Quantum Monte Carlo

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Abstract

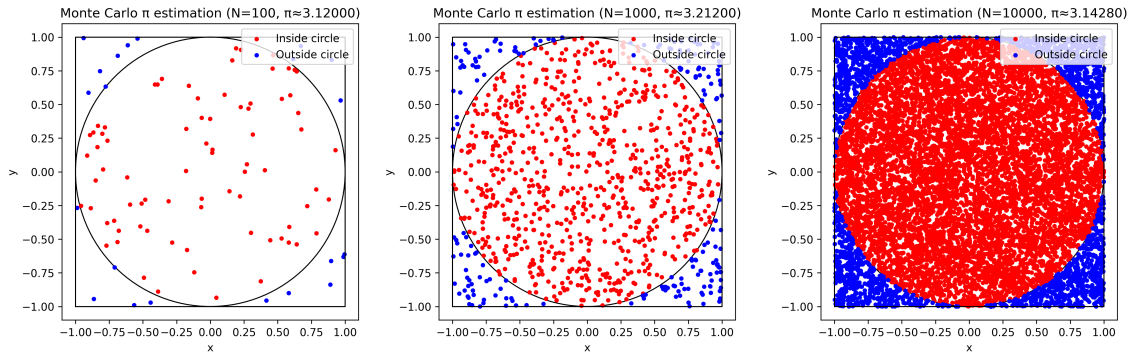(To be completed)

1 Introduction

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2 Monte Carlo Method

Monte Carlo method is a class of classical computational algorithm which aims to find a numerical value of interest through iterative random sampling according to a probability distribution. Such method is often applied when analytical solutions are too complex to solve. A simple case in which Monte Carlo method can be used is to approximate the value of π with only the knowledge of how to calculate the area of a circle. The process is outlined as such [KW08]:

1. Consider a square with edge length of 2, and centered at $(0,0)$.
2. Then, draw the inscribed circle of such a square which has radius 1, also centered at $(0,0)$.
3. **Uniformly at random** select a point within the square.
4. Calculate the ratio of the number of points within the circle and the total number of points sampled. This should approximate $\frac{\pi}{4}$.
5. Repeat Step 3 and 4 until a certain threshold. Calculate the approximated value of π by multiplying the ratio stated in Step 4 by 4.

By applying this process, we can obtain the following result (link to code, see A.1):

Monte Carlo π estimation (N=100, $\pi \approx 3.12000$) — Monte Carlo π estimation (N=1000, $\pi \approx 3.21200$) — Monte Carlo π estimation (N=10000, $\pi \approx 3.14280$)

The key idea from this demonstration is that random sampling can be used to evaluate a definite integral [KW08]:

$$I = \int_0^1 \int_0^{\sqrt{1-x^2}} \mathrm{d}y \mathrm{d}x$$

From the above demonstration, it is observed that the main goal of Monte Carlo method is to solve a certain mathematical problem with the core process to be iterated random sampling, where each additional iteration gives more accurate results.

3 Variational Monte Carlo

In quantum many-body problems, investigating the ground-state energy of the many-body system is essential, as the system's ground state captures its equilibrium properties [FMNR01]. However, as the number of interacting particles in a given system scale, analytically solving the Schrödinger's equation of the entire system while incorporating the interaction of particles within becomes intractable. In this case, the Variational Monte Carlo (abbreviated as VMC) method provides a practical approximation to the ground state energy.

3.1 Main Process of VMC

To begin with, consider the following relevant physical definitions.

Definition 3.1. *Consider a general quantum system, denoted mathematically as a Hilbert space $\mathcal{H}$, with N particles. Each particle i has 3-dimensional position vector $\mathbf{r}_i$. Define a $3N$-dimensional vector $\mathbf{R} = (\mathbf{r}_1, \ldots, \mathbf{r}_N)$. A general quantum state $|\Psi\rangle$ in this system can be denoted as:*

$$|\Psi\rangle = \int \Psi(\mathbf{R}) |\mathbf{R}\rangle \, \mathrm{d}\mathbf{R} \tag{1}$$

where $\Psi(\mathbf{R})$ is the position-space wavefunction, which satisfies the following properties:

1. *$|\Psi(\mathbf{R})|^2 \geq 0$*

2. *$\int \Psi^*(\mathbf{R})\Psi(\mathbf{R})\mathrm{d}\mathbf{R} = 1$*

Definition 3.2. *An **observable** $\mathcal{O}$ is a Hermitian operator, where measuring $\mathcal{O}$ mathematically amounts to doing a projective measurement with respect to the orthonormal basis of eigenvectors of $\mathcal{O}$.*

Definition 3.3. *Given an observable $\mathcal{O}$ and a quantum state $|\Psi\rangle$, the **expected value** of this observable with respect to this state is*

$$\langle \mathcal{O} \rangle = \langle \Psi | \mathcal{O} | \Psi \rangle \tag{2}$$

*and the **variance** of the above observable and the above state is:*

$$(\Delta \mathcal{O})^2 = \langle \mathcal{O}^2 \rangle - (\langle \mathcal{O} \rangle)^2 \tag{3}$$

To characterize the time evolution of the quantum state, the observable $\hat{H}$ is introduced to give the following.

Definition 3.4. *The **time-dependent Schrödinger's equation** of a given quantum state* $|\Psi\rangle$ *that is dependent on time t is*

$$i\hbar\frac{\partial}{\partial t}|\Psi(t)\rangle = \hat{H}|\Psi(t)\rangle \tag{4}$$

where i *is the imaginary unit,* $\hbar$ *is Planck's constant,* $\hat{H}$ *is the Hamiltonian operator for the quantum state* $|\Psi\rangle$.

In the context of VMC, the quantity of interest is the ground state energy. After the system reaches this equilibrium, the Hamiltonian can be considered to be time-independent. Thus, from 3.4

Definition 3.5. *If the Hamiltonian* $\hat{H}$ *is time-independent, it induces the **time-independent Schrödinger's equation** for* $|\Psi\rangle$ *to be:*

$$\hat{H}|\Psi\rangle = E|\Psi\rangle \tag{5}$$

From Eq. (2) and Eq. (5), it follows that

$$\left\langle \hat{H} \right\rangle = E \tag{6}$$

which indicates that, for an eigenstate $|\Psi\rangle$ of the Hamiltonian $\hat{H}$, the expected value of $\hat{H}$ is the eigenvalue of $|\Psi\rangle$, which physically represents the energy of the system when it is in the state of $|\Psi\rangle$.

If the ground state wavefunction is denoted to be $\Psi_0(\mathbf{R})$, it follows from Eq. (6), the ground state energy E_0 is:

$$\begin{aligned} E_0 &= \langle\Psi_0|\hat{H}|\Psi_0\rangle \\ &= \int \Psi_0^*(\mathbf{R})\hat{H}\Psi_0(\mathbf{R})\mathrm{d}\mathbf{R} \end{aligned}$$

To approximate this energy, a trial wavefunction Ψ_T is first selected, satisfying certain conditions [FMNR01]:

1. Ψ_T and $\boldsymbol{\nabla}\Psi_T$ must be continuous wherever the potential is finite.

2. The integrals $\int \Psi_T^*\Psi_T$, $\int \Psi_T^*\hat{H}\Psi_T$, and $\int \Psi_T^*\hat{H}^2\Psi_T$ all must exist

With this trial wavefunction, the expected value of the Hamiltonian is calculated to be [FMNR01] [Aci97] [KW08]:

$$E_V = \frac{\int \Psi_T^*(\mathbf{R})\hat{H}\Psi_T(\mathbf{R})\mathrm{d}\mathbf{R}}{\int |\Psi_T(\mathbf{R})|^2\mathrm{d}\mathbf{R}} \geq E_0 \tag{7}$$

To use VMC, sampling needs to be conducted according to a certain probability distribution. The trial energy E_V can be considered as an expected value of all local energies E_{loc}. From Eq. (5), energy of the system in state $|\Psi\rangle$ can also be calculated as:

$$E = \frac{\hat{H}|\Psi\rangle}{|\Psi\rangle}$$

Therefore, each local energy sampled from $\mathbf{R}$ is evaluated to be [KW08]:

$$E_{\mathrm{loc}}(\mathbf{R}) = \frac{\hat{H}\Psi_T(\mathbf{R})}{\Psi_T(\mathbf{R})} \tag{8}$$

This gives the probability density for sampling to naturally be [KW08]:

$$f(\mathbf{R}) = \frac{|\Psi_T(\mathbf{R})|^2}{\int |\Psi_T(\mathbf{R})|^2 \mathrm{d}\mathbf{R}} \tag{9}$$

From Eq. (8) and Eq. (9), Eq. (7) becomes:

$$E_V = \int f(\mathbf{R}) E_{\mathrm{loc}}(\mathbf{R}) \mathrm{d}\mathbf{R} \tag{10}$$

which can be approximated by [FMNR01][Aci97]:

$$E_V \approx \frac{1}{M} \sum_{m=1}^{M} E_{\mathrm{loc}}(\mathbf{R}_m) \tag{11}$$

The essential steps of VMC have been established, showing how the ground-state energy can be estimated through Monte Carlo sampling. However, in this process, two key challenges remain: the choice and optimization of the trial wavefunction and the sampling of the configuration $\mathbf{R}$. These two aspects will be discussed in the following sections.

3.2 Selection and Optimization of the Trial Wavefunction

3.3 Sampling Method

In the previous section, it is discussed how a trial wavefunction can be selected and optimized. Yet, it is still unclear how a configuration $\mathbf{R}$ is sampled such that it satisfies the probability density in Eq. (9).

Naïvely, one should sample according to this probability density function. However, it should be noted that the integral present in the denominator of Eq. (9) becomes computationally implausible to calculate or normalize when the dimension of $\mathbf{R}$ scales, because as stated before, configuration $\mathbf{R}$ is a $3N$-dimensional vector. Furthermore, uniformly sampling in a $3N$-dimensional space suffers from the "curse of dimensionality" where if only a given number of data points are being sampled, the samples would be so sparse that they cannot represent the population well [MRR$^+$53]. Furthermore, depending on the form of the selected trial wavefunction, the wavefunction can take different shapes and correlations which further complicates a naïve sampling method.

Hence, Metropolis et al. developed an algorithm that accepts or rejects a configuration starting from an initial configuration using only probability ratios [MRR$^+$53]. This algorithm ensures that the final list of accepted configurations follows the same distribution as the probability density distribution [MRR$^+$53].

Analogous to the paper in which Metropolis et al. demonstrated how they sampled according to the Boltzmann distribution, the following steps is taken to sample the selected trial wavefunction [MRR$^+$53]:

1. Place the N particles in any configuration, and denote it as $\mathbf{R}_1$. Calculate $|\Psi_T(\mathbf{R}_1)|^2$.
2. Since the initial configuration is a vector that contains the Cartesian positions of N particles, it is possible to select one particle, say particle i, who has the initial position of (x_i, y_i, z_i), and displace particle within a small cube, say with an edge length of ε. Mathematically, this displacement is denoted as:

$$x_i \mapsto x_i + \varepsilon \delta_x, y_i \mapsto y_i + \varepsilon \delta_y, z_i \mapsto z_i + \varepsilon \delta_z$$

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where $\delta_x, \delta_y, \delta_z \in [-1, 1]$. Denote the new configuration as $\mathbf{R}_2$. Calculate $|\Psi_T(\mathbf{R}_2)|^2$.

3. Calculate the ratio between the amplitude probabilities of the two configurations:

$$p := \frac{|\Psi_T(\mathbf{R}_2)|^2}{|\Psi_T(\mathbf{R}_1)|^2}$$

4. If $p \geq 1$, confirm moving the particle to the new position. If $p < 1$, move the particle to the new position with probability p. Mathematically, move the particle to the new position with probability

$$P = \min(1, p)$$

5. If the new configuration is accepted, repeat step 2 to 4 which generates another configuration and determine whether to accept or reject it based on the latest accepted configuration. If the new configuration is rejected, start from the latest accepted configuration, and repeat step 2 to 4.

6. This above process returns a list of M configurations $\mathbf{R}_1, \mathbf{R}_2, \ldots, \mathbf{R}_M$.

This algorithm developed by Metropolis et al. prevents one from needing to sample configurations that grows exponentially large as the dimension scales, and efficiently generates a set of configurations who satisfy the probability distribution from the trial wavefunction.

From the list of M configurations, it is then possible to calculate the local energy for each configuration following Eq. (8), and compute the variational approximation of the ground-state energy using Eq. (11).

4 Diffusion Monte Carlo

Similar to VMC, the Diffusion Monte Carlo (abbreviated as DMC) method provides an alternative way of approximating the ground-state properties of a many-body system.

There exists a key difference between VMC and DMC. VMC method selects a trial wavefunction with respect to certain parameters and updates these parameters from results of an iteration to optimize the wavefunction, which leads to the convergence to ground-state properties. DMC method, however, starts with a trial wavefunction, instead of optimizing this wavefunction through updating parameters, it samples certain "walkers", which will be explained in detail later, and allows them to diffuse over time with respect to an appropriate function, such that they converge to the ground state.

4.1 Mathematical Background

Additional to Definition 3.4, DMC is based on the solution to a "modified" version of the time-dependent Schrödinger's equation, where it is written in imaginary time [Tro11] [FMNR01] [KW08]:

Definition 4.1. *A time-dependent Schrödinger's equation written in imaginary time is*

$$-\frac{\partial}{\partial \tau}\Psi(\mathbf{R}, \tau) = (\hat{H} - E_T)\Psi(\mathbf{R}, \tau)$$

where $\tau = \frac{\mathrm{i}t}{\hbar}$, and E_T is an energy offset.

Additionally, in [Tro11], it is shown that as $\tau \to \infty$, the solution wavefunction to the above equation will have the ground state dominating other states. Furthermore, the introduction of the energy offset allows the wavefunction to be normalized [Tro11].

For the wavefunction to "diffuse" in time, Green's function is needed to describe the process, where [Tro11] [FMNR01] [KW08]:

Definition 4.2. *A Green's function that describes the diffusion process for the wavefunction described above, $\Psi(\mathbf{R}, \tau)$, is given to be:*

$$G(\mathbf{R}, \mathbf{R}', \delta\tau) = \left\langle \mathbf{R} \middle| \exp\left(-\delta\tau(\hat{H} - E_T)\right) \middle| \mathbf{R}' \right\rangle \tag{12}$$

where $\delta\tau$ is the change in time.

This permits us to write the general wavefunction to be the result of a diffusion process [Tro11] [FMNR01] [KW08]:

$$\Psi(\mathbf{R}, \tau) = \int G(\mathbf{R}, \mathbf{R}', \tau)\Psi(\mathbf{R}', 0)\mathrm{d}\mathbf{R}'$$

where the Green's function acts like the probability density that the starting configuration $\mathbf{R}'$ evolves to $\mathbf{R}$ after time τ.

As $\delta\tau \to 0$, while assuming that $\hat{H} = \hat{T} + \hat{V}$, where $\hat{T}$ is the kinetic-energy operator and $\hat{V}$ is the potential-energy operator, by applying the Trotter-Suzuki formula and approximation for small $\delta\tau$, Eq. (12) can be rewritten as [Tro11] [FMNR01]:

$$G(\mathbf{R}, \mathbf{R}', \delta\tau) = (2\pi\delta\tau)^{-\frac{3N}{2}} \exp\left(-\frac{(\mathbf{R} - \mathbf{R}')^2}{2\delta\tau}\right) \exp\left(-\delta\tau \frac{V(\mathbf{R}) + V(\mathbf{R}') - 2E_T}{2}\right) \tag{13}$$

where the rate term [KW08]

$$p := \exp\left(-\delta\tau \frac{V(\mathbf{R}) + V(\mathbf{R}') - 2E_T}{2}\right) \tag{14}$$

determines the number of "walkers" that survive to the next step [FMNR01]. For each original "walker", the number of descendants that "branches" out is:

$$n_d := \mathrm{int}(p + \eta) \tag{15}$$

where int takes the integer part of the value, and η is a random number drawn uniformly at random on the interval $[0, 1]$ [Tro11] [FMNR01].

Additionally, the rest of Eq. (13) excluding Eq. (14) is a time propagator, G_d, which generates a random walk, and is a Gaussian distribution [Tro11][KW08].

4.2   Main Process

With the mathematical setup, it is possible to describe DMC in the following steps [KW08]:

Step 1: Sample the first generation of points $\mathbf{R}'$ according to a trial wavefunction $\Psi_T(\mathbf{R}')$.

Step 2: For each point in $\mathbf{R}'$, obtain a new set of points, which form a new configuration $\mathbf{R}$, by sampling according to the Gaussian distribution described by G_d, which gives us $\mathbf{R} - \mathbf{R}'$. This is where the idea of Monte Carlo is embedded.

Step 3: For each point in $\mathbf{R}$ and its corresponding point in $\mathbf{R}'$, generate n_d according to Eq. (15). If $n_d = 0$, remove the point from future random walks. If $n_d > 1$, replace the point with n_d clones.

Step 4: Adjust E_T accordingly to control the size of "walkers". After a sufficient enough time of repeating Step 2 and Step 3, for each point in the final configuration $\mathbf{R}_f$, find the ground-state energy by Eq. (11).

4.3 Importance Sampling

The process described above is generally extremely inefficient for a large number of particles due to possible complicated inter-particle interactions [Tro11], which can lead to Eq. (14) fluctuate wildly [FMNR01]. The technique of *importance sampling* is introduced to overcome these difficulties. Without extending into the mathematical details embedded in this technique, the key idea of the technique can be described as the following:

1. Design a *trial wavefunction*, $\Phi(\mathbf{R})$, that approximately describes the exact ground state Φ_0 [Tro11].

2. Introduce a new function $f(\mathbf{R}, \tau)$ such that [Tro11] [FMNR01]

$$f(\mathbf{R}, \tau) := \Phi(\mathbf{R})\Psi_T(\mathbf{R}, \tau) \tag{16}$$

where $f(\mathbf{R}, \tau)$ is interpreted as the probability density distribution of the population of "walkers" instead of $\Psi_T(\mathbf{R}, \tau)$.

3. Follow a similar diffusion process as described in the main process, except that, before deciding to "branch" or not, one need to introduce a *drift*, or *pseudo force*, $\mathbf{F}$, to the new configuration $\mathbf{R}$ relative to $\mathbf{R}'$, where [Tro11]

$$\mathbf{R} = \mathbf{R}' + \frac{\delta\tau}{2}\mathbf{F}(\mathbf{R}') \tag{17}$$

and

$$\mathbf{F} = \frac{2\nabla\Phi(\mathbf{R})}{\Phi(\mathbf{R})} \tag{18}$$

The introduction of the "drift" guides the walkers in regions with high probability, hence, reducing fluctuations in Eq. (14) and local energies [Tro11].

Another difficulty that DMC runs into is that it requires the wavefunction to be positive definite [FMNR01]. This means DMC can simulate Bosonic systems at zero temperature, but for fermionic systems like electronic systems that have positive and negative values due to antisymmetry, DMC runs into the *fermion sign problem*, which will be discussed in Section 6.1.

5 Path Integral Monte Carlo

6 Fermion Sign Problem

To generalize the fermion sign problem, it arises because of antisymmetric fermionic wavefunctions which produce weights of both signs in Monte Carlo [TW05]. This will lead to an exponential growth in statistical noise that prevents a Monte Carlo sampling from being possible and practical [TW05]. Computationally, the sign problem is NP-hard, which reflects a generic solution of the sign problem is non-existent unless NP = P [TW05].

Both DMC and PIMC suffer from this problem, and the following sections discuss briefly how each route overcomes this difficulty.

6.1 DMC - Fixed-node Approximation

The principle that DMC uses to "circumvent" the sign problem is to force the ground state of a fermionic system, described by a wavefunction Ψ_F, to have the same nodal structure as the trial

wavefunction, Ψ_T [Tro11]. Specifically, given a trial wavefunction Ψ_T that describes a N-particle system, find a trial nodal surface to be a $(3N-1)$-dimensional surface on which the function Ψ_T evaluates to 0, and crossing such a surface would change the sign of Ψ_T [FMNR01]. For a DMC simulation to proceed, this nodal constraint forces the "walkers" not to cross the nodal surface described above [Tro11]. This further indicates that the accuracy would be limited, and the result from such a modification only provides an upper bound to the actual ground-state energy [Tro11].

Acknowledgments

If you have discussions with your classmates about your chosen topic, you can thank them here.

Appendix

A   Monte Carlo Method

A.1   Using Monte Carlo Method to Find π

The link to the Jupyter Notebook that demonstrates this process can be accessed here on GitHub.

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