### Assignment 2 by 160050064 and 160050090

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All Primitives like ellipsoids (sphere is a special case of cones), cones (cylinder is a special case of cones), cuboids, discs and quads are implemented in primitive.cpp and primitive.hpp

All the above mentioned primitives are rendered using GL\_TRIANGLES.

Hierarchical modelling is implemented in hierarchy node.cpp and hierarchy node.hpp

The main code is implemented in model.cpp and model.hpp

All the key bindings are implemented in gl framework.cpp and gl framework.hpp

#### **Control of Units**

- The default model selected is the humanoid clown.
- "M" choose the model by typing the input in terminal.

  Model 1 is the humanoid clown, Model 2 is the box, Model 3 is R2D2
- "C" choose the limb to rotate by typing in the terminal
- "R" rotate the selected limb about z axis
- "Y" rotate the selected limb about z axis
- "T" rotate the selected limb about x axis
- "G" rotate the selected limb about x axis
- "F" rotate the selected limb about y axis
- "H" rotate the selected limb about y axis

To rotate about the centroids choose the respective center limb.

Center limbs:

Model1 Torso

Model2 There is only one limb and it is selected always

Model3 Torso

## **Hierarchy Tree for Model 1**

### Key for body parts:

- 0 LowerTorso
- 1 UpperTorso
- 2 Neck
- 3 Head
- 4 RShoulder
- 5 LShoulder
- 6 RUpperArm
- 7 LUpperArm
- 8 RElbow
- 9 LElbow
- 10 RLowerArm
- 11 LLowerArm
- 12 Hip
- 13 RLegShoulder
- 14 LLegShoulder
- 15 RUpperLeg
- 16 LUpperLeg
- 17 RKnee
- 18 LKnee
- 19 RLowerLeg
- 20 LLowerLeg

Parent	Child
NULL	0
0	1
0	2
2	3
0	4
0	5
4	6
5	7
6	8
7	9
8	10

9	11
0	12
12	13
12	14
13	15
14	16
15	17
16	18
17	19
18	20

# **Hierarchy Tree for Model 3**

# Key for body parts:

_	_
0	Torso
1	Head
2	Bottom Leg
3	Bottom Feet
4	RShoulder
5	LShoulder
6	RArm
7	LArm
8	RHand
9	LHand
10	RArm-Disc
11	LArm-Disc
12	Torso-Bottom-Disk
13	Eye-Scanner

Eye-Scanner-Disc

Parent	Child
NULL	0
0	1
0	2
2	3
0	4
0	5
4	6
5	7
6	8

14

7	9
4	10
5	11
0	12
1	13
13	14