Control Engineering

Homework 1: Laplace

Homework: Laplace Transform

For the following functions, assume that
$$f(t)=0$$
, for all $t<0$. Compute the Laplace transform of the following functions:

(1) $f(t)=t^2e^{3t}$

$$=\frac{2!}{(s+2)^{2+2}}-\frac{2!}{(s+2)^{2+2}}-\frac{2!}{(s+2)^{2}}$$

$$=\frac{2!}{(s+2)^{2}}-\frac{2!}{(s+2)^{2}}$$

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LUalHHH)= exs [Ef (++x)]

1 [va(+)] = 1 e-as

1

 $f(+) = \frac{1}{\alpha} - \frac{2}{\alpha} u_{\alpha}(+) + \frac{1}{\alpha} u_{2\alpha}(+)$

f(+) = = = = = = = H(+-a) + = H(+-2a)

195(+)9=1[-20a(+)+1202a(+)]]

= 11-1y - 2 1100(+)9 + - 1020(+)9

$$F(s) = \frac{1}{\alpha s} - \frac{2}{\alpha} \left[\frac{1}{5} e^{\alpha s} \right] + \frac{1}{\alpha} \left[\frac{1}{5} e^{-2\alpha s} \right]$$

$$F(s) = \frac{1}{\alpha s} - \frac{2e^{-\alpha s}}{\alpha s} + \frac{e^{-2\alpha s}}{\alpha s} / I$$

$$F(s) = \frac{1}{\alpha s} \left[1 - 2e^{\alpha s} + e^{2\alpha s} \right] /$$

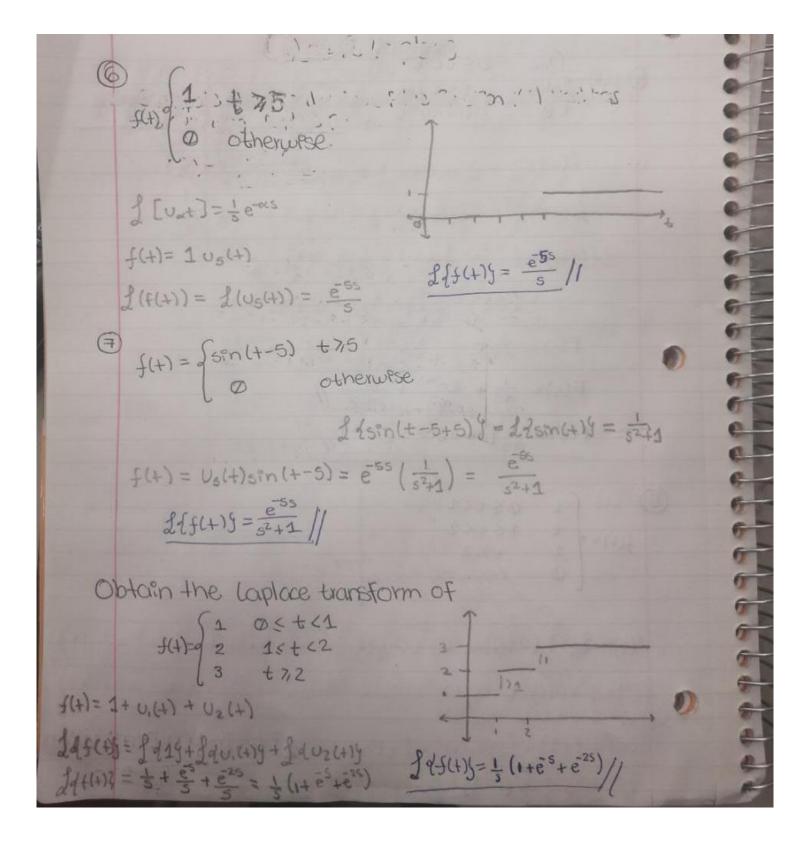
$$\begin{array}{c}
\text{(5)} \\
f(+) = \begin{cases}
1 & 0 \le t < 1 \\
t & 1 \le t < 2 \\
2 & t > 7/2 \\
0 & \text{otherwise}
\end{array}$$

$$f(t) = 1 + t (v_1(t) - v_2(t)) + 2v_2(t) \qquad d[t+1)] = \frac{1}{52} + \frac{1}{5} = \frac{1}{5}(1+\frac{1}{5})$$

$$f(4) = 1 + v_1(4) + v_2(4) + 2v_2(4)$$

$$f(4) = 1 + v_1(4) + v_2(4) + v_2(4$$

$$=\frac{1}{5}+\frac{\bar{e}^5}{5}(1+\frac{1}{5})+\frac{\bar{e}^2}{5}(2+\frac{1}{5})$$



Idexty= 1 Idtexty= 15ta)2

Compute the inverse Laplace Transform of the following functions

$$*F(s) = \frac{s-2}{(s+3)(s+2)^2} = \frac{A}{s+3} + \frac{B}{s+2} + \frac{C}{(s+2)^2}$$

5-2 = A(s+2)2 +B(s+3)(s+2) + C (s+3) 5-2 = A (52+45+4) +B (52+55+6) +Cs+3G 5-2= As2+4AS+4A+BS2+5BS+68+66+3C

A+B=0 8=-A/ 4A+58+C=1 4A+5(-A)+C=1 -A+C=1 4A+6B+3C= -2

4A+6(-A)+3(1+A)=-2 4A-6A+3+3A=-2

A=-51, 8=51, C=-4/1

 $f(+) = -5e^{3t} + 5e^{2t} - 4te^{-2t}$

$$* + (s) = \frac{e^{-3s}(s+1)}{(s+2)(s-3)} \propto = 3 + (s) = \frac{(s+1)}{(s+2)(s-3)} = \frac{A}{s+2} + \frac{B}{s+3}$$

1-17 (F(S)) = 11-16 (5-12) + 4 1-17 = 5 (5-3) + B(S+2) = AS - 3A + BS + 7B = AS - 3A + BS + 7B A+B= 1 A=1-B f(+) = = + He34

8-1 {exsF(s)}= H(t-x)f(t-a) f(+)= H(t-3)(e2(+3) + 4e3(+-3)) -3+38+28=1 A=1/5

-3A+2B=1 -3(1-8)+28=1 B==1

1 dext cosuty = (5+x)2+w2 Determine $c(\infty) = l^n c(t)$ for $c(s) = \frac{(s-3)}{s^2 - s + 1 - \frac{3}{2} + \frac{3}{2}}$ Idsinuty = 52+w2 (5-1)2+3 and $C(5) = \frac{2}{52125+1}$ O c(s) = (5-\frac{1}{2})-\frac{5}{2} = \frac{5-\frac{1}{2}}{(5-\frac{1}{2})^2+\frac{3}{2}} - \frac{5}{2} \cdot \frac{1}{2}\frac{1}{2}\frac{3}{2} 引·((cs))= 引·(s-1)-5 引·(s-1)2+3) - 5 引·(s-a)9=を報 = e 2005(是七)一年十十十十十十十一日 c(+)=et/2 cos(事+)- 5et/2 sin(事+) lim c(+) = divergent since it has cos and sin,

$$2 | c(s)| = \frac{2}{s^{2}+2s+1} = \frac{2}{(s+1)^{2}}$$

$$2 - (c(s)) = 2 - (c$$

= D/1 c(00) = D/1

· Describe a closed - icop control system in your field (electronics), describe the plant, the sensor and transducers, and the actuators required.

An inverter AC where the sensor measure the air temperature at that moment, the plant is the AC itself the actuators change the speed in the AC.