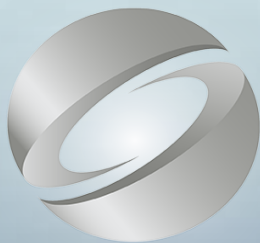


An Introduction to OpenGL Programming

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- OpenGL is a computer graphics rendering *application programming interface*, or API (for short)
 - With it, you can generate high-quality color images by rendering with geometric and image primitives
 - It forms the basis of many interactive applications that include 3D graphics
 - By using OpenGL, the graphics part of your application can be
 - operating system independent
 - window system independent

- We'll concentrate on newer versions of OpenGL
- They enforce a new way to program with OpenGL
 - Allows more efficient use of GPU resources
- Modern OpenGL doesn't support many of the “classic” ways of doing things, such as
 - Fixed-function graphics operations, like vertex lighting and transformations
- All applications must use *shaders* for their graphics processing
 - we only introduce a subset of OpenGL's shader capabilities in this course

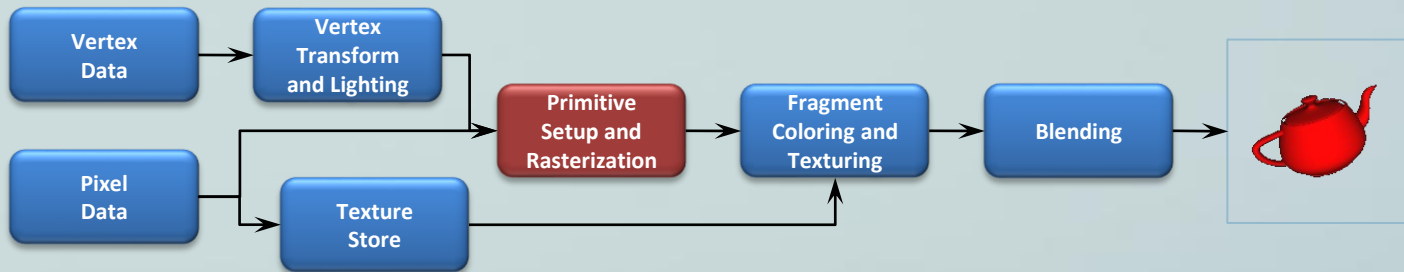
Evolution of the OpenGL Pipeline



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- OpenGL 1.0 was released on July 1st, 1994
- Its pipeline was entirely *fixed-function*
 - the only operations available were fixed by the implementation

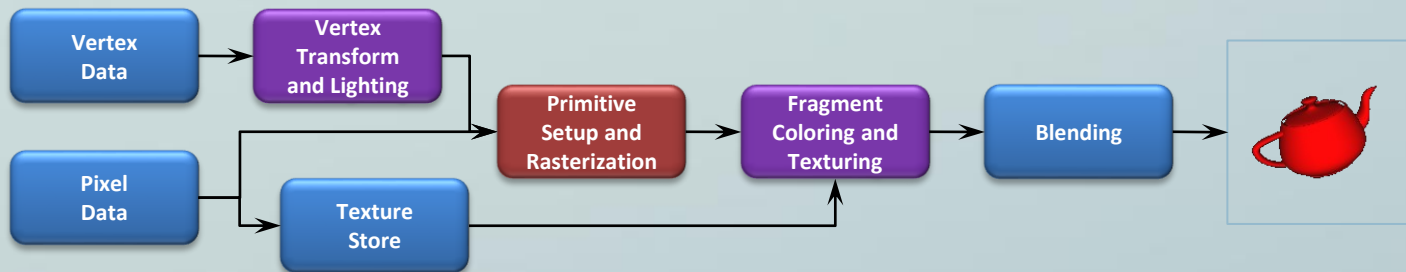


- The pipeline evolved
 - but remained based on fixed-function operation through OpenGL versions 1.1 through 2.0 (Sept. 2004)



Beginnings of The Programmable Pipeline

- OpenGL 2.0 (officially) added programmable shaders
 - *vertex shading* augmented the fixed-function transform and lighting stage
 - *fragment shading* augmented the fragment coloring stage
- However, the fixed-function pipeline was still available



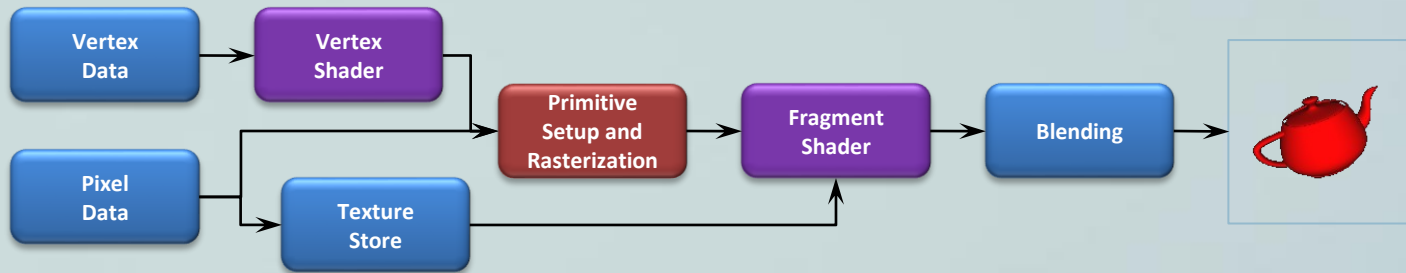
An Evolutionary Change

- OpenGL 3.0 introduced the *deprecation model*
 - the method used to remove features from OpenGL
- The pipeline remained the same until OpenGL 3.1 (released March 24th, 2009)
- Introduced a change in how OpenGL contexts are used

Context Type	Description
Full	Includes all features (including those marked deprecated) available in the current version of OpenGL
Forward Compatible	Includes all non-deprecated features (i.e., creates a context that would be similar to the next version of OpenGL)

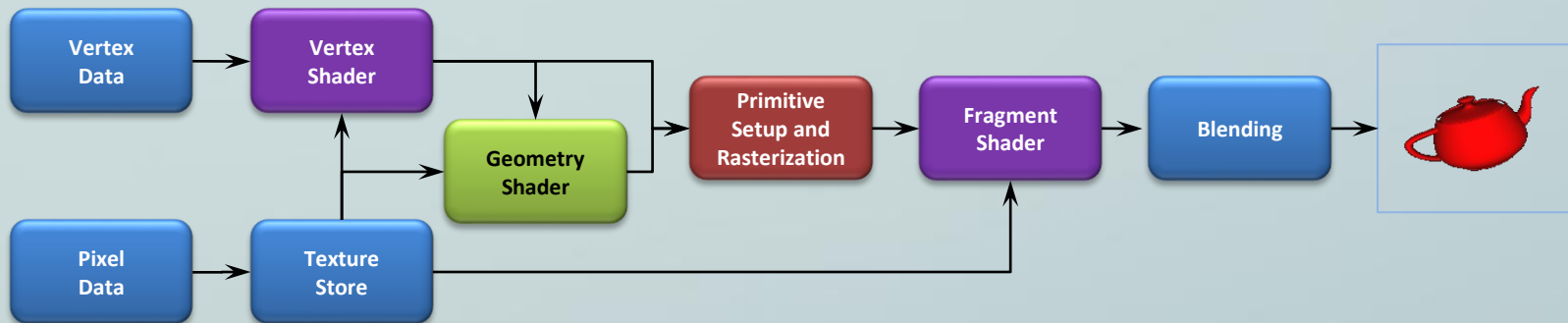
The Exclusively Programmable Pipeline

- OpenGL 3.1 removed the fixed-function pipeline
 - programs were required to use only shaders



- Additionally, almost all data is GPU-resident
 - all vertex data sent using buffer objects

- OpenGL 3.2 (released August 3rd, 2009) added an additional shading stage – geometry shaders
 - modify geometric primitives within the graphics pipeline

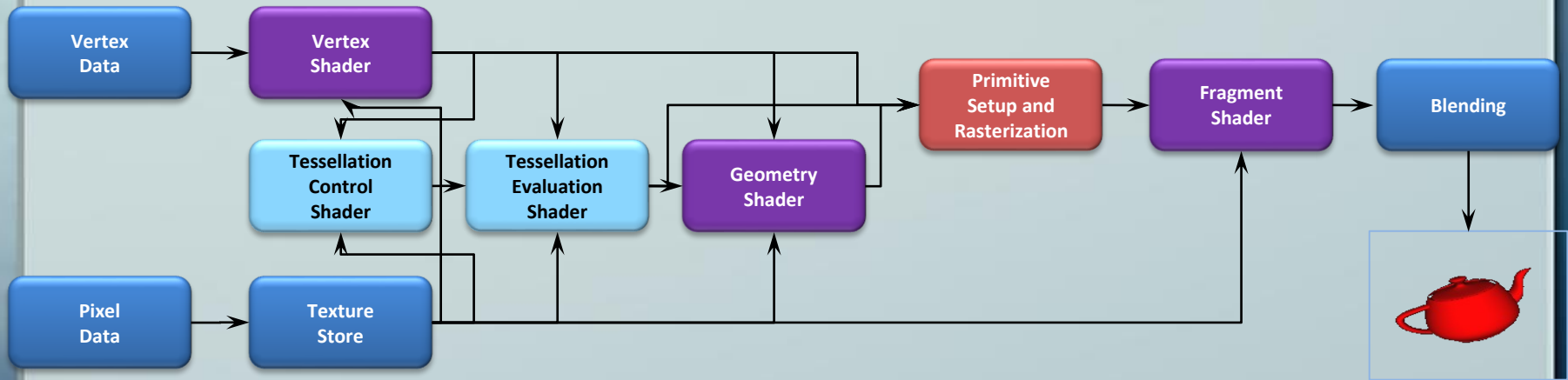


More Evolution – Context Profiles

- OpenGL 3.2 also introduced *context profiles*
 - profiles control which features are exposed
 - it's like `GL_ARB_compatibility`, only not insane 😊
 - currently two types of profiles: *core* and *compatible*

Context Type	Profile	Description
Full	core	All features of the current release
	compatible	All features ever in OpenGL
Forward Compatible	core	All non-deprecated features
	compatible	Not supported

- OpenGL 4.1 (released July 25th, 2010) included additional shading stages – *tessellation-control* and *tessellation-evaluation* shaders
- Latest version is 4.6



- OpenGL ES 2.0
 - Designed for embedded and hand-held devices such as cell phones
 - Based on OpenGL 3.1
 - Shader based
- WebGL
 - JavaScript implementation of ES 2.0
 - Runs on most recent browsers

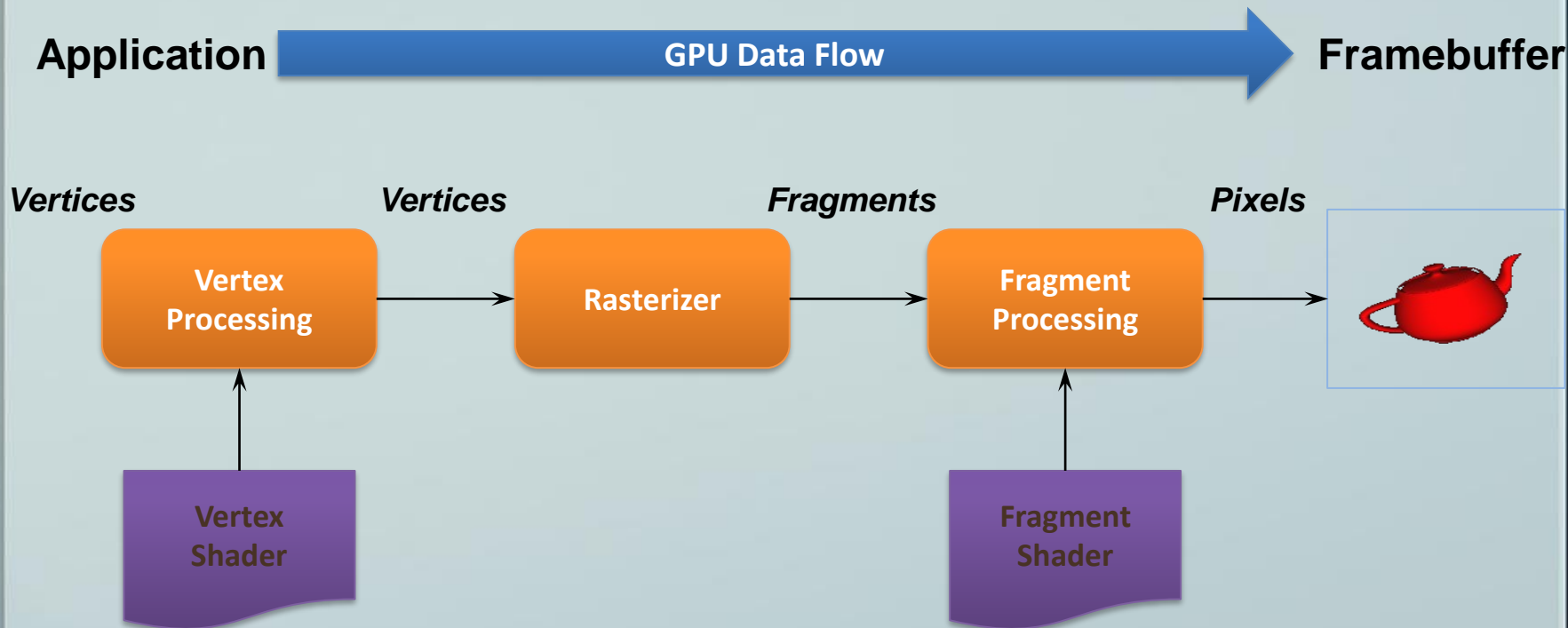
OpenGL Application Development



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A Simplified Pipeline Model



OpenGL Programming in a Nutshell

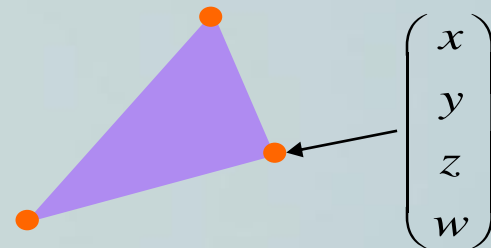
- Modern OpenGL programs essentially do the following steps:
 - Create shader programs
 - Create buffer objects and load data into them
 - “Connect” data locations with shader variables
 - Render

Application Framework Requirements

- OpenGL applications need a place to render into
 - usually an on-screen window
- Need to communicate with native windowing system
- Each windowing system interface is different
- On Android, we have built-in functions that can help create a render target and a window.
 - GLSurfaceView

Representing Geometric Objects

- Geometric objects are represented using *vertices*
- A vertex is a collection of generic attributes
 - positional coordinates
 - colors
 - texture coordinates
 - any other data associated with that point in space
- Position stored in 4 dimensional homogeneous coordinates
 - Allows us to express all vertex transformations using matrix-vector multiplies
- Vertex data must be stored in vertex buffer objects (VBOs)
- VBOs must be stored in vertex array objects (VAOs)



Vertex Array Objects (VAOs)

- VAOs store the data of an geometric object
- Steps in using a VAO
 - generate VAO names by calling `glGenVertexArrays()`
 - bind a specific VAO for initialization by calling `glBindVertexArray()`
 - update VBOs associated with this VAO
 - bind VAO for use in rendering
- This approach allows a single function call to specify all the data for an objects
 - previously, you might have needed to make many calls to make all the data current

- Create a vertex array object

```
GLuint vao;  
glGenVertexArrays( 1, &vao );  
glBindVertexArray( vao );
```

Storing Vertex Attributes

- Vertex data must be stored in a VBO, and associated with a VAO
- The code-flow is similar to configuring a VAO
 - generate VBO names by calling `glGenBuffers()`
 - bind a specific VBO for initialization by calling

```
glBindBuffer( GL_ARRAY_BUFFER, ... )
```

- load data into VBO using

```
glBufferData( GL_ARRAY_BUFFER, ... )
```

- bind VAO for use in rendering `glBindVertexArray()`

Connecting Vertex Shaders with Geometric Data

- Application vertex data enters the OpenGL pipeline through the vertex shader
- Need to connect vertex data to shader variables
 - requires knowing the attribute location
- Attribute location can either be queried by calling `glGetVertexAttribLocation()`

Drawing Geometric Primitives

- For contiguous groups of vertices

```
glDrawArrays( GL_TRIANGLES, 0, NumVertices );
```

- Usually invoked in display callback
- Initiates vertex shader

Shaders and GLSL



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- Scalar types: `float, int, bool`
- Vector types: `vec2, vec3, vec4`
`ivec2, ivec3, ivec4`
`bvec2, bvec3, bvec4`
- Matrix types: `mat2, mat3, mat4`
- Texture sampling: `sampler1D, sampler2D,`
`sampler3D, samplerCube`
- C++ Style Constructors
`vec3 a = vec3(1.0, 2.0, 3.0);`

- Standard C/C++ arithmetic and logic operators
- Overloaded operators for matrix and vector operations

```
mat4 m;  
vec4 a, b, c;
```

```
b = a*m;  
c = m*a;
```

Components and Swizzling

- Access vector components using either:
 - `[]` (c-style array indexing)
 - `xyzw`, `rgba` or `strq` (named components)
- For example:
`vec3 v;`
`v[1]`, `v.y`, `v.g`, `v.t` - all refer to the same element
- Component swizzling:
`vec3 a, b;`
`a.xy = b.yx;`

- **in, out**
 - Copy vertex attributes and other variable into and out of shaders

```
in  vec2 texCoord;  
out vec4 color;
```

- **uniform**
 - shader-constant variable from application

```
uniform float time;  
uniform vec4 rotation;
```

- Built in
 - Arithmetic: `sqrt`, `power`, `abs`
 - Trigonometric: `sin`, `asin`
 - Graphical: `length`, `reflect`
- User defined

- `gl_Position`
 - (required) output position from vertex shader
- `gl_FragCoord`
 - input fragment position
- `gl_FragDepth`
 - input depth value in fragment shader

Simple Vertex Shader for Cube Example

```
#version 430

in vec4 vPosition;
in vec4 vColor;

out vec4 color;

void main()
{
    color = vColor;
    gl_Position = vPosition;
}
```

The Simplest Fragment Shader

```
#version 430

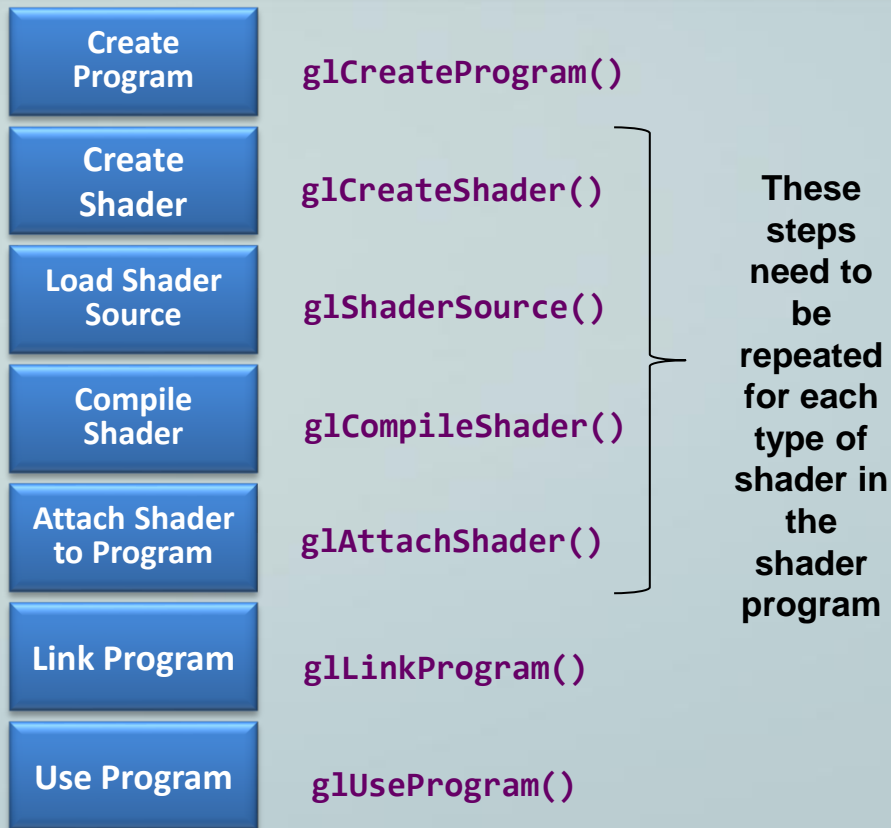
in vec4 color;

out vec4 fColor; // fragment's final color

void main()
{
    fColor = color;
}
```

Getting Your Shaders into OpenGL

- Shaders need to be compiled and linked to form an executable shader program
- OpenGL provides the compiler and linker
- A program must contain
 - vertex and fragment shaders
 - other shaders are optional



Associating Shader Variables and Data

- Need to associate a shader variable with an OpenGL data source
 - vertex shader attributes → app vertex attributes
 - shader uniforms → app provided uniform values
- OpenGL relates shader variables to indices for the app to set
- Two methods for determining variable/index association
 - specify association before program linkage
 - query association after program linkage

Determining Locations After Linking

- Assumes you already know the variables' names

```
GLint loc = glGetUniformLocation( program, "name" );
```

```
GLint loc = glGetUniformLocation( program, "name" );
```

Vertex Shader Examples

- A vertex shader is initiated by each vertex output by `glDrawArrays()`
- A vertex shader must output a position in clip coordinates to the rasterizer
- Basic uses of vertex shaders
 - Transformations
 - Lighting
 - Moving vertex positions

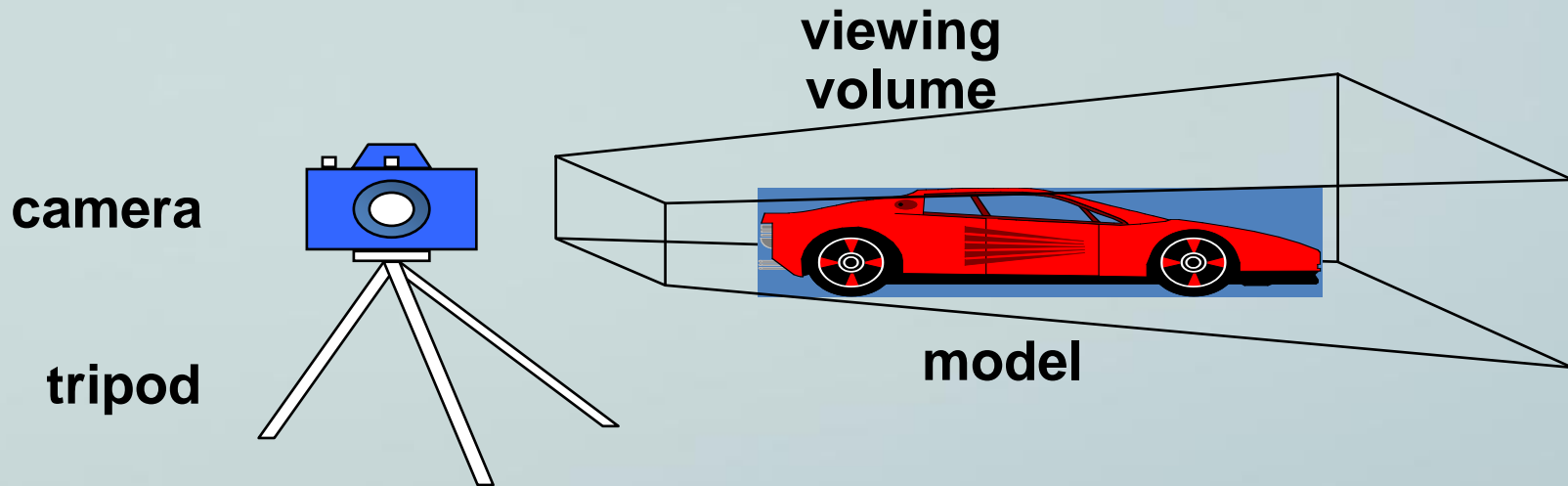
Transformations



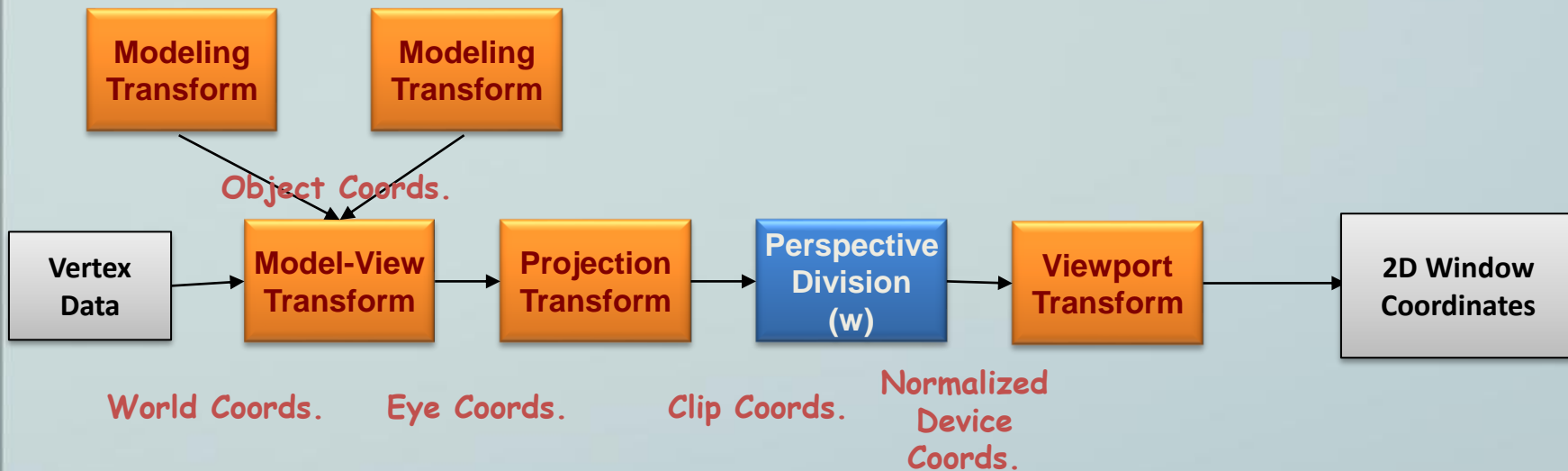
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- 3D is just like taking a photograph (lots of photographs!)



- Transformations take us from one “space” to another
 - All of our transforms are 4×4 matrices



Camera Analogy and Transformations

- Projection transformations
 - adjust the lens of the camera
- Viewing transformations
 - tripod—define position and orientation of the viewing volume in the world
- Modeling transformations
 - moving the model
- Viewport transformations
 - enlarge or reduce the physical photograph

- A vertex is transformed by 4×4 matrices
 - all affine operations are matrix multiplications
- All matrices are stored column-major in OpenGL
 - this is opposite of what “C” programmers expect
- Product of matrix and vector is $\mathbf{M}\vec{v}$

$$\mathbf{M} = \begin{bmatrix} m_0 & m_4 & m_8 & m_{12} \\ m_1 & m_5 & m_9 & m_{13} \\ m_2 & m_6 & m_{10} & m_{14} \\ m_3 & m_7 & m_{11} & m_{15} \end{bmatrix}$$

Specifying What You Can See

- Set up a viewing frustum to specify how much of the world we can see
- Done in two steps
 - specify the size of the frustum (projection transform)
 - specify its location in space (model-view transform)
- Anything outside of the viewing frustum is clipped
 - primitive is either modified or discarded (if entirely outside frustum)

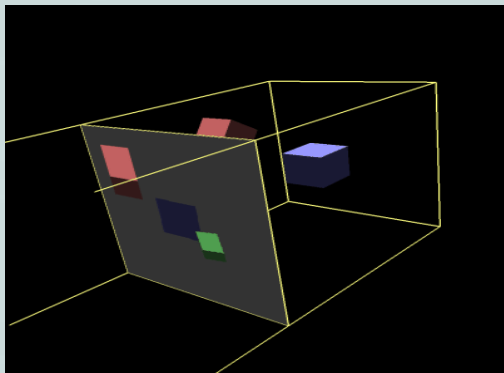
Specifying What You Can See (cont'd)

- OpenGL projection model uses eye coordinates
 - the “eye” is located at the origin
 - looking down the -z axis
- Projection matrices use a six-plane model:
 - near (image) plane and far (infinite) plane
 - both are distances from the eye (positive values)
 - enclosing planes
 - top & bottom, left & right



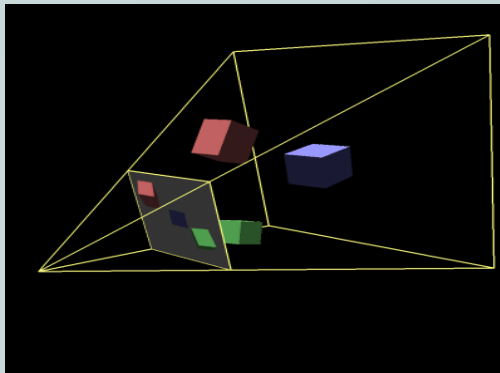
Specifying What You Can See (cont'd)

Orthographic View



$$O = \begin{pmatrix} \frac{2}{r-l} & 0 & 0 & \frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & \frac{t+b}{t-b} \\ 0 & 0 & \frac{-2}{f-n} & \frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Perspective View



$$P = \begin{pmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & \frac{-(f+n)}{f-n} & \frac{-2fn}{f-n} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

Viewing Transformations

- Position the camera/eye in the scene
 - place the tripod down; aim camera
- To “fly through” a scene
 - change viewing transformation and redraw scene
- LookAt(eyex, eyey, eyez,
 lookx, looky, lookz,
 upx, upy, upz)
 - up vector determines unique orientation
 - careful of degenerate positions



Creating the LookAt Matrix

$$\hat{n} = \frac{\overrightarrow{look-eye}}{\|\overrightarrow{look-eye}\|}$$

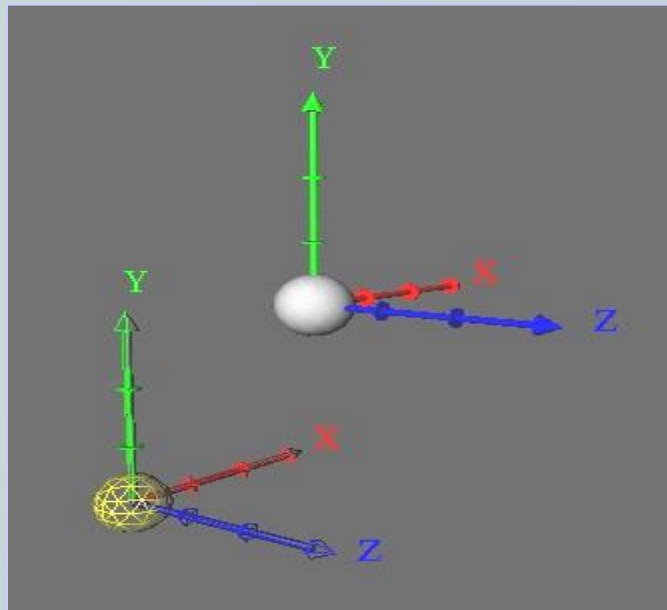
$$\hat{u} = \frac{\hat{n} \times \overrightarrow{up}}{\|\hat{n} \times \overrightarrow{up}\|}$$

$$\hat{v} = \hat{u} \times \hat{n}$$

$$D = \begin{pmatrix} u_x & u_y & u_z & -(eye \times \vec{u}) & 0 \\ v_x & v_y & v_z & -(eye \times \vec{v}) & 0 \\ -n_x & -n_y & -n_z & -(eye \times \vec{n}) & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

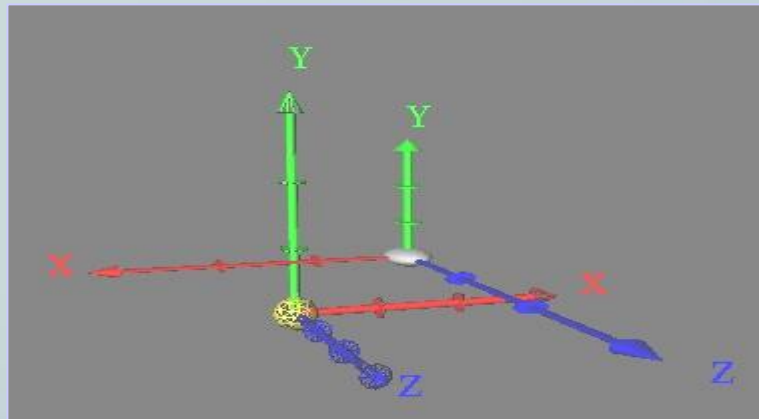
- Move the origin to a new location

$$T(t_x, t_y, t_z) = \begin{pmatrix} 1 & 0 & 0 & t_x \\ 0 & 1 & 0 & t_y \\ 0 & 0 & 1 & t_z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



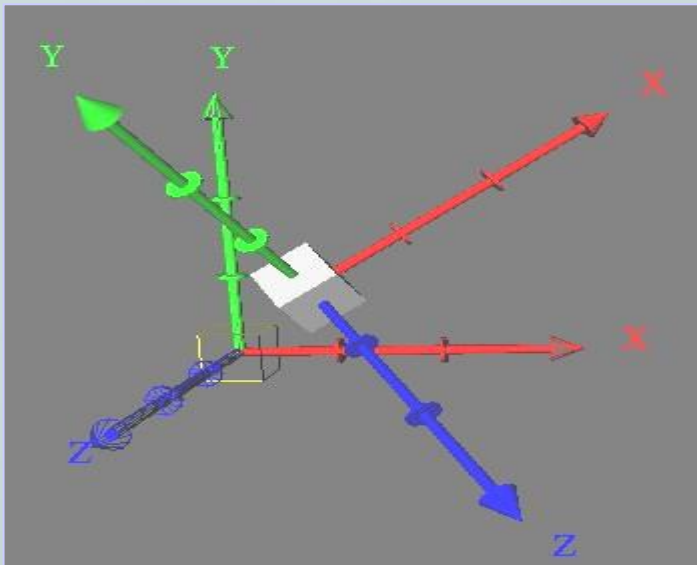
- Stretch, mirror or decimate a coordinate direction

$$S(s_x, s_y, s_z) = \begin{pmatrix} s_x & 0 & 0 & 0 \\ 0 & s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



Note, there's a translation applied here to make things easier to see

- Rotate coordinate system about an axis in space



Note, there's a translation applied here to make things easier to see

$$\vec{v} = \begin{pmatrix} x & y & z \end{pmatrix}$$

$$\vec{u} = \frac{\vec{v}}{\|\vec{v}\|} = \begin{pmatrix} x_{\mathbb{C}} & y_{\mathbb{C}} & z_{\mathbb{C}} \end{pmatrix}$$

$$M = \vec{u}^t \vec{u} + \cos(q)(I - \vec{u}^t \vec{u}) + \sin(q)S$$

$$S = \begin{pmatrix} \mathfrak{x} & \mathbf{0} & -z^{\mathfrak{C}} & y^{\mathfrak{C}} & \ddot{0} \\ \mathfrak{C} & z^{\mathfrak{C}} & \mathbf{0} & -x^{\mathfrak{C}} & \ddot{} \\ \mathfrak{C} & -y^{\mathfrak{C}} & x^{\mathfrak{C}} & \mathbf{0} & \ddot{} \\ \mathfrak{C} & & & & \ddot{} \end{pmatrix}$$

$$R_{\vec{v}}(\mathbf{q}) = \begin{matrix} \mathfrak{X} & & & 0 \\ \zeta & & & \ddot{0} \\ \zeta & & & \div \\ \zeta & & & 0 \\ \zeta & & & \div \\ \zeta & & & \div \\ \zeta & & & 0 \\ \zeta & & & \div \\ \zeta & & & \div \\ \mathfrak{E} & 0 & 0 & 0 & 1 \\ & & & & \div \\ & & & & \emptyset \end{matrix} \mathbf{M}$$

Vertex Shader for Rotation of Cube

```
in vec4 vPosition;  
in vec4 vColor;  
out vec4 color;  
uniform vec3 theta;  
  
void main()  
{  
    // Compute the sines and cosines of theta for  
    // each of the three axes in one computation.  
    vec3 angles = radians( theta );  
    vec3 c = cos( angles );  
    vec3 s = sin( angles );
```



// Remember: these matrices are column-major

```
mat4 rx = mat4( 1.0,  0.0,  0.0, 0.0,  
                0.0,  c.x,  s.x, 0.0,  
                0.0, -s.x,  c.x, 0.0,  
                0.0,  0.0,  0.0, 1.0 );
```

```
mat4 ry = mat4( c.y, 0.0, -s.y, 0.0,  
                0.0, 1.0,  0.0, 0.0,  
                s.y, 0.0,  c.y, 0.0,  
                0.0, 0.0,  0.0, 1.0 );
```



```
mat4 rz = mat4( c.z, -s.z, 0.0, 0.0,  
                s.z,  c.z, 0.0, 0.0,  
                0.0,  0.0, 1.0, 0.0,  
                0.0,  0.0, 0.0, 1.0 );  
  
color = vColor;  
gl_Position = rz * ry * rx * vPosition;  
}
```

Sending Angles from Application

- Here, we compute our angles (**Theta**) in our mouse callback

```
GLuint theta; // theta uniform location
vec3  Theta;  // Axis angles

void display( void )
{
    glClear( GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT );

    glUniform3fv( theta, 1, Theta );
    glDrawArrays( GL_TRIANGLES, 0, NumVertices );

    glutSwapBuffers();
}
```

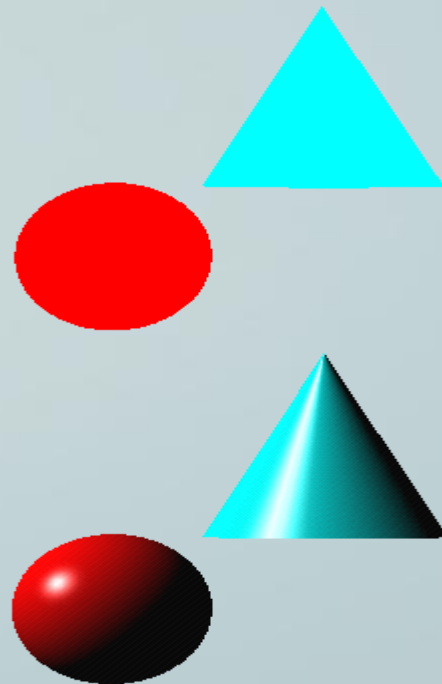
Lighting



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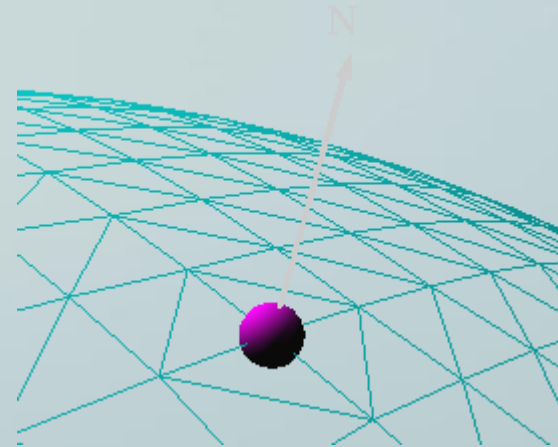
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- Lighting simulates how objects reflect light
 - material composition of object
 - light's color and position
 - global lighting parameters
- Usually implemented in
 - vertex shader for faster speed
 - fragment shader for nicer shading



- Computes a color for each vertex using
 - Surface normals
 - Diffuse and specular reflections
 - Viewer's position and viewing direction
 - Ambient light
 - Emission
- Vertex colors are interpolated across polygons by the rasterizer
 - *Phong shading* does the same computation per pixel, interpolating the normal across the polygon
 - more accurate results

- Normals define how a surface reflects light
 - Application usually provides normals as a vertex attribute
 - Current normal is used to compute vertex's color
 - Use unit normals for proper lighting
 - scaling affects a normal's length



- Define the surface properties of a primitive

Property	Description
Diffuse	Base object color
Specular	Highlight color
Ambient	Low-light color
Emission	Glow color
Shininess	Surface smoothness

- you can have separate materials for front and back

Adding Lighting to Cube

```
// vertex shader
```

```
in vec4 vPosition;  
in vec3 vNormal;  
out vec4 color;
```

```
uniform vec4  
    AmbientProduct, DiffuseProduct, SpecularProduct;  
uniform mat4 ModelView;  
uniform mat4 Projection;  
uniform vec4 LightPosition;  
uniform float Shininess;
```

```
void main()
{
    // Transform vertex position into eye coordinates
    vec3 pos = vec3(ModelView * vPosition);

    vec3 L = normalize(LightPosition.xyz - pos);
    vec3 E = normalize(-pos);
    vec3 H = normalize(L + E);

    // Transform vertex normal into eye coordinates
    vec3 N = normalize(vec3(ModelView * vNormal));
```

```
// Compute terms in the illumination equation
vec4 ambient = AmbientProduct;

float Kd = max( dot(L, N), 0.0 );
vec4  diffuse = Kd*DiffuseProduct;

float Ks = pow( max(dot(N, H), 0.0), Shininess );
vec4  specular = Ks * SpecularProduct;
if( dot(L, N) < 0.0 )
    specular = vec4(0.0, 0.0, 0.0, 1.0)

gl_Position = Projection * ModelView * vPosition;

color = ambient + diffuse + specular;
color.a = 1.0;
}
```

Fragment Shaders



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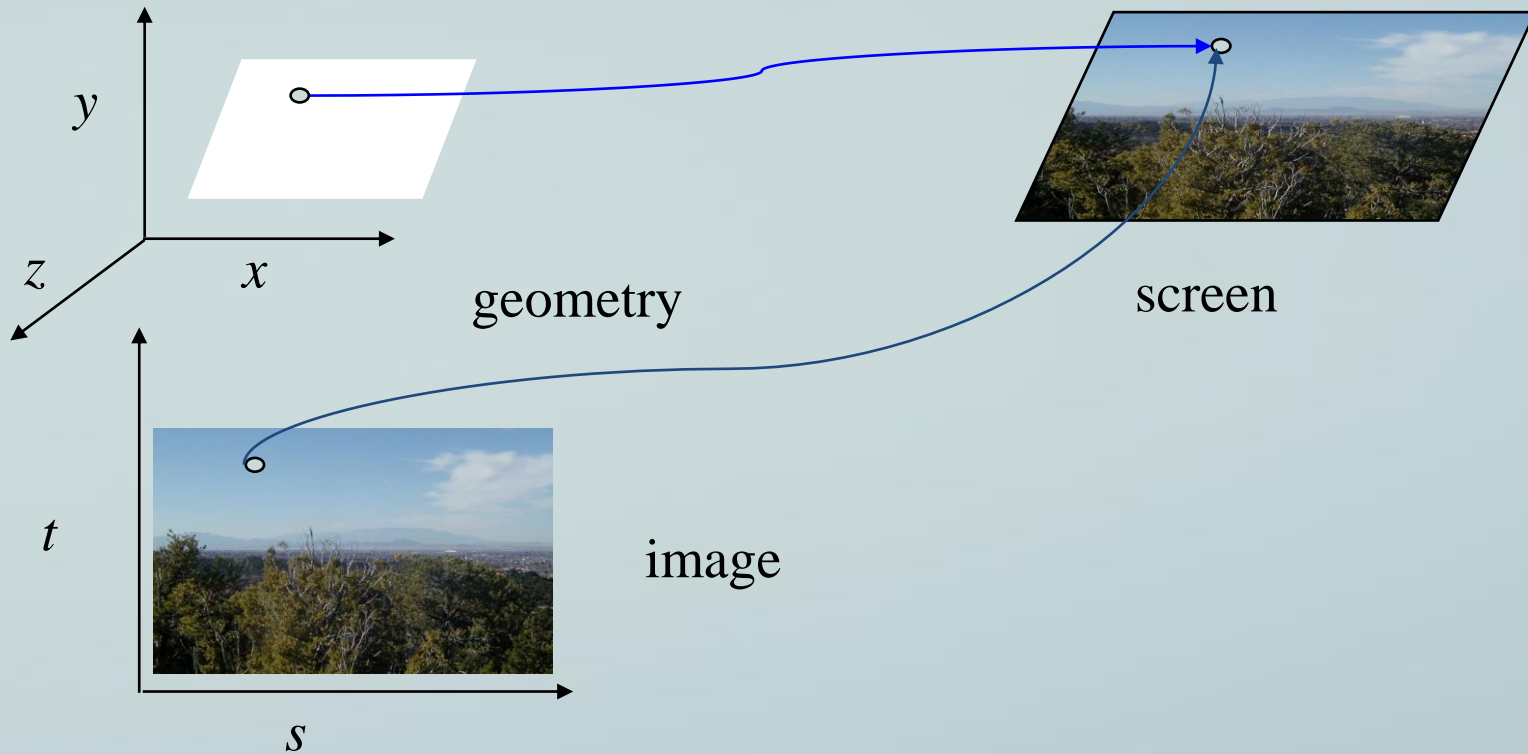
- A shader that's executed for each “potential” pixel
 - fragments still need to pass several tests before making it to the framebuffer
- There are lots of effects we can do in fragment shaders
 - Per-fragment lighting
 - Texture and bump Mapping
 - Environment (Reflection) Maps

Texture Mapping



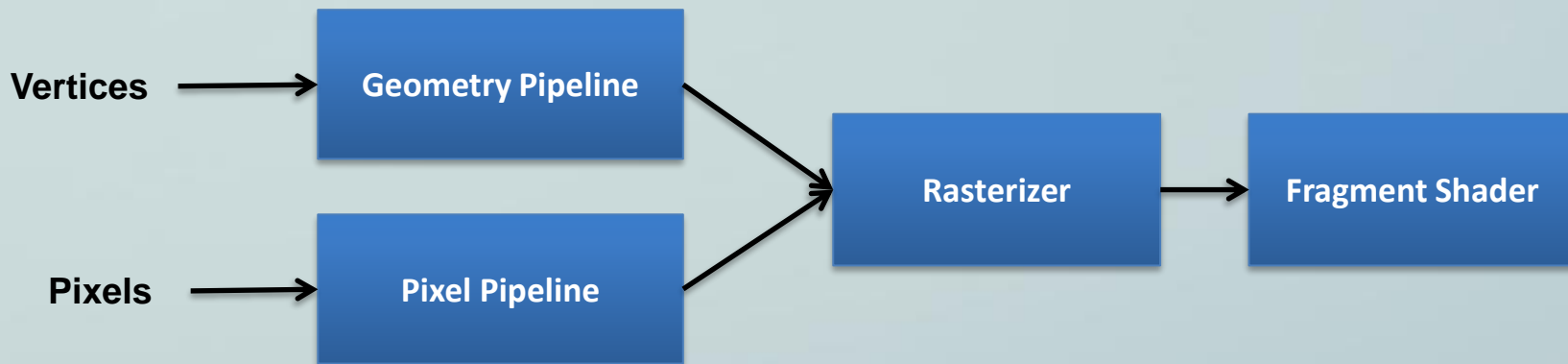
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Texture Mapping and the OpenGL Pipeline

- Images and geometry flow through separate pipelines that join at the rasterizer
 - “complex” textures do not affect geometric complexity



- Three basic steps to applying a texture
 1. specify the texture
 - read or generate image
 - assign to texture
 - enable texturing
 2. assign texture coordinates to vertices
 3. specify texture parameters
 - wrapping, filtering

- Have OpenGL store your images
 - one image per texture object
 - may be shared by several graphics contexts
- Generate texture names

```
glGenTextures( n, *texIds );
```

- Create texture objects with texture data and state

```
glBindTexture( target, id );
```

- Bind textures before using

```
glBindTexture( target, id );
```

Specifying a Texture Image

- Define a texture image from an array of *texels* in CPU memory

```
glTexImage2D( target, level, components,  
              w, h, border,  
              format, type, *texels );
```

Mapping a Texture

- Based on parametric texture coordinates
- coordinates needs to be specified at each vertex
- So goes into vertex shader

