

# VAMSHI NARAYANA BABU

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## Education

### Arizona State University

Expected Graduation: May 2026

Master's in Robotics and Autonomous Systems, GPA:3.67/4.0

AZ, USA

- Courses: Python, Mechatronics, Kinematics and dynamics, Robotics -2 (UAV).

### National Institute of Technology Karnataka

May 2022

Bachelor's, Electronics and Communication Engineering

KA, India

- Courses: Control systems, Microprocessors, Image and Video Processing, Internet of Things, C/C++.

## Technical Skills

**Languages:** Java, Python, C++, C, SQL, MATLAB, PLC Programming.

**Robotics and Simulation:** ROS/ROS2, Gazebo, MuJoCo, Sensor Fusion, SLAM, OpenCV, OCR, Pytorch, Pydobot.

**Developer Tools:** Linux, Github, Postman, Dbeaver, AWS, Azure, Docker, Kubernetes, Maven, Simulink.

**Libraries/Frameworks:** REST APIs, Springboot, NodeJs, Redis, Kafka, RabbitMQ, MSSQL, Django, Tensorflow.

## Work Experience

### Addverb Technologies Ltd.

Aug 2022 – Aug 2023

Graduate Engineer Trainee - Robotics Software Engineer

Noida, India

- Built warehouse automation solution integrating AMRs, ASRS, WCS in **Java, Spring Boot, MSSQL**, enhancing inventory tracking, task scheduling and robot fleet coordination while efficiently processing **10K+** orders daily.
- Designed a DWS system with **Springboot and REST APIs**, increasing inbound workflow automation by **80%**.
- Integrated **TCP/IP and PLC programming**, reducing signal transmission latency by **20%** for robot communication.
- Refactored WCS scheduling with **Python** and **Django** fixing **70+** bugs and optimizing storage by **35%** in warehouse.
- Optimized messaging with **Redis, Kafka, RabbitMQ**, improving coordination by **15%** between Zippy and SortIE.

### OpenNets

May 2021 – Jul 2021

Full-Stack Developer Intern

Bengaluru, India

- Created a network simulator with **Mininet, Node.js, and MongoDB** to support 10+ network topologies, enabling traffic testing and performance evaluation under various configurations, cutting down configuration errors by **30%**.
- Utilized **AngularJS** to develop UI responsible for editing topology settings, contributing to **30%** of overall UI coverage.
- Collaborated with engineers using **Git** and **Agile** methods to deliver iterative improvements aligned with user needs.

## Projects

### UAV Autonomous Landing & Color-Based Navigation

Jan 2025 - Present

- Designed Motor mixing Algorithm utilizing **OpenCV, Python, Gazebo, MATLAB** for motion control, increasing stability, adaptive control, precision and dynamic path optimization achieving **97%** landing accuracy in **50+** test flights.

### Path planning for Maze Solving with MyCobot Pro 600

Aug 2024 - Nov 2024

- Programmed a robot for autonomous navigation, motion planning and path optimization, incorporating inverse kinematics with **Python, OpenCV, MATLAB Simulink, ROS2**, reducing maze-solving time by **40%**.

### Performance enhancement of underwater communication

Jan 2022 - May 2022

- Developed a deep learning model with **PyTorch, MATLAB, NumPy**, reaching **92%** accuracy and improving classification reliability, feature extraction, signal processing efficiency, and decision-making accuracy by **30%**.

### Image Restoration of Natural Images

Aug 2021 - Nov 2021

- Implemented a **PyTorch-based CNN encoder-decoder** network with **ORSNet** to restore rain-affected images, achieving **90%** restoration accuracy on a dataset of **10,000+** natural images with enhanced texture preservation.

## Achievements

### Runner-up, Devils Invent Hackathon — Sponsored by Los Alamos National Laboratory (LANL)

Mar 2025

- Automated MiniFlow Ion Cell unpacking system with Dobot Magician Lite, AI, **Python** and pydobot for more efficiency.

### Visual AI Hackathon Winner — Sponsored by Voxel51

Feb 2025

- Led the development of an OCR-based AI model for food safety using **Python, OCR, Pytesseract**.

### Aerospace Factory Automation Devils Invent Hackathon — Sponsored by Honeywell Aerospace

Apr 2025

- Engineered a blockchain-based supply chain platform using React.js and smart contracts for traceability and compliance.