

# Goal

Simulate a spring-mass-gravity system

## Constants

$$k = 100$$

$$l_0 = 1$$

$$m = 1$$

$$g = 9.8$$

Duration: 20s

Framerate: 25fps

## Initial Values

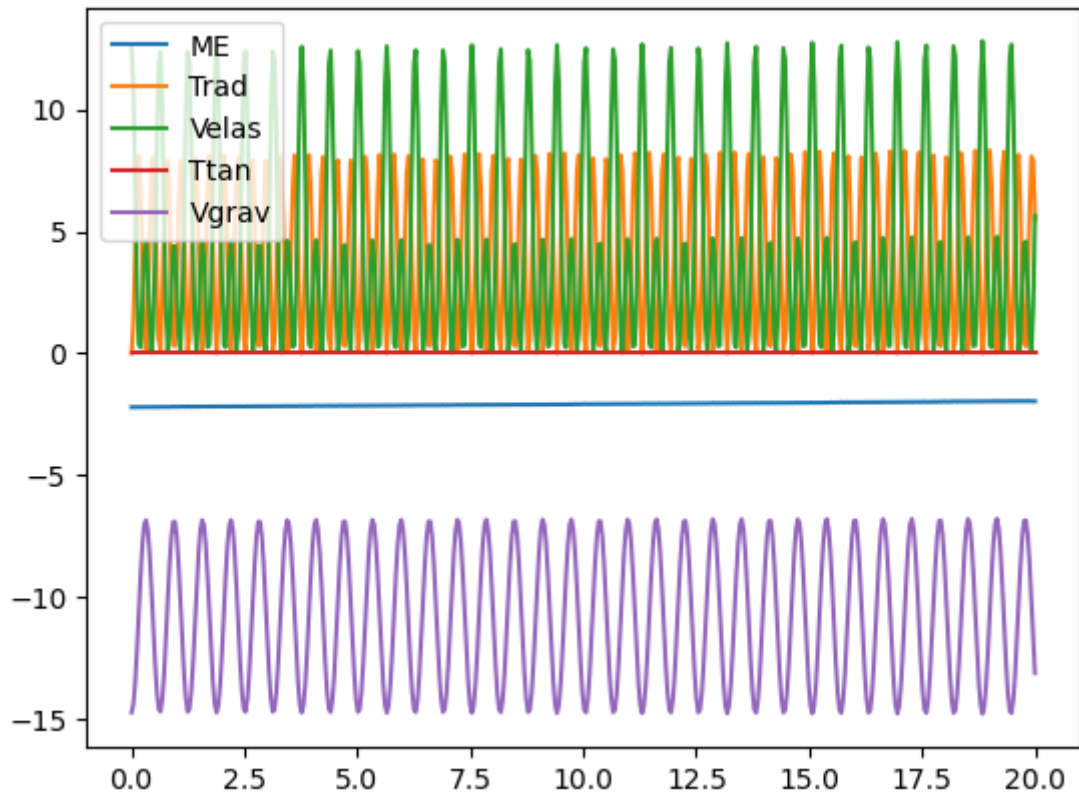
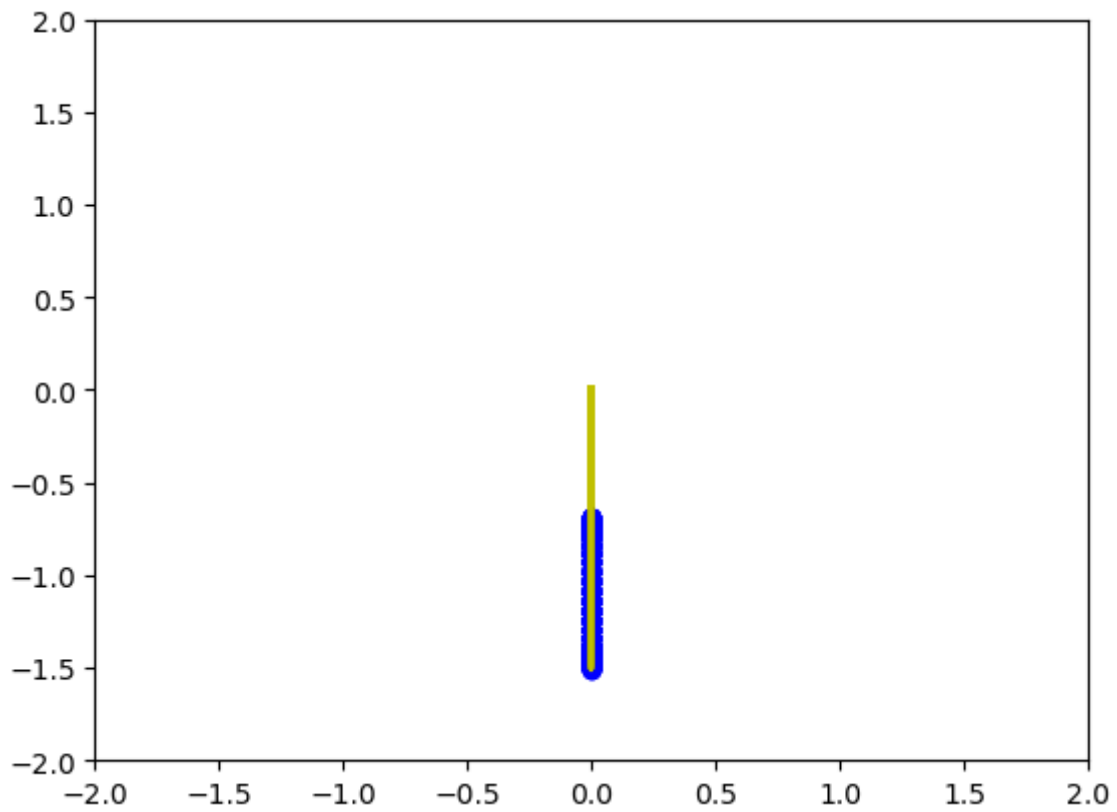
$$l = 1.5$$

$$\dot{l} = 0$$

$$\theta = 0$$

$$\dot{\theta} = 0$$

## Results



In which  $ME$  stands for mechanical energy,  $T_{rad}$  stands for radical kinetic energy,  $T_{tan}$  stands for tangential kinetic energy,  $V_{elas}$  stands for elastic potential energy,  $V_{grav}$  stands for gravitational potential energy.

The theoretical mechanic energy is  $-2.2000000000000001$  J

The average calculated mechanical energy is  $-2.0769138619149143 \text{ J}$

The Root Mean Square Error of mechanical energy is  
 $0.1424396880941304$

the standard deviation of mechanical energy is  $0.017137885306576336$

Therefore the calculated energy stays close to the theoretical energy,  
meaning the energy of this system converges to the theoretical value. This  
simulation has a high accuracy and a high preciseness.