Name: Manoj Bastin. M

ROHNO: M200401EE

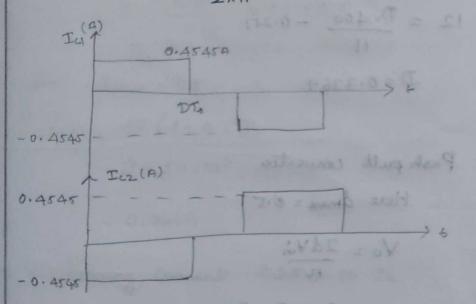
Branch: Power Electronics

EE6308D Switched Mode & Resonant Converters.

Test -2

2) For the current in the capacitors 33 ptf,  $I_{c_1} = -I_{c_2}$ 

$$T_{c_1} = \frac{T_0}{2n} = \frac{10}{2x11} = 0.4545A$$



Here given is ideal so

b). 3% leakage inductance 0.03 x 2.7 mH = 81 MH

Voltage loss = 
$$\left(\frac{3}{2} f_3 \frac{1}{h^2}\right) I_0$$
  
=  $1.5 \times 25 \times 10^3 \times 81 \times 10^{-6}$   
 $\frac{11^2}{11^2}$ 

= 0.251 V

$$V_0 = \frac{DV_{in}}{n} - V_{loss}$$

$$12 = \frac{D_0 400}{11} - 0.251$$

$$D = 0.3369.$$

6. Push pull converter Here dmax = 0.5

$$48 = \frac{2 \times 0.5 \times 200}{000 \text{ no hope and }}$$

n=4.166 = 4.

$$I_{LP-P} = \frac{V_0(1-d) T_3}{2L}$$

$$1 = \frac{48(1-0.3428) \times 1}{2 \times 0.50 \times 10^3 \times L}$$

$$L = 315 \mu H$$

$$\Rightarrow ESR \times 1 = 0.48$$

$$ESR = 0.48 \text{ Ling 30 } \text{ bandy}$$

$$C = \frac{30\mu}{0.48} = 62.5 \mu \text{ F}$$

$$0.48$$
For  $d_{max} = 0.5$ ,
$$(1-0.5)$$

$$2 \times 50 \times 10^3 \times 315 \times 10^{-6}$$

For 
$$d_{max} = 0.5$$
,  
 $i_{1pp} = \frac{48(1-0.5)}{2 \times 50 \times 10^{3} \times 315 \times 10^{-6}}$ 

$$= 0.7619$$

Magnetising current = 25 % ob IL APAID 0 = = 0.25 X5

$$= 1.25 A$$

$$= 1.25 A$$

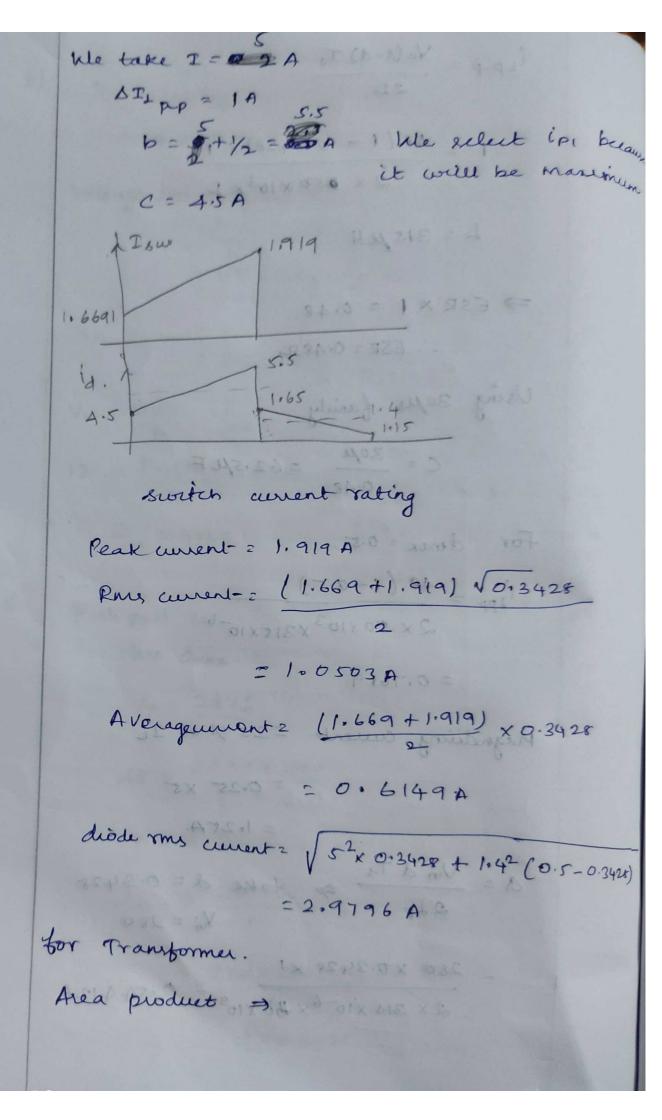
$$= 1.25 A$$

$$= 1.25 A$$

$$= 0.3428$$

$$V_{ij} = 280$$

$$= \frac{280 \times 0.3428 \times 1}{2 \times 315 \times 10^{-6} \times 50 \times 10^{3}} = 0.544126$$



Primary rms current = 1.0503A

A= 1.0503 = 0.3501m2

sciendary mms current = 2.9796 A

A = 2.9796 2 0.993 mm<sup>2</sup>

Ks Aw = np x 0.3950H ns x 0.993

AW = np (0.3501 + 0.993) = 0.59835 np

nvo B = Bm Ac Dp

A = 4 × 48 × 106 50 × 103 × Np × 012

 $=\frac{19200}{Np}$ 

 $Ap = \frac{11488.32}{11488.32} = 32823 \text{ min}$ 

We select E 47/20/16.

Inductor derign

Ki= ( 1+ .20 ) = 1.1

Ap= 1/2× 315×1026×52× 2/×1.1×106 0.35×3×0.2

2 41280,

We use same EA7/20/16

1. Design equation for an inductor with DC Bias

Maximum flux linkage = LIp

· Ac Bman N must be & LIp.

where  $A_c = area of cross section of core = Ae of core

<math display="block">A_c \ge \frac{L_p}{N_{Bmax}}$ 

Lie, Ac Kil I where Ki is as follows

Ki = ( 1+ P-Préple in/.)

Let J be the chosen derign eurrent density Value. Usually it is between 2 A/mm² to 3 A/mm²

3 A/mm²

.'. Whire copper Area = [izmi] = I mm²

Irlindow area need for N turns with spawing bactor accounted

 $Aw = \frac{NI}{k_s J}$  with  $k_s$  between 0.3 to 0.45

.. Area product needed

in the cone =  $Ap = Ac Aw = \frac{Ki}{Ks} \cdot \frac{19^2}{JBmax}$ 

 $= \left(\frac{1}{2} \perp \mathbb{P}^2\right) \left(\frac{2 \times \mathcal{C}}{\times_{\text{3JBman}}}\right)$ 

from the above equation, we get size ob core is & Magnetic energy storage for DC current

N→ not there in Ap

Small N → Act, Awt

large N → Act, Awt.

5) Flux walking publem:

Upward traval amount of B will be different from downward travel amount of B. Hence B will either climb towards the saturation (or) towards negative satisfaction with time. This B called flux walking problem Now the supply whent takes on slope as follows



Covert reach stable shapes when Volt- see boss is path resultances of the Path which had a higher volt- see applied to it reaches such a value that the het Volt-see in the other path. The

resulting current unbalance observirely depends on resertances in the path leads to damage ob switches

## of dutions

- il Handle it problem source laved pay attention to asserbain symmetry ob clements. Minimise the difference between duty ratio in two half eyeles.
- ii) Keep identical turns in primaries & secondaries.
  - iii)Use matched droides from same parkage.
    iv)Use identical gate drive crimits

External Measures.

- a) gapping the core.
  b). Match switches & avoid BJTs & wed

  MOSFETS
- d) Use went mode control.

of the

antiday current parties 7). Vo = 2 d vin

for D=?

Vin = 180V

12 = 2 x d x 180

12 = 2 x d x 240

d=0,2

d vary from 0.15 to 0.2.

take maximum Value of ZarioA

V = 10 × 0.4 = 4V

take Vfw 21.

n Lm > 100 d max (V+Vfw)

Here take x=1

nlm = 100 x 0.2 (4+1) 20 X 10 2 X 10

nlm = 500 pc H - To

Bm = Dman (V+Vsw) Mas Ac

Bm wb/m2 654 Ism T10. the private days 424 4 28 T12 T16 0 1 337 20 20 29 200 08 T20 T32 206 · 0.0217 0.0

Let J=2.5 A/mm² 0.0217 0.008196 Jerms 2 10 Jaman A 2 0.0217 We select T32./2067/SWG19. = 0.0086 V= 2 dman (V+Vjw) - Vjw = 1-dman de Del amy = 0.2 (4+1) - 1 = 1-0.2 (4+1) - 1 = 0.25 V. E WAS = 29 9 = 09 We select standard as 2:4V. Power rating ob Tener diode Im Imt for Imax 1% of Imax 2 2 1×10-6×(0.1)<sup>2</sup>×20×16<sup>+3</sup> Eake Im = 1 µH = 0-100 loopen. Judon ... is Inthe tenen power rating = 0.1w.  $R_s = \frac{nV}{I} = \frac{206 \times 4}{10} = 82.4 \Omega$ 

Response loss = 
$$(4 \times \sqrt{0.2})^2$$

$$82.4$$

=0.0388W.

80 we take Rs as 82.4 / 1/4 w.

4. output power of full bridge converter is twice as half beidge converte. To derive the half bridge.

l's1 ms = 0.5 To \2d+1

ipms = V2d To/n.

Pin = Avg ob Vpip z Vin Zo d.

Po= Ppin = 7 d Vin Io

> Vin d Te = 2 Ac B man np

d Vin = 4Ac Bmax npfs

Po = 7 4Ac Bman npfa To

Area product

In np = Rs Aw J Fed + 12d+1

Po =  $\left(\frac{4}{12d} + \sqrt{2d+1}\right)^2 B_{man} \int_{-\infty}^{\infty} f_{s} K_{s} A_{s} A_{s} A_{s}$ if d = 0.5Po =  $\left(1.72 \int_{-\infty}^{\infty} B_{man} \int_{-\infty}^{\infty} f_{s} K_{s}\right) A_{s} A_{s} A_{s}$ This is for half bridge convertes, for full bridge convertes,

Po full =  $2 \int_{-\infty}^{\infty} h_{s} ds$ 

Popul = (3.44 M Bman Ifs Ks) (Ac Aw)

3. CCM and DCM flyback operation:

Trf becomes much bigger than in DCM.

Reason: Nearly 1:2 input voltage range and 1:10 load went range nequering a large Lp to keep converte in com

-s Jarge Load range is better accommodated in a Duna design

-3 The surje of inductor in can will be larger than that of DCM design tor summe power output

-s current est mers in devices will be lesser in com design

POCO SHOT ON POCO M2 PRO