

# DANIEL RODRIGUEZ CRIADO, PHD

Malaga, Spain

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## EDUCATION

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**Aston University, Birmingham**

**2019–2023**

***Ph.D. on Computer Science and Deep Learning***

My doctoral thesis at Aston University explored the intersection of traditional deep learning approaches and Graph Neural Networks (GNNs) in sensorized environments. I focused on three key application areas: Human-Aware Navigation for robots, Human Pose Estimation, and Traffic Image Generation.

**University of Malaga**

**2015–2019**

***MSc. on Electronic Systems for Smart Environments***

Modules included:

- Artificial Intelligence: Artificial Vision, Smart Environments, Data Processing, Smart Cities
- Electronics: Sensor Networks, Design of PCBs, Interfaces and Communications, Embedded systems based on FPGAs, Microcontrollers, Microkernels.
- Management: Planning, Management and Project Development.

Master's final thesis titled: "Table Cleaner Robot TCBot using Hi-NW Light Technology for Disinfection".

**University of Malaga**

**2017–2019**

***Master of Engineering, Industrial Engineering***

Modules included:

- A\* in "Electronic Systems in Industry"
- A\* in "Control and Quality Management"
- A\* in "Energy Technologies"

Master's final thesis titled: "Implementation and design of a processor architecture for detection of objects slippage over a tactile sensors array using a FPGA." Passed with honours.

**University of Malaga**

**2010–2015**

***Bachelor in Industrial Technologies Engineering.***

Specialized in automatic and electronic control, modules included:

- Honours in "Integrated Circuits"
- A\* in "Computer Architecture"
- A\* in "Power Electronic"
- A\* in "Transducers and interface"

Bachelor final thesis titled: "Basic Quadcopter Design with Stabilization Control" Passed with honours.

## INTERNSHIPS

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**Hong Kong University of Science and technology (HKUST), Hong Kong** **2017–2018**  
*EURASIACAT program*

- During my internship, I spearheaded the design and development of a compact robot for disinfecting tables using a synergistic approach of blue and UV light. This innovative solution leverages the Hi-NW technology, a groundbreaking advancement developed by the CBE department of HKUST.

**Vilnius Gediminas Technical University (VGTU), Vilna (Lithuania)** **2016**  
*Erasmus+ program*

- This stay boosted my knowledge of the English language since it was the first time for me living in a foreign country.
- It allowed me to do a different culture immersion and even learn a bit of Lithuanian language and culture.
- Gave me the chance of studying electronic related subjects in a different language (English) such as: wind and photovoltaic energy systems, electronic converters and modern electrical engineering.

## DIGITAL SKILLS

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<b>Programming Languages</b>	Python, Bash scripting, C/C++, MATLAB, VHDL, Assembler
<b>Web languages</b>	Typescript/Javascript, HTML, CSS, PostCSS, PHP, SQL
<b>Tools and frameworks</b>	PyTorch, Qt, Numpy, Docker, Laravel, Astro
<b>Op. Systems</b>	Linux (Ubuntu and Parrot OS), Windows, Mac OS, Android
<b>IDEs</b>	Visual Studio Code, PyCharm, Jupyter notebooks

## CARRIER OBJECTIVE

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Eager to contribute to cutting-edge deep learning advancements, I seek a position in a dynamic organization that fosters continuous learning and professional growth. I am looking forward to joining a team that empowers me to contribute to the development of groundbreaking software enabling deep learning applications in diverse fields such as robotics, smart devices, home automation, self-driving cars, biochemistry and others. I am excited to collaborate with innovative technology, implement new algorithms, optimize solutions, and make a significant impact on the ML ecosystem, including engaging with partners and the broader ML community.

## WORK EXPERIENCE

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**PhD research at Aston University, Birmingham (UK)** **10/2019–12/2023**  
*Research student*

- Contributed to the development of cutting-edge applications utilizing Graph Neural Networks in conjunction with traditional Artificial Neural Networks.
- Pioneered research in Human-Aware Navigation for robots, Human Pose Estimation, and Traffic Image Generation, employing GNNs to achieve significant advancements.
- Authored and published papers in prominent conferences and journals, establishing a strong research portfolio in the aforementioned areas.
- Demonstrated exceptional communication and teamwork skills through collaboration with research scientists and presenting findings at international conferences.
- Cultivated problem-solving, time management, and adaptability skills, effectively managing multiple research projects simultaneously.
- Engaged in critical thinking by peer-reviewing scientific papers.

Google Summer of code, online  
*Mentor*

06/2020–09/2020 and 06/2021–09/2021

- Developed skills as a team leader by spearheading a project in robotics and machine learning, guiding a team of diverse individuals worldwide.

Aston University, Birmingham (UK)  
*Laboratory Instructor*

09/2021–07/2022

- Cultivated confidence as a communicator by delivering undergraduate-level courses with passion and clarity.
- Effectively taught courses in bash scripting, computer systems, web technologies, and machine learning, fostering student engagement and comprehension.

## PUBLICATIONS

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**SNGNN2D-v2: a learning-based scenario-agnostic model for the generation of socially-aware cost maps in dynamic environments** 2024  
*Rodriguez-Criado, Daniel, Pilar Bachiller, and Luis J. Manso.*

Under submission to the International Journal of Social Robotics

**Synthesizing Traffic Datasets using Graph Neural Networks.** 2023  
*Rodriguez-Criado, Daniel, Maria Chli, Luis J. Manso, and George Vogiatzis.*

26th IEEE International Conference on Intelligent Transportation Systems ITSC 2023. **(I presented the work in the conference)**

**Multi-person 3D pose estimation from unlabelled data.** 2022  
*Rodriguez-Criado, Daniel, Pilar Bachiller, George Vogiatzis, and Luis J. Manso.*

Under submission to The Journal of Machine Learning Research (JMLR).

**A graph neural network to model disruption in human-aware robot navigation** 2022  
*Bachiller, Pilar, Rodriguez-Criado, Daniel, Ronit R. Jorvekar, Pablo Bustos, Diego R. Faria, and Luis J. Manso.*

Multimedia Tools and Applications 81, no. 3.

**Generation of human-aware navigation maps using graph neural networks.** 2021  
*Rodriguez-Criado, Daniel, Pilar Bachiller, and Luis J. Manso.*

In International Conference on Innovative Techniques and Applications of Artificial Intelligence. **(I presented the work in the conference) (Best student paper award).**

**toolkit to generate social navigation datasets** 2021  
*Baghel, Rishabh, Aditya Kapoor, Pilar Bachiller, Ronit R. Jorvekar, Rodriguez-Criado, Daniel, and Luis J. Manso.*

In Advances in Physical Agents II: Proceedings of the 21st International Workshop of Physical Agents (WAF). **(I presented the work in the conference) (Best paper award)**

**Multi-camera torso pose estimation using graph neural networks.** 2020  
*Rodriguez-Criado, Daniel, Pilar Bachiller, Pablo Bustos, George Vogiatzis, and Luis J. Manso.*

In 2020 29th IEEE International Conference on Robot and Human Interactive Communication (RO-MAN). **(I presented the work in the conference)**

## TRAINING COURSES

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### **Aston University**

*2022*

Fundamentals of Accelerated Computing with CUDA C/C++.

### **Coursera**

*2020*

Convolutional Neural Networks

Structuring Machine Learning Projects

Improving Deep Neural Networks

Neural Networks and Deep Learning

Machine Learning by University of Stanford

### **Polytechnic University of Madrid**

*2016*

Development in HTML5, CSS and JavaScript of web apps, android and IOS.

### **University of Malaga**

*2011*

Advanced course in GPUs. Programming and performance against the CPU

Basic course of graphic processors

## PERSONAL SKILLS

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### **Languages**

#### **Mother tongue**

Spanish

#### **Foreign languages**

English — Full professional profency

### **Soft skills**

- Teamwork.
- Problem solving.
- Communication.
- Adaptability.
- Critical thinking.
- Time management.
- Interpersonal.