Incomplete Data Analysis

Vanda Inácio

University of Edinburgh



Semester 1, 2018/2019

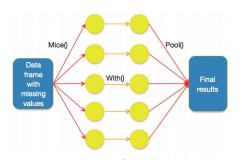
MI in practice - the mice package

- → R provides several useful packages for MI. The most commonly used include Amelia, mice, and MI.
- They basically differ in the specific algorithm they implement for the imputation model (step 1).
- → We will learn how the mice package works for conducting MI analyses.

MI in practice - the mice package

- → mice contains several popular methods for imputation under the normal linear model.
 Specifically:
 - → Regression imputation, as we have seen it in lecture 3. The method is available as norm.predict.
 - → Stochastic regression imputation. This method is available as norm.nob.
 - → Bayesian multiple imputation that implements the method described in slide 30 of lecture 9. This method is available as norm.
 - → The bootstrap alternative to the Bayesian multiple imputation, slide 33 of lecture 9, is
 also implemented and is available as norm.boot.

MI in practice - the mice package



Imputed datasets Results of statistical analysis

Schematic illustration of how mice package works with a dataset with missing values. Note the sequential use of mice (), with (), and pool () functions. Figure from Annals of Translational Medicine, 4, 2016.

MI in practice - the mice package

- \hookrightarrow We start with the function mice() which will perform the imputation step (step 1). We need to specify the method we want to use to impute the missing values and the number of imputations. By default this function creates 5 copies of the dataset, i.e., M=5. We can also set a seed within this function, so results are reproducible.
- → Now having the complete datasets at hand, the conventional statistical analysis that would have been conducted had the data been complete can be performed. This is done via the function with () and we need to feed this function with the imputed data from the previous step and with the model we want to fit (e.g., through the use of lm for linear regression and glm for generalised linear models).
- \hookrightarrow Lastly, we use the function pool () to combine the results of the M analyses (obtained in the previous step using with ()).
- \hookrightarrow See the supplementary file on Learn for a concrete application.

Imputation under non-normal distributions

- → The imputation methods discussed so far produce imputations draws from a normal distribution.
- → In practice, the data could be skewed, heavy tailed, non negative, bimodal or rounded to name only some deviations from normality.
- This creates an obvious mismatch between observed and imputed data which could adversely affect the estimates of interest.
- → The effect of non normality is general small for measures that rely on the center of the distribution, like means, but it could be substantial for estimates like a variance or a percentile (van Buuren, 2012).
- → A sensible approach is to transform the data toward normality before imputation and back-transform after imputation.
- → A beneficial side effect of transformation is that the relation between the missing and observed variables may become closer to a linear relation.



Imputation under non-normal distributions

- Sometimes applying a simple function to the data, like the logarithmic is all that is needed. More generally, the transformation could be made to depend on known covariates like, for instance, age and gender.
- → It is also possible to directly draw imputations from non-normal distributions. For instance, Liu (1995) proposed methods for drawing imputations under the t distribution instead of the normal (the t distribution has heavier tails than the normal distribution).
- He and Raghunathan (2006) created imputations by drawing from Tukey's gh distribution, which can take many different shapes.
- Demirtas and Hedeker (2008) investigated the behaviour of methods for drawing imputations from the Beta and Weibull distributions.

Other types of variables

- → When the variable to be imputed has a binary form, a sensible imputation model is a logistic regression model. In mice the procedure is implemented as mice.impute.logreg.
- → If the variable to be imputed is categorical with K unordered categories then a reasonable model is a multinomial logit model, and this is implemented in mice as mice.impute.polyreg.
- → A categorical variable with K ordered categories is imputed by the ordered logit model or proportional odds model. Implementation is done in mice.impute.polr function.

- → In general, a dataset may have many variables with missing values.
- → To make good imputations we should use a multivariate analysis of all variables within a single 'platform'.
- → There are several methods for dealing with missingness in several variables, but all them require a quite advanced knowledge of Bayesian methods.
- The package mice also accommodates multivariate multiple imputations, with some pre-defined procedures.
- \hookrightarrow I will very briefly describe the main idea of how things would work in general.

- \hookrightarrow The following is from Schafer and Graham (2002).
- \hookrightarrow Consider a hypothetical data set with three variables Y_1 , Y_2 , and Y_3 , which we assume to be jointly normally distributed.
- Suppose that one group of participants (Group A) has measurements for all three variables, another group (Group B) has measurements for Y₁ and Y₂ but missing values for Y₃, and a third group (Group C) has measurements for Y₃ but missing values for Y₁ and Y₂.
- → The parameters of the trivariate normal model—three means, three variances and three correlations—are not known and should be estimated from all three groups.

- → Group A requires no imputation.
- \hookrightarrow For Group B, we would need to compute the linear regression of Y_3 on Y_1 and Y_2 . Then, for each participant in Group B, we would use his or her own values of Y_1 and Y_2 to predict the unknown value of Y_3 and impute the predicted value $\widehat{Y_3}$ plus random noise drawn from a normal distribution with the appropriate residual variance.
- \hookrightarrow For Group C, we would compute the bivariate regression of Y_1 and Y_2 on Y_3 , obtain the joint prediction $(\widehat{Y_1}, \widehat{Y_2})$ for each participant, and add random noise drawn from a bivariate normal distribution with the appropriate residual variance-covariance matrix.

- A crucial feature of MI is that the missing values for each participant are predicted from his or her own observed values, with random noise added to preserve a correct amount of variability in the imputed data.
- \hookrightarrow Another feature is that the joint relationships among the variables Y_1 , Y_2 , and Y_3 must be estimated from all available data in Groups A, B, and C.
- Therefore, instead of using maximum likelihood estimates, we need to draw random values of the parameters from a posterior distribution based on the observed data likelihood and a prior.

- The form of this posterior distribution is not easy to describe, but it can be sampled from by a variety of techniques; data augmentation (Schafer, 1997) is straightforward, but one could also use importance resampling.
- The effect of drawing parameters from a posterior distribution, rather than using maximum likelihood estimates, means that for Group B the regression of Y₃ on Y₁ and Y₂ will be randomly perturbed from one set of imputations to the next; similarly, in Group C the joint regression of (Y₁, Y₂) on Y₃ will also be perturbed.

Summary

- Multiple imputation overcomes the main problem associated with single imputation (underestimating variability) and is one of the state-of-the-art technique that researchers/methodologists currently recommend.
- → As all the other techniques we have learned, MI assumes MAR data.
- → A multiple imputation analysis consists of three distinct steps: the imputation phase, the analysis phase, and the pooling phase.
- → The imputation phase creates multiple copies of the dataset, each of which contains different estimates of the missing values.
- → The imputation phase, i.e., the specification of an appropriate imputation model, is the crux of MI, since if such model is misspecified there is the potential for bias.

14 / 15

Summary

- → Finally, the pooling phase uses Rubin's rules to combine the M sets of estimates and standard errors into a single set of results.
- → The pooled parameter estimate is simply the arithmetic average of the estimates from the analysis phase.
- → Combining standard errors is somewhat more complex because it involves two sources of sampling variation.
- The within imputation variance is the arithmetic average of the M sampling variances, and the between imputation variance quantifies the variability of an estimate across the M imputations.
- The within imputation variance estimates the sampling fluctuation that would have resulted had there been no missing data, and the between imputation variance captures the increase in sampling error due to missing data.