





FRETting and Formal Modelling: A Mechanical Lung Ventilator

Marie Farrell Matt Luckcuck Rosemary Monahan Conor Reynolds Oisín Sheridan

Department of Computer Science, The University of Manchester, Manchester, UK

School of Computer Science, University of Nottingham, Nottingham, UK

Department of Computer Science, Maynooth University/Hamilton Institute, Maynooth, Ireland

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Introduction

Overview

- ▶ We describe a methodology that captures the requirements of the ABZ 2024 case study, the Mechanical Lung Ventilator, using the Formal Requirements Eliciation Tool (FRET)
- Our workflow uses the requirements, written in FRET's structured-natural requirements language FRETISH, to guide the development of a formal model in Event-B.
- Our goal was to examine how formalising the requirements could uncover problems in the requirements, thus improving the requirements set and helping with the construction of a system model

Mechanical Lung Ventilator: ABZ Case Study

Case Study Overview

- Many requirements in the documentation.
- Partitioned into
 - ► Functional Requirements (FUN),
 - ► Values and Ranges (PER),
 - ► Sensors and Interfaces (INT),
 - ► Alarm Requirements (SAV),
 - ► GUI Requirements (GUI),
 - ► Controller Requirements (CONT), and
 - Alarms (AL).
- Some requirements have 'child' requirements; for example, FUN6 is decomposed into FUN6_1-6.
- Requirements also reference others; for example, CONT4 refers to FUN6.



Mechanical Lung Ventilator: ABZ Case Study

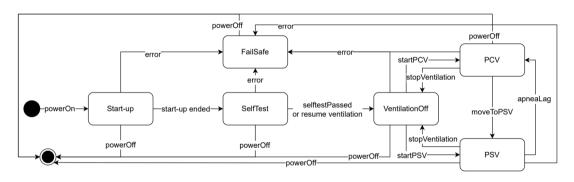


Figure 1: The controller state machine is labelled as Fig 4.1 in the case study documentation.

Formalisation with FRET

The Formal Requirements Elicitation Tool (FRET)

FRET

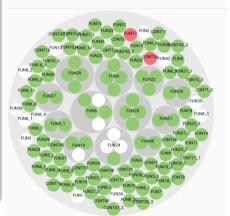
- ► An open source tool for requirements engineering developed by NASA
- Requirements are written in a structured natural-language called FRETish
- FRET provides automated translations from FRETish to CoCoSpec contracts, which can be verified with the Kind2 model checker, and Copilot runtime monitors
- ► Formalised requirements are indicated in green, those in white have not been formalised, and a red circle indicates invalid FRETish

Ventilator v0.6.1

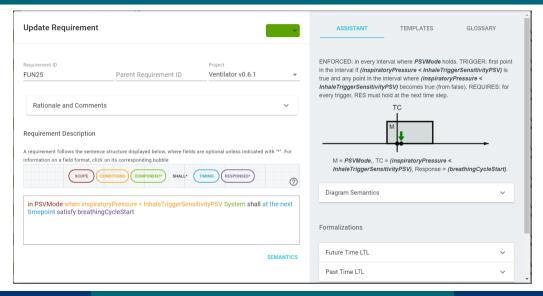
Total Requirements

Formalized Requirements 84.51 %

Hierarchical Cluster



The Formal Requirements Elicitation Tool (FRET)



Formalisation in FRETish - Methodology

Method

- ▶ We focused on the Functional and Controller requirements from the case study document. In total, we formalised 121 requirements in FRET, out of 142 total natural-language requirements in these categories.
- ► The formalisation was performed in stages, producing multiple versions of the requirements set:
 - ▶ v0.1 and v0.2 comprised the initial formalisation of the FUN requirements
 - ▶ v0.3, v0.3.1, and v0.4 included revisions to better align with the case study documentation where possible, and fix invalid variable names
 - v0.5 and v0.5.1 formalised the Controller requirements
 - ▶ v0.6 and v0.6.1 updated all requirements to use explicit timing conditions
- For traceability, we created FRETish requirements for all of the FUN and CONT requirements, even those that could not be formalised

Formalisation in FRETish - Examples

	If the self-test fails, the user shall be warned that the system is out-of-service.					
FUN.7	In addition, any other operations shall be not allowed					
	in SelfTestMode if selfTestFail System shall at the next timepoint					
	satisfy OutOfServiceWarning & FailSafeMode					
	In PCV mode it shall be possible to initiate with the push of a single button					
FUN.22	a lung recruitment procedure, termed Recruitment Maneuver (RM)					
	in PCVMode when RMButton System shall at the next timepoint satisfy RM					
CONT.19	If the SelfTest fails, the controller shall not be able to proceed to ventilation					
	in SelfTestMode if SelfTestFail Controller shall until off satisfy					
	!StandbyMode & !ventilating					
CONT.32	The inspiration phase lasts until the inspiration peak is reached but no later					
	than the max_insp_time_psv is over. After that the expiration phase begins.					
	<pre>in PSVMode Controller shall until (P_insp >= MaxP_insp inspClock >=</pre>					
	<pre>inspiratoryTime) satisfy inspiratoryPhase</pre>					

Formalisation in FRETish - Metrics

scope-option	null = 49, in = 70, before = 1, after =1			
condition-option	null = 51, trigger (regular) = 70			
timing-option	null/eventually =22, until =6, always=34, after=5, for =4, next=50			
parent-child	41 child requirements were assigned a parent requirement			
Total Requirements	121 specified in FRETish, of 142 natural-language requirements			

Fields

- ► FRET generates a Metric Temporal Logic (MTL) semantics for requirements using template keys
- ► Each template key is a tuple of: [scope-option, condition-option, timing-option]
- ▶ We used the scope field wherever the requirements explicitly mentioned a syetm mode

Formalisation in FRETish - Metrics

Timing

- ▶ Initially, we only included timing where it was explicitly mentioned in natural-language.
- ▶ On a second pass, we rechecked the timing conditions and added them explicitly.
- ► We usually used:
 - ▶ always when the requirement had no conditions,
 - eventually for events that would take an indeterminate amount of time (e.g. waiting for a process to finish or for user input), and
 - ▶ at the next timepoint for a response triggered by an event or button-press. We chose at the next timepoint instead of immediately to represent the time taken to react to the trigger and generate the response.

```
timing-option null/eventually =22, until =6, always=34, after=5, for =4, next=50
```

Formalisation in FRETish - Analysis

Inconsistencies

- ▶ We encountered some cases where the Functional and Controller requirements didn't quite align, or where the language used wasn't entirely consistent.
- ► The mode that comes after the self test has passed and before the system moves to PCV or PSV mode is called "Standby Mode" in the FUN requirements, but is named "VentilationOff" in the CONT requirements.
- ➤ CONT24 and FUN22 refer to the Recruitment Maneuver. FUN22 says the maneuver should be initiated "with the push of a single button", which seemed to imply that the maneuver starts immediately when the button is pressed. However, CONT24 says that the maneuver should start at the end of an inspiration phase (if it has been set by the GUI).
- ► Formalising requirements in a structured language like FRETish helps to find cases like these where a requirement lacks important details.

Formalisation in FRETish - Analysis

Unformalised and Invalid Requirements

- ► The unformalised requirements often related to capabilities of the overall system, rather than specifiable behaviour
 - ▶ e.g. FUN.1: "The system shall provide ventilation support for patients who require mechanical ventilation and weigh more than 40 kg (88 lbs). Rationale: ventilation of children and infants is more challenging",
- Similarly, there was no meaningful way to capture the "Measured and displayed parameters" requirements without a more detailed understanding of the sensors and GUI
- Some requirements were not written in a form that works in FRET. For example, CONT.36 simply reads: "If the patient is in expiration phase:", and rely on its three child requirements to provide details

Modelling in Event-B

Modelling in Event-B

Overview

- ▶ Using the natural-language and FRETish requirements as a base, we constructed a model of the ventilator system in Event-B
- ► The structure of the initial model was based on the "controller state machine" diagram from the case study documentation.
- ▶ We then encoded the requirements into Event-B in different ways, depending on what they specified. Some requirements were easily represented in a context, others became part of the behavioural event specifications, and some became invariant specifications.

Event-B Model

```
MACHINE mac00
     SEES ctv00
                                                                 24
                                                                        Event StartPSV -
     VARIABLES mode
                                                                          when grd0_1: mode = VentilationOff
     INVARIANTS typeof__mode: mode ∈ Mode
                                                                 26
                                                                                     \vee mode = PCV
                                                                 27
                                                                           then act0.1: mode := PSV
     EVENTS
     Initialisation
                                                                 28
                                                                        Event StopVentilation =
       then act1: mode := PoweredOff
                                                                          when grd0 1: mode = PCV
                                                                                     V mode - PSV
                                                                 30
      Event PowerOn ≘
                                                                 31
                                                                          then act0 1: mode := VentilationOff
        when grd0_1: mode = PoweredOff
10
        then act0_1: mode := StartUp
                                                                 32
                                                                        Event MoveToPSV 

                                                                 33
                                                                          when grd0 1: mode = PCV
       Event StartUpEnded 

                                                                 34
                                                                          then act0 1: mode := PSV
         when grd0_1: mode = StartUp
         then act0 1: mode := SelfTest
                                                                 35
                                                                        Event ApneaLag 

                                                                 36
                                                                          when grd0_1: mode = PSV
14
       Event ResumeVentilation 

                                                                 37
                                                                           then act0 1: mode := PCV
15
         when grd0 1: mode = SelfTest
         then act0 1: mode := VentilationOff
                                                                 38
                                                                        Event Error =
16
                                                                 39
                                                                          when grd0_1: mode \neq PoweredOff
17
       Event SelfTestPassed 

                                                                 40
                                                                                grd0_2: mode \neq Failsafe
         when grd0 1: mode = SelfTest
                                                                          then act0 1: mode := Failsafe
                                                                 41
         then act0 1: mode := VentilationOff
                                                                 42
                                                                        Event PowerOff ≘
                                                                          when grd0_1: mode \neq PoweredOff
20
       Fuent StartPCV @
                                                                 43
21
         when grd0_1: mode = VentilationOff
                                                                 44
                                                                          then act0 1: mode := PoweredOff
                    \lor mode = PSV
                                                                 45 END
         then act0 1: mode := PCV
```

Event-B Model

```
1 CONTEXT ctx00
2 SETS Mode
3 CONSTANTS
4 Failsafe, PoweredOff, VentilationOff
5 PCV, PSV, SelfTest, StartUp
6 AXIOMS
7 axm0_1: partition(Mode, {StartUp}, {SelfTest}, {VentilationOff}, 9 {PCV}, {PSV}, {Failsafe}, 10 {PoweredOff})
11 END
```

Context for the abstract machine, capturing FUN4/CONT1.

```
1 CONTEXT ctx01
2 EXTENDS ctx00
3 SETS ValveState, TestResult
4 CONSTANTS
5 ValveOpen, ValveClosed,
6 TestPassed, TestFailed, TestSkipped
7 AXIOMS
8 axm1_1: partition(ValveState,
9 {ValveOpen}, {ValveClosed})
10 axm1_2: partition(TestResult,
11 {TestPassed}, {TestFailed},
12 {TestPskipped})
```

Extending context to capture necessary sets and constants related to the selftest process (FUN6_1-6).

Event-B Model

```
1 Event SelfTestPassedOrSkipped =
     REFINES SelfTestPassed
     any timePoweredOff
       when
         grd0 1: mode = SelfTest
         grd1_1: testPowerSwitch \in \{TestPassed, TestSkipped\}
         grd1_2: testLeaks \in \{TestPassed, TestSkipped\}
         grd1_3: testFF12 \in \{TestPassed, TestSkipped\}
         grd1_4: testPS_EXP \in \{TestPassed, TestSkipped\}
         grd1_5: testOxygenSensor \in \{TestPassed, TestSkipped\}
         grd1 6: testAlarms ∈ { TestPassed, TestSkipped}
         grd1 7: timePoweredOff \in \mathbb{Z}
         grd1 8: timePoweredOff < 15 \wedge is new patient = FALSE
       then
         act0 1: mode := VentilationOff
         act1_1: in_valve := ValveClosed
         act1 2: out valve := ValveOpen
```

SelfTestPassedOrSkipped event after the first refinement step. This captures requirements FUN10 and some of its children, along with FUN6.

- ► FUN6: The system shall have a self-test procedure that ensures the system and its accessories are fully functional and the alarms work
- ► FUN10.3: If "Resume Ventilation" is selected, every step of the selftest procedure FUN.6 can be skipped or optionally rerun individually.
- FUN10.4: Once all self-test steps have been completed successfully, it shall be possible to proceed to the Standby Mode.

Requirements in Event-B

This table outlines how various requirements were captured in the Event-B model

FRETish ID	Context(s)	Event(s)	Invariant(s)	Event-B File(s)
FUN4	✓	√		mac00, ctx00
FUN5		✓		mac01
FUN5 3		✓	✓	mac01
FUN6	✓	✓		mac00, mac01, ctx01
FUN6 1-FUN6 6	✓	✓		mac01, ctx01
FUN7		✓		mac01
FUN10		✓		mac00
FUN10 1	✓	✓		macO1, ctxO1
FUN10 3-FUN10 6		✓		mac01
FUN23		✓		mac01
FUN27		✓		mac01
CONT1	✓	✓		mac00, ctx00
CONT1 1		✓		mac01
CONT1 ³			✓	mac01
CONT1_6			✓	mac01
CONT3		✓		mac00
CONT4		✓		mac00
CONT12		✓		mac00, mac01
CONT18	✓	✓		macO1, ctxO1
CONT19		✓		mac01
CONT38			✓	mac01
CONT46		✓		mac01

Verification in Event-B

Proofs

- ► The Rodin Platform generates proof obligations for Event-B models, which can be discharged automatically or interactively
- ▶ We were able to discharge all 79 proof obligations generated by Rodin automatically
- ➤ Some requirements were verified by construction. For example, adherence to the controller state machine is obtained by constructing a model that evolves following the mode changes indicated by the diagram. Thus, we consider requirements referring to this sequence of states, e.g. FUN4 and CONT1, to be correct-by-construction.
- ▶ Other requirements are verified more directly, by inspecting the guard or action of the event that corresponds to the behaviour described by that requirement.

Discussion

- Expected many requirements to become machine invariants, but most basic requirements become machine functionality and are not formally verifiable properties of the machine.
- ► Clarification of apparently inconsistent requirements difficult without domain experts, sometimes unclear what is meant to happen.
- ▶ Wanted to capture functional and controller requirements (not GUI), but some functional requirements mix types: "If the self-test mode fails, the user shall be warned that the system is out-of-service. In addition, any other operations shall be not allowed."

Conclusion

Summary

- ▶ We used FRET and Event-B to formalise and model the requirements for the ABZ 2024 Mechanical Lung Ventilator case study
- ► We formalised the Functional and Controller requirements in FRETish, and described the methodology we followed
- We used these requirements to construct a model of the ventilator system in Event-B, and captured many of the requirements
- ► The FRET and Event-B artefacts are available at: https://github.com/mariefarrell/abz2024 (link also included in the paper)