Coverage Report for ABS_v1

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Analysis Information

Coverage Data Information

Collected in version (R2022a)

Model Information

Model version 1.19

Author DELL

Last saved Sat Mar 26 16:49:44 2022

Harness information

Harness model(s) Not Unique

Harness model owner ABS_v1

Simulation Optimization Options

Default parameter behavior tunable

Block reduction forced off

Conditional branch optimization on

Coverage Options

Analyzed model ABS_v1

Logic block short circuiting off

Aggregated Tests

Run	Test Name	Date
Model: "ABS_v1"		
T1	Run 1	26-Mar-2022 17:06:48

Summary

Model Hierarchy/Complexity

	Decision	TBL	Execution
1. <u>ABS_v1</u>	NA	86%	100%
2 <u>ABS control System</u>	NA	86%	100%
3 <u>relative slip calculator</u>	NA	NA	100%
4 wheel speed calculator	NA	NA	100%
5 <u>bang-bang controller</u>	NA	NA	100%

Details

1. Model "ABS_v1"

Child Systems: <u>ABS control System</u>

Metric	Coverage (this object)	Coverage (inc. descendants)
Cyclomatic Complexity	0	0
Decision	NA	NA
Lookup Table	NA	86% (19/22) interpolation/extrapolation intervals
Execution	NA	100% (26/26) objective outcomes

Full Coverage

Model Object	Metric
Step block "Step"	Execution

2. SubSystem block "ABS control System"

Justify or Exclude

Parent: /ABS_v1

Child Systems: relative slip calculator, wheel speed calculator

Metric	Coverage (this object)	Coverage (inc. descendants)
Cyclomatic Complexity	0	0
Lookup Table	NA	86% (19/22) interpolation/extrapolation intervals
Execution	NA	100% (25/25) objective outcomes

Lookup_n-D block "mu-slip lookup table"

Justify or Exclude

Parent: ABS_v1/ABS_control System

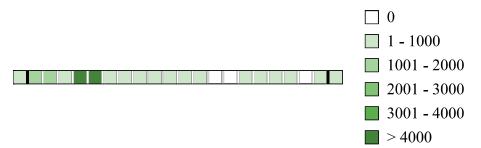
Metric Coverage

Cyclomatic Complexity 0

Lookup Table 86% (19/22) interpolation/extrapolation intervals

Execution 100% (1/1) objective outcomes

Look-up Table Details



Full Coverage

Model Object	Metric
Gain block "Gain"	Execution
Gain block "Relative Slip"	Execution
Gain block "angular vehicle speed"	Execution
Gain block "normal force"	Execution
Gain block "wheel radius"	Execution
Sum block "Sum"	Execution
Stop block "Stop Simulation"	Execution
Integrator block "ang vehicle speed"	Execution
Integrator block "stopping distance"	Execution

3. SubSystem block "relative slip calculator"

Justify or Exclude

Parent: ABS v1/ABS control System

Metric	Coverage (this object)	Coverage (inc. descendants)
Cyclomatic Complexity	0	0
Execution	NA	100% (3/3) objective outcomes

Full Coverage

Model Object	Metric
Product block "Divide"	Execution
Sum block "Sum1"	Execution
Constant block "Constant"	Execution

4. SubSystem block "wheel speed calculator"

Justify or Exclude

Parent: ABS v1/ABS control System

Child Systems: <u>bang-bang controller</u>

Metric Coverage (this object) Coverage (inc. descendants)

Cyclomatic Complexity 0

Execution NA 100% (12/12) objective outcomes

Full Coverage

Model Object	Metric
Gain block "Gain"	Execution
Gain block "force and torque"	Execution
Sum block "Sum1"	Execution
Integrator block "Integrator Limited"	Execution
Integrator block "braking pressure"	Execution
TransferFcn block "hydraulic lag"	Execution

5. SubSystem block "bang-bang controller"

Justify or Exclude

Parent: ABS v1/ABS control System/wheel speed calculator

Metric Coverage (this object) Coverage (inc. descendants)

Cyclomatic Complexity 0 0

Execution NA 100% (6/6) objective outcomes

Full Coverage

Model Object Metric

DataTypeConversion block "Data Type Conversion" Execution

DataTypeConversion block "Data Type
Conversion1" Execution

Sum block "Sum1" Execution

RelationalOperator block "GreaterThan" Execution

RelationalOperator block "Less Than" Execution

Constant block "Constant" Execution