

## Probabilistic Models

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### Conditional Probability

**Definition 1** (Conditional Probability). The *conditional probability* of an event  $A$ , given an event  $B$  with  $\mathbf{P}(B) > 0$ , is defined by

$$\mathbf{P}(A|B) = \frac{\mathbf{P}(A \cap B)}{\mathbf{P}(B)},$$

and specifies a new probability law on the same sample space  $\Omega$ . In particular, all properties of probability laws remain valid for conditional probability laws.

**Remark 1.** If the possible outcomes are finitely many and equally likely, then

$$\mathbf{P}(A|B) = \frac{\text{number of elements of } A \cap B}{\text{number of elements of } B}$$

**Definition 2** (Multiplication Rule). Assuming that all the conditioning events have positive probability, we have

$$\mathbf{P}(\cap_{i=1}^n A_i) = \mathbf{P}(A_1) \mathbf{P}(A_2|A_1) \mathbf{P}(A_3|A_1 \cap A_2) \cdots \mathbf{P}(A_n|\cap_{i=1}^{n-1} A_i)$$

### Total probability theorem and Baye's rule

**Definition 3** (Total Probability Theorem). Let  $A_1, A_2, \dots, A_n$  be disjoint events that form a partition of the sample space and  $\mathbf{P}(A_i) > 0$ , for all  $i$ . Then, for any event  $B$ , we have

$$\begin{aligned} \mathbf{P}(B) &= \mathbf{P}(A_1 \cap B) + \cdots + \mathbf{P}(A_n \cap B) \\ &= \mathbf{P}(A_1) \mathbf{P}(B|A_1) + \cdots + \mathbf{P}(A_n) \mathbf{P}(B|A_n) \end{aligned}$$

**Definition 4** (Baye's Rule). Let  $A_1, A_2, \dots, A_n$  be disjoint events that form a partition of the sample space, and assume that  $\mathbf{P}(A_i) > 0$ , for all  $i$ . Then, for any event  $B$  such that  $\mathbf{P}(B) > 0$ , we have

$$\begin{aligned} \mathbf{P}(A_i|B) &= \frac{\mathbf{P}(A_i) \mathbf{P}(B|A_i)}{\mathbf{P}(B)} \\ &= \frac{\mathbf{P}(A_i) \mathbf{P}(B|A_i)}{\mathbf{P}(A_1) \mathbf{P}(B|A_1) + \cdots + \mathbf{P}(A_n) \mathbf{P}(B|A_n)} \end{aligned}$$

### Independence

**Definition 5** (Independence). Two events  $A$  and  $B$  are said to be *independent* if

$$\mathbf{P}(A \cap B) = \mathbf{P}(A) \mathbf{P}(B)$$

**Remark 2.** If  $A, B$  are independent, then  $A, B^c$  and  $A^c, B^c$  are also independent.

### *Conditional Independence*

**Definition 6** (Conditional Independence). Two events  $A$  and  $B$  are said to be *conditionally independent* given another event  $C$  with  $\mathbf{P}(C) > 0$ , if

$$\mathbf{P}(A \cap B | C) = \mathbf{P}(A | C) \mathbf{P}(B | C)$$

**Remark 3.** If  $\mathbf{P}(B \cap C) > 0$ , conditional independence is equivalent to the condition

$$\mathbf{P}(A | B \cap C) = \mathbf{P}(A | C)$$

**Remark 4.** Independence does not imply conditional independence, and vice versa.

### *Independence of a Collection of Events*

**Definition 7** (Independence of Several Events). We say that the events  $A_1, A_2, \dots, A_n$  are *independent* if

$$\mathbf{P}\left(\bigcap_{i \in S} A_i\right) = \prod_{i \in S} \mathbf{P}(A_i) \quad \text{for every subset } S \text{ of } \{1, 2, \dots, n\}.$$