



**Tecnológico de Monterrey**  
**Escuela de Ingeniería y Ciencias**

**1st Simulation Project**

Control Engineering

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## General Parameters.

**Date of Birth:** May 10, 1999.

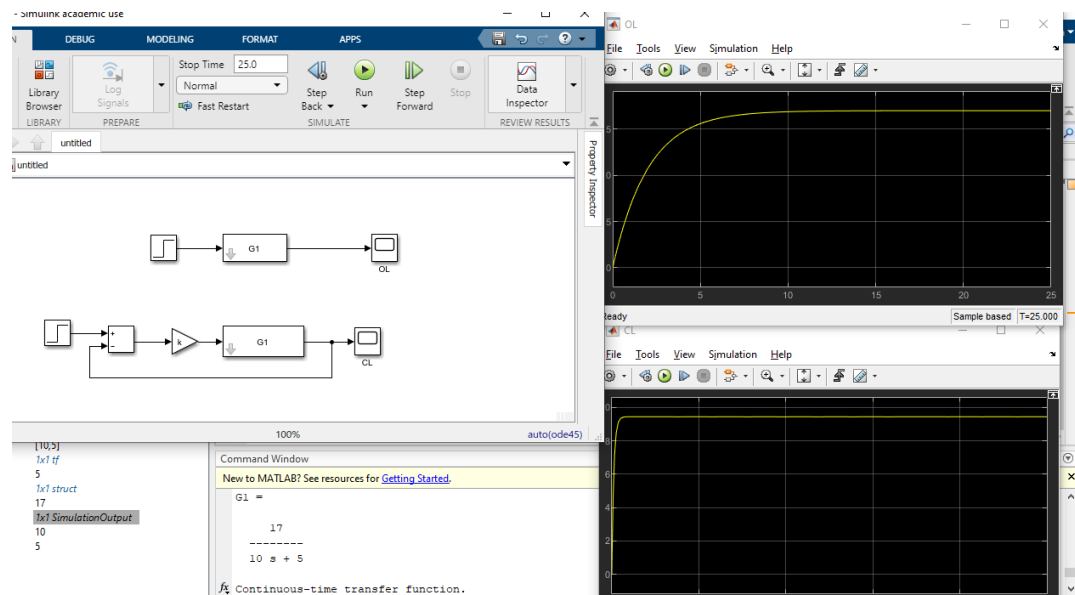
```
1      %General
2 -    a=10;
3 -    b=5;
4 -    c=17;
5 -    ut=a/2;
6 -    rt=a;
7 -    k=b;
8
9 -    matricula=struct;
10 -   matricula.general=struct;
11 -   matricula.P01=struct;
12 -   matricula.P02=struct;
13 -   matricula.P03=struct;
14 -   matricula.P04=struct;
15 -   matricula.P05=struct;
16 -   a00344428=matricula;
17
18 -   a00344428.general.a=a;
19 -   a00344428.general.b=b;
20 -   a00344428.general.c=c;
21
```

## System 1

### Code.

```
22
23     %Problema 1
24
25 -   num1=[c];
26 -   den1=[a b];
27 -   G1=tf(num1,den1);
28
29     %Open Loop P01
30 -   a00344428.P01.OL.tau=a/b;
31 -   a00344428.P01.OL.tss=5*a/b;
32 -   a00344428.P01.OL.yss=ut*c/b;
33
34     %Close Loop P01
35
36 -   a00344428.P01.CL.yss=rt*((k*c)/(b+k*c));
37 -   a00344428.P01.CL.tau=a/b;
38 -   a00344428.P01 CL.tss=5*a/b;
39
```

## Simulink.



## Transfer function.

$$\frac{17}{10s + 5}$$

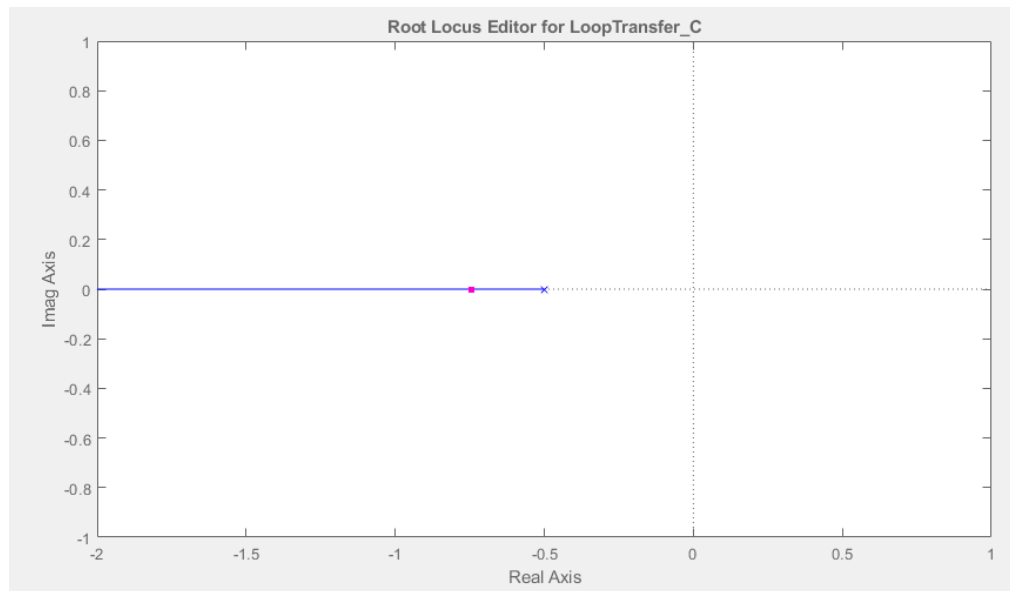
## Characterization of the system in Open Loop.

```
>> a00344428.P01.OL.tau  
  
ans =  
  
2  
  
>> a00344428.P01.OL.tss  
  
ans =  
  
10  
  
>> a00344428.P01.OL.yss  
  
ans =  
  
17
```

## Characterization of the system in Close Loop

```
>> a00344428.P01.CL.yss  
  
ans =  
  
    9.4444  
  
>> a00344428.P01.CL.tau  
  
ans =  
  
    2  
  
>> a00344428.P01.CL.tss  
  
ans =  
  
    10
```

## Gain range

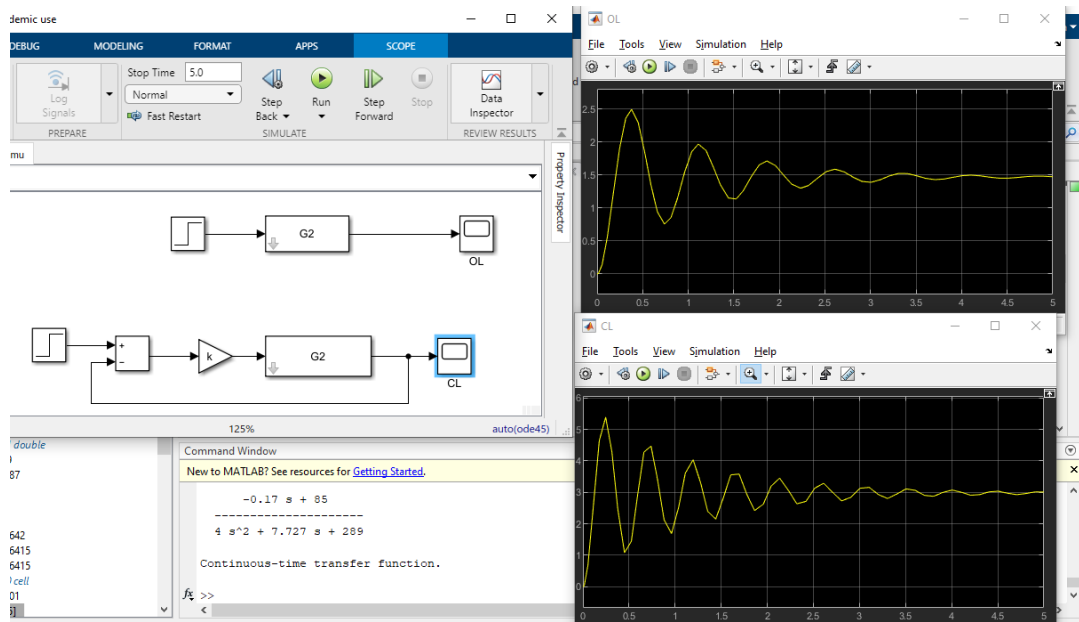


## System 2.

### Code.

```
40 %Problema 2
41 % e^(-0.004s) = -0.004s/2 + 1
42
43 num2 = [b*c*-0.004/2 b*c];
44 den2 = [4 c*a/22 c^2];
45 G2 = tf(num2,den2);
46
47
48 %Open Loop P02
49 a00344428.P02.OL.yss=ut*b*c/c^2;
50
51 a00344428.P02.OL.wn=sqrt(c^2/4);
52 a00344428.P02.OL.d=(c*a/22)/(2*4*a00344428.P02.OL.wn);
53 a00344428.P02.OL.wd=a00344428.P02.OL.wn*sqrt(1-(a00344428.P02.OL.d)^2);
54 a00344428.P02.OL.tss= 4/(a00344428.P02.OL.d*a00344428.P02.OL.wn);
55
56 %Close Loop P02
57 a00344428.P02.CL.yss = rt*((k*b*c)/(c^2+k*b*c));
58
59 a00344428.P02.CL.wn = sqrt((c^2+b*c*k)/4);
60 a00344428.P02.CL.d = ((c*a/22)+(-0.004*b*c/2)*k)/(2*4*a00344428.P02.CL.wn);
61 a00344428.P02.CL.wd=a00344428.P02.CL.wn*sqrt(1-(a00344428.P02.CL.d)^2);
62 a00344428.P02.CL.tss= 4/(a00344428.P02.CL.d*a00344428.P02.CL.wn);
```

### Simulink.



## Transfer Function.

```
G2 =  
  
      -0.17 s + 85  
      -----  
      4 s^2 + 7.727 s + 289  
  
Continuous-time transfer function.
```

## Characterization of the system in Open Loop.

```
>> a00344428.P02.OL.yss  
  
ans =  
  
      1.4706  
  
>> a00344428.P02.OL.wn  
  
ans =  
  
      8.5000  
  
>> a00344428.P02.OL.d  
  
ans =  
  
      0.1136  
  
>> a00344428.P02.OL.wd  
  
ans =  
  
      8.4449  
  
>> a00344428.P02.OL.tss  
  
ans =  
  
      4.1412
```

## Characterization of the system in Open Loop.

```
>> a00344428.P02.CL.yss
```

```
ans =
```

```
5.9524
```

```
>> a00344428.P02.CL.wn
```

```
ans =
```

```
13.3604
```

```
>> a00344428.P02.CL.d
```

```
ans =
```

```
0.0643
```

```
>> a00344428.P02.CL.wd
```

```
ans =
```

```
13.3327
```

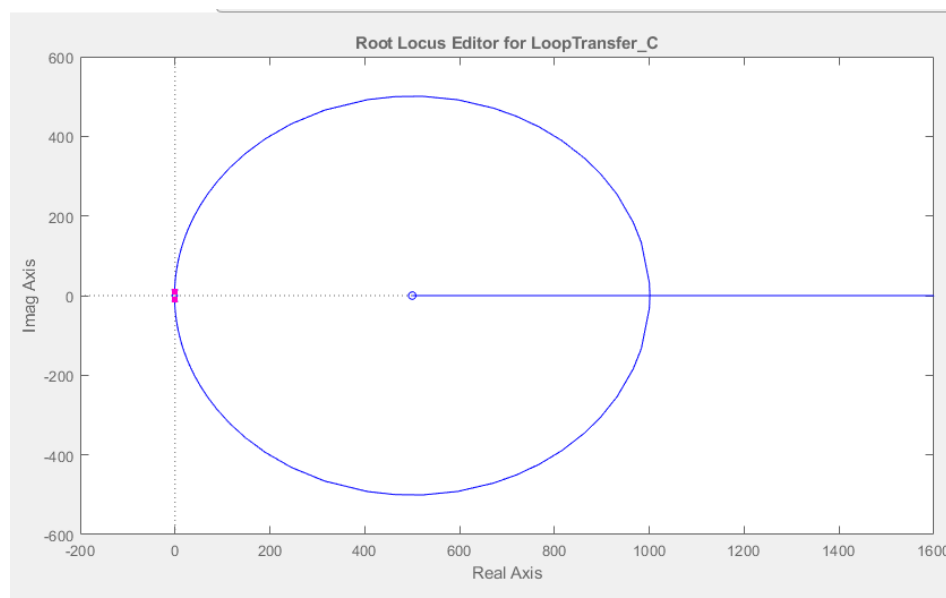
```
>> a00344428.P02.CL.tss
```

```
ans =
```

```
4.6530
```

*f<sub>x</sub>*

## Gain range

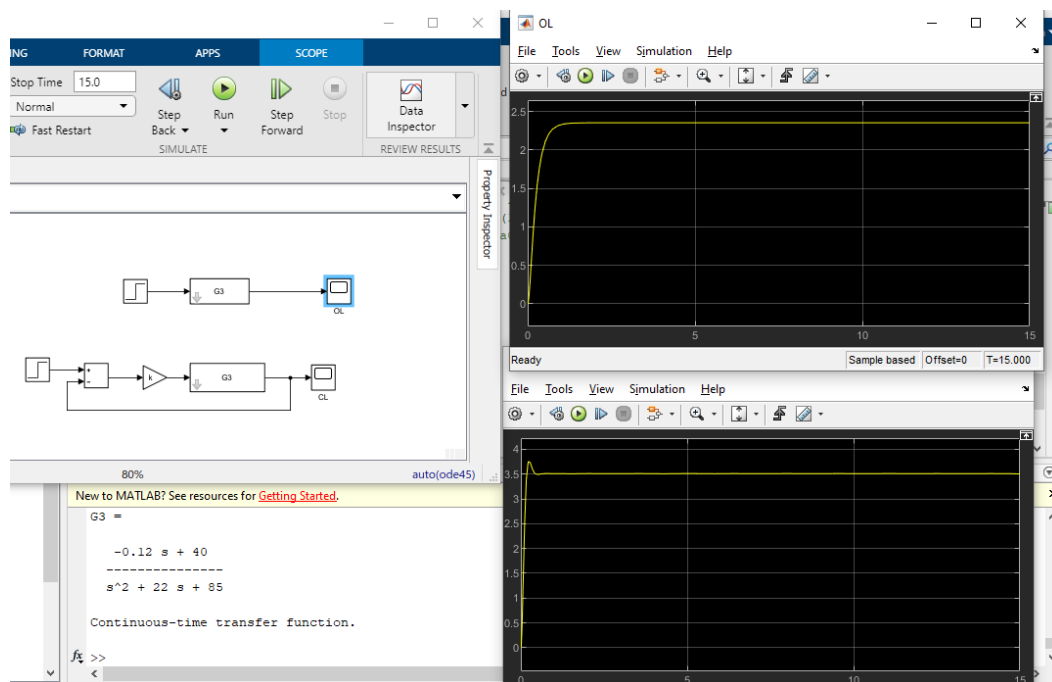


## System 3.

### Code.

```
64 %Problema 3
65 % e^(-0.006s) = -0.006s/2 + 1
66
67 num3 = [4*a*(-.006/2) 4*a];
68 den3 = [1 (b+c) b*c];
69 G3 = tf(num3,den3);
70
71 a00344428.P03.num=num3;
72 a00344428.P03.den=den3;
73
74 %Open Loop P03
75 a00344428.P03.OL.yss=ut*4*a/(b*c);
76
77 a00344428.P03.OL.wn=sqrt(b*c);
78 a00344428.P03.OL.d=(b+c)/(2*a00344428.P03.OL.wn);
79 a00344428.P03.OL.wd=a00344428.P03.OL.wn*sqrt(1-(a00344428.P03.OL.d)^2);
80 a00344428.P03.OL.tss=4/(a00344428.P03.OL.d*a00344428.P03.OL.wn);
81
82 %Close Loop P03
83 a00344428.P03.CL.yss=rt*4*a*k/(b*c+4*a*k);
84
85 a00344428.P03.CL.wn=sqrt(b*c + 4*a*k);
86 a00344428.P03.CL.d=(b+c+(-0.006*4*a*k/2))/(2*a00344428.P03.CL.wn);
87 a00344428.P03.CL.wd=a00344428.P03.CL.wn*sqrt(1-(a00344428.P03.CL.d)^2);
88 a00344428.P03.CL.tss=4/(a00344428.P03.CL.d*a00344428.P03.CL.wn);
```

### Simulink.





## Transfer Function:

$$G3 = \frac{-0.12 s + 40}{s^2 + 22 s + 85}$$

## Characterization of the system in Open Loop.

```
>> a00344428.P03.OL.yss
```

```
ans =
```

```
2.3529
```

```
>> a00344428.P03.OL.wn
```

```
ans =
```

```
9.2195
```

```
>> a00344428.P03.OL.d
```

```
ans =
```

```
1.1931
```

```
>> a00344428.P03.OL.wd
```

```
ans =
```

```
0.0000 + 6.0000i
```

```
>> a00344428.P03.OL.tss
```

```
ans =
```

```
0.3636
```

## Characterization of the system in Close Loop

```
>> a00344428.P03.CL.yss
```

```
ans =
```

```
7.0175
```

```
>> a00344428.P03.CL.wn
```

```
ans =
```

```
16.8819
```

```
>> a00344428.P03.CL.d
```

```
ans =
```

```
0.6338
```

```
>> a00344428.P03.CL.wd
```

```
ans =
```

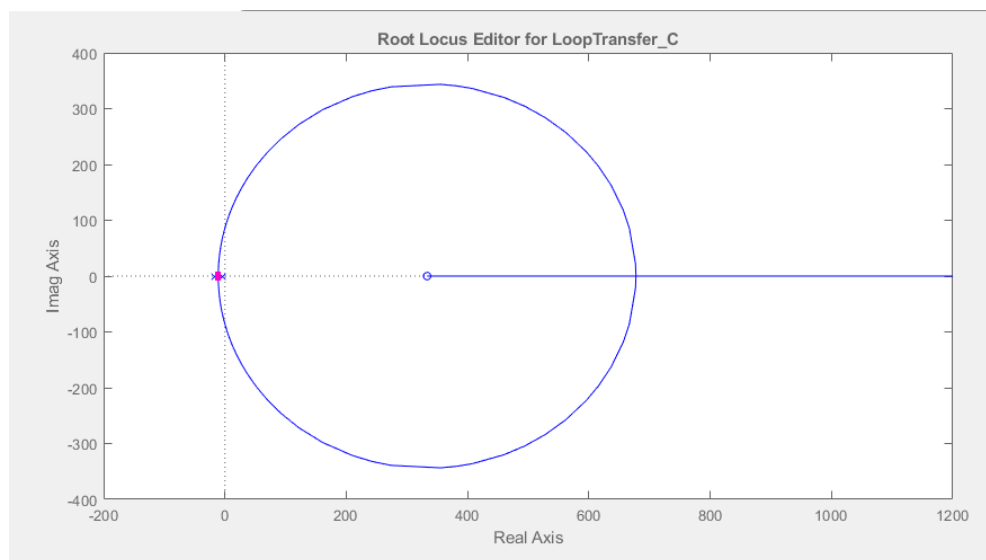
```
13.0579
```

```
>> a00344428.P03.CL.tss
```

```
ans =
```

```
0.3738
```

## Gain range.

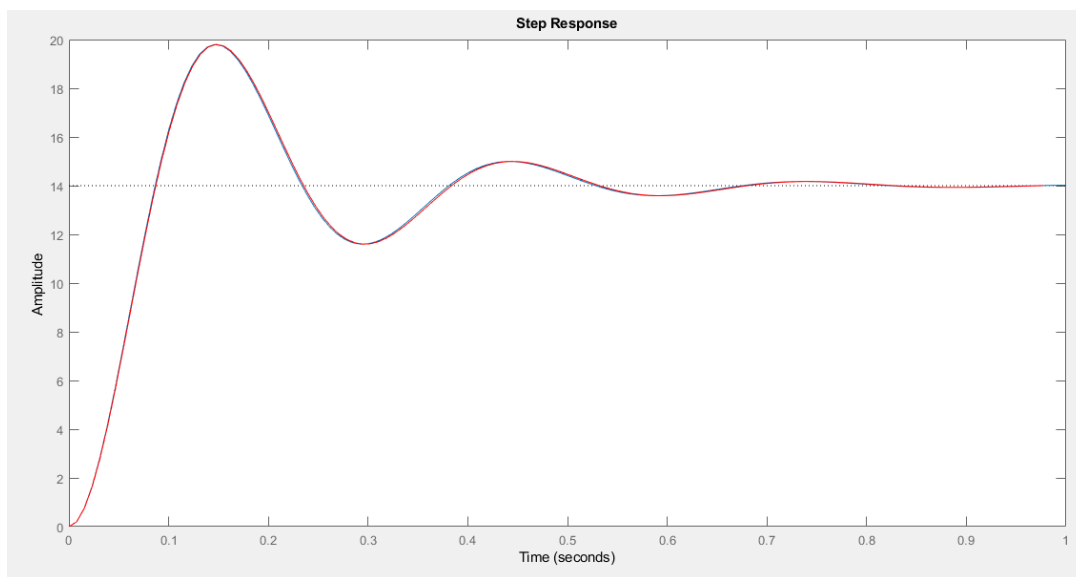


## System 4

### Code for identification Second Order.

```
1 %Using the array from DataID (given for the project)
2 - MV = DataID{2};
3 - t = MV(:,1);
4 - y = MV(:,2);
5
6 %k = last value in array from y axis
7 - k = y(end,:);
8
9 %Output of system when -> t = 5T
10 - T = (k*0.9933);
11
12 - my = max(y);
13 - mp = (my-k)/k;
14
15 - w = -log(mp)/pi;
16 - delta = sqrt((w*w)/(1+(w*w)));
17
18 - Fnd = find(y == my);
19 - tp = t(Fnd);
20
21 %Finding the damped natural frequency
22 - wd = pi/tp;
23
24 %Finding the damping factor
25 - wn = wd/sqrt(1-(delta*delta));
26
```

### Graph from the result of the identification.



## Transfer function and values.

```
G =  
  
      6869  
-----  
s^2 + 11.96 s + 490.6  
  
Continuous-time transfer function.
```

```
>> b  
  
b =  
  
      1  
  
>> c  
  
c =  
  
11.9642  
  
>> d  
  
d =  
  
490.6415
```

## Code:

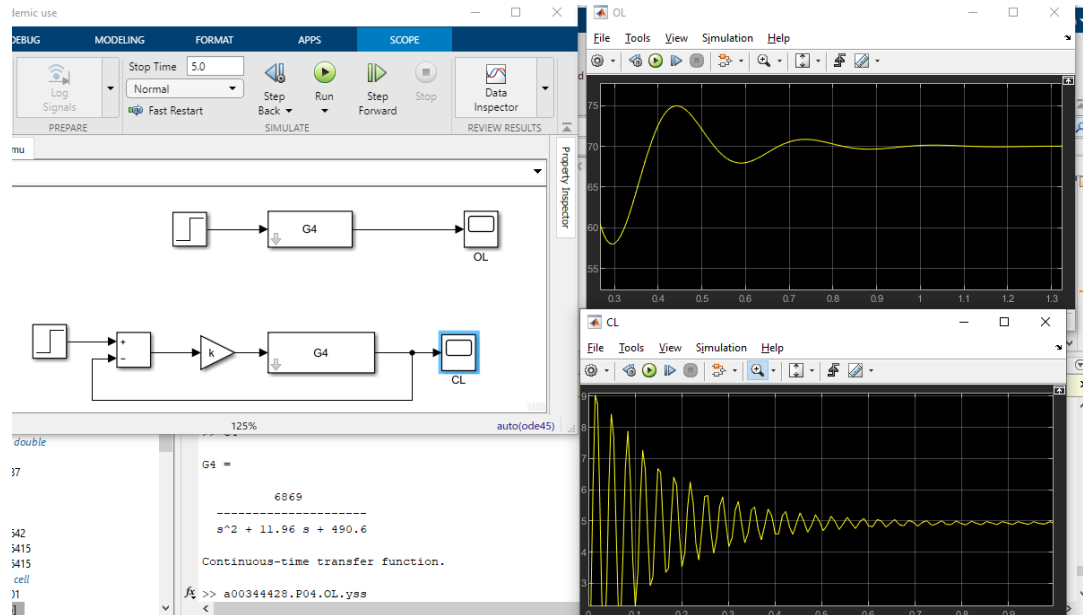
```
90 %Problema 4  
91 %Identificacion DataID{2}  
92 %6869/(s^2 + 11.9642s + 490.6415)  
93 %a/(bs^2 +cs + d)  
94 - a4=6869;  
95 - b4=1;  
96 - c4=11.9642;  
97 - d4=490.6415;  
98  
99 - num4 = [a4];  
100 - den4 = [b4 c4 d4];  
101 - G4 = tf(num4,den4);  
102  
103 - a00344428.P04.num=num4;  
104 - a00344428.P04.den=den4;  
105  
106 %Open Loop  
107 - a00344428.P04.OL.yss=ut*a4/(d4);  
108  
109 - a00344428.P04.OL.wn=sqrt(d4);  
110 - a00344428.P04.OL.d=c4/(2*a00344428.P04.OL.wn);  
111 - a00344428.P04.OL.wd = a00344428.P04.OL.wn*sqrt(1-(a00344428.P04.OL.d)^2);  
112 - a00344428.P04.OL.tss=4/(a00344428.P1OL.d*a00344428.P04.OL.wn);  
113
```

```

114 %Close Loop
115 a00344428.P04.CL.yss=rt*a4*k/(d4+a4*k);
116
117 a00344428.P04.CL.wn=sqrt(d4 + a4*k);
118 a00344428.P04.CL.d=c4/(2*a00344428.P04.CL.wn);
119 a00344428.P04.CL.wd=a00344428.P04.CL.wn*sqrt(1-(a00344428.P04.CL.d)^2);
120 a00344428.P04.CL.tss=4/(a00344428.P04.CL.d*a00344428.P04.CL.wn);

```

## Simulink.



## Transfer function.

$$G4 = \frac{6869}{s^2 + 11.96 s + 490.6}$$

## Characterization of the system in Open Loop.

```
>> a00344428.P04.OL.yss
ans =

    70.0002

>> a00344428.P04.OL.wn
ans =

    22.1504

>> a00344428.P04.OL.d
ans =

    0.2701

>> a00344428.P04.OL.wd
ans =

    21.3274

>> a00344428.P04.OL.tss
ans =

    0.6687
```

## Characterization of the system in Close Loop.

```
>> a00344428.P04.CL.yss
ans =

    9.8592

>> a00344428.P04.CL.wn
ans =

   186.6431

>> a00344428.P04.CL.d
ans =

    0.0321

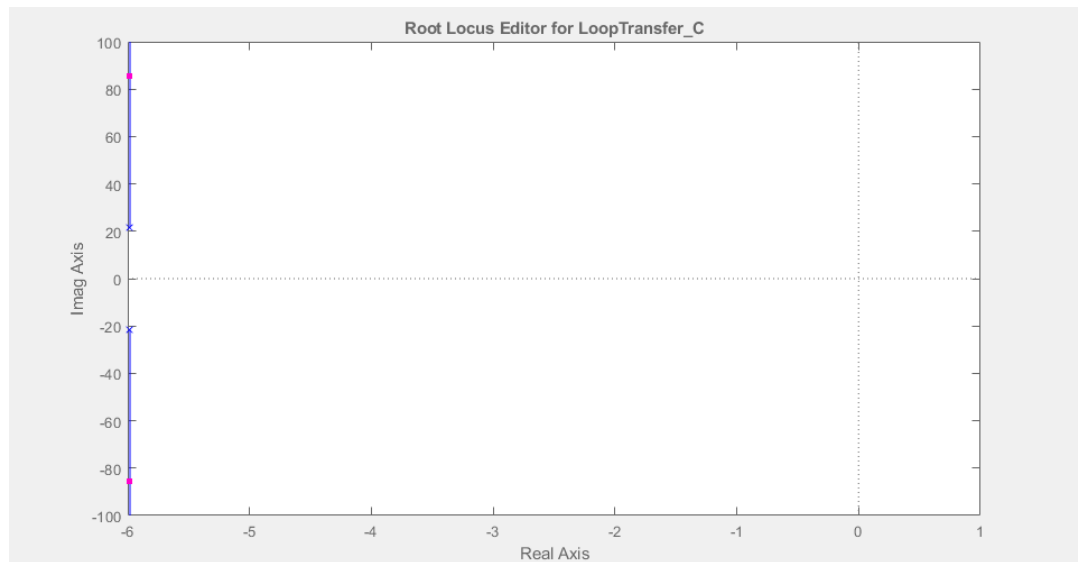
>> a00344428.P04.CL.wd
ans =

   186.5472

>> a00344428.P04.CL.tss
ans =

    0.6687
```

## Gain range.



## System 5

### General:

```
%Problema 5
Q1 = Qin_1(2);
H1Max = H1max(2);
A01 = A1(2);
R01 = R1(2);

Q2 = Qin_2(2);
H2Max = H2max(2);
A02 = A2(2);
R02 = R2(2);
```

1.

```
%1.
%   H1(s)/Qin(s)= ?
%   From the book we know that: (R1Cs + 1)H(s)=R1Qin(s) where C = A1
%   Therefore: H1(s)/Qin(s) = R1/(R1A1s + 1)
num1 = [R01];
den1 = [(R01*A01) 1];

%   H2(s)/ Qin(s) = ?
%   From the equation above, we obtain H2(s) = R2, however, since now the
%   Qin is the multiplication of the 1st tank and the 2nd tank
%   Qin(s) = (R1A1s + 1)(R2A2s + 1) = (R1A1R2A2)s^2 + (R1A1+R2A2)s + 1
%   Therefore: H2(s)/ Qin(s) = R2/(R1A1R2A2)s^2 + (R1A1+R2A2)s + 1
num2 = [R02];
den2 = [(R01*A01*R02*A02) (R01*A01 + R02*A02) 1]
```

2.

```
%2
%   H1(s)/Qin(s)= ?
G1 = tf(num1, den1);
%   H2(s)/ Qin(s) = ?
G2 = tf(num2, den2);
```

```
G1 =

      1.7
-----
66.3 s + 1

Continuous-time transfer function.

>> G2

G2 =

           4
-----
1.724e04 s^2 + 326.3 s + 1

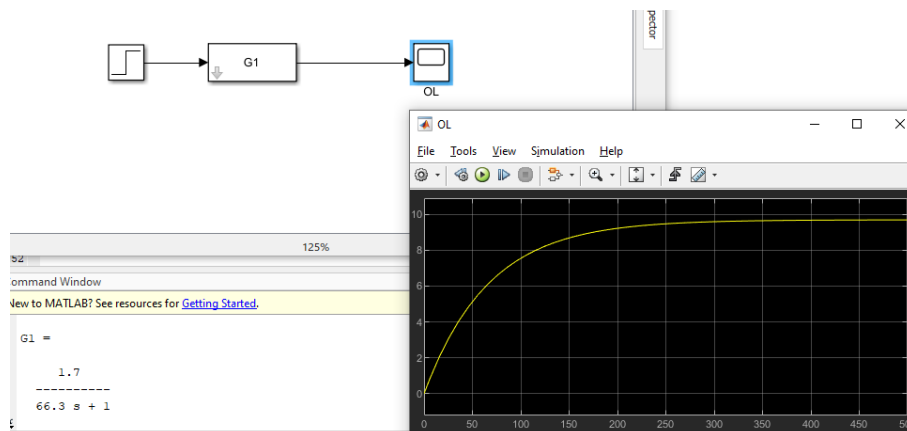
Continuous-time transfer function.
```



3.

```
%3  
a00344428.P05.H1.yss= Qin1*R01;  
a00344428.P05.H1.tss= 5*R01*A01;
```

```
>> G1  
  
G1 =  
  
    1.7  
-----  
66.3 s + 1  
  
Continuous-time transfer function.  
  
>> a00344428.P05.H1.yss  
  
ans =  
  
    9.6900  
  
>> a00344428.P05.H1.tss  
  
ans =  
  
   331.5000
```



4.

```
%4
a00344428.P05.H2.yss= Qin2*R02;

a00344428.P05.H2.wn=sqrt(1/(R01*A01*R02*A02));
a00344428.P05.H2.d=(R01*A01 + R02*A02)/(2*R01*A01*R02*A02*a00344428.P05.H2.wn);
a00344428.P05.H2.wd=a00344428.P05.H2.wn*sqrt(1-(a00344428.P05.H2.d)^2);
a00344428.P05.H2.tss=4/(a00344428.P05.H2.d*a00344428.P05.H2.wn);
```

```
G2 =

          4
-----
1.724e04 s^2 + 326.3 s + 1

Continuous-time transfer function.
```

```
>> a00344428.P05.H2.yss
```

```
ans =
```

```
12.4000
```

```
>> a00344428.P05.H2.d
```

```
ans =
```

```
1.2426
```

```
>> a00344428.P05.H2.wn
```

```
ans =
```

```
0.0076
```

```
>> a00344428.P05.H2.wd
```

```
ans =
```

```
0.0000 + 0.0056i
```

```
>> a00344428.P05.H2.tss
```

```
ans =
```

```
422.6295
```

