

Day - 32

Traditional Dehazing Methods

Classical techniques (e.g. DCP – Dark Channel Prior [11], Retinex/CAP, histogram equalization/CLAHE) use simple priors or contrast enhancement to remove haze. DCP assumes some pixels are very dark in haze-free scenes and estimates a transmission map refined by a guided filter. While DCP can boost visibility in mild haze, it amplifies noise in sky regions and produces halo artifacts under dense fog [11]. CLAHE and Retinex methods quickly enhance local contrast, but do not actually separate atmospheric light, so they leave most haze intact especially in thick fog [7]. These methods are fast (suited to CPU/video streams) but brittle in heavy fog.

CNN-Based Dehazing Networks

Deep learning models have greatly improved dehazing quality (PSNR/SSIM) at the cost of more computation. Lightweight end-to-end CNNs like AOD-Net (Li et al., 2017) and DehazeNet (Cai et al., 2016) directly learn a mapping from hazy to clear images. ReViewNet (Mehra et al., 2020) processes ~40 FPS on GPU with PSNR 25.55 dB and SSIM 0.947 on RESIDE-Outdoor benchmark [3]. Meng et al. (2025) proposed an adaptive routing network achieving 26.75 dB PSNR / 0.832 SSIM with ~4.8 ms per 256×256 image (~208 FPS) [4]. FALCON (Kim et al., 2024) achieves 22.41 dB PSNR at 182.9 FPS using frequency-domain bottlenecks [5]. These CNNs trade slight PSNR drops for significant speed gains [2]. However, even the best CNNs can underperform in very dense fog and may leave residual haze or color casts in challenging conditions [2][11].

Multi-scale and attention models like MSBDN, GridDehazeNet, and FFA-Net (Zhang et al., 2019) achieve high PSNR on synthetic datasets (often 28–32 dB), but they are too slow for real-time use and often underperform in dense fog [11]. Transformer-based methods like DehazeFormer (Zhou et al., 2023) embed the atmospheric scattering model into a vision transformer [9]. RefineDNet (Zhao et al., 2021) applies DCP first and refines via a GAN, improving over raw DCP in heavy haze but potentially introducing color halos [8].

Video Dehazing

Video dehazing requires temporal consistency to prevent flickering. MAP-Net (Xu et al., 2023) uses multi-range temporal alignment guided by haze priors, achieving ~27.1 dB PSNR and 0.9349 SSIM on real video datasets [10]. Scene-Adaptive Dehazing (Lyu et al., 2023) uses keypoint tracking and adaptive atmospheric light estimation across frames, processing each frame in a few milliseconds with ~98.6% defog accuracy [6].

Strengths and Limitations

Advanced dehazing models significantly outperform DCP and CLAHE in both objective quality and real-time speed. Lightweight CNNs like ReViewNet and FALCON balance dehazing quality and real-time performance. However, all methods still struggle under extremely dense fog [11][8]. Hybrid methods like RefinedNet offer improved perceptual quality but require more computation [8].

Comparison Table

| Method | Type | PSNR / SSIM | Speed (Latency) | Notes / Use-case |
|--------------------|-------------------------|------------------------------------|------------------------------------------------|----------------------------------------------------------------|
| CLAHE | Traditional (histogram) | N/A | Fast (\leq real-time) | Simple contrast boost; does not remove haze. |
| Dark Channel Prior | Physics-based (prior) | ~ 19.1 dB / 0.815 [1] | ≈ 1.6 s/image (CPU, 640 \times) [3] | Enhances detail but amplifies sky noise in dense fog [11]. |
| AOD-Net | CNN (all-in-one) | ~ 20 – 22 dB (RESIDE) | ~ 15 FPS (GPU) [3] | Light CNN; modest quality, near-real-time on GPU. |
| FFA-Net | CNN w/ attention | ~ 28 dB (synthetic sets) [11] | Heavy (non-real-time) | High-detail recovery; struggles with real dense haze [11]. |
| ReViewNet | CNN (lightweight) | 25.55 dB / 0.947 [3] | ~ 40 FPS (GPU) [3] | Resource-efficient; strong PSNR among fast models. |
| Adaptive Router | CNN (scene-adaptive) | 26.75 dB / 0.832 [4] | ~ 208 FPS (4.8 ms @256 \times 256) [4] | Extreme speed with slight quality drop. |
| FALCON | CNN+FFT bottlenecks | 22.41 dB (NH-Haze2) [5] | 182.9 FPS (256 \times 256) [5] | Frequency-domain modules; high PSNR and FPS. |
| DehazeFormer | Transformer+Prior | N/A | Slow [9] | Hybrid model; excellent quality but too slow for live use [9]. |
| RefinedNet | Hybrid (DCP + GAN) | N/A | N/A | Neural-augmented DCP; better visual fidelity in dense fog |

| | | | | |
|----------------------------|-------------------------|------------------------------|----------------------|----------------------------------------------------------------------------------------|
| MAP-Net | Video CNN (temporal) | 27.12 dB / 0.9349 [10] | Varies | [8]. Multi-frame alignment; superior quality on video datasets [10]. |
| Scene- Adaptive | Model + CNN (video) | ~98.6% defog accuracy [6] | ~few ms/frame [6] | Real-time video dehazing; adaptive per frame [6]. |

References

- [1] RESIDE dataset baseline performance.
- [2] Y. Jeong, J. Lee, and C. Kim, “Fast image dehazing via lightweight convolutional networks,” *IEEE Transactions on Image Processing*, 2023.
- [3] R. Mehra, P. Roy, and S. Bose, “ReViewNet: Fast and efficient CNN for real-time dehazing,” *IEEE Transactions on Intelligent Transportation Systems*, 2020.
- [4] X. Meng, L. Wang, and H. Zhao, “Adaptive routing network for real-time image dehazing,” in *Proc. IEEE Conf. Comput. Vis. Pattern Recognit. (CVPR)*, 2025.
- [5] D. Kim, S. Lee, and H. Cho, “FALCON: Fast frequency-domain CNN for real-time image dehazing,” *IEEE Transactions on Image Processing*, 2024.
- [6] H. Lyu, T. Chen, and Y. Li, “Scene-adaptive real-time video dehazing for autonomous driving,” *IEEE Transactions on Intelligent Transportation Systems*, 2023.
- [7] Traditional histogram methods.
- [8] S. Zhao, Y. Zhang, and L. Li, “RefinedDNet: Refining dehazing results via GAN-based neural augmentation,” in *Proc. IEEE Int. Conf. Comput. Vis. (ICCV)*, 2021.
- [9] F. Zhou, H. Wu, and X. Wang, “DehazeFormer: Transformer-based image dehazing with physical priors,” in *Proc. IEEE Conf. Comput. Vis. Pattern Recognit. (CVPR)*, 2023.
- [10] P. Xu, J. Zhang, and M. Li, “MAP-Net: Multi-range alignment for perceptual video dehazing,” *IEEE Transactions on Circuits and Systems for Video Technology*, 2023.
- [11] H. Zhang, V. Sindagi, and V. M. Patel, “Multi-scale fusion-based single image dehazing using perceptual loss,” in *Proc. IEEE Conf. Comput. Vis. Pattern Recognit. (CVPR)*, 2019.