Vanshil Shah

Website: vanshilshah97.github.io

EDUCATION

• University of Pennsylvania

Philadelphia, USA

MS in Mechanical Engineering with Robotics Specialisation | GPA 4.0/4.0

Aug. 2021 - May 2023

Relevant coursework: Machine Learning, Introduction to Robotics, Design of Mechatronic system

 \bullet Institute of Technology, Nirma University

Gujarat, India

Bachelor of Technology in Mechanical Engineering | CGPA 8.12/10.0

Aug. 2015 - May 2019

Publications

- Prashant Kumar*, Sabyasachi Sahoo*, Vanshil Shah, Vineetha Kondameedi, Abhinav Jain, Akshaj Verma, Chiranjib Bhattacharyya, Vinay V. "DSLR: Dynamic to Static LiDAR scan Reconstruction using adversarially trained autoencoder" (Proceedings of the AAAI Conference on Artificial Intelligence 2021)
- Unni Krishnan R Nair*, Anish Gupta*, D. A. Sasi Kiran, Ajay Shrihari, Vanshil Shah, K. Madhava Krishna "Non Holonomic Collision Avoidance under Non-Parametric Uncertainty: A Hilbert Space Approach" (Proceedings of European Control Conference (ECC) 2021)

WORK EXPERIENCE

• ZF Friedrichshafen

Feb 2021 - June 2021

SDE, Machine Learning and Data Team

Varun Jain

- Made a framework for automating the Global Talent tracker using Microsoft Sharepoint API
- o Deployed the whole framework on Azure as a Function App for periodic updation
- Indian Institute of Science(IISc), Bangalore

Nov 2019 - Sept 2020

Research Intern, Machine Learning Lab | Collaboration: Ati Motors

Sabyasachi Sahoo

- Integrated Google Cartographer with our model DSLR for improving navigation in a dynamic setting.
- Devised a novel dataset generation pipeline to create a first of its kind LiDAR based static-dynamic frame dataset.
- Achieved 4 times better reconstruction on Chamfer Distance over state of the art baselines.
- Robert Bosch Center for Cyber Physical Studies(RBCCPS), Bangalore

June 2019 - Nov 2019

Perception Team, MBZIRC 2020 | Collaboration: TCS Innovation Labs

Dr. Raghu Krishanpuram

- Benchmarked visual SLAM algorithms for facilitating quad copter autonomy in degraded environments [Video]
- Defence Research and Development Organisation(DRDO), Bangalore

Jan 2019 - May 2019

Research Intern, Center for Artificial Intelligence and Robotics

Dr. Shubhashisha Sahoo

• Deployed the navigation stack on autonomous tracked robots used by Indian Defence Forces.

PROJECTS

- MEAM 520: Pick and Place challenge 2021
 - Developed a modular library for facilitating dexterous manipulation of Franka Panda arm. [Video](Hardware) [Video](Simulation)
- Search and Rescue Snake Robot
 - Fabricated a modular snake robot with the purpose of inspection in narrow crevices. [Video](Hardware) [Video](Simulation)

SKILLS

Deep Learning Framework: PyTorch Languages: C++, Python Software tools: Git, LATEX, CMake

Simulator: Carla, Gazebo, V-REP ROS Misc: Azure