

RoadEye

by

Marcelo Dias Avelino (0840416)



CMI-Program *Technical Informatics* – Rotterdam University

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First supervisor *Mrs. T. Ubert*
Second supervisor *Mr. A. van Raamt*

Abstract

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Introduction

Background information

This project has been made available by CGI Nederland BV, which is a daughter company of the CGI Group Inc. located in The Netherlands. CGI is a multinational IT (Information Technology) company which provides consulting, systems integration, outsourcing, etc. on a multitude of different technological areas. Because of its affinity with these different kinds of technology, CGI researches various technologies to solve problems facing modern society. As a result of this drive, the idea for this project arose: How can people be given the ability to help track stolen cars, and by extension improve their community? Since everyone nowadays carries a smart phone around in their pocket, there is a lot of untapped processing power which could be used for this purpose. This led to the invitation of a student to research and implement this project as the topic for a bachelor thesis. I chose this project because of its relation with Computer Vision, a computer science topic I have worked with before and found interesting.

Problem

Even nowadays, it is still difficult for law enforcement to follow up on every case of stolen property, e.g. cars, simply because they cannot be everywhere at once. A possible way to improve law enforcement's efficiency would be by including the aid of civilians through the voluntary provision of gathered information from one's environment. This used to be a very difficult issue because required people to carry dedicated, and often large, hardware devices which made the gathering of information possible. Since the breaking of the smart phone age, a large number of people carry a computer in their pockets. This Internet-connected all-purpose device allows for a whole range of new possibilities and with the right software, gives the user the possibility to help his own community and therefore help making it a better place. One of these possibilities is to capture video images using the smart phone's camera. These images when paired with a Computer Vision algorithm are able to produce amazing results. This project will therefore be focused on applying the Computer Vision discipline to solve this problem and try to answer the following question: *How can license plate information be gathered from images of a video camera using software?*

But this only concerns the problem of this project in a more general way, without taking any requirements or conditions into account. Because the software must run on a mobile platform it must take all the limitations of such a platform or the environment where it will operate into consideration, i.e. limited processing power, battery life, unstable images or car distance. To keep these conditions in mind while developing the application, the following questions will be answered: *'How can the software be optimized to work in a correct way from within a mobile device?'* and *'What are the limitations of such an application?'*

Objective

The objective of this project consists in creating an Android smart phone software application that is able to locate license plates in images gathered from the smart phone's camera. From these images, the application must be capable of reading the alphanumeric text displayed on the plates. This information will then be compared to a list of license plate information, which was fetched from an website beforehand. If there is a match, the application must inform a central application of the said match, along with its position when the image was captured and how reliable the recognition is.

Scope

The scope of this project will encompass the development of the android application which will recognize license plates using the images from the phone's camera, the communication with the web page where the license plate information will be fetched from and the communication with the main application where information over the recognition will be sent to. It will only take into account dutch yellow car license plates and might therefore not work with foreign plates. It will take into account, implementation and design wise, privacy concerns according to the dutch law. The software will only be written and tested for Android version 4.2.2, running on an HTC One X. It might therefore not work on different versions.

Methodology

insert text here

Thesis

Algorithms

When searching for possible algorithms with the functionality to find license plates in an image, two main types came forth from the research: feature detection and edge detection.

The feature detection algorithms work by finding so called *features* in a image, which are used to recognize the first image in a second one. These features are segments of an image which must be uncommon, as to reduce the possibility of retrieving a false positive when applying the algorithm, and also consist of something which can be objectively described to a computer. Because of these requirements, the features extracted from an images are usually corners since a corner only matches itself if compared to other segments of the image, as opposed to flat surfaces or lines which may appear in multiple times in multiple places. Because this algorithm focuses on detecting the uniqueness of an image and using that attribute to detect it in different images, it becomes difficult to use feature detection to recognize license plates because every license plate contains unique text. These false positives originate from the diversity in shapes that exist in the latin alphabet and this considerable collection features is often detected in random and incorrect locations. One possible approach to use this algorithm to find the plate location would be by creating a feature database of every possible alphanumeric character and then finding the highest concentration of text as a possible location. Due to little information on the performance of this algorithm, the other algorithm was chosen.

The other possible algorithm is mostly based on edge detection. This kind of algorithm works by applying an edge detection algorithm to a greyscale version of the image where the car is present, e.g. the Sobel Filter [ref here] or Canny Edge Filter [ref here]. This creates a black and white image where the edges of every object in the images are displayed in white. One of the characteristics of a license plate is the presence of a high amount of edges due to the text displayed on it. This means that by using this algorithm it is possible to find the location of the license plate by looking for the highest edge density area in the image. This method of plate location has been chosen because of the large amount of information that proves its efficiency and performance.

Architecture

Implementation

Conclusion and recommendations

Conclusies en aanbevelingen moeten verzameld worden in een apart en herkenbaar deel van het verslag. Hoewel in het hoofdverslag op diverse plaatsen conclusies getrokken kunnen worden, moeten de belangrijkste conclusies samengevoegd en samengevat worden.

Belangrijk is dat het verschil tussen objectief controleerbare conclusies en subjectieve aanbevelingen duidelijk wordt aangegeven. Ook is het aan te bevelen om de belangrijkste conclusies conform de opdrachtoomschrijving te formuleren.

References

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Evaluatie

In de evaluatie reflecteer je over je eigen afstudeerproces. Daarbij moet je vooral letten op de leereffecten. Welke competenties had je nodig? Welke competenties kwam je tekort en moest je zelf verwerven? Waren dit algemene of specifieke competenties? Voldeden de beroepscompetenties aan de standaard van het *HBO-I* (analyseren, adviseren, ontwerpen, realiseren en beheren)? Vielen de algemene competenties in de vijf categorieën van de *Dublin Descriptoren*¹ zoals het verkrijgen van kennis en inzicht, het toepassen van kennis en inzicht, het maken van onderbouwde keuzen (oordeelsvorming), het communiceren (schriftelijk en mondeling) en het verkrijgen van leervaardigheden?

¹Dublin Descriptoren zijn eisen aan de competenties voor de bachelor en master studies aan universiteiten en hogescholen in Europa.

Appendix A

Achtergrond materiaal

In de bijlagen komen alle gegevens die nodig zijn voor de onderbouwing, maar die de leesbaarheid van het hoofdverslag verlagen.