

# Autonomous Vehicles Research Studio

Setup Guide – Workspace Setup and Safety

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**This equipment is designed to be used for educational and research purposes and is not intended for use by the public.** The user is responsible for ensuring that the equipment will be used by technically qualified personnel only. **NOTE:** While the GPIO, and USB ports provides connections for external user devices, users are responsible for certifying any modifications or additions they make to the default configuration.

#### Waste Electrical and Electronic Equipment (WEEE)



This symbol indicates that waste products must be disposed of separately from municipal household waste, according to Directive 012/19/EU of the European Parliament and the Council on waste electrical and electronic equipment (WEEE). All products at the end of their life cycle must be sent to a WEEE collection and recycling center. Proper WEEE disposal reduces the environmental impact and the risk to human health due to potentially hazardous substances used in such equipment. Your cooperation in proper WEEE disposal will contribute to the effective usage of natural resources.

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## A. Operator Warnings



### Caution

This symbol marks specific safety warnings and operating procedures that are important for the safety of the Autonomous Vehicles Research Studio users and involved vehicles (QDrone 1/2 and QBot 2/2e). Read these warnings carefully.



### Caution

The QDrone 1/2 are powerful and potentially dangerous vehicles if used improperly. Always follow safe operating procedures when using the QDrone. Quanser is not responsible for damages and injury resulting from improper or unsafe use of the QDrone.



### Caution

The QBot 2/2e is a powerful and potentially dangerous vehicle if used improperly. Always follow safe operating procedures when using the QBot 2/2e. Quanser is not responsible for damages and injury resulting from improper or unsafe use of the QBot 2/2e.



### Caution

Before connecting batteries or attempting to run the QDrone 1/2, be sure to read this document and become familiar with the safety features and operating procedures of the QDrone 1/2.



### Caution

Before connecting batteries or attempting to run the QBot 2/2e, be sure to read this document and become familiar with the safety features and operating procedures of the QBot 2/2e.



### Caution

When handling the QDrone 1/2, always make sure there are no models running and that the power is turned off, unless otherwise and explicitly stated. The user should always wear protective gloves and safety eye goggles (provided), even when not in the workspace.



### Caution

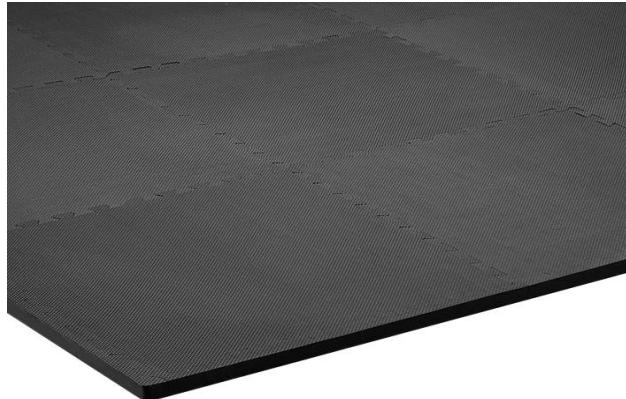
The vehicles in the Autonomous Vehicles Research Studio use Lithium Polymer (LiPo) and Lithium Ion (Li-ion) batteries as their power source. Please carefully read and follow the safety guidelines and warnings regarding LiPo and Li-ion battery handling.

### Note

This document consists of numerous important details that are highlighted in the form of notes. Please read these carefully.

## B. Floor Mats

The **Autonomous Vehicles Research Studio** comes with 2 ft x 2 ft interlocking rubber mats, as seen in Figure 1, that are intended to protect the drones from drop impacts to the floor and reduce reflections off of the floor.



*Figure 1. Interlocking rubber flooring*

Keep the following in mind:

**Note:** The entire localization workspace should be covered with the floor matting

**Note:** The floor mats can be cleaned with soap and water

**Note:** The boundary outline of the localization workspace can be marked using tape, which will come in handy when orienting and calibrating the localization cameras.



**Caution:** When wet, the floor mats can be slippery



**Caution:** Broken propellers can get lodged into the floor mats and would pose a walking hazard. Inspect the mats and remove any debris from time to time.

## C. Netting

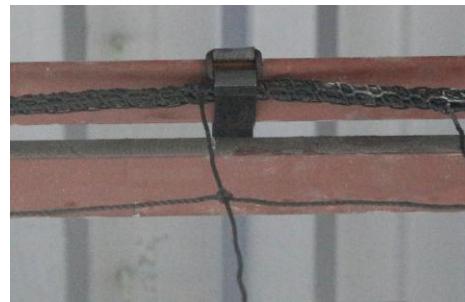
The **Autonomous Vehicles Research Studio** comes with multiple of 20 ft (length) x 20 ft (height) (approx. 6m x 6m) netting that is required to protect the users from autonomous vehicles operating in the workspace. This netting can be attached to the ceiling using Velcro straps (also provided, Figure 2). Also secure the net at the base (table legs, wall hooks etc.) to ensure that the net is taut.



a. Attaching a net to a false ceiling using Velcro straps



b. Velcro strap attachment



c. Attaching net to I-beams

Figure 2: Attaching the netting using Velcro straps to a false ceiling/I-beam

Keep the following in mind:

**Note:** Always secure the net when flying - manually or autonomously

**Note:** Ensure the net is tightly secured and stretched (attached to both the top and bottom), and that there are no openings for the drone to pass through the net

**Note:** Safety eyeglasses should always be worn, even outside the net.

**Note:** Whenever a drone flies into the net, verify that the netting has not been damaged in any way.

**Note:** Do not attach the netting to the same mounts as the localization system. When the net is pulled, the localization system may be disturbed, resulting in a loss of calibration.



**Caution:** The net can be a tripping hazard



**Caution:** Never cross the net into the workspace when a model is running



**Caution:** Do not stand close to the net; if a drone flies into the net, the net will deflect

## D. General Safety Guidelines

The **Autonomous Vehicles Research Studio** comes with safety eyeglasses, as well as protective gloves. Keep the following in mind:

**Note:** Safety eyeglasses should always be worn, even outside the net.

**Note:** Always assume the QDrone is live until the battery is disconnected.

**Note:** Always manipulate the drone from the handle mounted on the top of the frame (Figure 3)

**Note:** After crashes, inspect the QDrone for damaged structure or wiring. If wires are exposed, repair them immediately.



Figure 3: QDrone handle on top frame



**Caution:** Always remove propellers when running a model on the QDrone outside of the netting.



**Caution:** The propellers on the QDrone have sharp edges.



**Caution:** Always wear the gloves and safety eyeglasses when installing or removing propellers.

## E. Studio Space

The area within the installed netting space will be referred to as the workspace. The ground control station components (PC, router, battery chargers, joystick, and any vehicles not in use) should be placed outside the workspace and away from operating vehicles. Set up a dedicated space for the ground control station PC (with monitors) in a way that the user can visually inspect the workspace at all times. Ideally, the user should be able to see the workspace and monitors at the same time. The Localization system should be placed within the workspace to avoid the netting blocking the camera's viewpoint.

## F. Checkpoint – Workspace Picture

Take a picture of your workspace with the netting and matting to confirm with a Quanser engineer or technical support specialist ([tech@quanser.com](mailto:tech@quanser.com)) that the workspace is properly configured.

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