# Incremental Coarse-to-Fine Parsing

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#### Incremental Motivation

#### Understanding ... One Step at a Time

- ► Cognitive motivations
  - Operates on incomplete information (Cloze testing)
- Engineering motivations
  - Can make use of information about recent content/structure (coreference, pragmatics)
  - Unsegmented input
  - $\triangleright$   $\mathcal{O}(n)$  Streaming task

### Coarse-to-Fine Motivation

What is it?

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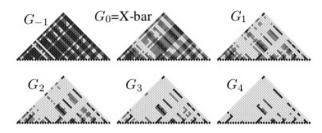
#### What is it?

► A way of improving parse speed/accuracy through pruning the search space.

#### Coarse-to-Fine Motivation

#### What is it?

- ▶ A way of improving parse speed/accuracy through pruning the search space.
- It has massively sped up parsers in the recent past
  - ▶ [Petrov and Klein, 2007] 50x



### CTF Theory

How does it work?

# CTF Theory

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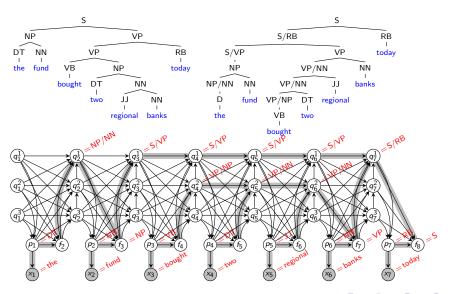
Parse in phases [Charniak et al., 2006]

### **CTF** History

Some ways of implementing Coarse-to-Fine:

- ▶ Do it by hand [III and Kaplan, 1993, Charniak et al., 2006] or machine [Petrov and Klein, 2007]
- Single or Multi-layered
- ▶ If we assume the Berkeley Parser paradigm:
  - ► Trainer derives split-merge grammar files
  - Initialization phase creates a predictive chain back to coarse grammar

# Sequence Model Parsing



Split-Merge Berkeley Grammar Trainer [Petrov et al., 2006]

- Input: Boring tagged sentences (S (ADVP happily) (NP-SUBJ John)...)
- ▶ EM classification performed over a given number of split-merge cycles
- Output: Sleek new PCFG (S^g\_10 -> ADVP^g\_21 NP^g\_4 1.462527E-18) WOW!

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- Training time
- Increased size of grammar

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- Input: Sleek newly obtained PCFG (S^g\_10 → ADVP^g\_21 NP^g\_4 1.462527E-18)
- ► Generate virtual trees to give probabilities of component productions
- ► Output: Phase-, depth-specific grammar (B 2 S^g\_10 ADVP^g\_21 → NP^g\_4 2.348767*E*-20)

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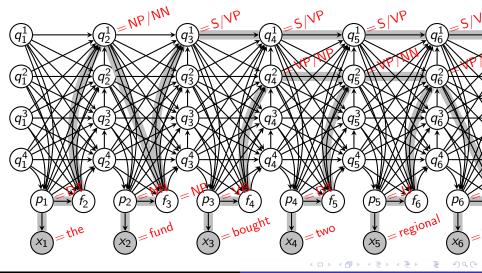
#### How does this work?

Approximate Inference

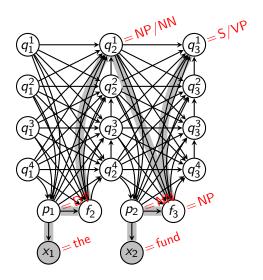
#### Variable Descriptions

- $lackbox{ } q_t^d$  represents an element of working memory/incomplete constituent
- ▶ These are decomposed into  $a_t^d$  and  $b_t^d$
- x<sub>t</sub> is the observation at time t
- $ightharpoonup p_t$  is the preterminal that expands into that observation
- f<sub>t</sub> is the final state obtained by integrating a new observation into the parse (expansion state)

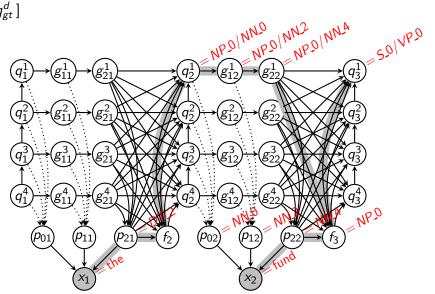
 $[q_t^d]$ 



 $\left[\,q_t^d\,\right]$ 



 $[q_{gt}^d]$ 



Theory/Equation time Most likely sequence

$$\hat{q}_{1...T}^{1...D} \stackrel{\text{def}}{=} \underset{q_{1...T}^{1...D}}{\operatorname{argmax}} \prod_{t=1}^{T} \mathsf{P}_{\theta_{Q}}(q_{t}^{1...D} \mid q_{t-1}^{1...D} \mid p_{t-1}) \cdot \mathsf{P}_{\theta_{P,d'}}(p_{t} \mid b_{t}^{d'}) \cdot \mathsf{P}_{\theta_{X}}(x_{t} \mid p_{t})$$
(1)

where d' is the lowest non-empty  $q_t^d$ 

Theory/Equation time

Right-Corner: Single expansion, Single reduction

E-R+, E-R-, E+R+, E+R-

 $\theta_Q$ 

$$\begin{split} & \mathsf{P}_{\theta_{Q}}(q_{t}^{1..D} \mid q_{t-1}^{1..D} \mid \rho_{t-1}) \\ & \stackrel{\mathrm{def}}{=} \mathsf{P}_{\theta_{E}}(``` \mid b_{t-1}^{d'} \mid \rho_{t-1}) \cdot \mathsf{P}_{\theta_{A,d'}}(``-' \mid b_{t-1}^{d'-1} \mid a_{t-1}^{d'}) \cdot \llbracket a_{t}^{d'-1} = a_{t-1}^{d'-1} \rrbracket \cdot \mathsf{P}_{\theta_{B,d'-1}}(b_{t}^{d'-1} \mid b_{t-1}^{d'-1} \mid a_{t-1}^{d'}) \\ & \cdot \llbracket q_{t}^{1..d'-2} = q_{t-1}^{1..d'-2} \rrbracket \cdot \llbracket q_{t}^{d'} \cdot D = `-' \rrbracket \\ & + \mathsf{P}_{\theta_{E}}(``` \mid b_{t-1}^{d'-1} \mid \rho_{t-1}) \cdot \mathsf{P}_{\theta_{A,d'}}(a_{t}^{d'} \mid b_{t-1}^{d'-1} \mid a_{t-1}^{d'}) \cdot \mathsf{P}_{\theta_{B,d'}}(b_{t}^{d'} \mid a_{t-1}^{d'} \mid a_{t-1}^{d'+1}) \\ & \cdot \llbracket q_{t}^{1..d'-1} = q_{t-1}^{1..d'-1} \rrbracket \cdot \llbracket q_{t}^{d'+1..D} = `-' \rrbracket \\ & + \mathsf{P}_{\theta_{E}}(``1' \mid b_{t-1}^{d'} \mid \rho_{t-1}) \cdot \mathsf{P}_{\theta_{A,d'}}(``-' \mid b_{t-1}^{d'} \mid \rho_{t-1}) \cdot \llbracket a_{t}^{d'} = a_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{\theta_{B,d'}}(b_{t}^{d'} \mid b_{t-1}^{d'} \mid \rho_{t-1}) \\ & \cdot \llbracket q_{t}^{1..d'-1} = q_{t-1}^{1..d'-1} \rrbracket \cdot \llbracket q_{t}^{d'+1..D} = `-' \rrbracket \\ & + \mathsf{P}_{\theta_{E}}(``1' \mid b_{t-1}^{d'} \mid \rho_{t-1}) \cdot \mathsf{P}_{\theta_{A,d'}}(a_{t}^{d'+1} \mid b_{t-1}^{d'} \mid \rho_{t-1}) \cdot \mathsf{P}_{\theta_{B,d'}}(b_{t}^{d'+1} \mid a_{t}^{d'+1} \mid \rho_{t-1}) \\ & \cdot \llbracket q_{t}^{1..d'} = q_{t-1}^{1..d'} \rrbracket \cdot \llbracket q_{t}^{d'+2..D} = `-' \rrbracket \end{aligned}$$

Theory/Equation time  $\theta_{F.d.g}$ 

$$\mathsf{P}_{\theta_{F,d,g}}(f_G \mid b_G, p_G) \stackrel{\text{def}}{=} \begin{cases} \mathsf{P}_{\theta_{F,d}}(f_G \mid b_G, p_G) & \text{if } g = 0\\ 1 & \text{else} \end{cases}$$
 (3)

 $\theta_{A,d,g}$ 

$$\mathsf{P}_{\theta_{A,d,g}}(\mathsf{a}_g \mid b_G, f_G, \pi(\mathsf{a}_g)) \stackrel{\text{def}}{=} \frac{\max_{\mathsf{a}_G \mid \mathsf{a}_g \prec \mathsf{a}_G} \mathsf{P}_{\theta_{A,d,g}}(\mathsf{a}_G \mid b_G, f_G, \pi(\mathsf{a}_G))}{\max_{\mathsf{a}_G' \mid \pi(\mathsf{a}_g) \prec \mathsf{a}_G'} \mathsf{P}_{\theta_{A,d,g}}(\mathsf{a}_G' \mid b_G, f_G, \pi(\mathsf{a}_G'))} \quad (4)$$

$$= \frac{\max_{a_G \mid a_g \prec a_G} P_{\theta_{A,d}}(a_G \mid b_G, f_G)}{\max_{a'_G \mid \pi(a_g) \prec a'_G} P_{\theta_{A,d}}(a'_G \mid b_G, f_G)}$$
(5)

# Theory/Equation time $\theta_{B,d,g}$

a) Active Transition

$$\mathsf{P}_{\theta_{B,d,g}}(b_g \mid a_g, f_G, \pi(b_g)) \stackrel{\text{def}}{=} \frac{\max_{b_G, a_G \mid b_g \prec b_G, a_g \prec a_G} \mathsf{P}_{\theta_{B,d,g}}(b_G \mid a_G, f_G, \pi(b_G))}{\max_{b'_G, a_G \mid \pi(b_g) \prec b'_G, a_g \prec a_G} \mathsf{P}_{\theta_{B,d,g}}(b'_G \mid a_G, f_G, \pi(b'_G))}$$
(6)

$$= \frac{\max_{b_G, a_G \mid b_g \prec b_G, a_g \prec a_G} \mathsf{P}_{\theta_{B,d}}(b_G \mid a_G, f_G)}{\max_{b_G', a_G \mid \pi(b_g) \prec b_G', a_g \prec a_G} \mathsf{P}_{\theta_{B,d}}(b_G' \mid a_G, f_G)}$$
(7)

b) Awaited Transition

$$P_{\theta_{B,d,g}}(b_{g} | b'_{G}, f_{G}, \pi(b_{g})) \stackrel{\text{def}}{=} \frac{\max_{b_{G} | b_{g} \prec b_{G}} P_{\theta_{B,d,g}}(b_{G} | b'_{G}, f_{G}, \pi(b_{G}))}{\max_{b''_{G} | \pi(b_{g}) \prec b''_{G}} P_{\theta_{B,d,g}}(b''_{G} | b'_{G}, f_{G}, \pi(b''_{G}))} = \frac{\max_{b_{G} | b_{g} \prec b_{G}} P_{\theta_{B,d}}(b_{G} | b'_{G}, f_{G})}{\max_{b''_{G} | \pi(b_{g}) \prec b''_{G}} P_{\theta_{B,d}}(b''_{G} | b'_{G}, f_{G})} \qquad (9)$$



Theory/Equation time  $\theta_{P,d,g}$ 

$$\mathsf{P}_{\theta_{P,d,g}}(p_g \mid b_g, \pi(p_g)) \stackrel{\text{def}}{=} \frac{\max_{p_G, b_G \mid p_g \prec p_G, b_g \prec b_G} \mathsf{P}_{\theta_{P,d,g}}(p_G \mid b_G, \pi(p_G))}{\max_{p_G', b_G \mid \pi(p_g) \prec p_G', b_g \prec b_G} \mathsf{P}_{\theta_{P,d,g}}(p_G' \mid b_G, \pi(p_G'))}$$
(10)

$$= \frac{\max_{p_{G}, b_{G} \mid p_{g} \prec p_{G}, b_{g} \prec b_{G}} \mathsf{P}_{\theta_{P,d}}(p_{G} \mid b_{G})}{\max_{p'_{G}, b_{G} \mid \pi(p_{g}) \prec p'_{G}, b_{g} \prec b_{G}} \mathsf{P}_{\theta_{P,d}}(p'_{G} \mid b_{G})}$$
(11)

 $\theta_{X,g}$ 

$$\mathsf{P}_{\theta_{X,g}}(x \mid p_g) \stackrel{\text{def}}{=} \frac{\max_{p_G \mid p_g \prec p_G} \mathsf{P}_{\theta_{X,g}}(x \mid p_G)}{\max_{p_G' \mid \pi(p_g) \prec p_G'} \mathsf{P}_{\theta_{X,g}}(x \mid p_G')} \tag{12}$$

$$= \frac{\max_{p_G \mid p_g \prec p_G} \mathsf{P}_{\theta_X}(x \mid p_G)}{\max_{p_G' \mid \pi(p_g) \prec p_G'} \mathsf{P}_{\theta_X}(x \mid p_G')} \tag{13}$$

### **Paydirt**

### Timing Results

System	CTF-FAWP	FAWP	Diff	
5sm-2000	30.3	61.05	0.496	
4sm-500	4.16	7.17	0.580	
3sm-500	2.11	4.83	0.437	
2sm-500	1.64	3.35	0.490	
		Ave	0.50	

Timing results with varying sm. (sec/sent)

### **Paydirt**

### CTF-FAWP Timing Results

System	Time	
3sm-2000	8.27	
3sm-1000	4.26	
3sm-500	2.00	
3sm-250	0.87	
3sm-100	0.33	

Timing results with varying beam-width. (sec/sent)

### **Paydirt**

### CTF Accuracy Results

System	Recall	Prec	F
Petrov Klein (Reported, 10-best)	91.2	91.1	91.2
Petrov Klein (5sm, U+B, 1-best)	88.5	88.8	88.7
Petrov Klein (5sm, Binary, 1-best)	88.2	87.9	88.0
FAWP (5sm, b5000)	87.9	87.7	87.8
CTF-FAWP (5sm, b5000)	88.0	87.6	87.8
FAWP (5sm, b2000)	87.7	87.6	87.6
CTF-FAWP (5sm, b2000)	86.2	86.3	86.3

Accuracy of CTF on various incarnations of FAWP.

### And Beyond!

# Future Work Where to now?

- Condition on more variables (MaxEnt)
- Weight predictions based on proportion of total beam predictions; More NP predictions make NP a better guess.

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### The Model

