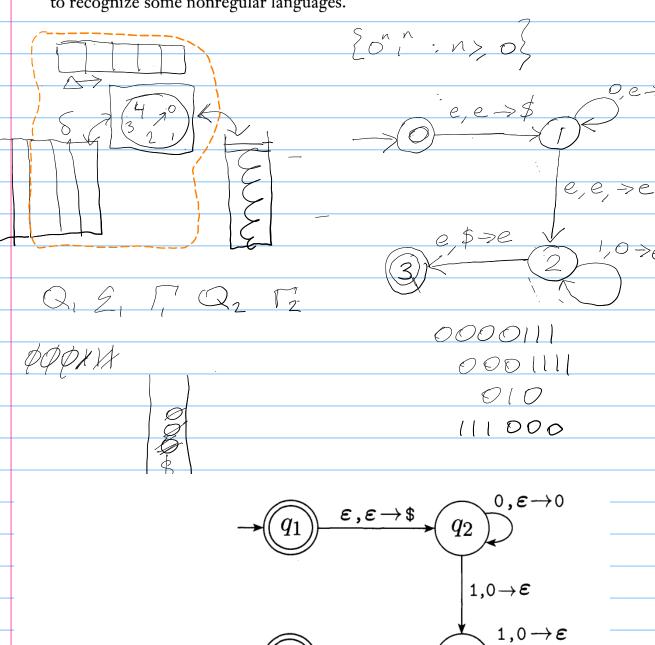
## 2.2

### **PUSHDOWN AUTOMATA**

In this section we introduce a new type of computational model called *pushdown automata*. These automata are like nondeterministic finite automata but have an extra component called a *stack*. The stack provides additional memory beyond the finite amount available in the control. The stack allows pushdown automata to recognize some nonregular languages.



## **FIGURE 2.15**

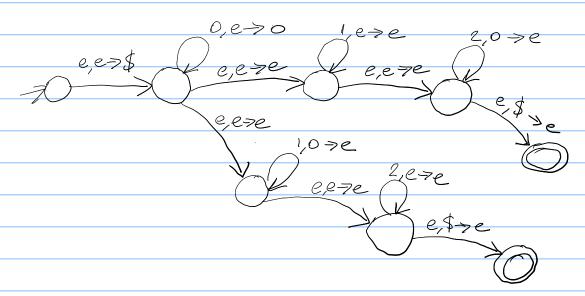
State diagram for the PDA  $M_1$  that recognizes  $\{0^n 1^n | n \ge 0\}$ 

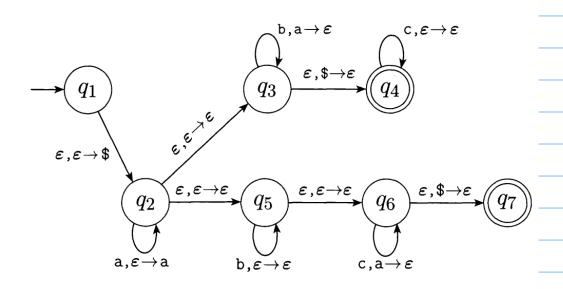
# This is a PDA to recognise #  $\{0^{\times}1^{y}2^{z} : x,y,z \ge 0, x=y \text{ or } x=z\}.$ 

00011122

000 XX 222







# FIGURE 2.17 State diagram for PDA $M_2$ that recognizes $\{\mathbf{a}^i\mathbf{b}^j\mathbf{c}^k|\ i,j,k\geq 0\ \text{and}\ i=j\ \text{or}\ i=k\}$

 $\{0^n1^n, n\geq 0\}$ Th1

 $\{0^{n}1^{x}2^{n}, x, n \ge 0\}$ 

 $\{a^xb^yc^z: x,y,z \ge 0, x=y \text{ or } x=z\}$ 

 $\{wxw^R, w \in \{0, 1\}^*\}$ 

to create during Friday morning (7th February 2025)

{xwyw2: x,y,z,w ∈ {a,b3\*, |w|>0}

L5 {w: we {0,1}t, whas twice as many of

to create during Friday afternoon (7th February 2025)

 $L46 \{ 0^{2n} | n > 0 \}$ 

L4c {w: we {0,1}th, what an equal number of 0s as 1s}

 $\{u111v : u,v \in \{0, 1\}^*, |u| = |v|\}$ L6

L= {ww : we {0,1}\*}. Prove L is c.f.

Proof

We will prove L is c.f. by constructing a

PDA M that recognises L. Let M be defined as

e,e >\$\frac{0}{1,e^{\frac{7}{1}}}

e,e^{\frac{7}{2}}

\text{0,0} \text{2.6}

\text{1,1} \text{7.6}

PDAM recognises L, therefore L is c.f.

L= {wxw: we {0,1}\*}. Prove L is c.f.

Proof

We will prove L is c.f. by constructing a

PDA M that recognises L. Let M be defined as

e,e =>\$

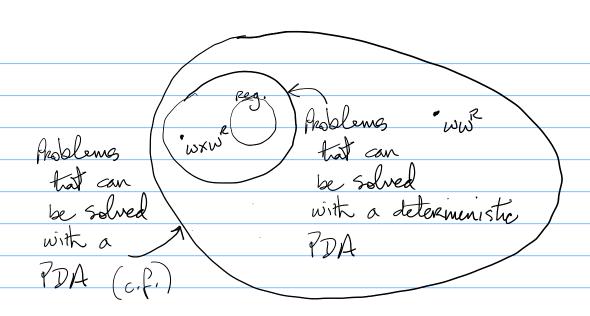
0,e =>0

x,e =>e

0,0 =>e

0,0 =>e

PDAM recognises L, therefore L is c.f.



### FORMAL DEFINITION OF A PUSHDOWN AUTOMATON

The formal definition of a pushdown automaton is similar to that of a finite automaton, except for the stack. The stack is a device containing symbols drawn from some alphabet. The machine may use different alphabets for its input and its stack, so now we specify both an input alphabet  $\Sigma$  and a stack alphabet  $\Gamma$ .

At the heart of any formal definition of an automaton is the transition function, which describes its behavior. Recall that  $\Sigma_{\varepsilon} = \Sigma \cup \{\varepsilon\}$  and  $\Gamma_{\varepsilon} = \Gamma \cup \{\varepsilon\}$ . The domain of the transition function is  $Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon}$ . Thus the current state, next input symbol read, and top symbol of the stack determine the next move of a pushdown automaton. Either symbol may be  $\varepsilon$ , causing the machine to move without reading a symbol from the input or without reading a symbol from the stack.

For the range of the transition function we need to consider what to allow the automaton to do when it is in a particular situation. It may enter some new state and possibly write a symbol on the top of the stack. The function  $\delta$ can indicate this action by returning a member of Q together with a member of  $\Gamma_{\varepsilon}$ , that is, a member of  $Q \times \Gamma_{\varepsilon}$ . Because we allow nondeterminism in this model, a situation may have several legal next moves. The transition function incorporates nondeterminism in the usual way, by returning a set of members of  $Q \times \Gamma_{\varepsilon}$ , that is, a member of  $\mathcal{P}(Q \times \Gamma_{\varepsilon})$ . Putting it all together, our transition function  $\delta$  takes the form  $\delta \colon Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon} \longrightarrow \mathcal{P}(Q \times \Gamma_{\varepsilon})$ .

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2xre

### DEFINITION 2.13

A *pushdown automaton* is a 6-tuple  $(Q, \Sigma, \Gamma, \delta, q_0, F)$ , where  $Q, \Sigma$ ,  $\Gamma$ , and F are all finite sets, and

- 1. Q is the set of states,
- 2.  $\Sigma$  is the input alphabet,
- 3.  $\Gamma$  is the stack alphabet,
- **4.**  $\delta: Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon} \longrightarrow \mathcal{P}(Q \times \Gamma_{\varepsilon})$  is the transition function,
- 5.  $q_0 \in Q$  is the start state, and
- **6.**  $F \subseteq Q$  is the set of accept states.

Formal definition of a PDA computation (what is the mathematical definition of whether a PDA accepts a word or not).

A pushdown automaton  $M=(Q,\Sigma,\Gamma,\delta,q_0,F)$  computes as follows. It accepts input w if w can be written as  $w=w_1w_2\cdots w_m$ , where each  $w_i\in\Sigma_\varepsilon$  and sequences of states  $r_0,r_1,\ldots,r_m\in Q$  and strings  $s_0,s_1,\ldots,s_m\in\Gamma^*$  exist that satisfy the following three conditions. The strings  $s_i$  represent the sequence of stack contents that M has on the accepting branch of the computation.

- 1.  $r_0 = q_0$  and  $s_0 = \varepsilon$ . This condition signifies that M starts out properly, in the start state and with an empty stack.
- **2.** For  $i=0,\ldots,m-1$ , we have  $(r_{i+1},b)\in \delta(r_i,w_{i+1},a)$ , where  $s_i=at$  and  $s_{i+1}=bt$  for some  $a,b\in \Gamma_{\varepsilon}$  and  $t\in \Gamma^*$ . This condition states that M moves properly according to the state, stack, and next input symbol.
- 3.  $r_m \in F$ . This condition states that an accept state occurs at the input end.

