

CS608

Software Testing

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CS608

Testing Object-Oriented Software in More Detail

(Essentials of Software Testing, Chapter 9, Sections 9.4-9.7)

ADVANCED OO TESTING

Overview of Advanced OO Testing

- Inheritance Testing
- UML-Based Testing
- Built-In Testing
- State-Based Testing

INHERITANCE TESTING

Inheritance Testing

- Addresses the Inheritance Fault Model
- Verify classes within an inheritance hierarchy behave correctly
- Simple form verifies that inherited superclass methods continue to work correctly in the context of the subclass
- This can be extended to ensure that all the methods in an entire inheritance tree continue to operate correctly

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- Simple form verifies that inherited superclass methods continue to work correctly in the context of the subclass
- This can be extended to ensure that all the methods in an entire inheritance tree continue to operate correctly
- **Fundamentally a test automation problem:**
 - **How to run XXXTest designed to run against class XXX against a subclass YYY**
- So we will address further under test automation

Note on Test Case Selection: Liskov Substitution Principle

- Not all subclasses fully support their superclass behaviour

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- If a subclass is fully substitutable, the superclass tests are executed against each subclass to verify that the subclasses work in superclass context
- If a subclass is **not** fully substitutable, then only a subset (and maybe none) of the superclass tests can be reused in the subclass inheritance test. Analysis must be performed to select the applicable tests. This analysis is made more difficult as the standard UML Class Diagram does not specify whether a subclass is fully substitutable or not.

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- Additional tests must be written to verify the extra subclass features – not really an inheritance test issue

UML-BASED TESTING

UML-Based Testing

- The UML (Unified Modelling Language) is the main analysis and design tool for object oriented software
- There are a large number of diagrams in UML 2.5
- Each of these is a potential source of information and test coverage items for the tester
- Each item on each diagram has a meaning: something to test
- Examples:
 - Class Diagram: relationships between classes and associated multiplicities (one-to-N)
 - Sequence Diagram, Activity Diagram, Interaction Overview Diagram: the interaction between classes and methods

UML-Based Testing

- **Class Diagrams:**
 - Method testing in class context
 - Inheritance testing
- **State Diagrams:**
 - State-based testing
- All of the other diagrams can also be used to generate tests
- Examples:
 - Class Diagram:
 - relationships between classes and associated multiplicities (e.g. 1-to-N)
 - Sequence Diagram, Activity Diagram, Interaction Overview Diagram:
 - the interaction between classes and methods

BUILT-IN TESTING (BIT)

Built-in Testing

- Encapsulation can make testing difficult, especially when trying to access the class attributes in order to verify the actual results match the expected results
 - We have used getters so far, but they are not always available
- Some solutions:
 - Use Java reflection to access private attributes at run-time
 - Use **assertions** for built-in testing (BIT)
 - Available in many languages
 - Referred to as **built-in tests** as the test assertions are built into the code, rather than being located in an external test class
- Example: `assert space>0;`

BIT Issues

- Can be very effective for ensuring that assumptions that the programmer has made are in fact true when required in the code
- Can be effective in verifying that **class invariants** are maintained by asserting them at the end of every method
- In simple terms, a class invariant is a property of a class which must hold true between API calls
 - It must be true when a public method is called
 - It must be true when a public method returns

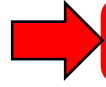
BIT Issues

- In Java, assertions can be turned on at runtime, so that during testing they are enabled, and in deployment they are disabled
- Less effective in replacing the usual unit tests, as often they need to refer to not only the **current** value of the method variables (attributes, parameters, and local variables) but also the **original** values when the method started execution
- Having the code keep copies of these values for testing can be very inefficient in terms of memory space and execution time. It also increases the effort required to code each method, and increases the chances of making a mistake

SpaceOrder with BIT

“safety
conditions”

Used for
class invariant



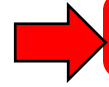
```
public class SpaceOrder {  
  
    boolean special;  
    boolean accept=false;  
    int acceptedSpace=0; // must always be in [0..1024]  
  
    public SpaceOrder(boolean isSpecial) {  
        special = isSpecial;  
        assert acceptedSpace >=0 && acceptedSpace <=1024;  
    }  
  
    public boolean getSpecial() {  
        return special;  
    }  
  
    public boolean acceptOrder(int space) {  
        assert acceptedSpace >=0 && acceptedSpace <=1024;  
        boolean status=true;  
        acceptedSpace = 0;  
        accept = false;  
        if (space<=0) {  
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        }  
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            accept = true;  
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        }  
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        return status;  
    }  
  
    public boolean getAccept() {  
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}
```

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Check
class invariant (end
of constructor)



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```

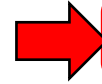
SpaceOrder with BIT

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Used for
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Check
class invariant

Check
class invariant
(start of method)



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SpaceOrder with BIT

“safety
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Used for
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Check
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Check
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(start of method)

Check
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```

Be Careful

- Sometime class invariants must be temporarily broken within a method
- And if you call a method from within that method...
- ...it will fail if it checks the invariant
- No real solution for manual BIT
- Except “be careful”
- Note: some formal methods provide solutions to this!

Verify acceptOrder() with BIT?

Check **acceptedSpace** is valid

Does not check **accept** or the
return value are correct

```
public boolean acceptOrder(int space) {  
    assert acceptedSpace >=0 && acceptedSpace <=1024;  
    boolean status=true;  
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    if (space<=0) {  
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    else if (space<=1024 && (space>=16 || special)) {  
        accept = true;  
        acceptedSpace = space;  
    }  
    // Check correct result here?  
    assert acceptedSpace >=0 && acceptedSpace <=1024;  
    return status;  
}
```

Verifying Functionality with BIT

- An assertion to verify that the method `acceptOrder()` has worked correctly cannot always be so easily implemented

- Line 29 checks that `acceptedSpace` is valid

```
// Check correct result here?  
assert acceptedSpace >=0 && acceptedSpace <=1024;  
return status;  
}
```

- But it does not check that the attribute `accept` or the return value is correct
- Requires access to the values of the **special** attribute and the **space** parameter when the method was entered
- These may have been changed during the method
- In this case they have not been modified, but a different algorithm or a fault in the code could have modified either of these

Saving Old Values

- As the values at the end of the method cannot be relied on to represent the values at the start of the method, copies need to be made at the start of the method
- In this simple code copies could be easily kept, but this would introduce the possibility of further faults
- And also, in general, complete copies of any referenced objects would be required: this is a non-trivial problem and often unrealistic to implement
- For example, if an array of Counters is passed as an input, then a copy of the entire array would need to be made, including copies of every Counter in the array

Results of Running EP Tests against SpaceOrder with BIT

```
PASSED: testConstructor("SpaceOrderTest T1", true, true, false)
PASSED: testConstructor("SpaceOrderTest T2", false, false, false)
PASSED: testAcceptOrder("SpaceOrderTest T3", true, 7, true, true)
PASSED: testAcceptOrder("SpaceOrderTest T4", false, 504, true, true)
PASSED: testAcceptOrder("SpaceOrderTest T5", false, 5000, true, false)
PASSED: testAcceptOrder("SpaceOrderTest T6", false, -5000, false, false)
```

```
=====
Command line suite
```

```
Total tests run: 6, Passes: 6, Failures: 0, Skips: 0
=====
```

```
public class SpaceOrder {
    boolean special;
    boolean accept=false;
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    }

    public boolean getSpecial() {
        return special;
    }

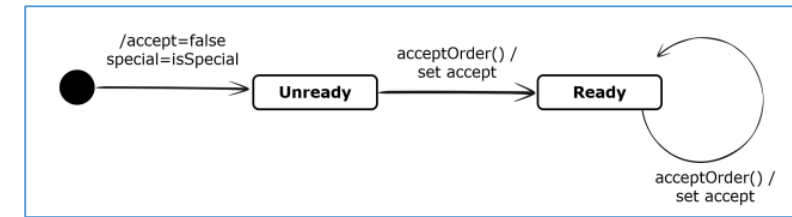
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        // Check correct result here?
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        return status;
    }

    public boolean getAccept() {
        return accept;
    }
}
```

- All the tests pass
- The correct values returned and verified in the EP tests
- All the assertions in the built-in tests have passed

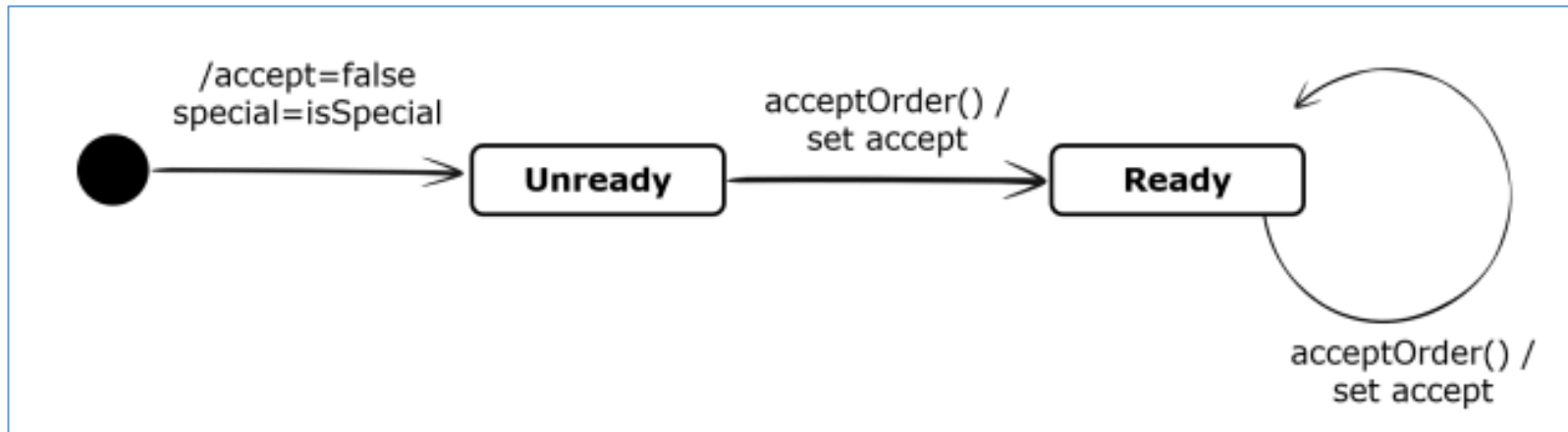
STATE-BASED TESTING

State-Based Testing



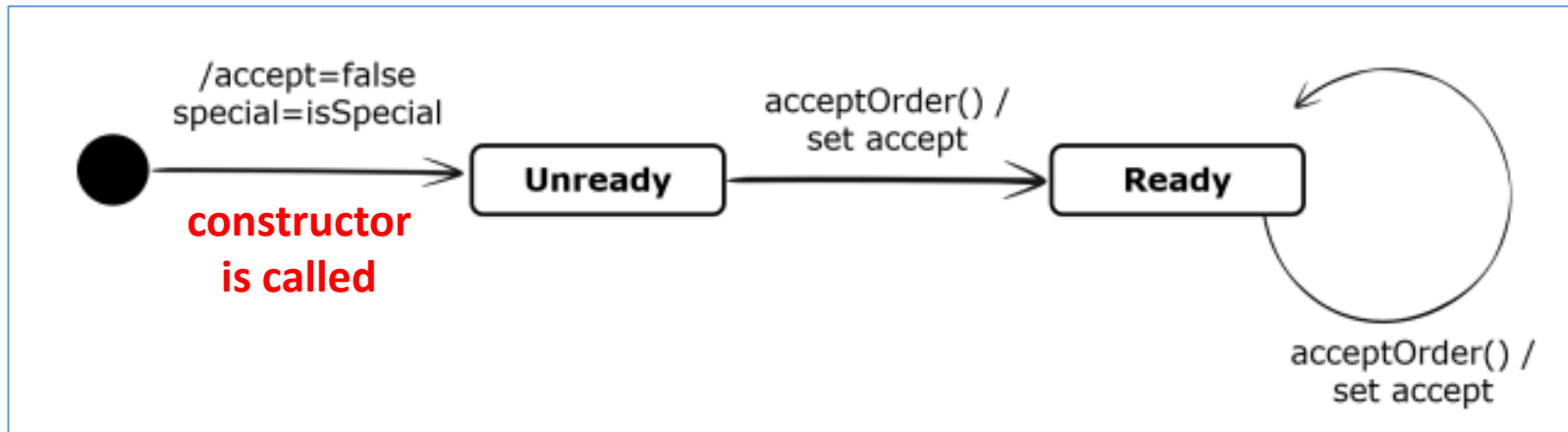
- This form of testing specifically addresses the class encapsulation/state fault model
- The purpose of state-based testing is to verify that a class behaves correctly with regards to its state specification (e.g. **UML State Machine Diagram**)
- A state diagram contains **states** and **transitions** between those states
- State-based testing verifies that the software transitions correctly between the states
- Not unique to OO – non-OO code can retain state between calls

Example State Diagram



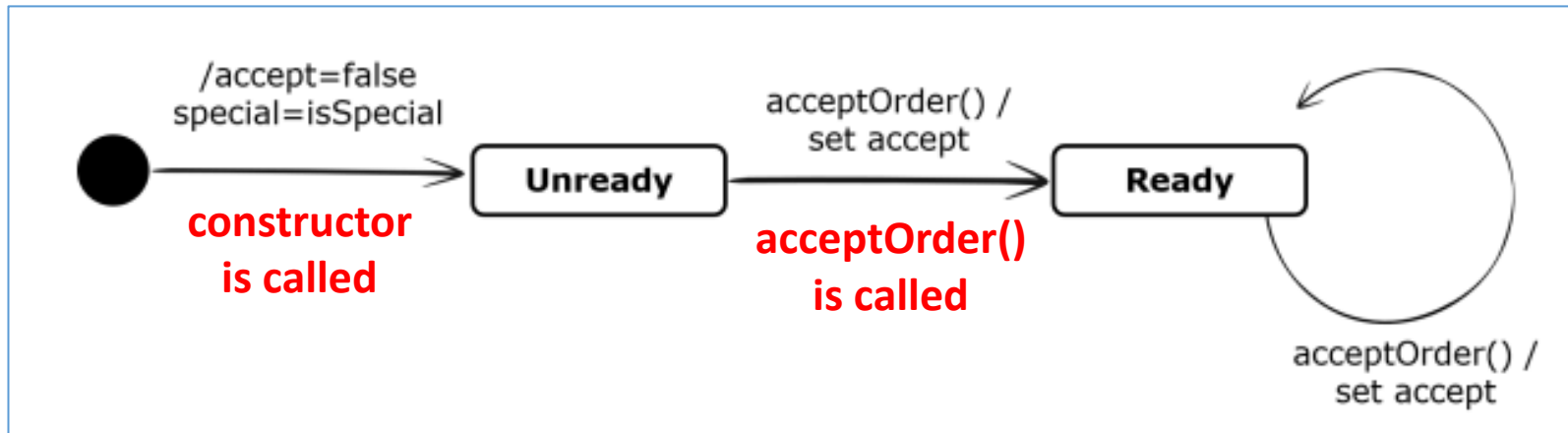
- Objects in the class can be in one of two states:
 1. Unready
 2. Ready
- This state will be represented in class attributes

Example State Diagram



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Example State Diagram



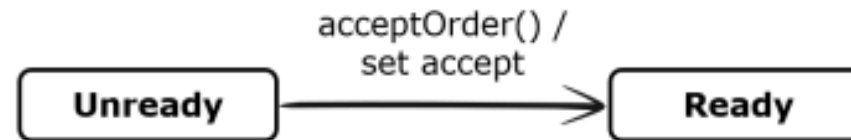
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 1. Unready
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Three Simple Test Strategies

- **All transitions** – every transition is verified at least once
- **All end-to-end paths** – every path from the start state to the end state is verified at least once. If there is no end state, which is common in software state diagrams, then every paths from the state to every *terminal state* (no outgoing transitions) can be used
- **All circuits** – every path that starts and ends in the same state is verified
- There are other more complex strategies also (see Binder)...

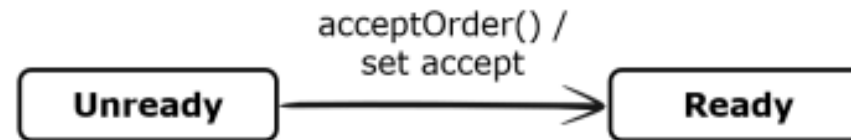
Transitions

- Each transition is specified by an event/activity pair:
 - The event which causes the transition
 - The accompanying action which should occur



Event / Action Pair

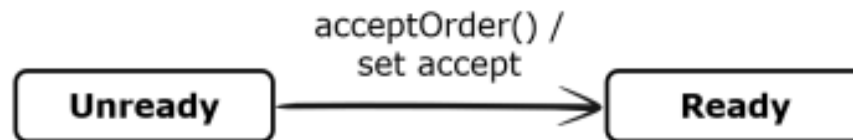
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- Event / Action
- Example:
 - event=**acceptOrder()**
 - action=**set accept** (to true or false as specified)

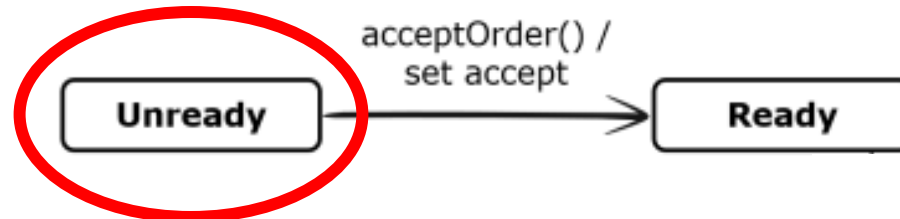
Checking a Transition

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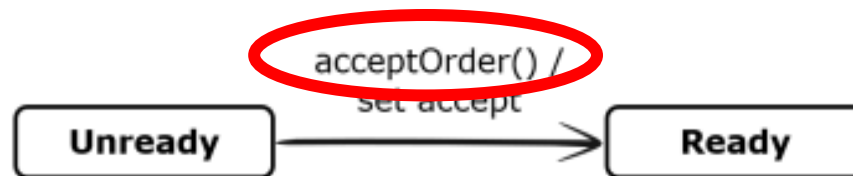
Checking a Transition

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 - Check that the software is in the correct start state (this may have already been done by the verification of the previous transition)



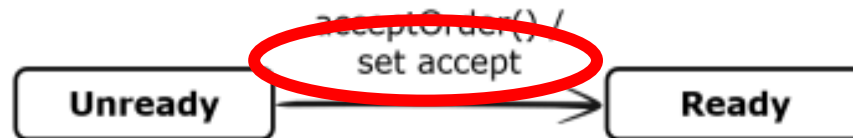
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 - Raise the event (method call)



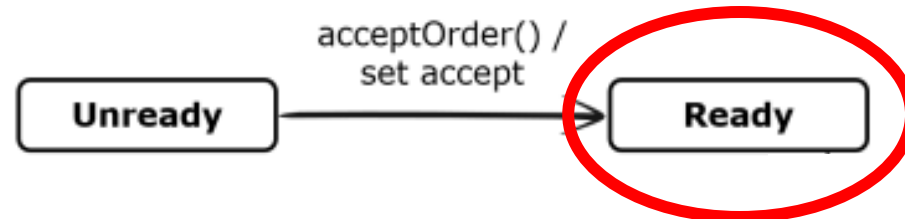
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 - Check that the specified activity has taken place correctly



Checking a Transition

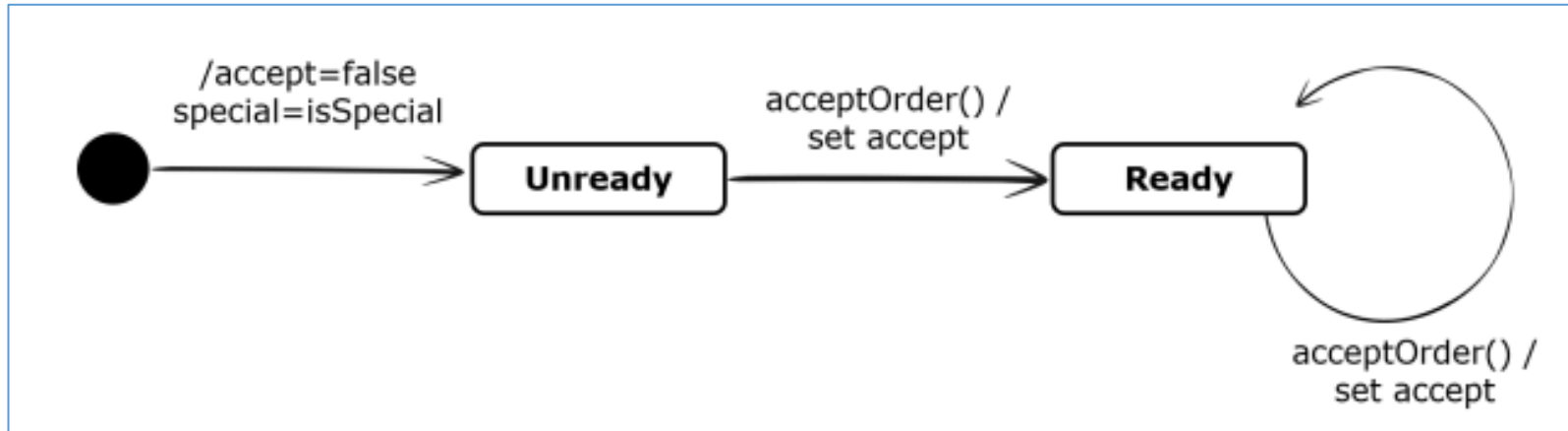
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- The correct operation of a transition is verified by:
 - Check that the software is in the correct start state (this may have already been done by the verification of the previous transition)
 - Raise the event (method call)
 - Check that the specified activity has taken place correctly
 - Checking that the software is in the correct end state



Checking a Transition

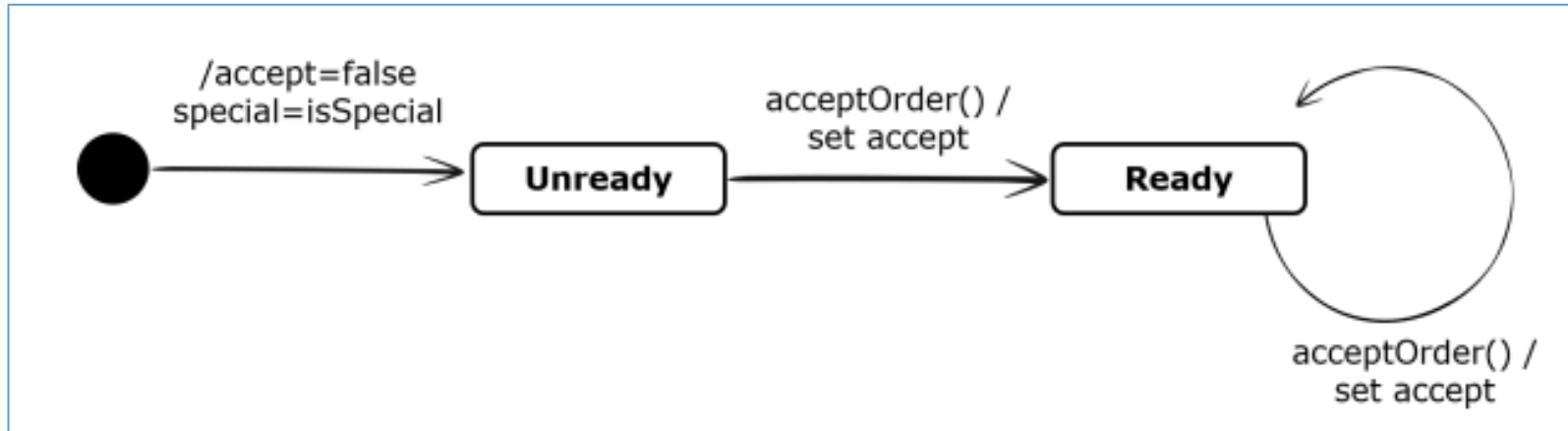
- Each transition is specified by an event/activity pair
- The correct operation of a transition is verified
- Not always possible to **fully** check that:
 - an object is in the correct state
 - or that the correct activity has taken place
- Design for Testability (DFT) issue
- May have to use a partial or “best-effort” check

Example: State Diagram for SpaceOrder



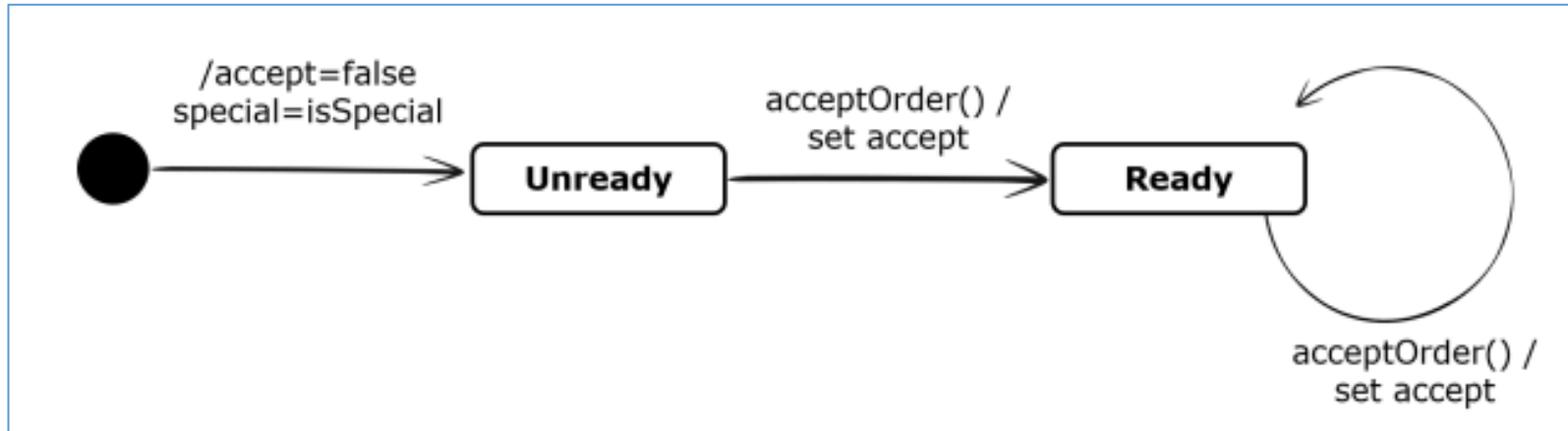
- Two states:
 - **Unready**
 - **Ready**

Example: State Diagram for SpaceOrder



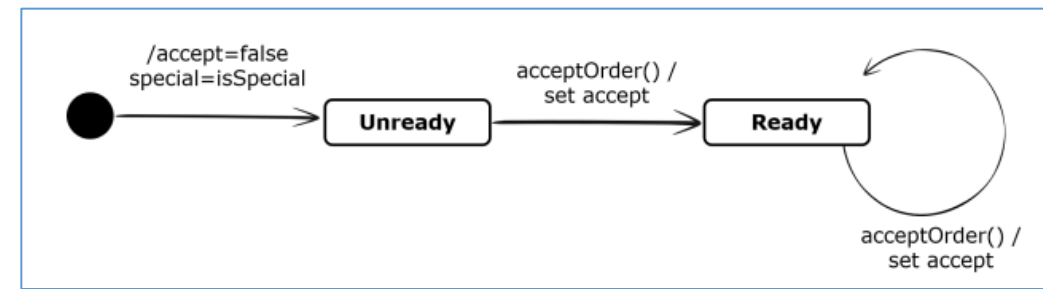
- Three (explicit) transitions:
 - **Constructor**
 - `acceptOrder()` in Unready state
 - `acceptOrder()` in Ready state

Example: State Diagram for SpaceOrder



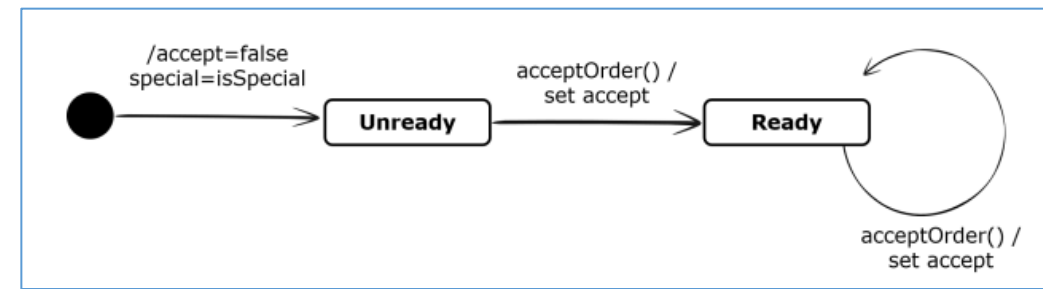
- Four (implicit) transitions – not shown on SD – should have no effect:
 - **getSpecial()** in Unready state
 - **setSpecial()** in Unready state
 - **getAccept()** in Unready state
 - **getAccept()** in Ready state

Example: Transitions for SpaceOrder



Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

Example: Transitions for SpaceOrder

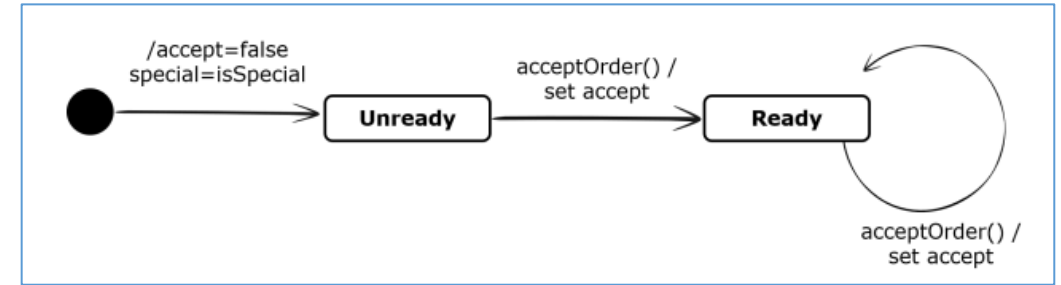


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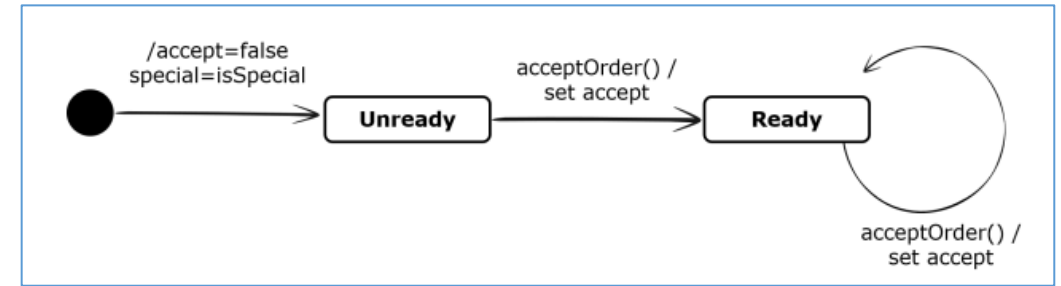
- Using the **all-transitions** strategy results in seven test coverage items: one for each transition

Example: Verifying State Transitions

- There is no getState() method
- Have to check the state by using available methods

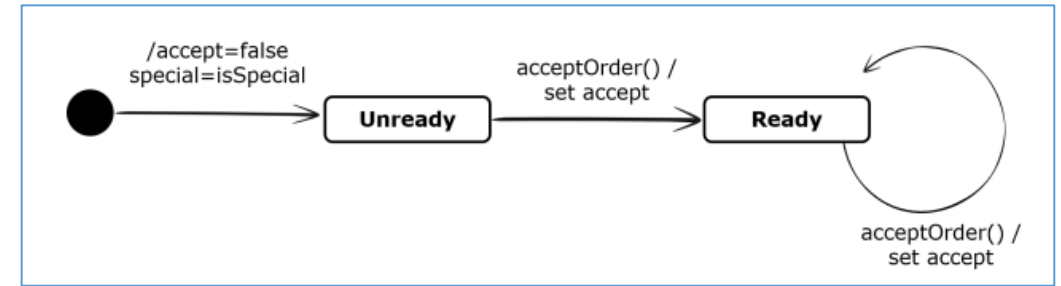


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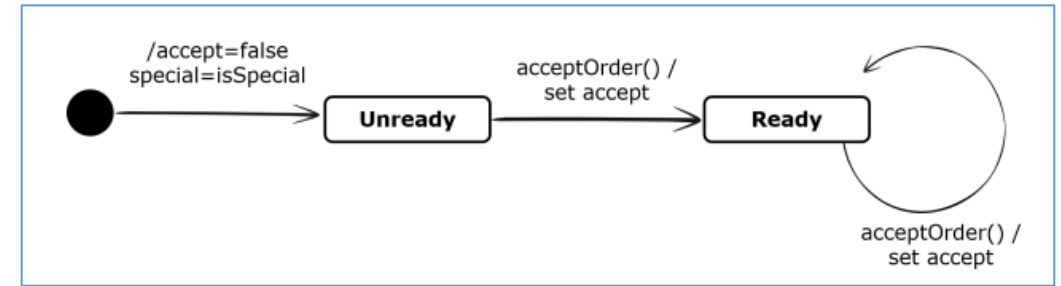
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 - `getAccept()`

Example: Verifying State Transitions



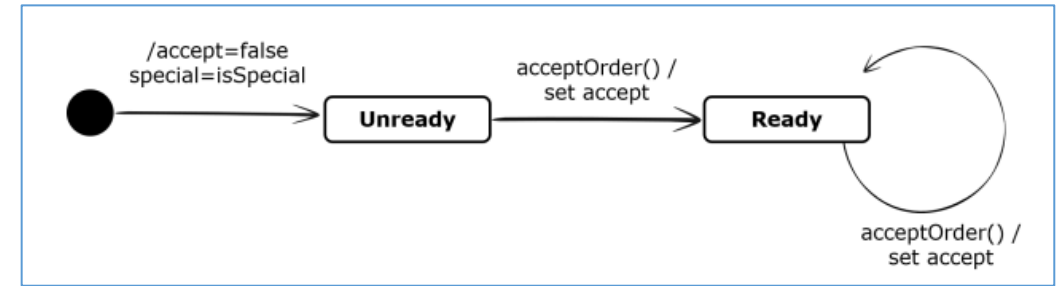
- There is no `getState()` method
- Have to check the state by using available methods
- Ideally use methods that don't change the state themselves
 - `getSpecial()`
 - `getAccept()`
- These are used to produce what is called a "**state signature**"
 - A sequence (or vector) of values returned by method calls that is unique to the state the object is in
 - If you call these methods, and get these return values, then the object was in the state associated with the state signature

Example: Verifying State Transitions



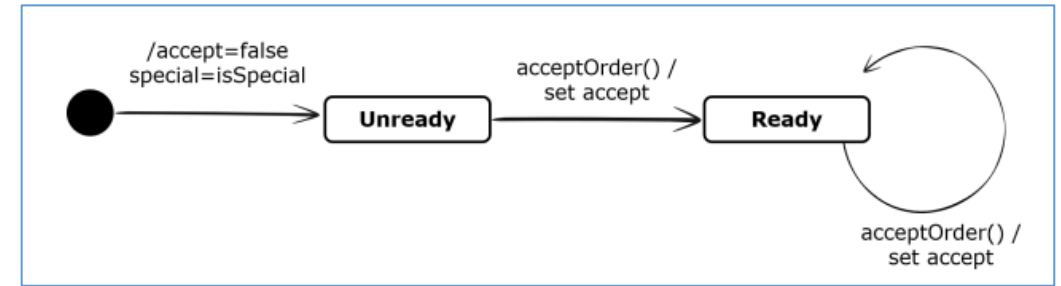
- You cannot fully verify that the software is in the **Unready** state: the best partial check is that `getAccept()` returns false, and `getSpecial()` returns the provided value of `isSpecial`

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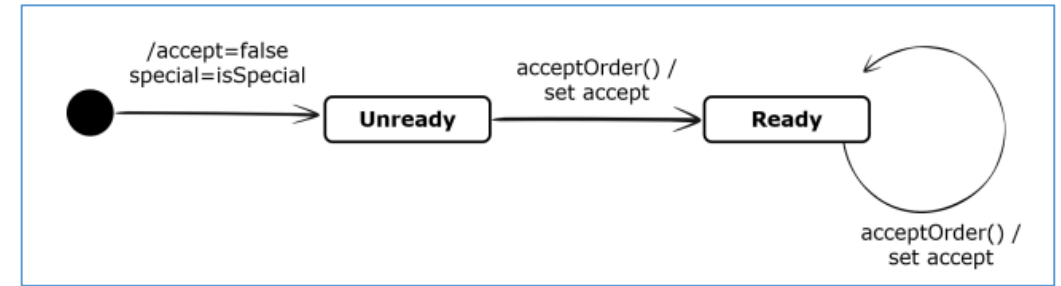
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- You can verify that the software is in the **Ready** state if `acceptOrder()` has set `accept` to true by calling `getAccept()`, which should return true, and `getSpecial()` which should return the provided value of `isSpecial`

Example: Verifying State Transitions



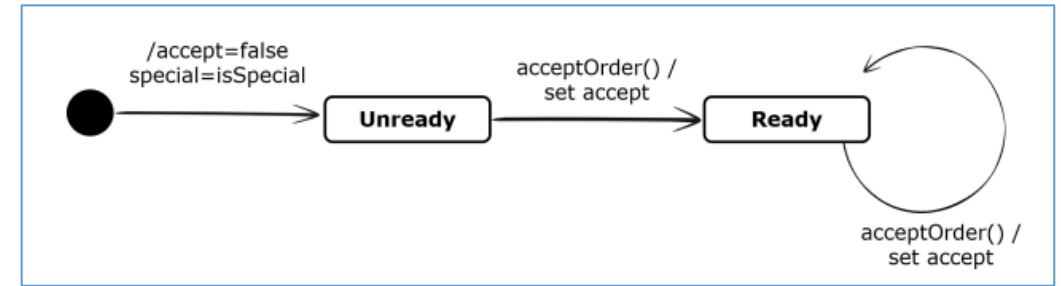
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- You cannot verify that the software is in the **Ready** state if `acceptOrder()` has set `accept` to false
 - As in **Unready** state, `getAccept()` returns false
 - And `getSpecial` returns provided value

Continued...



- The transition from Unready to Ready should be checked by setting values for special and space that should set accept to true
- This allows both the Unready and Ready states to be uniquely identified (if the software is working correctly)

Continued...



- The transition from Unready to Ready should be checked by setting values for special and space that should set accept to true
- This allows both the Unready and Ready states to be uniquely identified (if the software is working correctly)
- The transition from Ready to Ready by calling `acceptOrder()` can only be (partially) verified by using a value for space that causes accept to be set to false

Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- First: cause T1

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
```


Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- Then use the state signature for **Start** to check the state

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10    }
```

Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- The state signature has caused transitions T2 and T3
- So use the state signature again to check still in Unready

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13    }
14 }
```

Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- Now cause transition T4

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15    }
16 }
```

Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- And check in state Ready using the state signature

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15        // check activity and state for t4
16        assertFalse(o.getSpecial());
17        assertTrue(o.getAccept());
18    }
19 }
```

Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- The state signature has caused transitions T5 and T6
- So use the state signature again to check still in Ready

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15        // check activity and state for t4
16        assertFalse(o.getSpecial());
17        assertTrue(o.getAccept());
18        // check activity and state for t5 and t6
19        assertFalse(o.getSpecial());
20        assertTrue(o.getAccept());
21    }
22 }
```

Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- Next, cause transition T7

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15        // check activity and state for t4
16        assertFalse(o.getSpecial());
17        assertTrue(o.getAccept());
18        // check activity and state for t5 and t6
19        assertFalse(o.getSpecial());
20        assertTrue(o.getAccept());
21        // transition 7
22        o.acceptOrder(2000);
```


Implementation

- Tests for transitions T1, T2, T3, T4, T5, T6, T7 in order

Number	Start State	Event	End State
1	Start	Constructor	Unready
2	Unready	getSpecial()	Unready
3	Unready	getAccept()	Unready
4	Unready	acceptOrder()	Ready
5	Ready	getSpecial()	Ready
6	Ready	getAccept()	Ready
7	Ready	acceptOrder()	Ready

- And finally, use the state signature for T7 to check still in that state

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15        // check activity and state for t4
16        assertFalse(o.getSpecial());
17        assertTrue(o.getAccept());
18        // check activity and state for t5 and t6
19        assertFalse(o.getSpecial());
20        assertTrue(o.getAccept());
21        // transition 7
22        o.acceptOrder(2000);
23        // check activity and state for t7
24        assertFalse(o.getSpecial());
25        assertFalse(o.getAccept());
26    }
27 }
```

Implementation

- Note that the checks to verify the software is in the correct state often cause transitions themselves, which must also be checked for in turn
- For example: checking the state after T1 causes transitions T2 and T3 to occur
- So check these next

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15        // check activity and state for t4
16        assertFalse(o.getSpecial());
17        assertTrue(o.getAccept());
18        // check activity and state for t5 and t6
19        assertFalse(o.getSpecial());
20        assertTrue(o.getAccept());
21        // transition 7
22        o.acceptOrder(2000);
23        // check activity and state for t7
24        assertFalse(o.getSpecial());
25        assertFalse(o.getAccept());
26    }
27
28 }
```


Implementation

- Note that the checks to verify the software is in the correct state often cause transitions themselves, which must also be checked for in turn
- For example: checking the state after T1 causes transitions T2 and T3 to occur
- So check these next

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15        // check activity and state for t4
16        assertFalse(o.getSpecial());
17        assertTrue(o.getAccept());
18        // check activity and state for t5 and t6
19        assertFalse(o.getSpecial());
20        assertTrue(o.getAccept());
21        // transition 7
22        o.acceptOrder(2000);
23        // check activity and state for t7
24        assertFalse(o.getSpecial());
25        assertFalse(o.getAccept());
26    }
27
28 }
```

Implementation

- Note that the checks to verify the software is in the correct state often cause transitions themselves, which must also be checked for in turn
- This makes writing state-based tests quite challenging

```
1 public class SpaceOrderStateTest {
2
3     @Test
4     public void allTransitionsTest() {
5         // transition 1
6         SpaceOrder o = new SpaceOrder(false);
7         // check activity and state for t1
8         assertFalse(o.getSpecial());
9         assertFalse(o.getAccept());
10        // check activity and state for t2 and t3
11        assertFalse(o.getSpecial());
12        assertFalse(o.getAccept());
13        // transition 4
14        o.acceptOrder(1000);
15        // check activity and state for t4
16        assertFalse(o.getSpecial());
17        assertTrue(o.getAccept());
18        // check activity and state for t5 and t6
19        assertFalse(o.getSpecial());
20        assertTrue(o.getAccept());
21        // transition 7
22        o.acceptOrder(2000);
23        // check activity and state for t7
24        assertFalse(o.getSpecial());
25        assertFalse(o.getAccept());
26    }
27
28 }
```

Order of Testing

- The order in which transitions are tested is important. It would be possible to put each transition test into a separate test method and use dependencies to force them to execute in the correct order
- Or use a complex test method and a data provider
- The other approach, as shown, is to test all the transitions in a single method
- This is much clearer and simpler to implement, but has the disadvantage that it is more difficult to debug a failed test, as the test covers multiple transitions

All Transition Test Results

```
PASSED: allTransitionsTest
```

```
=====
```

```
Command line suite
```

```
Total tests run: 1, Passes: 1, Failures: 0, Skips: 0
```

```
=====
```

```
1 public class SpaceOrderStateTest {  
2  
3     @Test  
4     public void allTransitionsTest() {  
5         // transition 1  
6         SpaceOrder o = new SpaceOrder(false);  
7         // check activity and state for t1  
8         assertFalse(o.getSpecial());  
9         assertFalse(o.getAccept());  
10        // check activity and state for t2 and t3  
11        assertFalse(o.getSpecial());  
12        assertFalse(o.getAccept());  
13        // transition 4  
14        o.acceptOrder(1000);  
15        // check activity and state for t4  
16        assertFalse(o.getSpecial());  
17        assertTrue(o.getAccept());  
18        // check activity and state for t5 and t6  
19        assertFalse(o.getSpecial());  
20        assertTrue(o.getAccept());  
21        // transition 7  
22        o.acceptOrder(2000);  
23        // check activity and state for t7  
24        assertFalse(o.getSpecial());  
25        assertFalse(o.getAccept());  
26    }  
27  
28 }
```

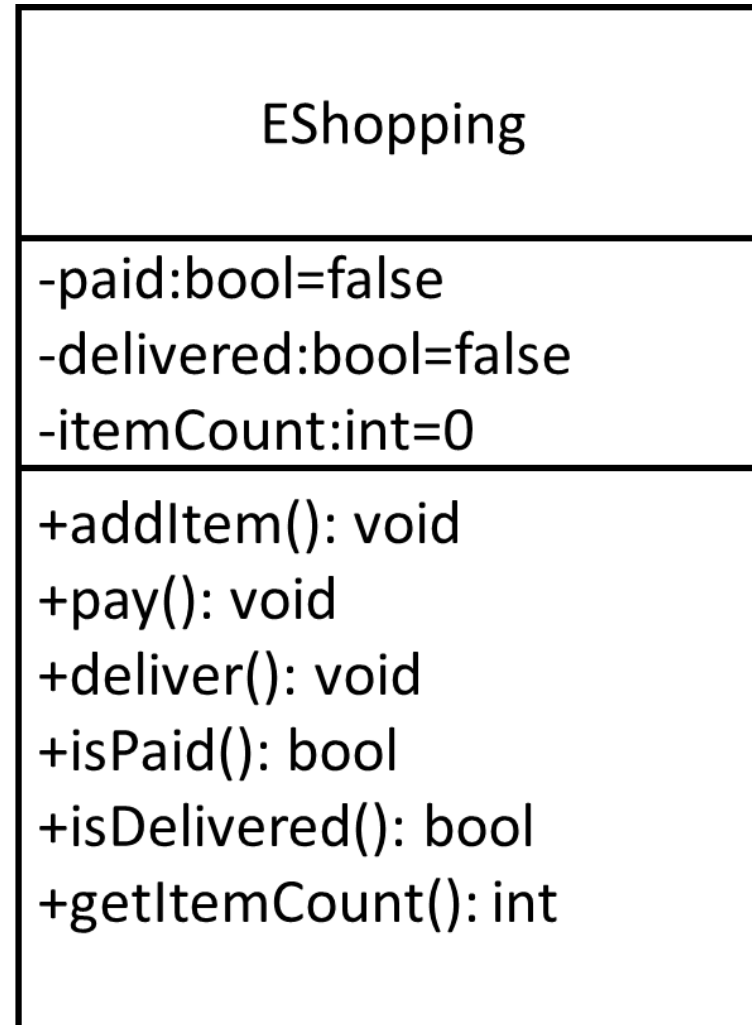
- All the tests have passed, showing as far as is possible that that each transition in the state diagram works
- Test effectiveness is limited by being unable to access the object state
- A tester can only test what is possible

This Afternoon's Lab

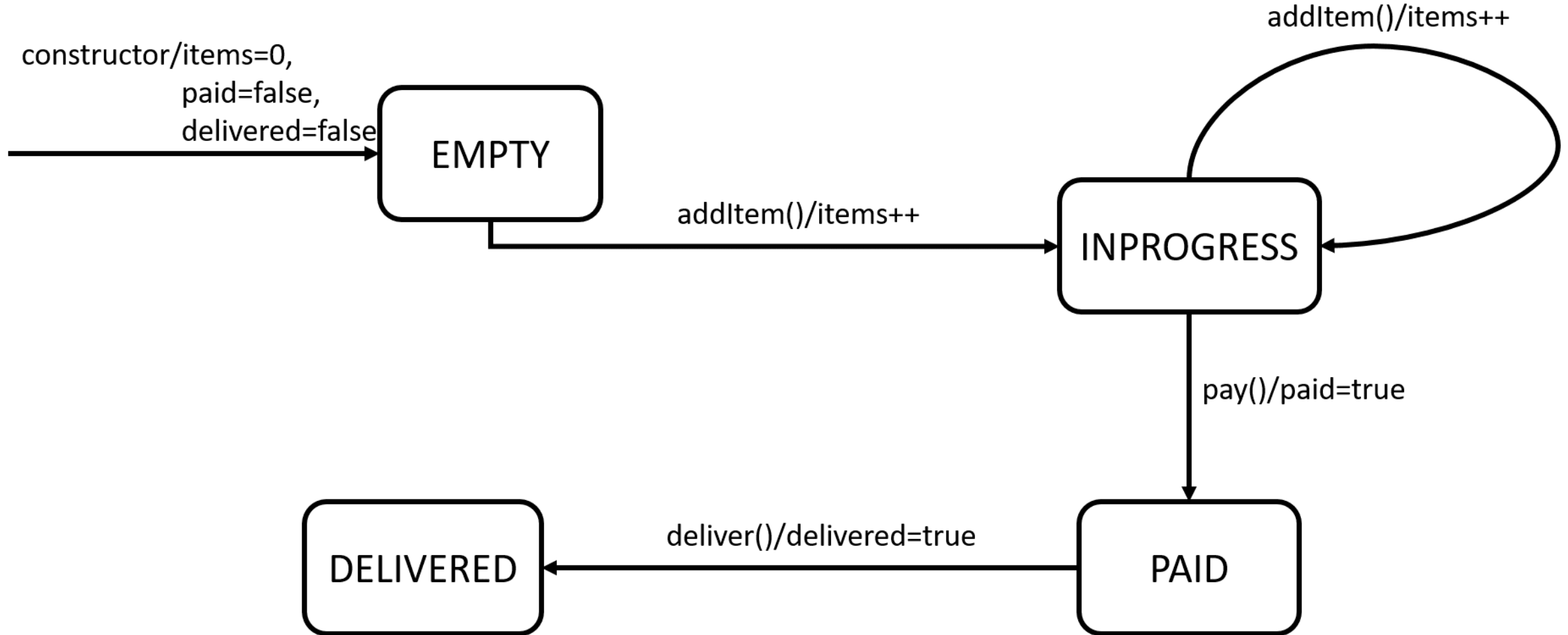
This Afternoon's Lab

- State-Based Testing
- Class: **EShopping**
- Make sure to test each state transition at least once
- Quiz
- Next: examine the state diagrams for EShopping

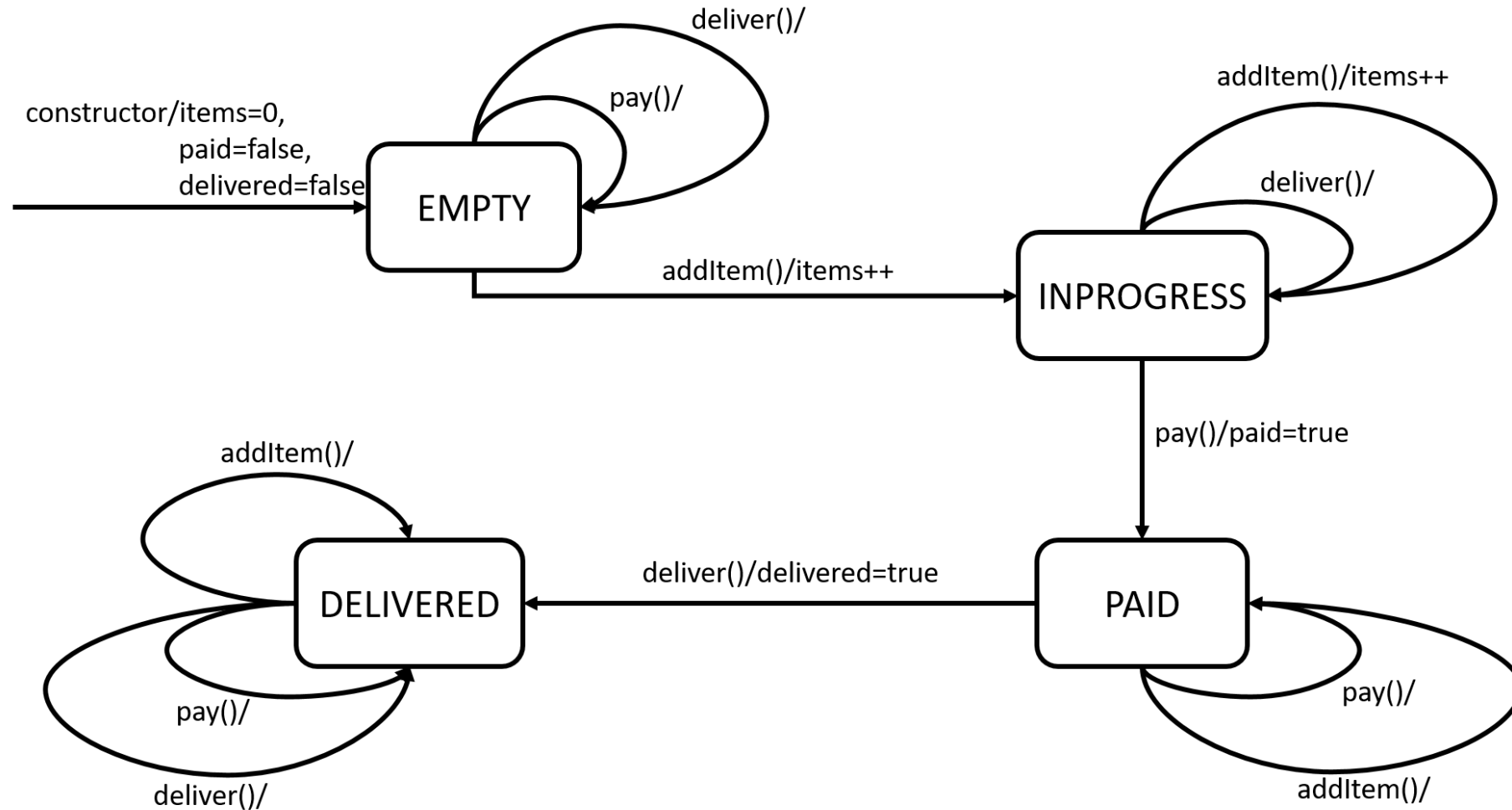
Class EShopping



LAB7 UML State Diagram



Expanded SD (implicit transitions)



Numbered SD

