

EXPLORATORY MEDIATION ANALYSIS WITH MANY POTENTIAL MEDIATORS

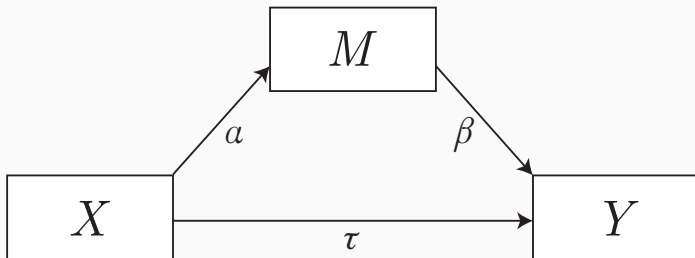
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MEDIATION

Q: When is M a mediator?



MacKinnon et al. (2002):

1. Causal steps: α & β
2. Difference in coefficients: $\tau - \tau|M$
3. Product of coefficients: $\alpha \times \beta$

VanderWeele (2015, p. 46): “Also take into account $X \cdot M$ interaction!”

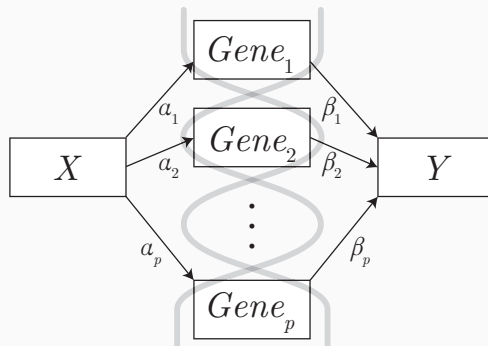
Theory-based **decision functions** using data from X, M, Y :

$$\mathcal{D}: \{\mathbf{x}, \mathbf{m}, \mathbf{y}\} \mapsto \{0, 1\}$$

(0 = not mediator, 1 = mediator)

MANY MEDIATORS

Q: When is *Gene_i* a mediator?

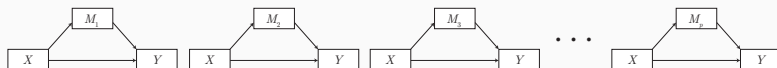


Preacher and Hayes (2008):

1. Fit the full SEM so your parameter estimates take all mediators into account
2. Select mediators using the estimated parameters

$\mathcal{D}(\mathbf{x}, \mathbf{m}_i, \mathbf{y})$ conditional on M_{-i}

p single mediator models



for (i in 1:p) $\mathcal{D}(\mathbf{x}, \mathbf{m}_i, \mathbf{y})$

The “filter” method (Guyon and Elisseeff, 2003)

Good

- Simple
- Quick
- Flexible

Bad

- Assumes uncorrelated mediators: won't work if mediation only visible conditionally

Jacobucci et al. (2016): We can now penalise SEM parameters

$$F_{\text{regsem}} = F_{\text{ML}} + \lambda P(\cdot)$$

Serang et al. (2017): We can use this to select mediators! Put a lasso penalty on α and β

The “XMed” method

Good

- "Full" SEM
- Does not assume uncorrelated mediators
- Regularisation is hip

Bad

- What are we actually optimising for?
- Find M for which α OR β but we want α AND β .

Our contribution:

$$\mathcal{D}(\mathbf{x}, \mathbf{m}_i, \mathbf{y}) \text{ conditional on } M_{-i}$$

Insight from regularisation literature (Hastie et al., 2015):

conditional parameter == parameter estimated on **residual**

Idea:

```
1 sel ← rep(0, p)
2
3 while (!convergence) {
4   for (i in 1:p) {
5     x_res ← x - M[, sel] %*% beta_x_sel
6     y_res ← y - M[, sel] %*% beta_y_sel
7     sel[i] ← decisionFunction(x_res, M[, i], y_res)
8   }
9 }
```

COORDINATE-WISE MEDIATION FILTER

for each mediator	Coordinate-wise
perform the decision function	Mediation
throw it out if 0	Filter

conditional on the other selected mediators

repeat until convergence

Good

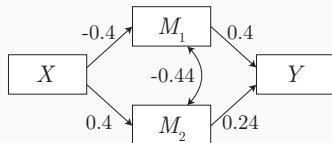
- Uses theoretically relevant \mathcal{D}
- Does not assume uncorrelated mediators

Bad

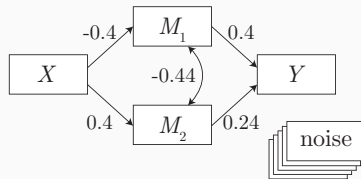
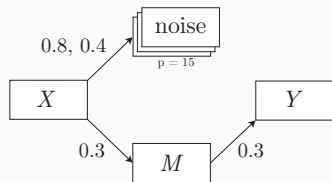
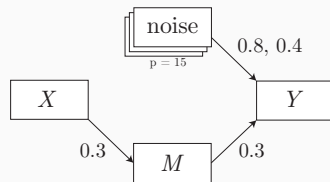
- Nonconvergence

SIMULATION

Conditional-only



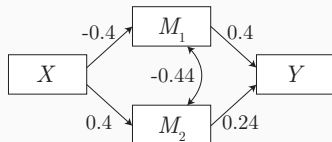
High-dimensional

Noise (α paths)Noise (β paths)

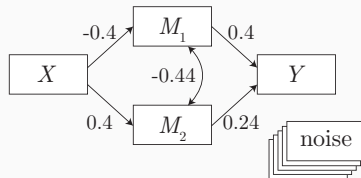
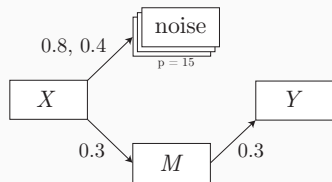
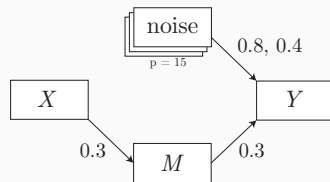
Suppression

Method	Power M_1	Power M_2
SEM	1	1
Filter	1	0
XMed	1	1
HIMA	1	1
CMF	1	1

Conditional-only



High-dimensional

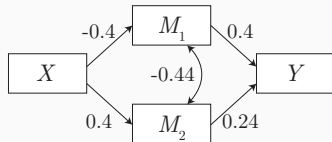
Noise (α paths)Noise (β paths)

SIMULATION RESULTS

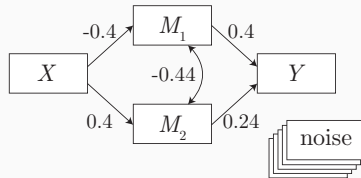
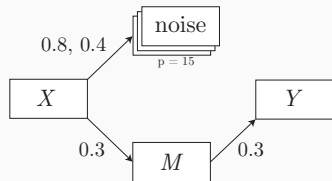
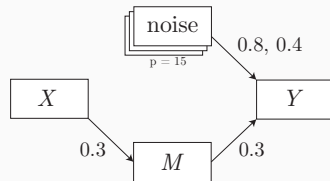
Noise α

	M	.	.	4	10	.	.	.	14	.	.
SEM	100
Filter	100	.	.	100	100	.	.	.	68	.	.
XMed	77
HIMA	100
CMF	100

Conditional-only



High-dimensional

Noise (α paths)Noise (β paths)

Noise β

	<i>M</i>
SEM	100
Filter	100
XMed	100
HIMA
CMF	100

IMPLEMENTATION

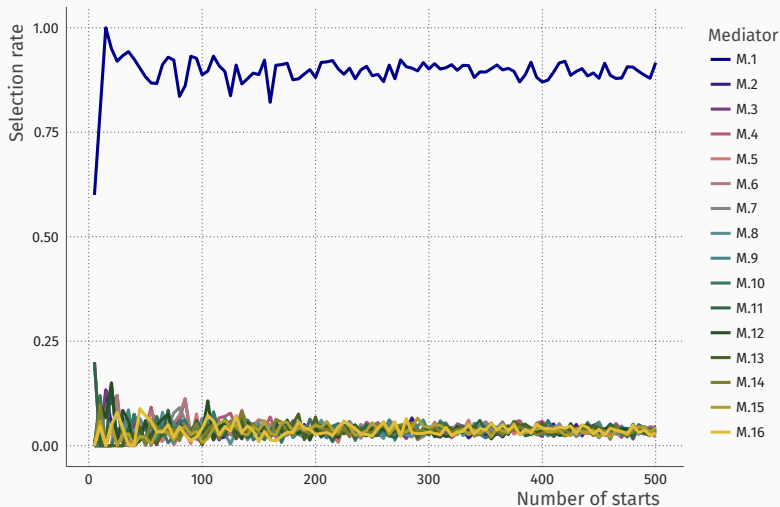
```
> devtools::install_github('vankesteren/cmfilter')
> library(cmfilter)
> res <- cmf(x, M, y, verbose = TRUE)
```

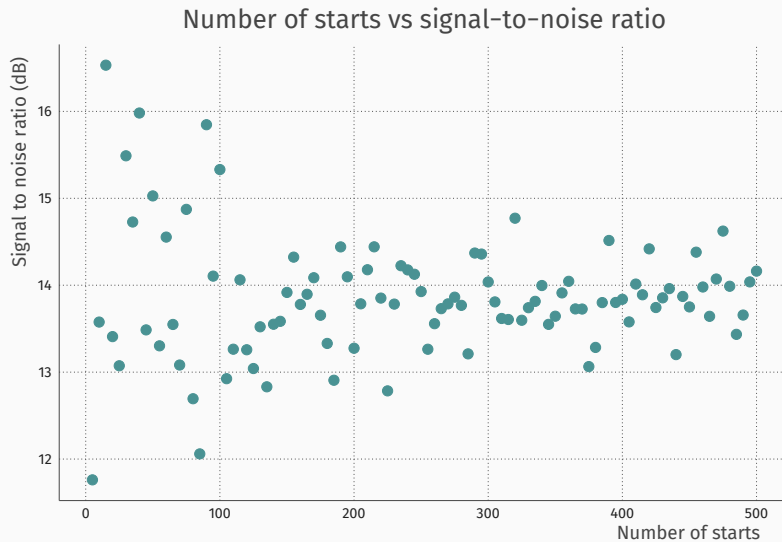
```
# CMF Algorithm
#
# -----
#
# 1 0 0 1 1 1 1 0 1 0 0 0 0 1 1 0 0
# 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
# 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
# 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
#
# Algorithm converged
#
# -----
```



```
cmf(x, M, y,  
    decisionFunction,  
    maxIter,  
    stableLag,  
>> nStarts,      <<  
>> randomStart, <<  
>> subSampling,  <<  
    parallel,  
    nCores,  
    progressBar)
```

Number of starts vs selection rate





CONCLUSION

- Novel method for selecting among many mediators
- Flexible choice of \mathcal{D}
- Conditional on M_{-i}
- Stable in boundary cases
- Traditional power/type-I tradeoff

- Group lasso
- Bayesian regularisation prior on $\alpha \times \beta$
- “Directions of mediation” (Chén et al., 2017)

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QUESTIONS
