

# E4540\_\_HW1

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## Problem 1

### Step 1. Prepare the data

```
np <- import("numpy")
npfile <- np$load("boston-full.npz")
data.train <- npfile$f[["Xtrain"]]
data.test <- npfile$f[["Xtest"]]
data.train[,14] = 1
```

### Step 2. Simulation

Calculate the average MSE of 1000 simulations. For each simulation, randomly pick 100 vector pairs to calculate the MSE (1 from Xtrain, 1 from Xtest) while make sure  $|x^T y| > 1$ .

```
set.seed(1)
vlen = 16
n.simu = 1000
n.pair = 100
n.feature = c(1, 2, 4, 6, 8, 10, 12, 14)
ran_dot <- function(k, G, v1, v2) {
  n.rows = sample(c(1:vlen), n.feature[k], replace = F) # randomly pick m features
  return((v1 %*% v2 - t((G[n.rows,] * (1/sqrt(n.feature[k]))) %*% t(t(v1))) %*% ((G[n.rows,] * (1/sqrt(n.feature[k]))))
})
res = tibble(IID = rep(0, length(n.feature)),
             CIRC = rep(0, length(n.feature)),
             GORT = rep(0, length(n.feature)),
             HD = rep(0, length(n.feature)),
             KAC = rep(0, length(n.feature)))

for (i in 1:n.simu) {
  # unstructured Gaussian matrices
  IID = matrix(rnorm(vlen*vlen), nrow = vlen, ncol = vlen)

  # circulant Gaussian matrices
  CIRC = matrix(nrow = vlen, ncol = vlen)
  tmp = rnorm(vlen)
  for (m in 1:vlen) CIRC[m, ] = c(tmp[m:vlen], tmp[-(m:vlen)])

  # Gaussian orthogonal matrices
  GORT = matrix(rnorm(vlen*vlen), nrow = vlen, ncol = vlen)
  for (m in 2:nrow(GORT)) {
    tmp = GORT[m,]
    for (n in 1:(m - 1)) {
      GORT[m,] = GORT[m,] - project(tmp ~ GORT[n,], coefficients = F)
    }
  }
}
```

```

}

# random Hadamard matrices with 3 HD blocks
had = hadamard(vlen)
HD = had %*% diag(sample(c(-1, 1), vlen, replace = T)) %*% had %*% diag(sample(c(-1, 1), vlen, replace = T))

# Kac's random walk matrices given random rotation
KAC = diag(rep(1, vlen))
for (m in 1:vlen) {
  istar = sample(c(1:vlen), 1)
  jstar = sample(c(1:vlen), 1)
  theta = runif(1, min = 0, max = 2*pi)
  G = diag(rep(1, vlen))

  G[istar, istar] = cos(theta)
  G[istar, jstar] = sin(theta)
  G[jstar, istar] = -sin(theta)
  G[jstar, jstar] = cos(theta)
  KAC = KAC %*% G
}
KAC = KAC * sqrt(vlen)

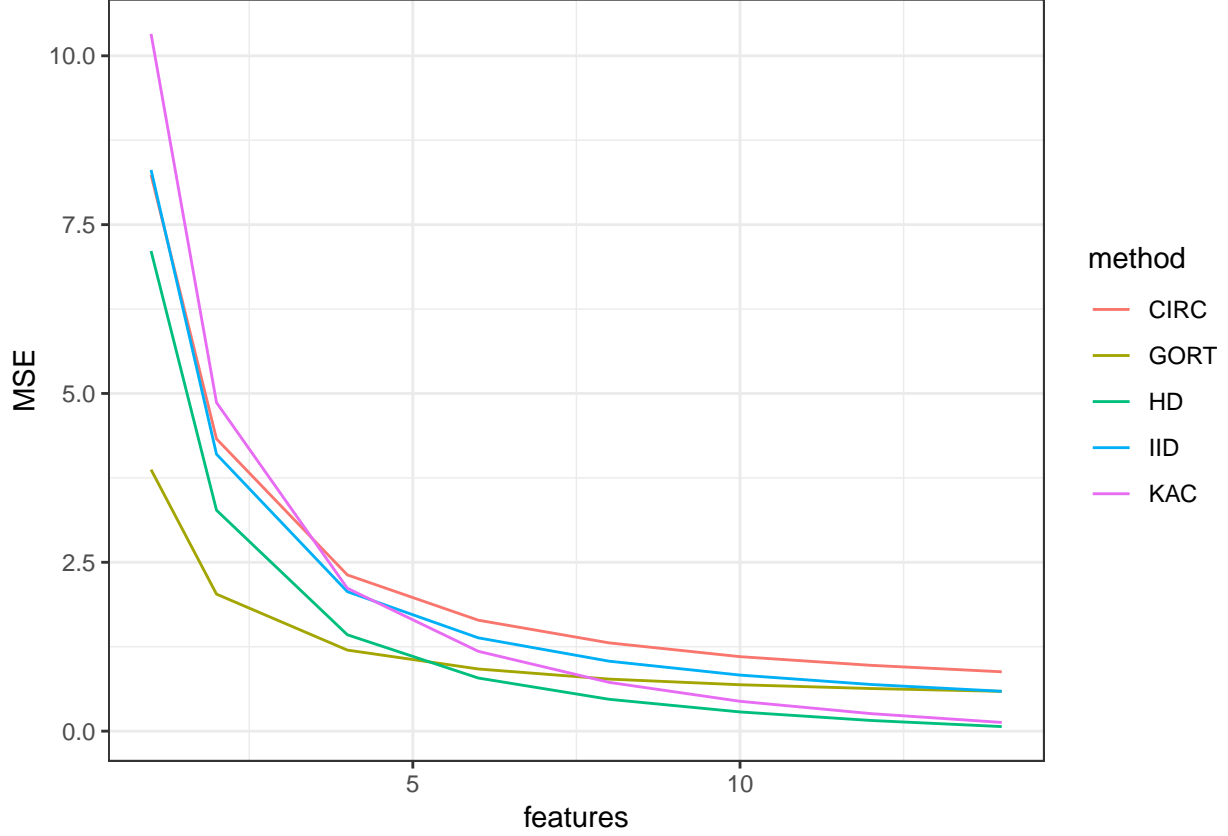
MSE = tibble(IID = rep(0, length(n.feature)),
              CIRC = rep(0, length(n.feature)),
              GORT = rep(0, length(n.feature)),
              HD = rep(0, length(n.feature)),
              KAC = rep(0, length(n.feature)))
for (j in 1:n.pair) {
  # randomly choose two vectors and apply some mechanism to make sure |xy| > 1
  v1 = data.train[sample(c(1:nrow(data.train)), 1), ]
  v2 = data.test[sample(c(1:nrow(data.test)), 1), ]
  if ((v1 %*% v2 >= 0) & (v1 %*% v2 < 1)) v2[14] = 1
  else if ((v1 %*% v2 < 0) & (v1 %*% v2 > -1)) v2[14] = -1

  for (k in 1:length(n.feature)) {

    MSE$IID[k] = MSE$IID[k] + ran_dot(k, IID, v1, v2)
    MSE$CIRC[k] = MSE$CIRC[k] + ran_dot(k, CIRC, v1, v2)
    MSE$GORT[k] = MSE$GORT[k] + ran_dot(k, GORT, v1, v2)
    MSE$HD[k] = MSE$HD[k] + ran_dot(k, HD, v1, v2)
    MSE$KAC[k] = MSE$KAC[k] + ran_dot(k, KAC, v1, v2)
  }
}
res = res + MSE / n.pair
}
res = res / n.simu

res %>%
  mutate(features = n.feature) %>%
  gather(key = method, value = MSE, IID:KAC) %>%
  ggplot(aes(x = features, y = MSE, group = method, col = method)) +
  geom_line()

```



## Conclusions

Comparing these 4 methods against the unstructured Gaussian matrices (IID, blue line), we can see that

- when number of features is small, Gaussian orthogonal matrices (GORT) are the best
- when number of features is large, random rotation matrices (KAC) and random Hadamard matrices with three HD blocks (HD) performs the best

## Problem 2

### Theory

For nonisotropic Gaussian kernels:

$$K(x, y) = \exp\left\{-\frac{\tau^T Q \tau}{2}\right\} = \int_{\mathbb{R}^d} p(\omega) \cos(\omega^T \tau) d\omega$$

$$p(\omega) = \frac{1}{\sqrt{2\pi} \cdot \det(Q)} \exp\left\{-\frac{\omega^T Q^{-1} \omega}{2}\right\}$$

where  $Q = VV^T, V \in \mathbb{R}^{d \times N}$ .

## Simulation

$$\begin{aligned}
\hat{K}(x, y) &= \frac{1}{m} \sum_{i=1}^m \cos(\omega_i^T (x - y)) \\
&= \frac{1}{m} \sum_{i=1}^m \cos(\omega_i^T x - \omega_i^T y) \\
&= \frac{1}{m} \sum_{i=1}^m (\cos \omega_i^T x \cdot \cos \omega_i^T y + \sin \omega_i^T x \cdot \sin \omega_i^T y) \\
&= \langle \phi(x), \phi(y) \rangle
\end{aligned}$$

$$\phi(x) = \frac{1}{\sqrt{m}} \begin{pmatrix} \cos(Gx) \\ \sin(Gx) \end{pmatrix}, G = \begin{pmatrix} \omega_1^T \\ \omega_2^T \\ \vdots \\ \omega_m^T \end{pmatrix}, \text{ where } \langle \omega_i, \omega_j \rangle = 0, \forall i \neq j$$

```

res_K = tibble(GORT = rep(0, length(n.feature)),
               IID_kernel = rep(0, length(n.feature)),
               GORT_kernel = rep(0, length(n.feature)))
ran_K_dot <- function(k, Q, v1, v2) {
  G = Q[sample(c(1:vlen), k, replace = F),] # G with randomly generated m features
  return((v1 %*% v2 - t(rbind(cos(G %*% t(t(v1))), sin(G %*% t(t(v1))))) %*% rbind(cos(G %*% t(t(v2))),
  })

for (i in 1:n.simu) {
  # construct Q
  V = matrix(rnorm(vlen * sample(100, 1)), nrow = vlen)
  Q = V %*% t(V)

  # Gaussian orthogonal matrices
  IID = matrix(rnorm(vlen*vlen), nrow = vlen, ncol = vlen)
  GORT = IID
  for (m in 2:nrow(GORT)) {
    tmp = GORT[m,]
    for (n in 1:(m - 1)) {
      GORT[m,] = GORT[m,] - project(tmp ~ GORT[n,], coefficients = F)
    }
  }

  MSE_K = tibble(GORT = rep(0, length(n.feature)),
                  IID_kernel = rep(0, length(n.feature)),
                  GORT_kernel = rep(0, length(n.feature)))
  for (j in 1:n.pair) {
    # randomly choose two vectors and apply some mechanism to make sure |xy| > 1
    v1 = data.train[sample(c(1:nrow(data.train)), 1), ]
    v2 = data.test[sample(c(1:nrow(data.test)), 1), ]
    if ((v1 %*% v2 >= 0) & (v1 %*% v2 < 1)) v2[14] = 1
    else if ((v1 %*% v2 < 0) & (v1 %*% v2 > -1)) v2[14] = -1

    for (k in 1:length(n.feature)) {
      MSE_K$GORT[k] = MSE$GORT[k] + ran_dot(k, GORT, v1, v2)
      MSE_K$IID_kernel[k] = MSE_K$IID_kernel[k] + ran_K_dot(k, IID, v1, v2)
    }
  }
}

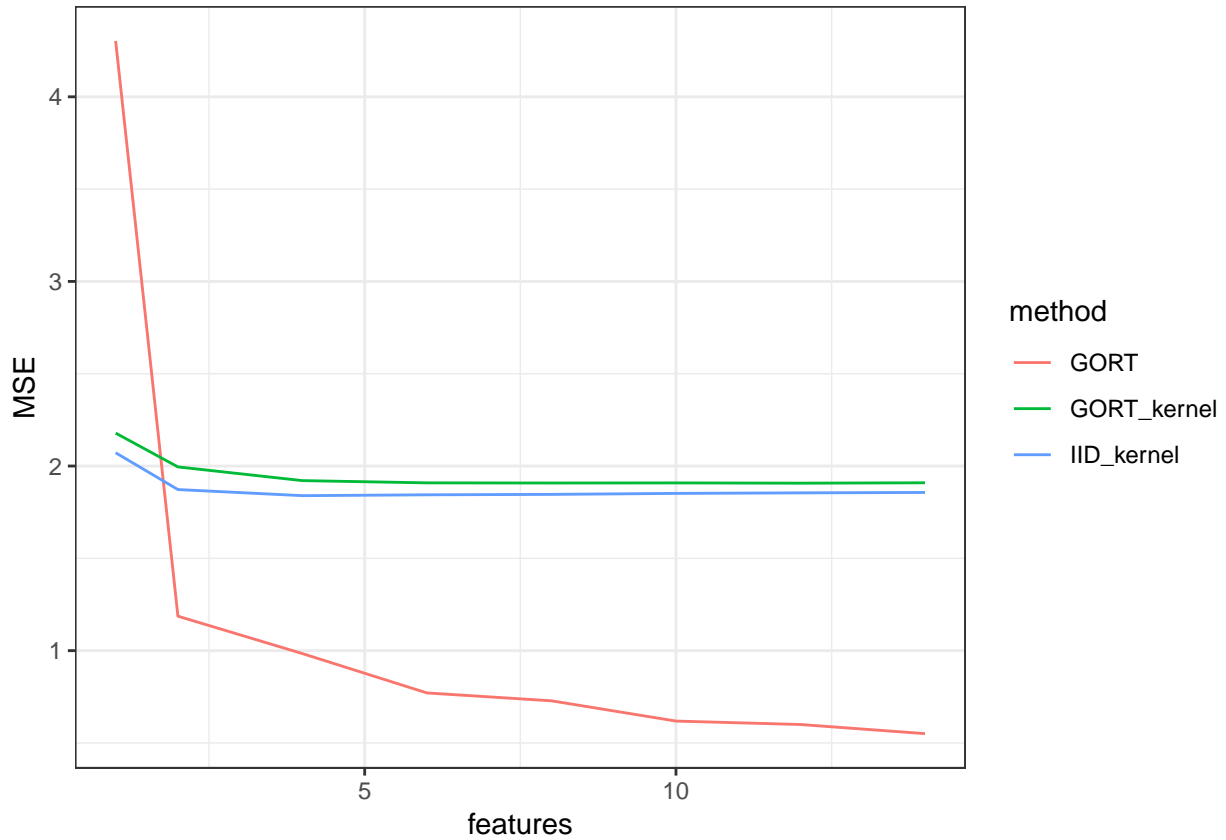
```

```

    MSE_K$GORT_kernel[k] = MSE_K$GORT_kernel[k] + ran_K_dot(k, GORT, v1, v2)
  }
}
res_K = res_K + MSE_K / n.pair
}
res_K = res_K / n.simu

res_K %>%
  mutate(features = n.feature) %>%
  gather(key = method, value = MSE, GORT:GORT_kernel) %>%
  ggplot(aes(x = features, y = MSE, group = method, col = method)) +
  geom_line()

```



## Conclusion

By comparing unstructured Gaussian kernels (IID\_kernel), Gaussian orthogonal kernel (GORT\_kernel) and Gaussian orthogonal matrices (GORT), we can see that:

- the estimation of IID\_kernel and GORT\_kernel are steadier than Gaussian orthogonal matrices
- when number of features is extremely small, kernel-based methods are better
- when number of features is large, Gaussian orthogonal matrices are better

## Time complexity

- The time complexity for unstructured Gaussian kernels is  $O(d) = d \cdot \log d$

- The time complexity for Gaussian orthogonal kernels is  $O(d) = d^3$ , because it includes Gram-Schmidt orthogonalization
- The time complexity for GORT is  $O(d) = d^3$ , because it includes Gram-Schmidt orthogonalization