_G(v))| = 1 \end{cases}$$

 $\phi(X \cap N_G(v))$  is the set of colors link to a vertex v.

The first case is here to make the formula false (we can not choose a color if the node is already linked to 3 different colors in X). In the second case y represent the last color.

Finally, we define the set  $\mathcal{C}$  of clauses :

$$\mathcal{C} = \bigcup_{v \in V(G) \backslash X} Cl(v) \cup \{ (\neg v_c \vee \neg n_c) | \forall n, c \in (N_G(v) \backslash X) \times (\phi(X \cap N_G(v)) \backslash C) \}$$
$$\cup \{ (\neg v_c \vee \neg v_c) | \forall c \in \phi(N_X(v)) \}$$

The middle union represents the constraints between the external nodes of X. The last union prevents an external node to have the same colors that a neighbor in X.

Proof:

• Coloring  $\Rightarrow$  2-Sat :

We assume that the vertices  $V(G)\backslash X$  can be colored.

We define for all v,  $v_{c(v)} = true$  and for other color c we define  $v_c = false$ .

All clauses generated by Cl are satisfied (the first case does not occur because the graph can be colored).

We need to make a case disjunction for the other clauses of the form  $(\neg v_c \lor \neg n_c)$ . If we have  $v_c = true$  then v has the color c has the color c and n cannot have the color c because they are neighbors, then  $n_c = false$ . Otherwise, v has not the color c, so  $v_c = false$ .

Finally, the clauses of the form  $(v_c \wedge v_c)$  (last union) is true because v is linked to a vertex in X which has the color c, so  $v(x) \neq c$ .

• 2-Sat  $\Rightarrow$  Coloring :

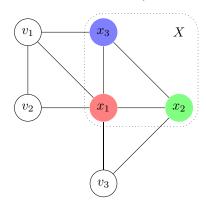
We assume that the formula for a dominating set X is satisfiable.

So we have for all variable v in  $V(G)\backslash X$  a c such that  $v_c=true$ , thanks to the function Cl.

The same vertex v has no neighbor n such that  $n_c = true$ . Because we have the clause  $(\neg v_c \lor \neg n_c)$ , if  $v_c = true$  then  $n_c = false$ .

And thanks to the last union we can not have  $v_c$  is v is linked to a vertex who has the color c in X.

Example:  $C = \{R, G, B\}$  (R: Red, G: Green, B: Blue)



For this graph we have the formula :

$$\begin{split} & \left(v_{1_G} \vee v_{1_G}\right) \wedge \left(\neg v_{1_B} \vee \neg v_{1_B}\right) \wedge \left(\neg v_{1_R} \vee \neg v_{1_R}\right) \wedge \left(\neg v_{1_G} \vee \neg v_{2_G}\right) \wedge \\ & \left(v_{2_G} \vee v_{2_B}\right) \wedge \left(\neg v_{2_R} \vee \neg v_{2_R}\right) \wedge \left(\neg v_{2_G} \vee \neg v_{1_G}\right) \wedge \left(\neg v_{2_B} \vee \neg v_{1_B}\right) \wedge \\ & \left(v_{3_B} \vee v_{3_B}\right) \wedge \left(\neg v_{3_R} \vee \neg v_{3_R}\right) \wedge \left(\neg v_{3_G} \vee \neg v_{3_G}\right) \end{split}$$

Now, we can construct  $c: V(G) \to [3]$ . If the formula is not satisfiable then c can not be constructed. Otherwise, we can define c like that:

$$c(x) = \begin{cases} \phi(x) & \text{if } x \in X \\ c & x_c = \text{true} \end{cases}$$

If the formula is satisfiable we necessarily have c such that  $x_c = true$  (by construction).

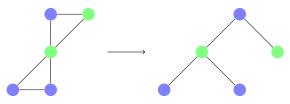
(b) Let G a graph such as  $V(G) \ge 2$  and T the corresponding BFS tree. We have  $S_i$  the set of vertices at layer i of tree T.

We define the sets  $D_e = \{v | v \in S_i, \exists k, i = 2 \times k\}$  (vertices in an even layer) and  $D_o = \{v | v \in S_i, \exists k, i = 2 \times k + 1\}$  (vertices in an odd layer).

 $D_e$  and  $D_o$  are distinct sets because in a BFT tree we can not have the same vertex several times, so the layer where the even and odd layers intersect is empty.

 $D_e$  De is a dominating set, because each layer is linked to the layer below and above it, so it is linked to all the other remaining vertices. We apply the same argument to  $D_o$ .

We can deduce that the upper bound of the smallest dominating set is  $\frac{n}{2}$  (n = |V(G)|). If  $|D_e| < |D_o|$ , then the smallest is  $D_e$  otherwise the smallest is  $D_o$ . So the worst case is when  $|D_e| = |D_o| = \frac{n}{2}$ . Example:



(c) The BFS\_tree, bi\_party and 2-Sat functions have a polynomial complexity. We use 3-coloring (Algorithm-1) on a graph such that  $|V(G)| = \frac{n}{2}$ , then the complexity is  $\mathcal{O}^*(3^{\frac{n}{2}}) = \mathcal{O}^*((\sqrt{3})^n)$ . Therefor, the algorithm below has a complexity of  $\mathcal{O}^*((\sqrt{3})^n)$ .

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### **Algorithm 2** $\mathcal{O}^*((\sqrt{3})^n)$ algorithm for 3-coloring with the smallest dominating set

```
1: function 3-coloring-opt(G: graph)
2: T = BFS\_TREE(G)
3: D_e, D_o = BI\_PARTY(T)
4: X = D_e
5: if |D_o| < B then
6: X \leftarrow D_o
7: \phi = 3\text{-coloring}(X)
8: \phi \leftarrow 2\text{-Sat}(G, X, \phi)
```

3. (a) Let  $X \subseteq V(G)$  and  $1 \le j < k$  such that  $\chi(G[X]) \le j$ .

We want to compute  $Y \subseteq V(G)$  such that  $\chi(G[Y]) \leq j+1$ . The function  $\mathcal{P}(X)$  give all possible subset of a set X.

So for all  $S \in \mathcal{P}(V(G))$  if S is on X then  $\chi(G[S]) \leq j \leq j+1$ .

Otherwise, if we find  $S_p \in \mathcal{P}(S)$  such as  $S_p \in X$  with  $\phi_p$  the j-coloring of  $S_p$  and  $\phi$  defined bellow is a j+1 coloring of S then S is in Y

$$\phi(x) = \begin{cases} \phi_p(x) & \text{if } x \in S \\ j+1 & \text{if } x \notin S \end{cases}$$

For all subset we have to potentially calculate all the subset of a subset of cardinal t ( $\mathcal{O}^*(2^t)$ ). We did this operation for all the subsets of vertices in the graph.

So we have a complexity of  $\mathcal{O}^*(3^n)$ 

(b) The final algorithm:

#### **Algorithm 3** $\mathcal{O}^*(3^n)$ algorithm for k-coloring

```
1: function K-COLORING(G: graph)
        k = 0
 2:
 3:
        X = \{\}
 4:
        while V(G) not in M do
            k = k + 1
 5:
            for all C \subseteq V(G) do
 6:
                if C \in X then
 7:
                     Continue
 8:
                for all S \subseteq C do
 9:
                     if S \notin X then
10:
                         Continue
11:
                     \phi_s = X[S] \cup \{v \to k | \forall v \in C \setminus S\}
12:
                     if is Coloring(C, \phi_s) then
13:
                         X[C] \leftarrow \phi_s
14:
                         Break
15:
16:
        return k
```

The algorithms above finished, because a graph always has a colouring ( $\leq n$ ). It repeats the algorithm detailed in the previous question at most n times, so it has a complexity of  $\mathcal{O}^*(3^n)$ .

The dictionary X containing, at worst, all the parts of the set of vertices. So the space complexity is  $\mathcal{O}^*(2^n)$