Master UAB - High Energy Physics, Astrophysics and Cosmology

# NSs, BHs and GWs

#### **EINSTEIN'S THEORY OF GRAVITY**

May 17th, 2021

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# Summary I:

#### Covered last lecture: special relativity

- Einstein combined earlier results to develop a **new theory of** (**special**) **relativity** based on two postulates: i) all inertial frames are equivalent, ii) the speed of light is constant.
- In SR, the laws of physics are invariant under **Lorentz trans- formations**, which couples space & time into **spacetime**.
- Special relativity **extends Newtonian physics** to those cases where speeds are close to that of light (but gravity negligible).

# **Summary II:**

#### Covered last lecture: tensor calculus

- To simplify the SR formalism and eventually appreciate the beauty of GR, we make use of **tensor calculus**. We will use tensors to write equations in **coordinate independent** form.
- Tensors are objects satisfying certain properties under **coordinate transformations**. We distinguish scalars (mass), contravariant (tangent vector) and covariant (gradient) tensors.
- Using the formalism, we can encode information about a manifold's **curvature** and determine **geodesics** and **distances**.

# **Overview:**

Covered so far: special relativity, tensor calculus

- 1. Equivalence principles
  - 2. Einstein equations
- 3. Why gravity is not a force!
  - 4. Schwarzschild solution

# **Overview:**

Covered so far: special relativity, tensor calculus

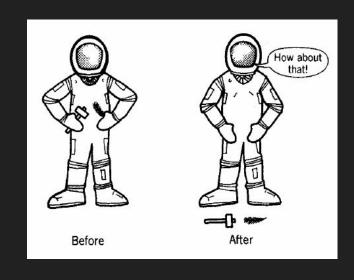
- 1. Equivalence principles (EPs)
  - 2. Einstein equations
  - 3. Why gravity is not a force!
    - 4. Schwarzschild solution

# 1.1 EPs - Mass in Newtonian theory

- So far, we haven't specified what the **mass** of a body actually is. In principle, one can distinguish 3 different masses:
  - o **inertial mass m<sup>i</sup>:** measure of a body's resistance to a change in motion; mass in Newton's second law  $\mathbf{F} = \mathbf{m}^{i}\mathbf{a}$ .
  - o **passive gravitational mass m**<sup>p</sup>: measure of a body's response to a gravitational field,  $\mathbf{F} = -\mathbf{m}^{p}$  grad  $\phi$ .
  - o **active gravitational mass m<sup>a</sup>:** measure of a body's strength to produce a gravitational field,  $\phi = -Gm^a/r$ .
- **Galileo** already realised in ~1610 that two bodies (of different mass) dropped from some height **reach** the ground **together**.

# 1.2 Galileo's or the weak EP (WEP)

• Galileo's observation suggests: *all* particles (regardless of mass and composition) fall with the same acceleration when placed in the same gravitational field. This is **one form** of the WEP. It implies that **free fall is universal**.



• This principle combined with Newton's laws suggests further that the **two gravitational masses** are **identical** and also **equivalent** to the **inertial mass**, i.e.,  $m = m^i = m^p = m^a$ .

# 1.3 EPs - Mass equivalence

 Equivalence of inertial and gravitational mass is one of the most accurately tested principles

in physics. Experiments typically measure the **Eötvös parameter** for two test masses A and B:

$$\eta(A,B) = 2 \frac{\left(\frac{m^g}{m^i}\right)_A - \left(\frac{m^g}{m^i}\right)_B}{\left(\frac{m^g}{m^i}\right)_A + \left(\frac{m^g}{m^i}\right)_B}$$



• The best constraint comes from the MICROSCOPE experiment onboard a satellite, confirming the universality of free fall with a **precision of 10**<sup>-15</sup>, a factor 100 better than tests on Earth.

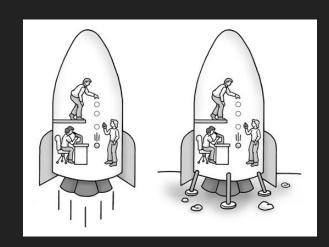
# 1.4 EPs - Einstein's contribution

• Einstein realised that no body can be shielded from a gravitational field, but we can **locally remove effects of gravity** (& recover SR) by considering a **free falling reference frame**.

• Someone falling from a roof feels **weightless**, so locally there

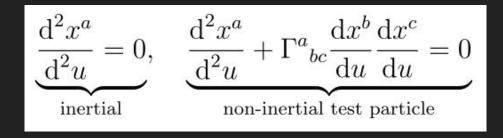
is not gravitational field and we have an **inertial frame**. Free falling observers are **inertial observer**!

• A frame **linearly accelerating** in empty space is locally identical to a **frame at rest** in a gravitational field.



#### 1.5 Einstein's EP

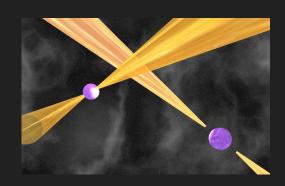
- We cannot distinguish between gravitational & inertial forces (accelerations) with any local experiment using test particles:
  - Gravitational forces can be described like inertial forces!



- When gravitational accelerations are present, then space cannot be flat: a gravitational field curves spacetime!
- o If gravity is present, **no inertial frames** can exist: there are no special frames & we have to use general coordinates!

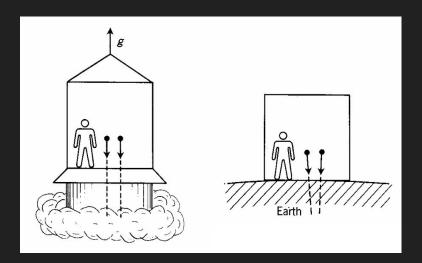
# 1.6 The strong EP (SEP)

- The WEP is only applicable to **test particles** and local but **non-gravitational experiments**. A stronger statement is: The WEP also holds for self-gravitating bodies (like stars) and any type of experiment (gravitational or non-gravitational).
- This form is **more restrictive** than the WEP: **only GR** seems to satisfy the SEP. Other gravity theories violate it to some level.
- **SEP tests** involve searching for **variations in G** or **compact binaries** (with at least one pulsar to 'measure' effects) as they strongly affect the spacetime.



# 1.7 EPs - Locality vs. non-locality

• Local experiments not only imply that an observer cannot look outside of their laboratory / spacecraft, but also that the lab / spacecraft is small enough so that tidal effects (due to a gradient in the gravitational field) are not detected.



• If their **rocket** is **wide** enough and the observer's **equipment sensitive** to detect **changes in a gravitational field**, they could distinguish the two cases illustrated on the left.

# 1.8 Questions

- Go to <u>www.menti.com</u> & enter 6689 6774.
  - $\circ$  1. Does the universality of free fall imply that  $m^i = m^g$ ?
    - Yes
    - No
  - 2. A (non-rotating) observer is able to perform a local experiment to determine whether they are freely falling in a gravitational field or moving at v=const in empty space?
    - Yes

#### 1.8 Answers

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    - Yes
    - No

# **Overview:**

Covered so far: special relativity, tensor calculus, equivalence principles

- 1. Equivalence principles
- 2. Einstein equations (EEs)
- 3. Why gravity is not a force!
  - 4. Schwarzschild solution

# 2.1 EEs - Minkowski spacetime

- As we have seen now, the **flat spacetime** we encountered in the Special Theory of Relativity plays an important role when gravity is absent or local inertial observers are considered.
- We can now write the **line element** in tensorial form using the **Minkowski metric**  $g_{ab} = \eta_{ab}$ :  $\mathrm{d}s^2 = \eta_{ab} \mathrm{d}x^a \mathrm{d}x^b$

$$\eta = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

 $\eta = \begin{pmatrix}
1 & 0 & 0 & 0 \\
0 & -1 & 0 & 0 \\
0 & 0 & -1 & 0 \\
0 & 0 & 0 & -1
\end{pmatrix}$ • Considering the **length** (norm)  $X^2 = X_a X^a$  of a vector, we distinguish timelike ( $X^2 > 0$ ), spacelike ( $X^2 < 0$ ) or **lightlike / null** (X<sup>2</sup>=0) vectors.

#### 2.2 EEs - Exercise

- Let's define a **timelike geodesic** as a geodesic, whose tangent vector is timelike everywhere. Show that the so-called **proper time**  $\tau$  (time measured by a clock following this geodesic, with  $d\tau = ds/c$ ) between  $t_1$  and  $t_2$  is given by
  - The following relations will help:

$$ds^2 = c^2 dt^2 - dx^2 - dy^2 - dz^2$$

$$\gamma = 1/\sqrt{1 - v^2/c^2}$$

$$oldsymbol{v} = \left( rac{\mathrm{d}x}{\mathrm{d}t}, rac{\mathrm{d}y}{\mathrm{d}t}, rac{\mathrm{d}z}{\mathrm{d}t} 
ight)$$

 $\tau = \int_{t_1}^{t_2} \frac{\mathrm{d}t}{\gamma(t)}$ 

#### 2.2 EEs - Exercise

Solution:

$$\tau = \int_{t_1}^{t_2} d\tau = \int_{t_1}^{t_2} \frac{ds}{c} = \int_{t_1}^{t_2} \frac{1}{c} \sqrt{c^2 dt^2 - dx^2 - dy^2 - dz^2}$$

$$= \int_{t_1}^{t_2} dt \sqrt{1 - \frac{1}{c^2} \left[ \left( \frac{dx}{dt} \right)^2 + \left( \frac{dy}{dt} \right)^2 + \left( \frac{dz}{dt} \right)^2 \right]}$$

$$= \int_{t_1}^{t_2} dt \sqrt{1 - \frac{v(t)^2}{c^2}} = \int_{t_1}^{t_2} \frac{dt}{\gamma(t)}$$

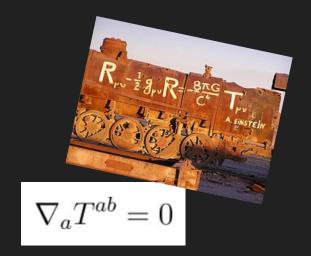
#### 2.3 EEs - The ideas

- All our considerations helped Einstein develop a **range of arguments** that determine how the equations that completely control the **dynamics of gravitation** will have to look like:
  - The correct Newtonian limit has to be recovered.
  - The equations should have tensorial form.
  - Mass and energy are sources of the gravitational field, so the *energy-momentum tensor*  $T_{ab}$  should appear.
  - Energy-momentum has to be conserved.
  - $\circ$  Second derivatives of the metric combined into some order 2 tensor  $A_{ab}$  should enter the equations.

# 2.4 Einstein equations

• Combining these suggests the following:

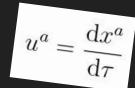
$$G_{ab} = R_{ab} - \frac{1}{2}Rg_{ab} = \kappa T_{ab} = \frac{8\pi G}{c^4}T_{ab}$$



- These equations (famously) describe (i) the way that matter and energy curve spacetime and (ii) how curved spacetime controls the motion of matter and energy.
- In **vacuum (empty space)**, these reduce to the simple case

$$T_{ab} = 0, \quad R_{ab} = 0$$

# 2.5 EEs - Energy-momentum tensor



- A generalisation of the Newtonian stress tensor, T<sub>ab</sub> describes the density and flux of energy and momentum in spacetime.
- In GR, the tensor is **symmetric**  $T_{ab} = T_{ba}$  and its **precise form** depends on the **type of matter/energy** considered, e.g.,  $T^{ab} = \rho_0 u^a u^b$ 
  - O Non-interacting matter (dust):  $T^{ab} = (\rho_0 + p/c^2)u^au^b pq^{ab}$
  - Perfect fluid:
- From the **conservation law**  $\nabla_a T^{ab} = o$  we recover conservation equations, e.g., continuity / Navier-Stokes /

# 2.6 EEs - Geodesics part II

We saw that a **free particle** (no external forces acting) follows a geodesic. These curves are typically parameterised by the **proper time**, i.e., u = τ. Thus, for a timelike geodesic:

$$\frac{\mathrm{d}^2 x^a}{\mathrm{d}^2 \tau} + \Gamma^a{}_{bc} \frac{\mathrm{d} x^b}{\mathrm{d} \tau} \frac{\mathrm{d} x^c}{\mathrm{d} \tau} = 0$$

• τ is an **affine parameter** (the tangent vector remains parallel or equivalently the acceleration is perpendicular to the curve / velocity vector). Note that the **coordinate time** t is not an affine parameter and the **equation of motion** would **differ**.

# 2.7 EEs - Newtonian limit I

• If our **spacetime is almost flat**, we expect the metric to differ only slightly from the Minkowski metric, i.e.,

$$g_{ab} = \eta_{ab} + \epsilon h_{ab} + \mathcal{O}(\epsilon^2)$$
 with  $\epsilon \sim v/c \ll 1$ 

• In the **slow-motion limit**, we can also assume that derivatives w.r.t  $x^0 = ct$  are smaller than the spatial ones w.r.t.  $x^\alpha = (x,y,z)$ :

 $\mathrm{d}x^{\alpha} \sim \epsilon c \, \mathrm{d}t$ 

• From c d $\tau$  = ds, we find to lowest order in  $\varepsilon$  that  $\tau \sim t$ , while the definition of the **connections** suggest that  $\Gamma^a_{bc} = \mathcal{O}(\epsilon)$ 

#### 2.8 EEs - Newtonian limit II

• We are now interested in the **geodesic equation**, specifically the spatial components. To first order in  $\varepsilon$ , we find

$$\begin{split} 0 &= \frac{1}{c^2} \, \frac{\mathrm{d}^2 x^\alpha}{\mathrm{d}^2 t} + \frac{1}{c^2} \, \Gamma^\alpha{}_{bc} \frac{\mathrm{d} x^b}{\mathrm{d} t} \frac{\mathrm{d} x^c}{\mathrm{d} t} \sim \frac{1}{c^2} \, \frac{\mathrm{d}^2 x^\alpha}{\mathrm{d}^2 t} + \Gamma^\alpha{}_{00} \\ &= \frac{1}{c^2} \, \frac{\mathrm{d}^2 x^\alpha}{\mathrm{d}^2 t} - \frac{1}{2} \epsilon \left( 2 \frac{\partial h_{0\alpha}}{\partial x^0} - \frac{\partial h_{00}}{\partial x^\alpha} \right) \sim \frac{1}{c^2} \, \frac{\mathrm{d}^2 x^\alpha}{\mathrm{d}^2 t} + \frac{1}{2} \epsilon \frac{\partial h_{00}}{\partial x^\alpha} \end{split}$$

• Analogy with the Newtonian equation gives weak-field limit

$$\frac{\mathrm{d}^2 x^{\alpha}}{\mathrm{d}^2 t} = -\frac{\partial \phi}{\partial x^{\alpha}}, \quad \Rightarrow \quad g_{00} = 1 + 2\frac{\phi}{c^2} + \mathcal{O}\left(\frac{v}{c}\right)$$

#### 2.9 Questions

- Go to <u>www.menti.com</u> & enter 6904 3933.
  - 1. Which of these statements does not hold for the EEs?
    - $\blacksquare$  Second derivatives of  $g_{ab}$  should appear.
    - The equations have scalar form.
    - Newtonian physics need to be recovered.
  - 2. Free particles move along geodesics. If external forces are present, we can account for these by adding extra force terms f<sup>a</sup> to the rhs of our geodesic equation?
    - Yes
    - No

#### 2.9 Answers

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    - Yes

# **Overview:**

Covered so far: special relativity, tensor calculus, equivalence principles, Einstein equations

- 1. Equivalence principles
  - 2. Einstein equations
- 3. Why gravity is not a force!
  - 4. Schwarzschild solution

# **3.1** <u>Video</u>

- To make sure that we have all understood the main concepts discussed in class so far, we are going to watch the following **Youtube video**. It summarises all the elements we have introduced last week and today (in ~15 min!!):
  - Why Gravity is NOT a Force by Veritasium

https://tinyurl.com/a3ean3tc

To break things up, we will watch in two
 blocks and have 2 rounds of questions.



### 3.2 Questions https://tinyurl.com/a3ean3tc

- Watch **until 6:55** & go to <u>www.menti.com</u> & enter 1792 886.
  - o 1. An observer in a spacecraft approaching a planet will not notice any difference but an external observer will see the spacecraft move on a bent path due to spacetime curvature?
    - Incorrect
    - Correct
  - 2. Why can the bent sheet or rubber sheet analogy of GR be somewhat misleading? Please type out your answer in 1 or 2 sentences, but not more.

# 3.3 Questions https://tinyurl.com/a3ean3tc

- Watch **the rest** & go to <u>www.menti.com</u> & enter 9342 1837.
  - 3. How can you be at rest (on the Earth's surface) if you are a non-inertial observer and 'accelerating upwards'? Please type out your answer in 1 or 2 sentences, but not more.
  - 4. GR predicts that in an accelerating frame of reference & similarly in curved spacetime the paths of light are bent.
    - Correct
    - Incorrect

#### 3.2 Answers

- Watch **until 6:55** & go to <u>www.menti.com</u> & enter 1792 886.
  - 1. An observer in a spacecraft approaching a planet will not notice any difference but an external observer will see the spacecraft move on a bent path due to spacetime curvature?
    - Incorrect
    - Correct
  - 2. The object's motion around the central mass is closer to the analogy of an object falling into a well due to a gravitational force. But in GR gravity is not a force and the test mass travels on a straight path through curved spacetime.

#### 3.3 Answers

- Watch the rest & go to <u>www.menti.com</u> & enter 9342 1837.
  - 3. A stationary position is possible if our acceleration is exactly cancelled by the product of a curvature term times the velocity squared. We can mathematically show this by adding force/acceleration terms to our geodesic equation.
  - 4. GR predicts that in an accelerating frame of reference & similarly in curved spacetime the paths of light are bent.
    - Correct
    - Incorrect

# 3.4 And more questions



 Are there any more questions from your side so far?



# **Overview:**

Covered so far: special relativity, tensor calculus, equivalence principles, Einstein equations

- 1. Equivalence principles
  - 2. Einstein equations
- 3. Why gravity is not a force!
- 4. Schwarzschild solution (SS)

# 4.1 SS - Solving EEs

- EEs are very **complicated** and difficult to solve, but there are a **few cases** where we can take advantage of special properties of the gravitational system and find **analytical solutions**.
- One such case is the **Schwarzschild solution** for which we will assume that the following statements hold:
  - o a.) Spacetime is *spherically symmetry*.
  - o b.) Spacetime is *static*.
  - o c.) Spacetime is *empty*.
  - od.) Spacetime is asymptotically flat.



#### 4.2 SS - General solution for a. & b.

- In broad terms, a **static spacetime** is one that does not change over time and is also irrotational. This implies that
  - $\circ$  i.) all *metric components*  $g_{ab}$  are independent of  $x^{o}$ .
  - $\circ$  ii.) the *line element* ds<sup>2</sup> is invariant under  $x^0 \rightarrow -x^0$ .
- A metric that only satisfies i.) is called **stationary**. If both hold,  $ds^2$  can only depend on rotational invariants of  $x^{\alpha}$  and their differentials, which implies the metric is **isotropic**. The most **general spherically symmetric line element** is given by

$$ds^{2} = e^{\nu(t,r)}dt^{2} - e^{\lambda(t,r)}dr^{2} - r^{2}(d\theta^{2} + \sin^{2}\theta d\phi^{2})$$

# 4.3 SS - Schwarzschild metric

• What remains is the **determination of** the **two functions** v and  $\lambda$ . To do this, we would have to consider the vacuum Einstein Equations and calculate  $R_{ab} = 0$  for our isotropic metric

$$g_{ab} = \operatorname{diag}(e^{\nu}, -e^{\lambda}, -r^2, -r^2\sin^2\theta)$$

• One would find that  $\lambda = \lambda(r) \& \nu = \nu(r)$  as well as  $\nu(r) = -\lambda(r)$ , and explicitly for the **Schwarzschild line element** 

$$ds^{2} = (1 - 2m/r)dt^{2} - (1 - 2m/r)^{-1}dr^{2} - r^{2}(d\theta^{2} + \sin^{2}\theta d\phi^{2})$$

#### 4.4 SS - Observations

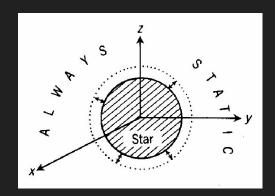
- In the **asymptotic limit**  $r \to \infty$ , we recover the flat metric in spherical coordinates, i.e., the SS metric is asymptotically flat.
- We can learn more about the **quantity m** in the line element, by considering the **weak-field limit**. On slide 2.8, we saw that in this case  $g_{oo} \sim 1+2\phi/c^2$ . For a point mass M at the origin, **Newtonian theory** gives rise to a potential  $\phi = -GM/r$ . Thus

$$1+2\phi/c^2=1-2GM/c^2r\stackrel{!}{=}1-2m/r \quad \Rightarrow \quad m=GM/c^2$$

• We interpret the SS solution as due to a point particle at the origin, with m as the **(geometric) mass** in relativistic units.

## 4.5 SS - Birkhoff's theorem

- While we have seen that the SS metric is a static & spherically symmetric solution of the vacuum Einstein equations, it is possible to show that this solution is **unique**. This implies that
  - any spherically symmetric solution of the vacuum field equations must be static and asymptotically flat.
  - spacetime outside of a spherical, nonrotating, gravitating body (exterior solution) MUST be given by the SS metric.
- A **spherically pulsating star** has a static exterior and **cannot emit GWs**.



# 4.6 Questions

- Go to <a href="https://www.menti.com">www.menti.com</a> & enter 7148 0271.
  - 1. A static solution to the Einstein Equations is always stationary, but the opposite is not automatically true.
    - Correct
    - Incorrect
  - 2. We interpret the Schwarzschild solution to the vacuum Einstein Equations as due to a point particle at the origin.

    - Yes

#### 4.6 Answers

- Go to <u>www.menti.com</u> & enter 7148 0271.
  - 1. A static solution to the Einstein Equations is always stationary, but the opposite is not automatically true.
    - Correct
    - Incorrect
  - 2. We interpret the Schwarzschild solution to the vacuum Einstein Equations as due to a point particle at the origin.

    - Yes

# <u>Summary I:</u>

# Covered today: equivalence principles, Einstein equations, Schwarzschild solution

- The **weak equivalence principle** has multiple forms, reflecting the fact that we cannot distinguish between gravitational & inertial forces with any local experiment using test particles.
- The **strong equivalence principle** generalises the WEP to self-gravitating bodies and gravitational experiments.
- The **Einstein equations** are a set of tensor equations that completely control the **dynamics of gravitation**.

# **Summary II:**

# Covered today: equivalence principles, Einstein equations, Schwarzschild solution

- The essence of the Einstein equations is that "Spacetime tells matter how to move, while matter tells spacetime how to curve." as summarised by John Wheeler.
- In General Relativity, **gravitational phenomena** arise not from forces or fields but from the curvature of spacetime itself.
- The (unique) **spherically symmetric & static solution** of the vacuum Einstein Equations is **Schwarzschild's solution**.

# Final impressions:

# Covered today: equivalence principles, Einstein equations, Schwarzschild solution

- Go to www.menti.com & enter 1882 8492.
  - If you could use **one word** to describe today's class, what would that word be?