

# Milestone Review Flysheet 2017-2018

**Institution** Vanderbilt University

**Milestone** Flight Readiness Review

## Vehicle Properties

Total Length (in)	82.35
Diameter (in)	5.5
Gross Lift Off Weigh (lb.)	29.3
Airframe Material(s)	Carbon Fiber
Fin Material and Thickness (in)	Carbon Fiber / 0.125
Coupler Length/Shoulder Length(s) (in)	4

## Stability Analysis

Center of Pressure (in from nose)	55.0
Center of Gravity (in from nose)	44.0
Static Stability Margin (on pad)	2.0
Static Stability Margin (at rail exit)	2.1
Thrust-to-Weight Ratio	11.5
Rail Size/Type and Length (in)	144
Rail Exit Velocity (ft/s)	92.0

## Recovery System Properties

### Drogue Parachute

Manufacturer/Model		Fruity Chutes
Size/Diameter (in or ft)		18 in
Altitude at Deployment (ft)		1s after apogee (2s)
Velocity at Deployment (ft/s)		32.2
Terminal Velocity (ft/s)		88.4
Recovery Harness Material		Kevlar
Recovery Harness Size/Thickness (in)		7/16" (5300 lb)
Recovery Harness Length (ft)		50 ft
Harness/Airframe Interfaces		U-bolt, Eye-bolts, and Quick Link
Kinetic Energy of Each Section (Ft-lbs)	Section 1	Section 2
	1724	1335

## Recovery Electronics

Altimeter(s)/Timer(s) (Make/Model)	PerfectFlite Stratologger CF
Redundancy Plan and Backup Deployment Settings	Two altimeters will be used for both the main and drogue deployments
Pad Stay Time (Launch Configuration)	>> 2 hrs

## Motor Properties

Motor Brand/Designation	Loki L1400
Max/Average Thrust (lb.)	609.3/314.7
Total Impulse (lbf-s)	640.8
Mass Before/After Burn (lb.)	29.3/26.2
Liftoff Thrust (lb.)	361.1
Motor Retention Method	Retaining Ring

## Ascent Analysis

Maximum Velocity (ft/s)	644
Maximum Mach Number	0.57
Maximum Acceleration (ft/s^2)	456
Predicted Apogee (From Sim.) (ft)	5,077

## Recovery System Properties

### Main Parachute

Manufacturer/Model		Fruity Chutes	
Size/Diameter (in or ft)		6 ft	
Altitude at Deployment (ft)		700 (500)	
Velocity at Deployment (ft/s)		88.4	
Terminal Velocity (ft/s)		18.1	
Recovery Harness Material		Kevlar	
Recovery Harness Size/Thickness (in)		7/16" (5300 lb)	
Recovery Harness Length (ft)		50 ft	
Harness/Airframe Interfaces		U-bolt, Eye-bolts, and Quick Link	
Kinetic Energy of Each Section (Ft-lbs)	Section 1	Section 2	Section 3
	55.8	21.1	40.8

## Recovery Electronics

Rocket Locators (Make/Model)	BigRedBee Beeline Transmitter	
Transmitting Frequencies (all - vehicle and payload)	433.910 MHz	
Ejection System Energetics (ex. Black Powder)		4F Black Powder
Energetics Mass - Drogue Chute (grams)	Primary	2.1
	Backup	2.6
Energetics Mass - Main Chute (grams)	Primary	3.3
	Backup	4.1
Energetics Masses - Other (grams) - If Applicable	Primary	
	Backup	

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### Payload

Payload 1 (official payload)	Overview
	The design team will implement an imaging target detection system which will inform the set point of a motorized sectional roll control system. The imaging system will detect ground-based targets in the frame of each image taken, while the roll control will center the targets in the frame of the image.
Payload 2 (non- scored payload)	Overview
	Additionally, the team will place a secondary IMU in the aft section of the rocket to fully characterize the dynamics of our system.

### Test Plans, Status, and Results

Ejection Charge Tests	Ground-based ejection charge testing will be performed prior to all test launches. This testing involves assembling the whole rocket including live charges, shear pins, and properly packed parachutes. The charges are then detonated to ensure proper parachute deployment and rocket separation. These tests will be performed before each launch.
Subscale Test Flights	The team has performed 3 subscale flights to date. The first two validated two stage recovery and the third provided partial payload validation.
Full-scale Test Flights	In order to demonstrate the functionality of the full-scale flight vehicle, a launch was performed on Sunday, February 25th. The full-scale launch was a complete success, with ideal execution of the dual deployment recovery system, safe recovery of all on-board systems, and limited drift. Furthermore, the launch validated the payload's logic and ability to control the upper section of the rocket to hold on an angular setpoint, as evidenced through IMU data gathered during the flight and the on-board camera footage of the rocket in flight.

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Additional Comments