

Parallel Physics Engine for the Front End

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Abstract

Physics simulations on the web has always sacrificed convenience for performance due to the limitations of the browser. With the introduction of web workers and the ability for content to run on multiple threads, this trade-off can be further minimized. Utilization of this new technology could help bring physics simulations to the web in order to benefit from the web's ease of access and usability.

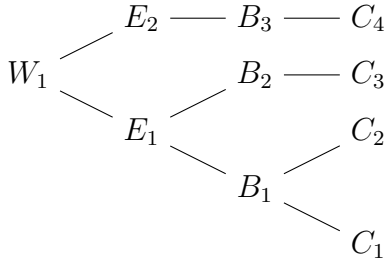
1. Hierarchy

A world (W) represents a system of rules that is being observed. An environment (E) represents an observed rule or a law of physic. A body (B) represents a single entity of interest that is being observed. A component (C) is a characteristic of a particular body that may be of interest i.g. position or rotation. Each world (W_i) has a set of environments (S_i^E) that are part of the simulation. Each environment (E_i) has a set of bodies (S_i^B) that must conform by its rule, and each body (B_i) has a set of components (S_i^C).

$$S_i^E = \{E_1, E_2, E_3 \dots\}$$

$$S_i^B = \{B_1, B_2, B_3 \dots\}$$

$$S_i^C = \{C_1, C_2, C_3 \dots\}$$



12 2. Components

13 A component C is represented as a parametric function $C(t)$ with time
 14 input t . Components should be able to be constructed using the raw para-
 15 metric equation or by specifying n-levels of derivatives. Let C^* represent the
 16 constructor.

$$C^*(< 0, -1/2, 0 > gt^2 + < 2, 0, 0 > t) = C(t) = < 0, -1/2, 0 > gt^2 + < 2, 0, 0 > t$$

17 $C^*(< 0, 0, 0 >, < 2, 0, 0 >, < 0, -1/2, 0 >) = C(t) = < 0, -1/2, 0 > gt^2 + < 2, 0, 0 > t$

18 Each component can thus be concurrently calculated. Let C_i^t be identified
 19 where t represents $C_i(t)$

$$C_2^{t1} \longrightarrow C_2^{t2}$$

20 $C_1^{t1} \longrightarrow C_1^{t2}$

21 3. Bodies