

Recommended Assessment

Play

1. When you used the left stick to turn the robot, what were the left and right wheel speeds? When you used the right stick to drive the robot forward and backward, what were the wheel speeds then?

2. What differences did you observe in video quality observed between the RGB feed and downward facing camera feed? What could have contributed to the differences?

3. What kind of information does the depth camera and LiDAR provide? How do they vary from each other and what limitations did you observe?